

Article

Dynamic Model of Impact Energy Absorption by a Conveyor Belt in Interaction with the Support System

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Abstract: Measurements of the dynamic load of conveyor belts of identical strengths were used to evaluate and compare the data for belts with and without a support system. The goal was to identify the effects of the support system in terms of a relative amount of impact energy absorbed by a conveyor belt. A dynamic model was designed based on selected parameters of the impact process. Damage to conveyor belts, caused by the absorption of impact energy, was evaluated using the applied methods of mathematical statistics.

Keywords: rubber-textile conveyor belt; support system; puncture resistance; absorbed energy



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1. Introduction

Due to the fact that conveyor belts are permanently exposed to dynamic load during their utilisation, it is necessary to understand their dynamic characteristics. Dynamic characteristics of conveyor belts affect smooth conveyance, especially in continuous conveyance. Failures caused by conveyor belt malfunctions that result from poor dynamic characteristics consequently incur high financial losses due to conveyor belt ruptures at belt joints or due to damage to conveyor belts [1,2]. Conveyor belts are the most expensive structural elements of belt conveyors and the costs of conveyor belts represent around 40–60% of the total operating costs of belt conveyance of materials [3].

The kinematic and dynamic processes that run at transfer chutes are very complex. As much as 60% of damage to conveyor belts occurs particularly at chutes. Reliability of chutes in belt conveyance represents a serious problem; therefore, there are efforts aimed at finding methods of how to reduce the number of chutes as the sources of potential failures [4]. Hence, conveyance systems with a large number of chutes exhibit higher complexity and are associated with higher energy consumption and maintenance cost. Provided the chutes are used in line with respective operating requirements, their optimal design significantly affects the service life of conveyor belts and associated energy consumption [5]. Chutes are the points where the energy loss occurs due to the dynamic impact and a consequent absorption of impact energy by a conveyor belt [6] and due to rotating pieces of a conveyed material.

Dynamic characteristics of belts existing in a dynamic impact process are difficult to examine during the belt operation; conveyor belts should therefore be examined in laboratory conditions (by simulations) [7,8]. The absorption ability of composite materials is an important parameter that affects dynamic behaviour of the structures [9]. A standard laboratory method for measuring dynamic properties is, for example, measuring the vibration-damping properties of composite materials, including conveyor belts [10]. Various testing devices have been constructed to facilitate laboratory testing of the dynamic impact process; for example, the test equipment at the Technical University of Wroclaw [11]

or the test equipment at the Technical University of Košice, which uses a laser distance sensor to measure a trajectory of the falling load [12]. Laboratory research into punctures in steel-cord conveyor belts was carried out by many others, including authors of papers [13] and [14], who have developed a magnetic high-resolution diagnostic device for steel cord conveyor belts. In addition to monitoring belts during their use in belt conveyors, this device can also be used in laboratories for testing puncture resistance of belts.

A support system is an important structural element of the chutes as it eliminates damage to conveyor belts in terms of punctures. At the chutes, material particles change their direction and velocity; this causes wearing of conveyor belts and punctures made by larger pieces of materials [15]. Experimental investigations conducted by many authors indicated that a support system design has a strong effect on energy consumption during the operation of belt conveyors and on damage to conveyor belts [16–20]. Ambriško et al. [17] applied the DOE method and carried out experimental measurements to create regression models describing a correlation between the tension load and the height at a given weight for two types of conveyance systems—with and without the support system. The effects of carrying idlers on energy consumption of a belt conveyor were discussed in the paper [18]. Loading of carrying idlers used in belt conveyors was investigated by the authors of paper [19], and an analysis of failures of idlers based on the measurements conducted during their operation was discussed in [20]. Sensors have become crucial components in identification of conveyor belt damage [3,12,21]. The authors in [21] developed a sensor system for the detection of stones and an automatic system for bulk materials for monitoring conveyor belt damage. Kovanic et al. proposed a method of measuring an impactor trajectory during the dynamic impact load using a laser distance sensor L-GAGE and experimental photography. This method has been experimentally tested and the results of the measurements were presented in publication [12]. Blažej et al. developed a magnetic sensor for monitoring steel-cord conveyor belts [3].

Dynamic characteristics have been investigated by many authors. For example, papers [22,23] investigated into long belt conveyance systems in terms of reducing production costs and optimise conveyor performance. Lodewijks [24] conducted the modelling of stresses in a conveyor belt during its launch and stoppage. Dynamic behaviour of a conveyance system was mathematically described by applying an analytical approach and the Finite Element Method (FEM). Authors Junxia Li and Xiaoxu Pang simulated various factors that affect longitudinal vibrations of belt conveyors and they proposed strategies for eliminating them [25]. The simulation approach proposed by those authors facilitates better accuracy of designing the dynamics of belt conveyors. The authors of papers [26,27] dealt with the stability of the motions of conveyor belts and bulk materials on long conveyor belts and proposed novel designs of actuators with the aim of reducing stresses in conveyor belts. Many of these topics address conveyance systems in terms of their dynamics, but they are not directly associated with modelling the dynamics that occur during the impact process. Modelling the dynamics of conveyance systems equipped with a support system is currently being investigated by only a few authors in their articles [28,29].

