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Brownian Motion and Thermophoresis Effects on MHD Three Dimensional Nanofluid Flow with Slip Conditions and Joule Dissipation Due to Porous Rotating Disk

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Abstract: This paper examines the time independent and incompressible flow of magnetohydrodynamic (MHD) nanofluid through a porous rotating disc with velocity slip conditions. The mass and heat transmission with viscous dissipation is scrutinized. The proposed partial differential equations (PDEs) are converted to ordinary differential equation (ODEs) by mean of similarity variables. Analytical and numerical approaches are applied to examine the modeled problem and compared each other, which verify the validation of both approaches. The variation in the nanofluid flow due to physical parameters is revealed through graphs. It is witnessed that the fluid velocities decrease with the escalation in magnetic, velocity slip, and porosity parameters. The fluid temperature escalates with heightening in the Prandtl number, while other parameters have opposite impacts. The fluid concentration augments with the intensification in the thermophoresis parameter. The validity of the proposed model is presented through Tables.

Keywords: nanofluid; porous medium; MHD; viscous dissipation; slip effect; rotating disk; HAM; shooting

1. Introduction

Nanofluid is the suspension (mixture) of base fluid (water, gasoline oil, kerosene oil, ethylene glycol) and nanometer-sized particles, which is called nanofluid. Nanofluids are made of different



martials, like metals (Ag, Au, Cu), carbon (CNTs, diamonds, graphite), metal nitrides and oxide ceramics (CuO, Al₂O₃), etc. In the current science era, nanofluid has turned in a significant constituency of research. Due to its extensive variety of applications in science, engineering, and technologies, like computers, heating and cooling devices, microelectronics, heat exchanger MHD micropumps, etc. Therefore, nanofluid flow in microchannel captivated the significant consideration of researchers. In the last several years, these fluids have been comprehensively use, one of them being 'nanofluid'. The word in this context nanofluid had first been actually invented by Choi [1], which characterizes the dilution of nanoscale materials in a base body fluid, like ethylene glycol, water, and oil. Makinde and Aziz [2] reported the heat transfer flow of nanofluid through the extending sheet. Turkyilmazoglu et al. [3] analyzed the cumulative consequences of the mass and heat transfer of nanofluids across a horizontal plate, together with radiation. Mustafa et al. [4] examined the boundary layer flow of nanofluid over a rashly stretched surface. Ashorynejad et al. [5] investigated the properties of MHD nanofluid flow and heat transmession. Murthy et al. [6] observed the thermal conduction transfer rate of stratified nanofluid coated with a non-dark porous medium thorough a horizontal layer. Rashidi et al. [7] demonstrated the entropy production of nanofluid in the existence of a magnetic field that is caused by a rotated porous disk. Tham et al. [8] examined the convection flow of gyrotactic microorganism-containing nanofluid to a solid sphere encoded in a porous medium. Aziz et al. [9] have reported convection heat transfer flow that is caused by nanofluid across a vertical flat plate comprising motile microorganisms. Shah et al. [10] numerically deliberated the heat transfer in MHD nanofluid with shape factor in permeable media. Zubair et al. [11] presented the MHD Casson nanofluid flow with entropy generation. Kumam et al. [12] scrutinized the radiative flow of MHD Casson nanofluid with entropy generation in rotating channels. Shah et al. [13] studied the ferrofluid with Cattaeo heat flux by means of thermal conductivity model.

Air cleaning machines, centrifugal filtration, food processing, power penetration, gas turbines rotors, medical apparatus, etc. are the real-world applications of rotating fluids flow documented by researchers. The viscous fluid flow by rotating disk was initially reported by Karman [14]. The MHD slip flow with entropy generation analysis by rotating disk was deliberated by Rashidi et al. [15]. Sheikholeslami et al. numerically analyzed the nanofluid flow through rotating disk [16]. Xun et al. [17] scrutinized the heat transfer in a fluid flow due to rotating disk. Latiff et al. examined the bioconvective flow of fluid due to rotating disk [18]. Imtiaz et al. [19] determined the MHD slip flow by rotating disk. Doh and Muthtamilselvan [20] probed the MHD fluid flow by rotating disk. Ellahi et al. [21] deliberated the multi-fluid flow with nano-sized gold and silver particles by rotating disk. Hayat et al. [22] explored the MHD fluid flow with slip conditions by rotating disk. Bhatti et al. [23] analyzed the MHD non-Newtonian nanofluid with entropy generation over a shrinking surface. Shah et al. [24] deliberated the MHD thin film flow of nanofluid through a rotating disk. Dawar et al. [26] scrutinized the MHD thin film flow by a rotating disk. Recently, Asma et al. analyzed the flow of nanofluid with chemical reaction [27]. Others related articles can be seen in [28–32].

