



# Article Model Development for State-of-Power Estimation of Large-Capacity Nickel-Manganese-Cobalt Oxide-Based Lithium-Ion Cell Validated Using a Real-Life Profile

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**Abstract:** This paper investigates the model development of the state-of-power (SoP) estimation for a 43 Ah large-capacity prismatic nickel-manganese-cobalt oxide (NMC) based lithium-ion cell with a thorough aging investigation of the cells' internal resistance increase. For a safe operation of the vehicle system, a battery management system (BMS) integrated with SoP estimation functions is crucial. In this study, the developed SoP model used for the estimation of power throughout the lifetime of the cell is coupled with a dual-polarization equivalent-circuit model (DP\_ECM) for achieving the precise estimation of desired parameters. The SoP model is developed based on the pulse-trained internal resistance evolution approach, and hence the power is estimated by determining the rate of internal resistance increase. Hybrid pulse power characterization (HPPC) test results are used for extraction of the impedance parameters. In the DP\_ECM, Coulomb counting and extended Kalman filter (EKF) state estimation methods are developed for the accurate estimation of the state of charge (SoC) of the cell. The SoP model validation is performed by using both dynamic Worldwide harmonized Light vehicles Test Cycles (WLTC) and static current profiles, achieving promising results with root-mean-square errors (RMSE) of 2% and 1%, respectively.

**Keywords:** state of power; state of charge; internal resistance increase; battery management system; aging; validation profiles

# 1. Introduction

With the consistent increment in power density and specific energy of Li-ion batteries, the intensive use of these battery types is becoming common practice in the automotive application sector. This contributes to a matured battery management system (BMS) utilized in Li-ion batteries, having high charge and discharge current rates and high energy density [1,2]. For the safe operation of the EV battery system, appropriate parameter identification methods of lithium-ion batteries are crucial [3]. Various methods are used for the estimation of SoC and SoP, whereas Xiong et al. [4] used the Kalman filter joint estimator method to calculate SoC and predict the SoP output. The study provides an SoP estimation model using the SoC result as an input without considering the resistance increase in the cells. On the other hand, a recursive extended least-squares (RELS) algorithm is used to estimate SoP using an online equivalent-circuit model parameter identification technique [5] with an assumption of constant current as input and temperature as an influencing factor. However, the study did not consider the use of discharging current and power for effective determination of the desired SoP. Jiang et al. [6] applied the multi-constraint SoP estimation method under high-temperature conditions, proving that the resulting SoP had



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**Copyright:** © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). good precision. Thermal characteristics of batteries during acceleration or deceleration of electric vehicles are also considered for assessing the temperature effect on SoP improving the estimation accuracy [7]. However, the study lacks the incorporation of the SoC and resistance effects on the resulting SoP.

Due to simplicity and a low computational time requirement, the equivalent-circuit model (ECM) approach has also been used by different researchers. Gao et al. [8] used a coupled ECM approach to estimate SoC and SoP. Jia et al. [9] made a comparative analysis between the extended Kalman filter (EKF), strong tracking EKF (STEKF), and multirate strong tracking EKF (MRSTEKF) and verified that the MRSTEKF has faster computation time during estimation of SoC and SoP. However, these methods were found to be relatively complex for utilization purposes. Different studies have also been conducted with online state-of-power estimation techniques of lithium-ion batteries performed using constantvoltage charging current and Kalman filtering state estimation methods [10–14] without assessing the aging effects of internal resistance increase on the SoP estimation. In addition to the SoC determination, a few kinds of research have been conducted to investigate the effect of aging on SoP estimation. Esfandyari et al. [15] and Sun et al. [16] analyzed the effect of aging status using a combined reference mode of constant-current and constant-voltage methods for estimation of fresh-cell SoP where the various aging states are adapted. In this method, the author tried to analyze the aging effect, which is limited to the beginning-of-life (BoL) state-of-health (SoH) data, which might result in inaccuracy on the SoP estimation. The state of charge (SoC) is one of the most important parameters in the battery cell study, which needs accurate determination where it is changed nonlinearly during the charge and discharge process. However, finding the most accurate SoC value becomes challenging as it can be affected by different factors, including temperature and self-discharge. Furthermore, the determination of the state of power (SoP) is the other crucial aspect that uses the estimated output of SoC as an input for its computation. Nowadays, in electric vehicle (EV) applications, the estimation of SoP is becoming an interesting study area that enables optimal control of the battery power management through the BMS to be achieved [17]. Therefore, for the reliable operation of the battery system used in either EV or renewable energy integration applications, an accurate estimation of battery SoP is essential, which is a function of load current, terminal voltage, and SoC [18].