The present article, in particular, addresses the absence of research into a dynamic impact process and proposes several dynamic models while applying selected statistical methods. Within the creation of dynamic models, the research objectives were to identify and compare the amounts of absorbed energy before the occurrence of damage to the conveyor belt (puncture) which leads to belt decommissioning. The authors wanted to verify the following hypothesis: “Do the drop hammer weight, impact height, and support system absence/presence have a significant effect on a relative amount of absorbed energy before a puncture occurs?” The main goal of the research was to create a model of a correlation between the relative amount of absorbed energy and the selected parameters.

The objectives of this experimental investigation were as follows:

Identification and comparison of the amounts of absorbed energy before the occurrence of damage to conveyor belts (puncture) which leads to belt decommissioning.

Identification of the effects of parameters (drop hammer weight, impact height, support system absence/presence) on a relative amount of absorbed energy before a puncture occurs.

Creation of a model of a correlation between the relative amount of absorbed energy and the selected parameters.

2. Materials and Methods

Test Equipment

The test equipment which was used in the experiments is shown in Figure 1. A more detailed description of the equipment is presented in papers [30]. The test equipment facilitates recording the drop hammer height and magnitudes of the tension force and the impact force over time. For the purpose of our experiment, we recorded the drop hammer height (at the impact and when bouncing) every millisecond. The measurements were carried out for two different assemblies—with and without the support system. The upper limits for the drop hammer weight and impact height were determined in order to avoid destruction of the test specimen. These limits were applied in the analyses of the measurements carried out with and without engaging the support system.

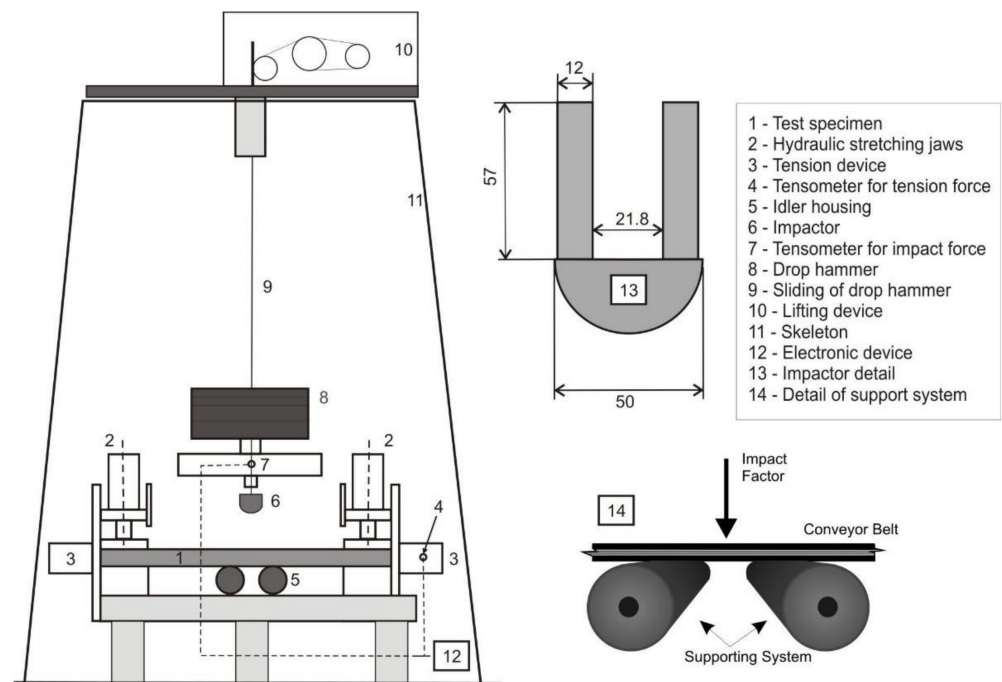


Figure 1. Test equipment scheme.

The support system consisted of two steel rollers with a diameter of 80 mm and an axial distance of 160 mm. The point of impact of the drop hammer was located between the rollers. The spherical impactor (Figure 1) simulated an impact of a bulk, brittle material. In the experiments, the simulated weights of the falling material were 50, 60, 70, 80, 90, and 100 kg. Drop heights ranged from 1 to 2.6 m, with 0.2 m increments. The investigated belt was a rubber-textile conveyor belt, type P2500 (P means the polyamide textile layer and 2500 expresses the rigidity of the conveyor belt [Nmm^{-1}]). Each specimen was sized 1400×160 mm. The specimens were prepared following the methodology described in paper [31]. The tension force applied in the experiments was 40 kN, representing 1/10 of the belt strength per millimetre of its width (manufacturer's recommendation).

3. Theory/Calculation

3.1. Absorbed Energy

With known heights to which the material bounced-back, while considering the differences in potential energies of an object prior to the impact and after the impact, it was possible to identify the amount of energy absorbed by the conveyor belt while neglecting the effects of the environment. The underlying principle is shown in Figure 2.