The procedure of heat transmission in engineering and industrial processes is exceedingly dependent on the structure of the surface from which heat transfer occurs to the fluid. The phenomenon of heat transmission occurs due to temperature differences. The heat transfer process can be studied via convective boundary condition, constant or prescribed surface temperature, constant or prescribed heat flux, and Newtonian heating. Vo et al. studied heat transport in the flow of nanomaterial with porous medium over a permeable stretched sheet [33]. Sheikholeslami et al. [34,35] examined magnetohydrodynamic flow of heated nanofluid with thermal radiation in a porous enclosure. They used numerical approached. Recent study about heat transfer and nanofluid with different approached in different geometries can be seen [36–39].

Here, in this article, we have presented the MHD nanofluid flow through a porous rotating disk with slip conditions. The impact of heat source sink is also studied. The nanofluid flow is analyzed with thermophoresis and Brownian motion impacts. The joule dissipation influence is also taken in

this nanofluid flow phenomenon. Analytical and numerical approaches are applied to examine the modeled problem and also compared each other, and good results were obtained.

2. Problem Formulation

The MHD nanofluid flow subject to velocity slip conditions is considered here. The nanofluid flow is considered as time dependent and incompressible. The flow is studied over a rotating porous disk. The disk rotates along *z*-axis with angular velocity Ω (see Figure 1). The magnetic field is functional along the *z*-direction. The electric and Hall current influences are ignored throughout the study. The fluid flow is treated with viscous dissipation impact. The heat and mass transmission characteristics are analyzed in the presence of thermophoresis and Brownian motion impacts. The nanofluid flow is based on the present situations [5,22,29]:

$$u_r + \frac{u}{r} + w_z = 0, \tag{1}$$

$$uu_{r} - \frac{v^{2}}{r} + wu_{z} = v \left(u_{rr} + \frac{u_{r}}{r} - \frac{u}{r^{2}} + u_{zz} \right) - \left(\frac{\sigma B_{0}^{2}}{\rho_{f}} u + \frac{v}{K} u \right),$$
(2)

$$uv_r + \frac{uv}{r} + wv_z = v\left(v_{rr} + \frac{v_r}{r} - \frac{v}{r^2} + v_{zz}\right) - \left(\frac{\sigma B_0^2}{\rho_f}v + \frac{v}{K}v\right),\tag{3}$$

$$uw_r + ww_z = v \Big(w_{rr} + \frac{w_r}{r} + w_{zz} \Big), \tag{4}$$

$$uT_r + wT_z = \alpha \Big(T_{rr} + \frac{T_r}{r} + T_{zz} \Big) + Q_0 (T - T_\infty) + \frac{\sigma B_0^2}{\rho_f} \Big(u^2 + v^2 \Big) \\ + \frac{(\rho c)_p}{(\rho c)_f} \Big[D_B (T_z C_z + T_r C_r) \Big] + \frac{(\rho c)_p}{(\rho c)_f} \Big[\frac{D_T}{T_\infty} \Big\{ (T_z)^2 + (T_r)^2 \Big\} \Big],$$
(5)

$$uC_{r} + wC_{z} = D_{B}\left(C_{zz} + \frac{C_{r}}{r} + C_{rr}\right) + \frac{D_{T}}{T_{\infty}}\left(T_{zz} + \frac{T_{r}}{r} + T_{rr}\right),$$
(6)



Figure 1. Fluid flow geometry.

The consistent boundary conditions are

$$u = Lu_z, v = \Omega r + Lv_z, w = 0, T = T_w, C = C_w \text{ at } z = 0,$$

$$u \to 0, v \to 0, T \to T_\infty, C \to C_\infty \text{ as } z \to \infty.$$
(7)

The similarity transformations are defined as

$$u = \Omega r f'(\xi), \ v = \Omega r g(\xi), \ w = -(2\Omega v)^{\frac{1}{2}} f(\xi), \\ \theta(\xi) = \frac{T - T_{\infty}}{T_w - T_{\infty}}, \ \phi(\xi) = \frac{C - C_{\infty}}{C_w - C_{\infty}}, \ \xi = \left(\frac{2\Omega}{v}\right)^{\frac{1}{2}} z.$$
(8)