The methods mentioned above have their own pros and cons in terms of complexity, accuracy, and computational time. Moreover, in the previous studies mentioned above, the SoP response of battery cells was not performed until the end of life (EoL) of the cells, and rather focused on the BoL parameter values. In this paper, the main objective of the study is to compromise the gaps observed from the above reviews by developing a robust SoP model used for the estimation of the state of power for an electric vehicle battery cell by considering the effect of internal resistance increase throughout the life of the cell. Following the parametrization of the SoP model with the proposed pulse-trained internal resistance evolution approach, novel results showing the promising accuracy of the model are achieved. The discharge peak currents and the influence of the aging effect in terms of internal resistance increase have been considered for the determination of the SoP output, which was not inclusively considered in previous studies. In addition to the SoP model, the dual-polarization equivalent-circuit model (DP\_ECM) is utilized for accurate estimation of SoC together with lookup table parameters, which in turn is taken as an input for the SoP model. The DP\_ECM is coupled to the SoP model and the desired power output is estimated. Finally, both the SoP and the DP\_ECM are validated using dynamic Worldwide harmonized Light vehicles Test Cycles (WLTC) and static current profiles, and promising results are found.

## 2. Experimental Setup

The remaining sections of the manuscript are organized as follows: Section 2 describes the experimental setup and parameter extraction. Section 3 discusses the model description,

mathematical representation, and SoP model development. Section 4 presents the SoC and SoP estimation results and model validation; and finally, the conclusion is presented in Section 5.

The overall battery test was performed using an efficient characterization methodology for nickel-manganese-cobalt oxide (NMC)-based lithium-ion cells. The type of battery cell used for testing is a 43 Ah large-capacity cell made up of NMC/C-based cathode material and graphite anode. The battery cell under study is categorized as preferable for vehicular services as it retains the properties of high-power density of 1200 W/kg, 840 g weight, and nominal voltage of 3.6 V. Moreover, the operating voltage of the cell ranges from 3 to 4.2 V, dimensions of 27.5 mm × 148 mm × 91 mm, and internal resistance of  $\leq 2 \text{ m}\Omega$ . During the test campaign, CTS custom climate chambers for controlling the temperature and PEC manufactured testers were used.

An average of eight HPPC tests with duration of 800 full equivalent cycles (FECs) were accomplished for all the four representative cells considered for the SoP estimation. The characterization of batteries at various environmental and battery state conditions, such as at different temperatures, state-of-charge, and current rates, were performed. The battery model development procedure consists of a series of standard testing procedures used to capture the electrical and thermal behaviors efficiently. The electrothermal characterization procedure mainly incorporates the capacity, open-circuit voltage (OCV), quasi-open-circuit voltage (qOCV), HPPC, and validation tests. Based on these characterization results, an electrothermal model is parametrized and developed for the determination of the cells' dynamic behaviors.

In Figure 1, it can be seen that the battery tester performs the charge/discharge process and monitors the cell's voltage, current, and temperature, and the climate chamber used to control the environmental temperature. The voltage, current, power, energy, cycle, and temperature are presented through the user interface.



Figure 1. Block representation of test bench topology during cell experiment [19].