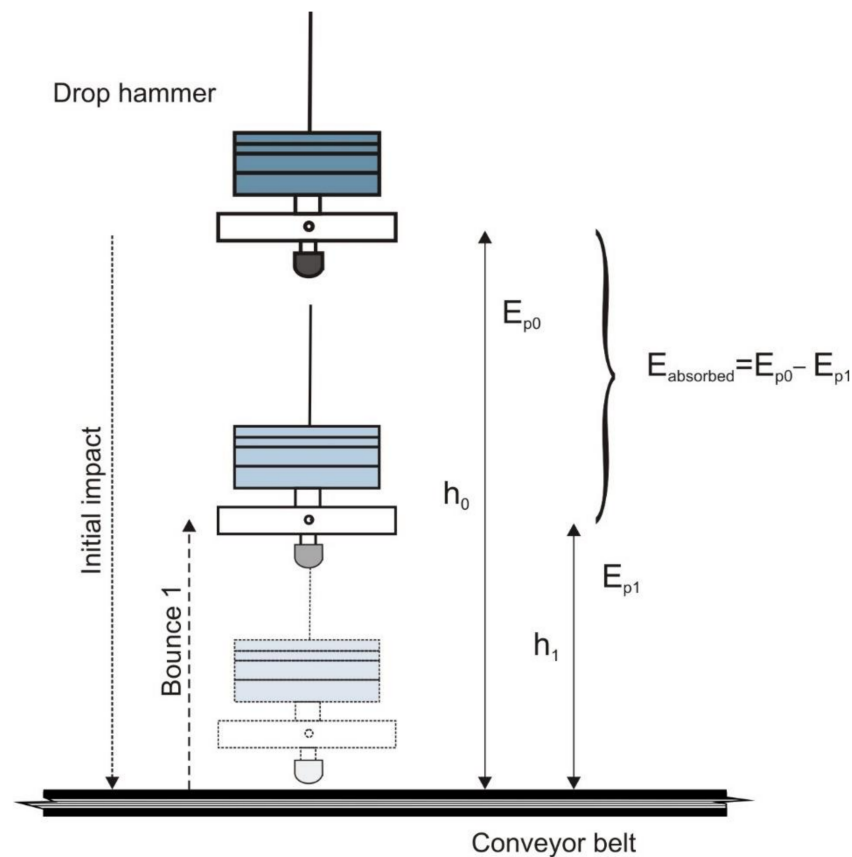


Figure 2. Impact and Bounce 1 of the drop hammer.

The absolute value of the amount of energy $E_{absorbed}$ absorbed after Bounce 1 was calculated using the following equation:

$$E_{absorbed} = E_{p0} - E_{p1}, \quad (1)$$

wherein E_{p0} is the amount of potential energy prior to the first impact, and E_{p1} is the amount of potential energy after the first bounce (Bounce 1).

The amount of impact energy (in %) absorbed by the conveyor belt after the first impact was calculated using a relative amount of absorbed energy E_{relat} . The following equation was used:

$$E_{relat} = \frac{E_{p0} - E_{p1}}{E_{p0}} \times 100\% = \left(1 - \frac{E_{p1}}{E_{p0}}\right) \times 100\%. \quad (2)$$

The following equation applies to the i^{th} bounce ($i = 1, 2, \dots$) of the drop hammer on the conveyor belt:

$$E_{relat,i} = \frac{E_{pi-1} - E_{pi}}{E_{pi-1}} \times 100\% = \left(1 - \frac{E_{pi}}{E_{pi-1}}\right) \times 100\%. \quad (3)$$

3.2. Evaluation Methods

The values were compared using the methods of statistical induction–hypothesis testing. Normality of data sets was verified using the Shapiro–Wilk test of normality. A comparison of two dependent data sets was carried out using the paired *t*-test. The null hypothesis acceptance or rejection was based on a *p*-value. In principle, if the *p*-value is lower than the significance level α , then the null hypothesis is rejected in favour of the alternative hypothesis. If the *p*-value equals to or is higher than the predetermined significance level α , then the null hypothesis is not rejected.

The correlations between the output variable and selected input variables were investigated using regression and correlation analyses. The following standard linear regression model was considered:

$$Y = \beta_0 + \sum_{j=1}^k \beta_j X_j + \varepsilon \quad (4)$$

wherein β_0 and β_j for $j = 1, 2, \dots, k$ are the model parameters; *Y* is the input (dependent) variable; variables X_j , $j = 1, 2, \dots, k$ represent *k* independent input variables; and ε is the random error. Model parameters were identified using the method of least squares.

Statistical significance of the regression model, or its parameters, was verified using the tests of statistical significance. The strengths of the effect of *Y* variable and the effects of *k* variables were expressed by means of the coefficient of multiple determination r^2 . The coefficient values ranged within the $<0;1>$ interval. In principle, as its value approaches 1, the correlation becomes stronger.

4. Results

Experimental tests were carried out with a P2500 rubber-textile conveyor belt. The measurements were carried out with two different assemblies—with and without the support system. During the experiments without the support system, no significant damage to the conveyor belt specimen was observed. With the support system engaged, destruction (punctures) of the conveyor belt specimen was observed at certain drop hammer weights and impact heights. A puncture is the type of damage that occurs to the top cover layer, the carcass and the bottom cover layer of the belt.

The input parameters were the weight *m* of the falling material and the impact height *h*.

Figure 3 shows the occurrence of punctures during the experiments. In order to facilitate a comparison of the amounts of absorbed energy with and without using the support system, a sub-set of the measurements, out of the whole set of the obtained results, was analysed for the weights ranging from 50 to 80 kg and for the impact heights ranging from 1 to 2 m at 4 consecutive bounces of the drop hammer.

The time course of the measured heights at the impact of the drop hammer onto the conveyor belt (at a certain weight *m* and a certain impact height *h*) is shown in Figures 4 and 5. The graphs illustrate the impacts of the drop hammer onto the conveyor belt with and without the support system.