Using (8), (1) satisfies, and ((2)-(7)) are reduced as

$$2f''' + 2ff'' + g^2 - (f')^2 - Mf' - \kappa f' = 0,$$
(9)

$$2g'' + 2fg' - 2gf' - Mg - \kappa g = 0, (10)$$

$$\frac{1}{\Pr}\theta'' + f\theta' + Nb\theta'\phi' + Nt(\theta')^2 + \gamma\theta + MEc\{(f')^2 + (g)^2\} = 0,$$
(11)

$$\phi'' + Le\Pr f \phi' + \frac{Nt}{Nb} \theta'' = 0, \qquad (12)$$

$$f = 0, \quad f' = \psi f'', \quad g = 1 + \psi g', \quad \theta = 1, \quad \phi = 1 \text{ at } \xi = 0,$$

$$f' \to 0, \quad g \to 0, \quad \theta \to 0, \quad \phi \to 0 \text{ as } \xi \to \infty.$$
 (13)

where the dimensionless parameters are defined as:

$$M = \sqrt{\frac{\sigma B_0^2}{\rho_f \Omega}}, \quad \kappa = \frac{v}{k\Omega}, \quad \Pr = \frac{v}{\alpha}, \quad \gamma = \frac{Q_0}{2\Omega}, \quad Nb = \frac{(\rho c)_p}{(\rho c)_f} \frac{(T_w - T_w)D_T}{T_w v},$$

$$Le = \frac{\alpha}{D_B}, \quad \psi = L \left(\frac{2\Omega}{v}\right)^{\frac{1}{2}}, \quad Nt = \frac{(\rho c)_p}{(\rho c)_f} \frac{(C_w - C_w)D_B}{v}, \quad Ec = \frac{(r\Omega)^2}{(T_w - T_w)}.$$
(14)

The dimensionless surface quantities are defined as

$$\sqrt{\operatorname{Re}_{r}}C_{f} = f''(0), \quad \sqrt{\operatorname{Re}_{r}}C_{g} = g'(0), \quad \frac{1}{\sqrt{\operatorname{Re}_{r}}}Nu = -\theta'(0), \quad \frac{1}{\sqrt{\operatorname{Re}_{r}}}Sh = -\phi'(0), \quad (15)$$

Entirely the overhead factors are defined in nomenclature.

3. Analytical Solution

Here, the proposed model is elucidated by using HAM [40–43]. In view of ((9)-(12)) with (13); the primary assumptions are deliberated as:

$$f_0(\xi) = 0, \ g_0(\xi) = \frac{1}{1+\psi} e^{-\xi}, \ \theta_0(\xi) = e^{-\xi}, \ \phi_0(\xi) = e^{-\xi}.$$
 (16)

The L_f , L_g , L_θ and L_ϕ are picked as:

$$L_f(f) = f''' - f', \ L_g(g) = g'' - g, \ L_{\theta}(F) = \theta'' - \theta, \ L_{\phi}(\phi) = \phi'' - \phi,$$
(17)

with the following properties:

$$L_f(m_1 + m_2 e^{-\xi} + m_3 e^{\xi}) = 0, \ L_g(m_4 e^{-\xi} + m_5 e^{\xi}) = 0, \ L_\theta(m_6 e^{-\xi} + m_7 e^{\xi}) = 0, \ L_\phi(m_8 e^{-\xi} + m_9 e^{\xi}) = 0,$$
(18)

where $m_i(i = 1 - 9)$ are constants.

The resultant non-linear operators N_f , N_g , N_{θ} , and N_{ϕ} are indicated as:

$$N_{f}[f(\xi;\tau), g(\xi;\tau)] = 2\frac{\partial^{3}f(\xi;\tau)}{\partial\xi^{3}} + 2f(\xi;\tau)\frac{\partial^{2}f(\xi;\tau)}{\partial^{2}\xi} + (g(\xi;\tau))^{2} - \left(\frac{\partial f(\xi;\tau)}{\partial\xi}\right)^{2} - M\frac{\partial f(\xi;\tau)}{\partial\xi} - \kappa\frac{\partial f(\xi;\tau)}{\partial\xi},$$
(19)

$$N_{g}[g(\xi;\tau), f(\xi;\tau)] = 2\frac{\partial^{2}g(\xi;\tau)}{\partial\xi^{2}} + 2f(\xi;\tau)\frac{\partial g(\xi;\tau)}{\partial\xi} - 2g(\xi;\tau)\frac{\partial f(\xi;\tau)}{\partial\xi} - Mg(\xi;\tau) - \kappa g(\xi;\tau), \quad (20)$$