This paper mainly deals with the development of the SoP estimation model, and therefore covers the SoP estimation and model validation based on the internal resistance increase. The proposed methodology incorporates the effect of resistance increase throughout the lifetime of the cells during the SoP estimation. The hybrid pulse power characterization (HPPC) test pattern used to find the resistance (R) and capacitance (C) parameters was analyzed. The internal resistance of the battery cells was extracted from the HPPC test conducted according to the defined test conditions of three different SoC points of 80%, 50%, and 20% with three different C-rates of 0.33 C, 0.5 C and 1 C [20]. The charge and discharge cycles were performed using predetermined current rate (C-rate)

values with constant current–constant voltage (CC-CV) standard charging of cells. The summary of the overall electrothermal and aging characterization procedure is presented in Figure 2. In addition to the electrical characterization procedure, the standard aging test protocols were followed by checkup tests performed from BoL to EoL of the cells to find the internal resistance and capacity fade results throughout the life of the cells.



Figure 2. Flowchart of the overall characterization procedure.

From Figure 2, it can be seen that two types of check-ups were performed during aging of the cells. The first check-up is the short check-up (SCU), which is performed every 100 cycles; and the second one is detailed check-up (DCU), performed every 300 FECs. The HPPC test is intended to measure the battery impedance using a test profile that incorporates both discharge and charge pulses. The primary objective of this test is to establish the internal resistance of the tested cell as a function of SoC. A representative figure showing the current pulses is presented in Figure S2 of the Supplementary Material provided separately. During the 10 s charge and discharge pulses, extended voltage limits were used. A preliminary simulation was performed using the different pulses and the electrical parameters needed for the model ( $R_0$ ,  $R_1$ ,  $C_1$ ,  $R_2$ , and  $C_2$ ) were extracted. The methodology for the parameter extraction is explained in Section 2.2.

In addition to the HPPC test, OCV test is another important characterization test performed to provide the open-circuit voltage level of the cell. In this characterization test,

the cell is first fully charged at 100% SoC with a C/2 current rate. During the test, the cell is resting for 3 h and the OCV is measured from the last voltage point. Then, it is discharged with C/2 for a 5% decrement of its total discharged capacity, rested for 3 h, and the OCV is measured for the new SoC. This process continues until the safety limit of the cell is reached ( $V_{min} = 3 V$ ). The last value is considered as the first point of charging the OCV, by which estimation starts with a similar way but with positive current until the upper safety limit of the battery cell ( $V_{max}$ ) is reached. An experimental result for 25 °C is shown in Figure S3 of the Supplementary Material.

## 2.1. ECM Parameter Extraction

It is well-known that the SoC and SoH of the battery cells are the most crucial parameters needing accurate determination for effective operation and control of the BMS on the overall power system [21–24]. However, in this paper, the scope of the SoP model development is mainly dependent on accurate determination of SoC parameters, and therefore, the aspects related to SoH parameters will not be addressed. The total SoC is the sum of the state of charge due to both voltage and current effect. Primarily, the SoC can also be determined by using the coulomb-counting method defined by [25]:

$$SoC = SoC_0 - \frac{1}{C_{init}} \int I_{batt} dt$$
(1)

where  $SoC_0$  is the initial state of charge of the cell and  $I_{batt}$  is the battery current.

With the combined use of the coulomb counting and EKF methods, the total SoC can be estimated by considering the sum of SoC with voltage and current inputs. Both algorithms consider the current input, with the EKF considering both voltage and current as input. Therefore, total SoC at  $K_{th}$  time step is given by:

$$SoC_k = SoC_{I,k} + SoC_{V,k}$$
<sup>(2)</sup>

where k stands for the time step, I stands for the current in (A), and V stands for the voltage in (V).

# 2.2. Table-Based Linear Interpolation (TBLI) Parameter Extraction

The ECM parameters, including  $R_0$ ,  $R_1$ ,  $C_1$ ,  $R_2$ , and  $C_2$ , are extracted at SoC\_HPPC points of 20%, 50%, and 80% intervals using table-based linear interpolation (TBLI) method in account of the varying SoC values and C-rates. The temperature considered for this scenario is limited to 0 °C, 10 °C, 25 °C, and 45 °C. The electrochemical reaction responses during a current pulse are shown in Figure 3.



Figure 3. The corresponding region of the pulse and the schematics of the electrical model.

The HPPC characterization results with the values of  $R_0$ ,  $R_1$ ,  $C_1$ ,  $R_2$ ,  $C_2$  versus HPPC\_SoC points at different temperatures are analyzed and presented below.