The individual drop hammer bounces exhibited apparent differences in the experiments with (SS) and without using the support system (WSS).

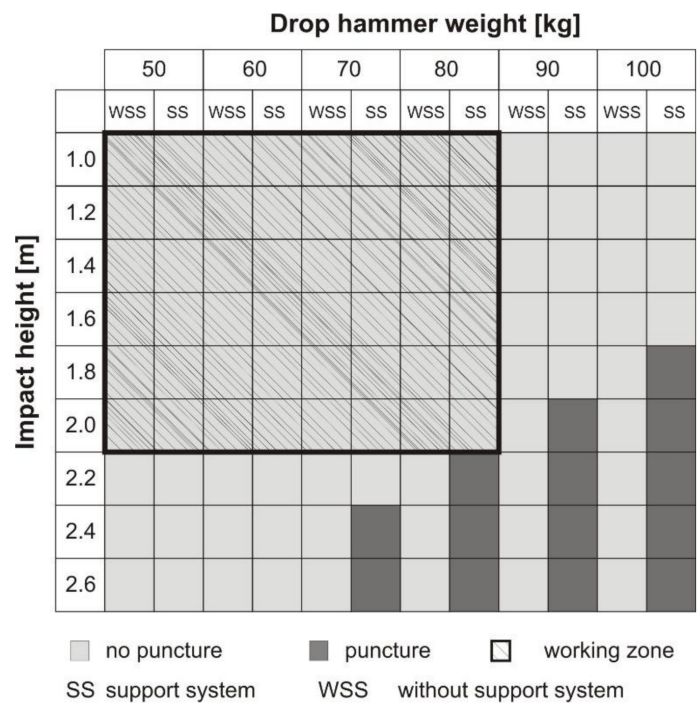


Figure 3. Puncture occurrence.

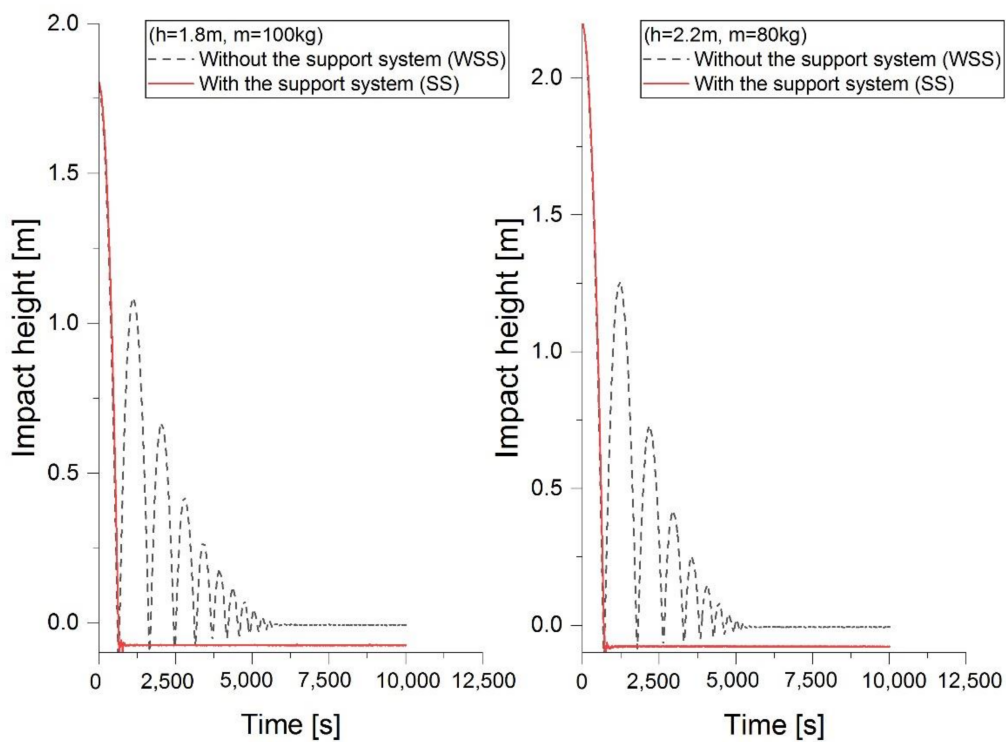


Figure 4. Time course of the drop hammer impacts with a final puncture.