$$N_{\theta}[\theta(\xi;\tau), f(\xi;\tau), g(\xi;\tau), \phi(\xi;\tau)] = \frac{1}{\Pr} \frac{\partial^{2}\theta(\xi;\tau)}{\partial\xi^{2}} + f(\xi;\tau) \frac{\partial\theta(\xi;\tau)}{\partial\xi} + Nb \frac{\partial\theta(\xi;\tau)}{\partial\xi} \frac{\partial\phi(\xi;\tau)}{\partial\xi} + Nt \left(\frac{\partial\theta(\xi;\tau)}{\partial\xi}\right)^{2} + \gamma\theta(\xi;\tau) + MEc \left\{ \left(\frac{\partial f(\xi;\tau)}{\partial\xi}\right)^{2} + \left(g(\xi;\tau)\right)^{2} \right\},$$
(21)

$$N_{\phi}[\phi(\xi;\tau), f(\xi;\tau), \theta(\xi;\tau)] = \frac{\partial^2 \phi(\xi;\tau)}{\partial \xi^2} + Le \Pr + f(\xi;\tau) \frac{\partial \phi(\xi;\tau)}{\partial \xi} + \frac{Nt}{Nb} \frac{\partial^2 \theta(\xi;\tau)}{\partial \xi^2}.$$
 (22)

The zeroth-order problem is

$$(1-\tau)L_f[f(\xi;\tau) - f_0(\xi)] = \tau h_f N_f[f(\xi;\tau), \ g(\xi;\tau)],$$
(23)

$$(1-\tau)L_g[g(\xi;\tau) - g_0(\xi)] = \tau h_g N_g[g(\xi;\tau), \ g(\xi;\tau)],$$
(24)

$$(1-\tau)L_{\theta}[\theta(\xi;\tau) - \theta_0(\xi)] = \tau h_{\theta} N_{\theta}[\theta(\xi;\tau), f(\xi;\tau), g(\xi;\tau), \phi(\xi;\tau)],$$
(25)

$$(1-\tau)L_{\phi}[\phi(\xi;\tau)-\phi_0(\xi)] = \tau h_{\phi}N_{\phi}[\phi(\xi;\tau), f(\xi;\tau), g(\xi;\tau), \theta(\xi;\tau)].$$

$$(26)$$

The equivalent boundary conditions are:

$$\begin{aligned} f(\xi;\tau)\big|_{\xi=0} &= 0, \ \left. \frac{\partial f(\xi;\tau)}{\partial \xi} \right|_{\xi=0} = \psi \frac{\partial^2 f(\xi;\tau)}{\partial \xi^2}, \ \left. \frac{\partial f(\xi;\tau)}{\partial \xi} \right|_{\xi\to\infty} = 0, \\ g(\xi;\tau)\big|_{\xi=0} &= 1 + \psi \frac{\partial g(\xi;\tau)}{\partial \xi}, \ g(\xi;\tau)\big|_{\xi\to\infty} = 0, \\ \theta(\xi;\tau)\big|_{\xi=0} &= 1, \ \left. \theta(\xi;\tau)\right|_{\xi\to\infty} = 0, \\ \phi(\xi;\tau)\big|_{\xi=0} &= 1, \ \left. \phi(\xi;\tau)\right|_{\xi\to\infty} = 0, \end{aligned}$$

$$(27)$$

where $\tau \in [0, 1]$ is the imbedding parameter and h_f , h_g , h_θ , and h_ϕ are used to regulate the convergence of the solution. When $\tau = 0$ and $\tau = 1$, we have:

$$f(\xi;0) = f_0(\xi), \quad f(\xi;1) = f(\xi), g(\xi;0) = g_0(\xi), \quad g(\xi;1) = g(\xi), \theta(\xi;0) = \theta_0(\xi), \quad \theta(\xi;1) = \theta(\xi), \phi(\xi;0) = \phi_0(\xi), \quad \phi(\xi;1) = \phi(\xi),$$
(28)