Figures 4–8 show the HPPC characterization results with the values of R and C parameters at different temperature ranges. As shown in the figures, the ohmic resistance is higher at lower SoC levels and decreases with the increase in SoC level. Moreover, the result shows that in most of the cases, at a lower temperature, resistance is higher; and at higher temperature, resistance is found to be lower, which is coherent with the previous reports in [26,27].



Figure 5. Polarization resistance 1 as a function of temperature and state of charge.



Figure 6. Polarization resistance 2 as a function of temperature and state of charge.



Figure 7. Capacitance 1 as a function of temperature and state of charge.



Figure 8. Capacitance 2 as a function of temperature and state of charge.

## 3. Model Description and Mathematical Representations

In addition to the SoP model, to identify the behaviors of the battery cell and find the electrical response, an electrothermal model is developed based on the Thevenin model [28] (Figure 3), which consists of a voltage source with an ohmic resistance and two parallel RC circuits. Based on the equivalent-circuit model, the battery output voltage of the Li-ion cell is the voltage drop resulting from the battery open-circuit voltage (OCV), the battery ohmic resistance (R<sub>0</sub>), and battery polarization impedances (R<sub>1</sub>C<sub>1</sub>, R<sub>2</sub>C<sub>2</sub> circuits). The output voltage of the cell is given by [28,29]:

$$V_{cell} = V_{oc} - R_1 I_1 - R_2 I_2 - R_0 I_{batt}$$
(3)

where  $I_{batt}$  is the flowing current in the battery (A),  $I_1$  is the current passing in the polarization resistance (A), and  $I_2$  is the current flowing through the charge transfer resistance (A).

As shown in Figure 9, the current, initial SoC, and temperature are the inputs for the DP\_ECM and its outputs are SoC, resistance, and energy. The resistance and SoC outputs are fed as an input to the SoP model together with lookup table parameters (cycling resistances and cycle numbers) and power is the output of the SoP model.



Figure 9. Schematic representation of DP\_ECM coupled SoP battery model.

# 3.1. SoC Estimation

The total SoC at time t, which is described in Equations (1) and (2) of Section 2.1, can also be expressed as z(t), which can be expressed in terms of battery capacity as shown in Equation (4):

$$z(t) = Q_{init} + \frac{\eta * i_0(t)}{Q_{norm}(t)}$$
(4)

where  $Q_{init}$  is the initial battery capacity (Ah),  $\eta$  is battery efficiency,  $Q_{norm}$  is the current battery capacity (Ah), and  $i_0$  is the load current passing through the ohmic resistor.

# 3.2. Proposed SoP Estimation Logic

To find out the SoP, the maximum discharge current first has to be defined, which is given by:

$$I_{max}^{dis} = C_{rate} * Q_{norm}$$
(5)

where C-rate is the current rate of the cell and  $Q_{norm}$  stands for the cell nominal capacity in Ah. The maximum discharge current due to SoC at  $k_{th}$  time step can be expressed as:

$$i_{\max,k}^{\text{dis,SoC}} = \eta * C_{\text{rate}} * Q_{\text{norm}} * (\text{SoC}_k - \text{SoC}_{\min})$$
(6)

where  $\eta$  is cell efficiency, commonly taken as 1 at BoL.

On the other hand, the maximum discharge current due to voltage is given as:

$$i_{\max,k}^{\text{dis, volt}} = |i_{0,k}| * (V_{\text{ocv}} - V_{\text{min}}) * \left(\frac{1}{|V_{\text{ocv}} - V_{\text{min}}|} + \frac{1}{V_{\text{max}} - (V_{\text{ocv}} - V_{\text{min}})}\right)$$
(7)

where  $V_{ocv}$  is the open-circuit voltage (V) at the SoC value of the  $K_{th}$  time step,  $V_{min}$  is the minimum cell voltage and  $V_{max}$  is the maximum cell voltage, and  $i_{0,k}$  is the load current at the  $K_{th}$  time step. For the battery cell under study, the following parameter values are considered.