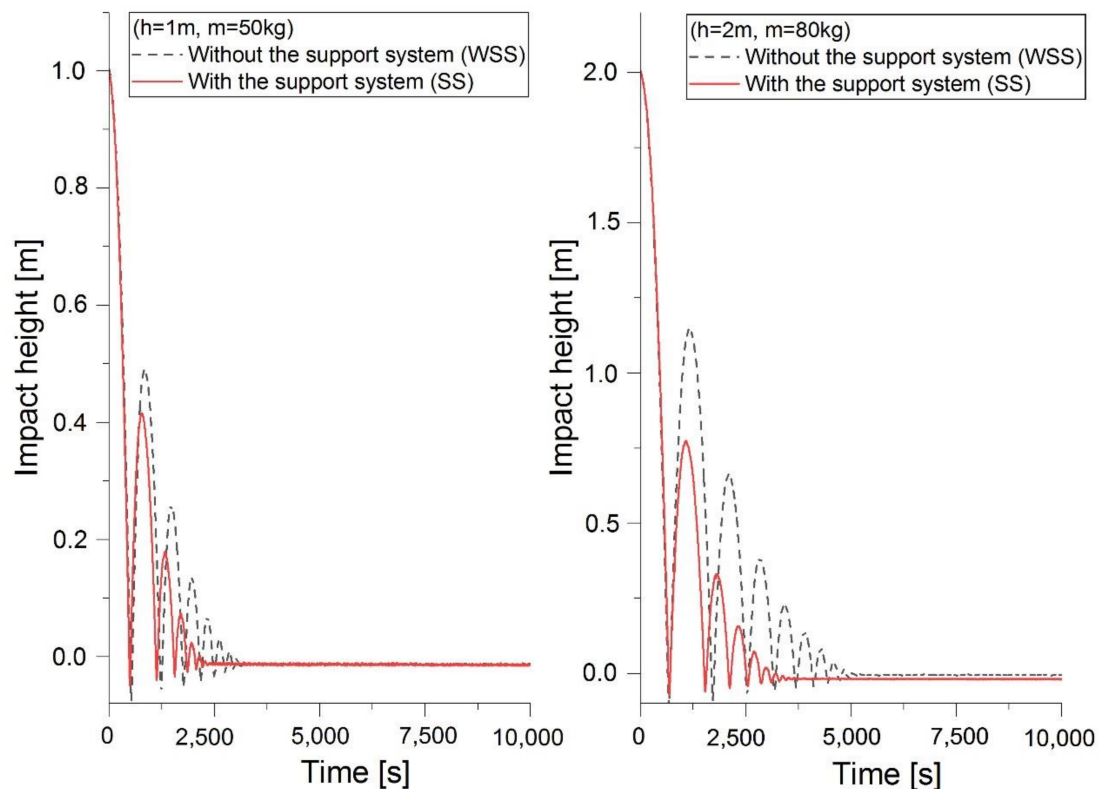


Figure 5. Time course of the drop hammer impacts.

4.1. Identification and Comparison of a Relative Amount of Absorbed Energy

Relative amounts of absorbed energy at first four bounces were expressed using Equation (3).

At drop hammer weights ranging from 50 kg to 80 kg, with 10 kg increments, impacts from six different heights were simulated. Figure 6 shows relative amounts of absorbed energy at first four bounces of the drop hammer on the conveyor belt. Two impact heights of the drop hammer, 100 cm and 200 cm, were applied to all of the tested drop hammer weights and to both system assemblies—with and without the support system.

For each drop hammer weight and each impact height, an average value of the relative amount of absorbed energy was determined. There were minimum differences between the obtained values for both impact heights, all impact weights and both system assemblies (with the support system (SS) and without the support system (WSS)) (Figure 6).

The initial comparison of the obtained values indicated a slight decrease in the values of the relative amount of absorbed energy with a growing number of bounces in both system assemblies (with and without the support system).

Average values of the relative amount of absorbed energy at the given weights, depending on whether the support system was or was not engaged, are listed in Table 1.

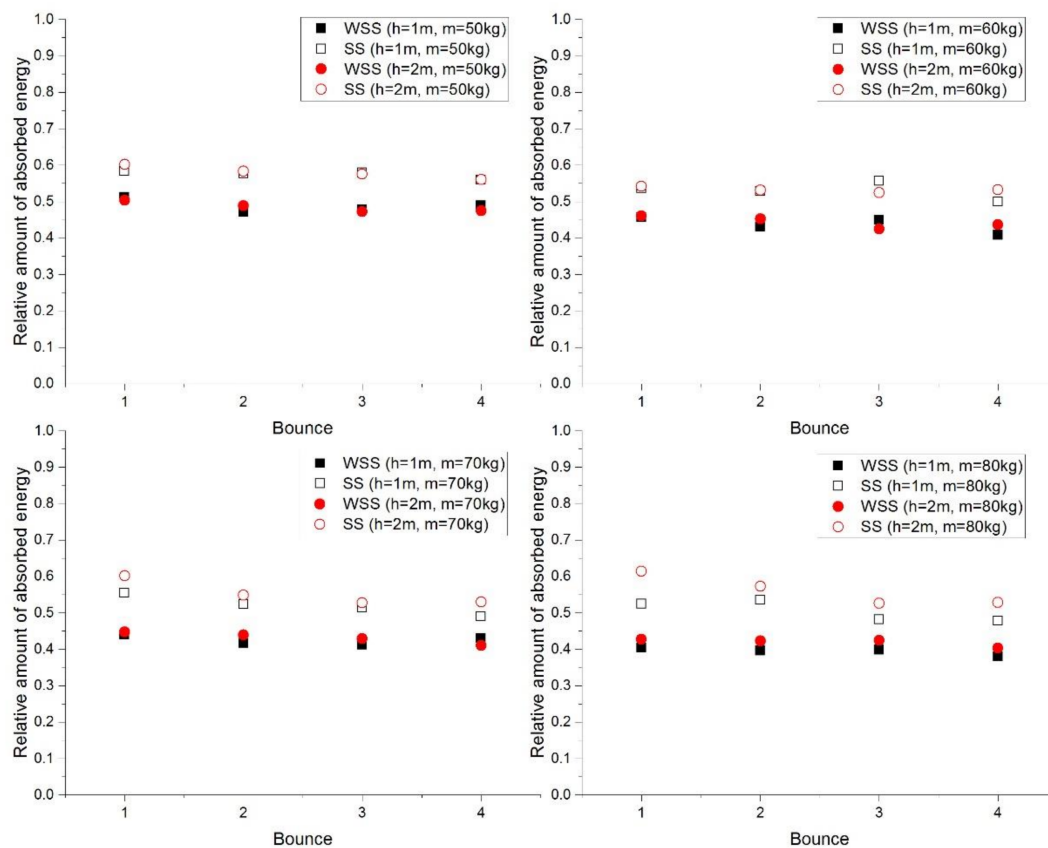


Figure 6. Relative amounts of absorbed energy.