Expanding $f(\xi; \tau)$, $g(\xi; \tau)$, $\theta(\xi; \tau)$ and $\phi(\xi; \tau)$ by Taylor's series

$$f(\xi;\tau) = f_{0}(\xi) + \sum_{q=1}^{\infty} f_{q}(\xi)\tau^{q},$$

$$g(\xi;\tau) = g_{0}(\xi) + \sum_{q=1}^{\infty} g_{q}(\xi)\tau^{q},$$

$$\theta(\xi;\tau) = \theta_{0}(\xi) + \sum_{q=1}^{\infty} \theta_{q}(\xi)\tau^{q},$$

$$\phi(\xi;\tau) = \phi_{0}(\xi) + \sum_{q=1}^{\infty} \phi_{q}(\xi)\tau^{q}.$$
(29)

where

$$f_{q}(\xi) = \frac{1}{q!} \frac{\partial f(\xi;\tau)}{\partial \xi} \Big|_{\tau=0'} g_{q}(\xi) = \frac{1}{q!} \frac{\partial g(\xi;\tau)}{\partial \xi} \Big|_{\tau=0'}, \quad \theta_{q}(\xi) = \frac{1}{q!} \frac{\partial \theta(\xi;\tau)}{\partial \xi} \Big|_{\tau=0}$$
and $\phi_{q}(\xi) = \frac{1}{q!} \frac{\partial \phi(\xi;\tau)}{\partial \xi} \Big|_{\tau=0}$.
(30)

The secondary constraints h_f , h_g , h_{θ} , and h_{ϕ} are selected, such that the series (29) converges at $\tau = 1$, changing $\tau = 1$ in (29), we get:

$$f(\xi) = f_0(\xi) + \sum_{q=1}^{\infty} f_q(\xi),$$

$$g(\xi) = g_0(\xi) + \sum_{q=1}^{\infty} g_q(\xi),$$

$$\theta(\xi) = \theta_0(\xi) + \sum_{q=1}^{\infty} \theta_q(\xi),$$

$$\phi(\xi) = \phi_0(\xi) + \sum_{q=1}^{\infty} \phi_q(\xi).$$

(31)

The *q*^{*th*}-order problem satisfies the following:

$$L_{f}\left[f_{q}(\xi) - \chi_{q}f_{q-1}(\xi)\right] = h_{f}U_{q}^{f}(\xi),$$

$$L_{g}\left[g_{q}(\xi) - \chi_{q}g_{q-1}(\xi)\right] = h_{g}U_{q}^{g}(\xi),$$

$$L_{\theta}\left[\theta_{q}(\xi) - \chi_{q}\theta_{q-1}(\xi)\right] = h_{\theta}U_{q}^{\theta}(\xi),$$

$$L_{\phi}\left[\phi_{q}(\xi) - \chi_{q}\phi_{q-1}(\xi)\right] = h_{\phi}U_{q}^{\phi}(\xi).$$
(32)

The equivalent boundary conditions are:

$$f_{q}(0) = f'_{q}(0) - \psi f''_{q}(0) = f'_{q}(\infty) = 0,$$

$$g_{q}(0) - \psi g'_{q}(0) - 1 = g_{q}(\infty) = 0,$$

$$\theta_{q}(0) = \theta_{q}(\infty) = 0,$$

$$\theta_{q}(0) = \theta_{q}(\infty) = 0.$$
(33)

Here

$$U_{q}^{f}(\xi) = 2f'''_{q-1} + 2\sum_{k=0}^{q-1} f_{q-1-k}f''_{k} + (g_{q-1})^{2} - (f'_{q-1})^{2} - M(f'_{q-1})^{2} - \kappa(f'_{q-1})^{2},$$
(34)

$$U_{q}^{g}(\xi) = 2g''_{q-1} + 2f_{q-1}g'_{q-1} - 2g_{q-1}f'_{q-1} - Mg_{q-1} - \kappa g_{q-1},$$
(35)

$$U_{q}^{\theta}(\xi) = \frac{1}{\Pr} \theta''_{q-1} + \sum_{k=0}^{q-1} f_{q-1-k} \theta'_{k} + Nb \sum_{k=0}^{q-1} \theta'_{q-1-k} \phi'_{k} + Nt (\theta'_{q-1})^{2} + \gamma \theta_{q-1} + MEc \left\{ \left(f'_{q-1}\right)^{2} + \left(g_{q-1}\right)^{2} \right\}, \quad (36)$$

$$U_{q}^{\phi}(\xi) = \phi''_{q-1} + Le \Pr \sum_{k=0}^{q-1} f_{q-1-k} \phi'_{k} + \frac{Nt}{Nb} \theta''_{q-1},$$
(37)

where

$$\chi_q = \begin{cases} 0, \text{ if } \tau \le 1\\ 1, \text{ if } \tau > 1 \end{cases}$$
(38)

4. Convergence Solution

HAM guarantees the convergence of the series solution of the modeled problem. The auxiliary parameter *h* plays an important role in adjusting the region of convergence of the series solution. Figure 2 indicates the *h*-curves of the velocities profiles. The auxiliary parameters h_f and h_g are $-0.26 \le h_f \le 0.1$ and $-0.22 \le h_g \le 0.06$. Figure 3 indicates the *h*-curves of the temperature and concentration profiles. The auxiliary parameters h_θ and h_ϕ are $-0.28 \le h_f \le 0.02$ and $-0.24 \le h_g \le 0.02$.