Here,  $V_{max} = 4.2 \text{ V}$  and  $V_{min} = 3 \text{ V}$ ,  $SoC_{min} = 0.1$ ,  $SoC_{max} = 1$ ,  $Q_{norm} = 43 \text{ Ah}$ ,  $C_{rate} = 1 \text{ C}$ .

$$i_{\max,k}^{\text{dis}} = \min\left(i_{\max}^{\text{dis}}, i_{\max,k}^{\text{dis},\text{SoC}}, i_{\max,k}^{\text{dis},\text{volt}}\right)$$
(8)

The maximum power where the cell could perform is also defined as:

$$P_{max}^{dis} = V_{max} * i_{max}^{dis}$$
<sup>(9)</sup>

Finally, the maximum discharge power  $P_{\max,k}^{dis}$  is defined as the function of the discharge current, voltage, and discharge resistance parameters.

$$P_{\max,k}^{\text{dis}} = \min\left(P_{\max}^{\text{dis}}, i_{\max,k}^{\text{dis}} * \left(V_{\text{ocv}} - i_{\max,k}^{\text{dis}} * R_{\text{dis}}\right)\right)$$
(10)

#### 3.3. SoP Estimation Model Development

The overall model is developed based on MATLAB/Simulink environment. The objective of the model development is to determine the SoP of the cell in relation to the internal resistance increase not only at BoL, but also throughout its lifetime for consideration of the aging effects. The model is a coupled model combined with electrothermal and SoP models. The electrothermal is used to reproduce the cell's electrical performances/behaviors, whereas the SoP model is used for the estimation of the SoP parameter crucial for the BMS. The SoP estimation model is developed based on Equations (5)–(10), parameterized using SoC, voltage, temperature, and current experimental data found from the test result. Using the electrothermal model output of these parameters, input of lookup table is provided to the SoP model and then maximum discharge current and discharge resistances are calculated. Finally, the SoP throughout the lifetime of the cell condition is estimated.

The estimation of SoP through lifetime until EoL condition is estimated by defining the range of equivalent cycles and internal resistance increase parameters. The reference resistance increase at EoL is estimated using the rate of internal resistance ( $R_i$ ) increase at 50% SoC. The total Ri increase rate is estimated by using the combined effect of the FECs, the resistance cycle (estimated using the difference between two consecutive  $R_i$  values), and the cycle test resistance values. To find out the total  $R_i$ , and hence estimate SoP at EoL condition, first the rate of  $R_i$  increase is multiplied with Ri value at BoL condition. Finally, using the respective current rate and total resistance increase, the SoP output of the cell is estimated until its EoL.

## 4. Results, Validations, and Discussions

#### 4.1. SoC Estimation and Model Validation

It is recalled that while estimating the SoP of the battery cell, the consideration and verification of the SoC result is essential for the safe operation and efficient control of the BMS. The SoC estimation and verification are accomplished through the DP\_ECM coupled with the SoP model. Using the WLTC as the input current validation profile, the estimation and validation of the DP\_ECM are performed and the output voltage with respective time is provided. The root-mean-square error (RMSE) of the output is also found according to the variation of the predefined SoC values. The summary of the validation result for the electro-thermal model is shown in Table 1.

DP_ECM Validation Deviation				
Temperature (°C)	0	10	25	45
<b>RMSE (%)</b>	1.9	1.8	1	1
Current profile	WLTC	WLTC	WLTC	WLTC

Table 1. Summary of RMSE deviation of DP\_ECM electrical model.

In addition to the voltage validation results shown in Figure 10, the SoC estimation result is provided in Figure 11. The estimation output shows a comparison between the measured and simulated results and a respective RMSE of 1% is found, which is in line with the voltage validation output ranging from 1% to 1.9% for different temperature values.

As the accurate result of SoC is among the determinant parameter fed as an input to the SoP model, the estimation and validation of the SoP model is dependent on the results found from the DP\_ECM illustrated in Figures 10 and 11. The validation result of the SoP model is presented in the below section.



**Figure 10.** Validation of the DP\_ECM at 0  $^{\circ}$ C (**a**), 10  $^{\circ}$ C (**b**), 25  $^{\circ}$ C (**c**), and 45  $^{\circ}$ C (**d**).



Figure 11. SoC estimation and validation result of the DP\_ECM.