Table 1. Average values of the relative amount of absorbed energy.

Parameters Weight	Drop Hammer Weight/Support System							
	50 kg		60 kg		70 kg		80 kg	
Support System	WSS	SS	WSS	SS	WSS	SS	WS	SS
Bounce								
Bounce 1	0.51	0.58	0.46	0.54	0.45	0.57	0.41	0.56
Bounce 2	0.48	0.57	0.44	0.53	0.43	0.54	0.41	0.54
Bounce 3	0.48	0.56	0.44	0.53	0.42	0.52	0.40	0.50
Bounce 4	0.48	0.62	0.44	0.55	0.42	0.54	0.41	0.54

The experimental measurements indicated that the effect of the impact height on the relative amount of impact energy absorbed at a given drop hammer weight was insignificant. This applied equally to both system assemblies—with (SS) and without the support system (WSS).

Nevertheless, there were some indications that a drop hammer weight affects a relative amount of absorbed impact energy. Apparently, the range of the values of the relative amount of absorbed energy is wider.

The effect of the presence of the support system on the relative amount of absorbed impact energy was evident (Figure 7, Table 1). With the support system engaged, the conveyor belt was able to absorb, for example at Bounce 1, 54% to 58% of impact energy, depending on the impact height and drop hammer weight. Without the support system, the conveyor belt was able to absorb 41% to 51% of energy at Bounce 1, depending on the impact height and drop hammer weight.

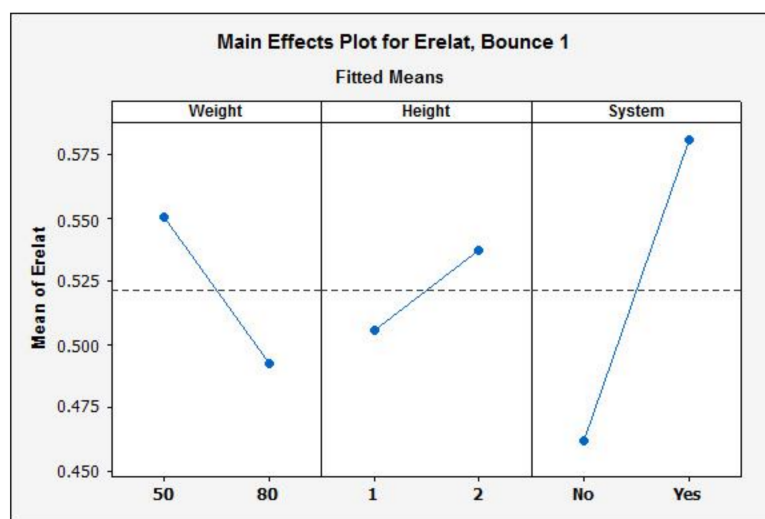


Figure 7. Graphical representation of the effects (Bounce 1).

The values obtained by measurements were compared using the testing methods. The measured values of relative absorption at the individual weights and impact heights met the normality requirement, which was verified by the Shapiro–Wilk test of normality (p -value $< \alpha$). A paired comparison of the values identified for the two system assemblies (with and without the support system) at each drop hammer weight and impact height was verified using a paired t -test. The resulting p -values obtained by the paired testing are listed in Table 2.

Table 2. Test results—paired t -test ($\alpha = 0.05$).

Impact Height [m]	Drop Hammer Weight (p -Value)			
	50 kg	60 kg	70 kg	80 kg
1.0	0.0429	0.0058	0.0006	0.0010
1.2	0.0051	0.0065	0.0004	0.0010
1.4	0.0221	0.0018	0.0006	0.0015
1.6	0.0313	0.0081	0.0014	0.0106
1.8	0.0115	0.0107	0.0005	0.0082
2.0	0.0061	0.0006	0.0004	0.0109

The results of the testing indicated that there were statistically significant differences in relative amounts of potential energy, and they depended on the conditions in which the experiments were carried out (i.e., with or without the support system, at a constant weight and impact height).

4.2. Monitoring the Effects of Selected Parameters on the Value of the Relative Amount of Absorbed Energy

The purpose of this investigation was to identify the variables (factors), or interactions between them, which have significant effects on the output variable (a value of the relative amount of absorbed energy) at the i^{th} bounce of the drop hammer on the conveyor belt. The tests were carried out for two different system assemblies (System variable): without the support system (No) and with the support system (Yes). The minimum impact height of the drop hammer in the working zone (Height variable) was determined as 1 m, and the maximum height was 2 m. The minimum weight of the drop hammer was 50 kg while the maximum weight was 80 kg (Weight variable). The input parameters and their levels are presented in Table 3.

Table 3. Input parameters for the DOE method.

Level	Weight [kg]	Height [m]	System
	A	B	C
Lower (−)	50	1.0	No
Upper (+)	80	2.0	Yes

The effects of the main input variables (A, B, C) for all of the monitored bounces are listed in Table 4. Significance of the effects of individual variables was tested by a *t*-test and by identifying a *p*-value.