Figure 2. Curves for velocities profiles f''(0) and g'(0).



Figure 3. Curves for temperature and concentration profiles $\phi'(0)$ and $\theta'(0)$.

5. Results and Discussion

The aim of this section is to visualize variations in velocities, temperature, concentration, Nusselt number, and skin friction coefficient due to involved parameters, like magnetic field (*M*), porosity (κ), velocity slip (ψ), Eckert number (*Ec*), heat source/sink (γ), thermophoresis (*Nt*), Prandtl number (Pr), Lewis number (*Le*), and Brownian motion (*Nb*) developed during the nanofluid flow that are displayed in Figures 4–18. Figures 4 and 5 depict the reducing influence of *M* on $f'(\xi)$ and $g(\xi)$. The increasing *M* causes deterioration in momentum boundary layer thickness and velocity profiles. *M* relates with the Lorentz force theory. The Lorentz force always creates conflicting force to the flow of fluid and decays motion of the fluid particles. Accordingly, the escalating magnetic force

declines the fluid velocity. The escalating κ declines $f'(\xi)$ and $g(\xi)$ is depicted in Figures 6 and 7. The porous media usually performs opposite behavior to the fluid flow. With an increase in the porous media, the fluid particles motion reduces and, thus, the fluid velocity diminishes. Therefore, the growing estimations of κ diminishes $f'(\xi)$ and $g(\xi)$. Figures 8 and 9 depict the escalating ψ diminishes $f'(\xi)$ and $g(\xi)$. The velocity slip parameter always performs a reverse impact on velocity profiles. The corresponding boundary layer thickness declines by ψ , which deescalates $f'(\xi)$ and $g(\xi)$. Figure 10 depicts the impression of *M* on $\theta(\xi)$. It is witnessed that the escalating *M* escalates $\theta(\xi)$. The influence of γ on $\theta(\xi)$ is demonstrated in Figure 11. The heat source/sink plays like heat producer. As the parameter estimations intensify, the fluid particles temperature heightens. For that reason $\theta(\xi)$ upsurges. Figure 12 portrays the effect of *Ec* on $\theta(\xi)$. It is used for extremely fast compressible flow. The positive Eckert number represents the freezing of wall and, as a result, the convection of heat transmission to the fluid is augmented. Figure 13 shows the consequence of Pr on $\theta(\xi)$. Pr makes the association of fluid viscosity with thermal conductivity. The fluids have high thermal conductivity with large Pr, while the impact is reverse for higher Pr. Hence, the escalating estimations of Pr deescalates $\theta(\xi)$. Figure 14 illustrates the effect of Nb on $\theta(\xi)$. Higher Brownian motion induces the random acceleration of the fluid particles. Extra energy is generated because of this random acceleration. Therefore, the thermal rise is reported. Figure 15 presents the impression of Nt on $\theta(\xi)$. In the thermophoresis phenomenon, tiny fluid particles are forced back from those in the warmer to the cold surface. As a result, the fluid particles returned from those in the warmed surface and the thermal curve then increased. The outcome of *Nb* and *Nt* on $\phi(\xi)$ are shown in Figures 16 and 17. The higher estimations of Nb shows reverse impact on $\phi(\xi)$. Figure 17 illustrates the rising impression of Nt on $\phi(\xi)$. Figure 18 demonstrates the influence of Le on $\phi(\xi)$. Le is the correlation of mass diffusion to fluid thermal conductivity. The increasing Le causes thickness of the concentration layer, which consequently escalates the concentration profile.



Figure 4. Varation in $f'(\xi)$ against *M*, when $\psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 5. Varation in $g(\xi)$ against *M*, when $\psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 6. Variation in $f'(\xi)$ gainst κ , when $M = \psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$.



Figure 7. Variation in $g(\xi)$ against κ , when $M = \psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$.



Figure 8. Varation in $f'(\xi)$ against ψ , when M = 0.2, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 9. Varation in $g(\xi)$ against ψ , when M = 0.2, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 10. Varation in $\theta(\xi)$ against *M*, when $\psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 11. Variation in $\theta(\xi)$ against γ , when $M = \psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\kappa = 1.0$.