4.2. SoP Estimation Results and Model Validation

Before the analysis of the SoP of the battery cell, the response of  $R_i$  as a function of the respective SoC of the cells was illustrated throughout the total FECs. Based on the measured data of the cell, the relation between the SoC, FECs, and  $R_i$  was presented with a 3D surface fitting curve, shown in Figure 12. Typically, a 100% internal resistance increase is considered as the first life EoL of the cell.



Figure 12. Internal resistance versus SoC relationship with 3D surface fitting.

SOP (W) 520 SOP (W) 500 480 SOP (W) 460 440 420 400 0 100 200 300 400 500 600 700 800 **FECs** 

R<sub>i</sub> increase throughout the total FECs.

Applying varying values of SoC between 0.1 and 1 as input, the SoP output from BoL to EoL of a representative single cell is shown in Figure 13, where the SoP output is dependent on the internal resistance [26,27]. The SoP result follows the magnitude of the

Figure 13. SoP output of the cell through 800 FECs.

From Figure 13, it can be seen that the SoP did not follow a uniform trend. This is because the measured internal resistance did not increase monotonically, which is a result of the dynamic current profile used; and the inconsistent R<sub>i</sub> measured data show that the resistance change is not dominant for these cells.

#### 4.3. Validation of the SoP Model

The validation of the SoP model was performed using two types of current profiles. The dynamic WLTC and static load current profiles were used for evaluation of the model performance and its accuracy. From Figure 14a, it can be seen that the estimated  $R_i$ output follows a similar trend to the measured R<sub>i</sub>. However, there is some deviation observed between the two curves. The resulting RMSE is found to be around 2%, which is almost comparable with the values reported by previous studies [9,15]. However, this error resulted mainly from the inconsistency of the measured internal resistance, where it was not constantly increasing in line with the respective FECs. Obviously, in the process of battery aging, the change of internal resistance contains a complex electrochemical mechanism evolution process, which could also result in inconsistent output. The SoP model validation expressed in terms of internal resistance is shown in Figure 14.

From Figure 14b, it is shown that the estimated output follows the measured value with better accuracy, showing that the static profile provides a better validation result compared to the dynamic profile. In this case, the RMSE is found to be around 1%, which seems better compared to the results found in previous reports [16,27].



Figure 14. SoP validation as function of internal resistance using (a) WLTC profile; (b) static current profile.

### 5. Conclusions

In addition to the accurate SoC parameter estimation, the development of the SoP estimation logic used in this study enables the evaluation of the cells' behaviors in terms of their SoP output, which is considered an essential parameter in the safe operation of the battery and BMS system. In this paper, an efficient method was used to estimate the SoC and to define the maximum discharge current, which is crucial for estimation of the SoP. Therefore, it is identified that an accurate estimation of the SoC is essential for precise estimation of battery cells' SoP. The result of the analysis show that high accuracy of SoC estimation from the DP\_ECM is found with an error of 1%. In addition, the maximum RMSE of SoP is found with the dynamic WLTC profile, whereas a relatively lower RMSE is found with the static validation profile. The RMSE result of the model validation with the dynamic and static profile is found to be 2% and 1%, respectively. The resulting error is mainly caused by the inconsistency of the measured internal resistance value where the resistance change is found as not dominant for the cells under study. In the future, the aspects of module-level SoP estimation model development and validation can be further investigated.

**Supplementary Materials:** The following supporting information can be downloaded at: https: //www.mdpi.com/article/10.3390/en15186497/s1, Figure S1: Cycling profile of cell 001 (100% DoD, 50% Mid-SoC, 1C charge-discharge rate; Figure S2: HPPC pulse train at 25°C with current profile and voltage output response; Figure S3: Results of the OCV test at 25°C with the current profile and output voltage; Figure S4: Single WLTC cycle current profile; Table S1: Lifetime check-up description.

**Author Contributions:** A.A.K. performed the formal result analysis, methodology, and writing; M.S.H. and T.K. conducted the investigation and review; H.A.B., T.J., J.V.M. and T.C. provided visualizations and guidance; M.B. performed supervision. All authors have read and agreed to the published version of the manuscript.

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