Table 4. Effects of main variables.

Bounce		Weight (A)	Height (B)	System (C)	R-Squared
1.	effect	−0.064	0.031	0.119	91.35%
	<i>p</i> -value	0.040	0.221 *	0.005	
2.	effect	−0.048	0.022	0.125	94.15%
	<i>p</i> -value	0.018	0.148 *	0.001	
3.	effect	−0.069	0.015	0.098	94.58%
	<i>p</i> -value	0.003	0.243 *	0.001	
4.	effect	−0.082	−0.035	0.156	95.73%
	<i>p</i> -value	0.005	0.070 *	0.0001	

*: *p*-value > α , $\alpha = 0.05$.

A graphical representation of the main effects of all factors at Bounce 1 is shown in Figure 7. A positive effect value means that, as the variable shifts from the lower level to the upper level, its effect increases and so does the output value. A negative value of the effect of the drop hammer weight means that, as the weight increases, with the other conditions being constant, the output variable slightly decreases.

Results of the DOE method confirmed the conclusions made on the basis of the experimental measurements. An analysis of the results indicated that System variable (C) and Weight variable (A) had significant effects on the output variable. On the other hand, the effect of the Impact Height (B) was negligible in terms of the amount of absorbed impact energy at the given drop hammer weight, regardless of the bounce sequence number (*p*-value > α).

In this case, only the Weight (A) and System (C) main variables exhibited statistically significant effects. Therefore, the model of a complete three-factor experiment was adjusted as follows:

$$E_{relat,i} = b_0 + b_1 Weight + b_2 System, \quad (5)$$

wherein $E_{relat,i}$ is the value of the relative amount of absorbed energy at i^{th} bounce and b_0 , b_1 , b_2 are the point estimates of the model parameters. Models (5), (6), (7), and (8) were created based on Equation (4).

The values of the parameters equalled half of the respective effect. The total informative value of the model was identified based on the coefficient of multiple determination R-squared (Table 4). High values of the R-squared coefficient at all the bounces mean that the created models explain the variability of the variables very well.

4.3. Creation of a Model of Correlations between the Relative Amount of Absorbed Energy and Selected Parameters

The purpose of this investigation was to find a regression model that would express the correlations between the relative amount of absorbed potential energy E_{relat} and four independent variables (Height, Weight, Bounce and System); the created model is as follows:

$$E_{relat} = \beta_0 + \beta_1 Height + \beta_2 Weight + \beta_3 Bounce + \beta_4 System + \varepsilon, \quad (6)$$

wherein β_0 and β_j for $j = 1, 2, 3, 4$ are the model parameters and ε is the random error.

Height was the input variable ranging from 1 m to 2 m, with 0.2 m increments and Weight ranged from 50 to 80 kg, with 10 kg increments. Bounce variable acquired four different values (1 for Bounce 1; 2 for Bounce 2; 3 for Bounce 3; and 4 for Bounce 4). System was a dichotomic variable, and it was converted into a numerical variable with two values: 1 for the support system being present (SS) and 0 for the support system being absent (WSS). The output variable E_{relat} was a continuous variable that ranged from 0 to 1.

The point estimate of the model (Model I) was as follows:

$$E_{relat} = b_0 + b_1 \text{Height} + b_2 \text{Weight} + b_3 \text{Bounce} + b_4 \text{System}. \quad (7)$$

Point estimates of the parameters, as well as their statistical significance, and interval estimates of the parameters are listed in Table 5.

Table 5. Estimated values of the regression Model I parameters ($\alpha = 0.05$).

Parameter	Estimate	Standard Error	t-Stat	p-Value	95%-Confidence Interval Lower	Interval Upper
Intercept	0.565	0.0117	48.311	<0.0001	0.5428	0.5890
Height	0.008	0.0045	1.674	0.096	−0.0013	0.0163
Weight	−0.002	0.0001	−13.800	<0.0001	−0.0021	−0.0016
Bounce	−0.005	0.0014	−3.845	<0.0001	−0.0080	−0.0026
System	0.101	0.0030	33.641	<0.0001	0.0955	0.1074

Results of the testing indicated that Model I was a statistically significant regression model ($p\text{-value} = 2.8 \times 10^{-82} < \alpha$) with the coefficient of determination representing 0.88. Apparently, Height variable was not statistically significant ($p\text{-value} > \alpha$), while the other input variables were statistically significant, i.e., they significantly affected the output variable.

A modified regression model (Model II) was as follows:

$$E_{relat} = b_0 + b_1 \text{Weight} + b_2 \text{Bounce} + b_3 \text{System}. \quad (8)$$

Point estimates of the parameters and statistical significance of the adjusted regression model are listed in Table 6.

Table 6. Estimated values of the regression Model II parameters ($\alpha = 0.05$).

Parameter	Estimate	Standard Error	t-Stat	p-Value	95%-Confidence Interval Lower	Interval Upper
Intercept	0.577	0.009	60.317	<0.0001	0.5584	0.5962
Weight	−0.002	0.0001	−13.795	<0.0001	−0.0021	−0.0016
Bounce	−0.005	0.0014	−3.725	0.0003	−0.0078	−0.0024
System	0.102	0.0030	33.508	<0.0001	0.0956	0.1076

The adjusted regression Model II was statistically significant ($p\text{-value} = 5 \times 10^{-83} < \alpha$) and the coefficient of determination equalled 0.88. All of the input variables were statistically significant ($p\text{-value} < \alpha$); this means that they had significant effects on the relative amount of absorbed potential energy.