Figure 12. Varation in $\theta(\xi)$ against *Ec*, when $M = \psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 13. Varation in $\theta(\xi)$ against Pr, when $M = \psi = 0.2$, Nt = Nb = 0.5, Le = 1.0, Ec = 1.0, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 14. Variation in $\theta(\xi)$ against *Nb*, when $M = \psi = 0.2$, Nt = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 15. Variation in $\theta(\xi)$ against *Nt*, when $M = \psi = 0.2$, Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 16. Varation in $\phi(\xi)$ against *Nb*, when $M = \psi = 0.2$, Nt = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 17. Variation in $\phi(\xi)$ against *Nt*, when $M = \psi = 0.2$, Nb = 0.5, Le = 1.0, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.



Figure 18. Varation in $\phi(\xi)$ against *Le*, when $M = \psi = 0.2$, Nt = Nb = 0.5, Ec = 1.0, Pr = 1.2, $\gamma = 0.1$, $\kappa = 1.0$.

Tables 1–3 are displayed to examine the surface drag force, heat transfer rate, and mass transfer rate, respectively. Table 1 depicts that the increasing *M* and κ reduce both C_f and C_g , while the rising values of ψ reduces C_f and increases C_g . From Table 2, the escalating *M*, ψ , *Le*, *Nb* and *Nt* reduces *Nu*, while the higher Pr escalates the *Nu*. From Table 3, *M* and ψ deescalate *Sh*, while the higher *Le*, Pr, *Nb*, and *Nt* escalate *Sh*. Tables 4 and 5 show the comparison of HAM and Shooting approaches for velocities, temperature, and concentration profiles. Both of the techniques are treated with the established computer codes and validated by publishing the results to the accessible standard and they

have computed with software mathematica. At 20th order of approximations, the results of HAM have been computed. Here, the validity of the proposed model is observed.

M	ψ	κ	C_{f}	C_g
0.0	0.7	0.5	0.110921	-1.038800
0.7			0.096164	-1.135091
1.4			0.071695	-1.377442
0.3	0.2	0.5	0.204806	-1.265867
	0.5		0.136281	-1.133058
	0.8		0.094705	-1.022374
0.3	0.7	0.6	0.103762	-1.077193
		0.8	0.098619	-1.116139
		1.0	0.093783	-1.153702

Table 1. Results of C_f and C_g against M, ψ , and κ .

Table 2. Results of *Nu* against *M*, ψ , *Le*, Pr, *Nb* and *Nt*.

M	ψ	Le	Pr	Nb	Nt	Nu
0.0	0.7	0.8	1.0	0.3	0.2	0.304942
0.7						0.244218
1.4						0.175662
0.3	0.2	0.8	1.0	0.3	0.2	0.326557
	0.5					0.303604
	0.8					0.287156
0.3	0.7	0.5	1.0	0.3	0.2	0.296330
		1.0				0.289543
		1.5				0.283952
0.3	0.7	0.8	0.5	0.3	0.2	0.249898
			1.0			0.292115
			1.5			0.322861
0.3	0.7	0.8	1.0	0.5	0.2	0.263410
				0.7		0.236772
				1.0		0.200563
0.3	0.7	0.8	1.0	0.3	0.5	0.259131
					0.7	0.238654
					1.0	0.210105

Table 3. Results of *Sh* against *M*, ψ , *Le*, Pr, *Nb*, and *Nt*.

ψ	Le	Pr	Nb	Nt	Sh
0.7	0.8	1.0	0.3	0.2	0.270000
					0.253871
					0.237227
0.2	0.8	1.0	0.3	0.2	0.275832
0.5					0.269335
0.8					0.264939
0.7	0.5	1.0	0.3	0.2	0.264933
	1.0				0.213734
	1.5				0.301323
0.7	0.8	0.5	0.3	0.2	0.386903
		1.0			0.229347
		1.5			0.266243
0.7	0.8	1.0	0.5	0.2	0.312629
			0.7		0.393384
			1.0		0.478752
0.7	0.8	1.0	0.3	0.5	0.329593
				0.7	0.222062
				1.0	0.225392
0.7	0.8	1.0	0.3	0.2	0.228550
	ψ 0.7 0.2 0.5 0.8 0.7 0.7 0.7 0.7 0.7	ψ Le 0.7 0.8 0.2 0.8 0.5 0.8 0.7 0.5 1.0 1.5 0.7 0.8 0.7 0.8 0.7 0.8 0.7 0.8 0.7 0.8 0.7 0.8 0.7 0.8 0.7 0.8	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

ξ	f (ξ)		g(ξ)	
	HAM Solution	Shooting Solution	HAM Solution	Shooting Solution
0.0	-0.025173	-0.025358	-0.364493	-0.373437
0.5	-0.028523	-0.028712	-1.177880	-1.190384
1.0	0.016743	-0.016840	-0.938948	-0.947851
1.5	-0.009319	-0.009366	-0.623657	-0.629256
2.0	-0.005282	-0.005307	-0.391893	-0.395249
2.5	-0.003064	-0.003078	-0.241243	-0.243298
3.0	-0.001808	-0.001853	-0.147222	-0.148561
3.5	-0.001078	-0.001083	-0.089652	-0.090400
4.0	-0.000647	-0.000650	-0.054470	-0.054923
4.5	-0.000390	-0.000391	-0.033069	-0.033343
5.0	-0.000235	-0.000236	-0.020068	-0.020234

Table 4. Comparison of HAM and Shooting techniques for $f'(\xi)$ and $g(\xi)$ while considering other parameters constant ($\psi = 0.3$, $\kappa = 0.8$, M = 0.6).

Table 5. Comparison of HAM and Shooting techniques for $\theta(\xi)$ and $\phi(\xi)$ considering other parameters constant (M = 0.6, Ec = 0.2, Nb = 0.4, Nt = 0.5, $\gamma = 0.6$, Pr = 7.0, Le = 1.0).

ξ	θ(ξ)		φ(ξ)	
	HAM Solution	Shooting Solution	HAM Solution	Shooting Solution
0.0	0.000000	1.000000	1.000000	1.000000
0.5	0.574478	0.574313	0.529982	0.529510
1.0	0.339813	0.339696	0.294610	0.294223
1.5	0.203589	0.203481	0.169102	0.168819
2.0	0.122669	0.122605	0.099093	0.098905
2.5	0.074132	0.074092	0.058838	0.058817
3.0	0.044869	0.044845	0.035224	0.035248
3.5	0.027181	0.027160	0.021194	0.021148
4.0	0.016474	0.016465	0.012793	0.012764
4.5	0.009988	0.009982	0.007736	0.007719
5.0	0.006056	0.006053	0.004643	0.004673

6. Conclusions

The steady and incompressible flow of MHD nanofluid over a porous rotating disc with slip conditions is examined. The mass and heat transmission with viscous dissipation impact is also intentional. The problem is solved with the help of analytical and numerical methods. The core points of the current inspection are mentioned beneath:

- Increasing magnetic, velocity slip, and porosity parameters perform reducing behavior on velocities profiles.
- Increasing Eckert number, thermophoresis, Brownian motion, magnetic, and heat source/sink parameters perform reducing behavior on temperature profile while the Prandtl number performs opposite conduct on temperature profile.
- Increasing thermophoresis parameter performs increasing behavior on concentration profile, while the Brownian motion and Lewis number perform reducing behavior on concentration profile.
- The numerical and analytical approaches both agreed on the validation of the modeled problem.

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Nomenclature

B ₀	Magnetic field $\left[NmA^{-1} \right]$		
С	Concentration		
C_w	Surface concentration		
C_{∞}	Concentration away from the surface		
D_B	Brownian coefficient $\left[m^2s^{-1}\right]$		
D_T	Thermophoretic coefficient $\left[m^2 s^{-1}\right]$		
Ec	Eckert number		
k	Thermal conductivity $\begin{bmatrix} Wm^{-1}K^{-1} \end{bmatrix}$		
L	Velocity slip constant		
Re _r	Local Reynolds number		
Т	Temperature [K]		
T_w	Surface temperature		
T_{∞}	Temperature away from the surface		
u, v, w	Components of velocity $\left[ms^{-1}\right]$		
r,ϕ,z	Coordinates [m]		
Q_0	Heat flux $[Wm^{-2}]$		
γ	Heat source/sink parameter		
υ	Kinematic viscosity $\left[m^2s^{-1}\right]$		
ρ_f	Density [Kgm ⁻³]		
σ	Electrical conductivity [Sm ⁻¹]		
$(\rho c)_f$	Fluid heat capacity		
$(\rho c)_p$	nanoparticles heat capacity		
Parameters			
Le	Lewis number		
М	Magnetic		
Nb	Brownian motion		
Nt	Thermophoresis		
Pr	Prandtl number		

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Sample Availability: Samples of the compounds are available from the authors.



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