A graphical representation of the empirical (real) values and the theoretical (model) values of the relative amount of absorbed energy is presented in Figure 8.

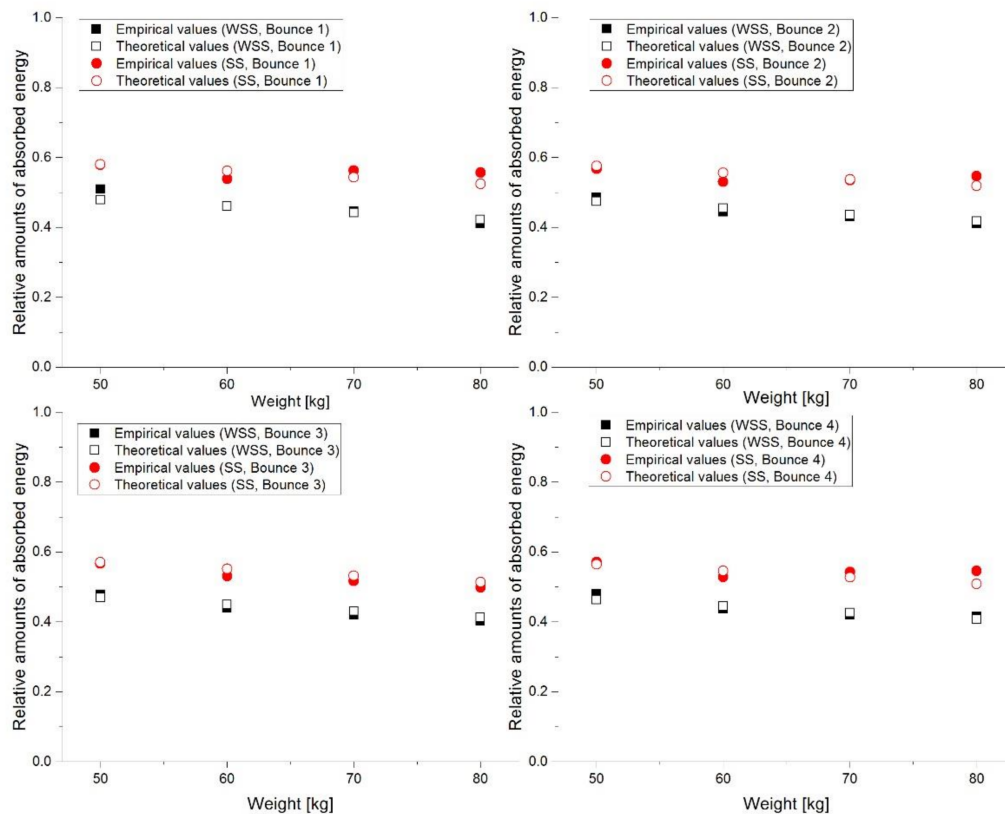


Figure 8. Empirical and theoretical values (Model II).

5. Conclusions

The purpose of this experimental research was to examine and compare the dynamic load of the P2500 rubber-textile conveyor belt. The resulting values of the relative amount of absorbed energy, obtained with and without engaging a support system, were compared. Experiments simulated various real conditions (impact of materials of various weights, falling from various heights). Conclusions that were made based on the experiments were as follows:

Within the identification and comparison of the amounts of absorbed energy before the occurrence of damage to the conveyor belt (puncture) which usually leads to belt decommissioning, it was observed that the tested conveyor belt absorbed, without suffering any damage, the energy of 1589 kJ when the support system was engaged, and 2551 kJ when the support system was absent, with a maximum impact weight of 100 kg and a maximum impact height of 2.6 m.

Based on the results of identification of the effects of the parameters (drop hammer weight, impact height and support system absence/presence) on a relative amount of absorbed energy before a puncture occurs, it was concluded that the effect of the impact height on the relative amount of absorbed impact energy at the given drop hammer weight was not strong in any of the two system assemblies, i.e., with and without the support system. However, the effect of the drop hammer weight on the relative amount of absorbed impact energy was strong. The range of the values of the relative amount of absorbed energy was apparently wider. A relative amount of absorbed energy decreased with an increasing drop hammer weight; this applied to both system assemblies, i.e., with and without the support system. Out of all the parameters, the support system presence exhibited the most evident effect on the relative amount of absorbed impact energy. The conveyor belt equipped with a support system absorbed 50% to 62% of the impact energy, depending on the drop hammer impact height and weight. Without the support system,

the conveyor belt absorbed 40% to 51% of energy, depending on the drop hammer impact height and weight.

The main purpose of the research was accomplished by creating a model of correlations between the relative amount of absorbed energy and selected parameters, while the proposed dynamic model included some of the impact process parameters. The resulting regression model (8) confirmed that a drop hammer weight and presence of the support system are the parameters with a statistically significant impact on the amount of absorbed energy.

In our further research, we will carry out experimental testing of interactions between a conveyor belt and an impact bed consisting of rubber impact bars of various designs (types). We will also compare the resulting amounts of energy absorbed by the conveyor belt to those observed with a conveyor belt equipped with a conventional support system consisting of idlers. We plan to test conveyor belts of various strengths and various carcass designs.

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