

Article

A Modified Variable Power Angle Control for Unified Power Quality Conditioner in a Distorted Utility Source

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Abstract: The distorted supply voltage degrades the control performance of a unified power quality conditioner (UPQC). This problem causes incorrect calculations in the harmonic identification and reference signal generation processes. This paper proposes a modified harmonic identification of the UPQC. The reference compensating current calculation for the shunt active power filter (shunt APF) is developed using the sliding window with the Fourier analysis (SWFA) method. In addition, the variable power angle control (PAC) is applied to operate the reference signal generation of the series APF and the shunt APF of the UPQC. Under the distorted voltage and nonlinear load conditions, the proposed approach can provide accurate reference compensating signals and successfully share the load reactive power compensation between the shunt APF and the series APF. In this work, a three-phase, three-wire power system with linear and nonlinear loads was implemented. The proposed method was validated using the processor-in-the-loop technique on an eZdsp™ F28335 board and the MATLAB/Simulink program. The testing results indicated that SWFA has excellent filtering performance and enhances harmonic identification compared to the operation without any filter or with low pass filters (LPF). With the proposed approach, the percentage of total harmonic distortion of voltage and current could be maintained within the IEEE519-2022 standard, and the magnitude of the RMS voltage across the load was in the recommended range specified by ANSI C84.1-2016.

Keywords: unified power quality conditioner; power angle control; sliding window with Fourier analysis; distorted utility source



Citation: Chaiyaphun, K.; Santiprapan, P.; Areerak, K. A Modified Variable Power Angle Control for Unified Power Quality Conditioner in a Distorted Utility Source. *Energies* **2024**, *17*, 2830. <https://doi.org/10.3390/en17122830>

Academic Editor: Ahmed Abu-Siada

Received: 29 April 2024

Revised: 28 May 2024

Accepted: 6 June 2024

Published: 8 June 2024



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1. Introduction

Modern power distribution systems are facing various power quality (PQ) problems. The widespread of renewable energy distributed generation [1] and the increase in nonlinear loads in industrial and domestic appliances [2] can potentially degrade both the voltage and current quality of the power system. Voltage sag, voltage swell, harmonic current, and harmonic supply voltage are common power quality problems [3]. These may lead to power system issues such as power losses in transmission lines [4], overheating of capacitors and transformers, and malfunctioning of protective relays [5]. Moreover, electronics-based instruments (e.g., computers and micro-controller systems) are growing rapidly in domestic and industrial applications. These devices require a high standard of power quality for a safe and stable operation [6]. Considering the distribution side and load side of the power system, it is essential to ensure a pure sinusoidal waveform of constant magnitude and frequency of supply.

To mitigate the problems mentioned above, capacitor banks and passive power filters are commonly selected in the conventional approach. Capacitor banks are used for reactive power compensation. Passive power filters (PPFs) are installed to mitigate harmonic issues due to their simplicity and low cost [7]. However, these devices are inflexible as they are

generally setup for one particular load. In other words, a change in load demand can worsen the compensation performance. PPFs are also sensitive to resonance between the system and filter [8]. This effect can cause an amplification of harmonic current, which may lead to excessive heat and machine breakdown. Therefore, active power filters (APFs) have been mostly adopted as they are more flexible and can suppress various PQ problems compared to PPFs [9]. APFs are classified into three configurations: shunt APFs, series APFs, and hybrid APFs. The combination of a series APF and a shunt APF called unified power quality conditioning (UPQC) is designed to simultaneously suppress disturbances on the load and supply sides [10]. A common UPQC structure is shown in Figure 1. This structure is called UPQC-R according to the position of the shunt APF with respect to the series APF. The control of UPQC can be divided into three main parts: reference signal generation, reference signal tracking control, and DC bus voltage control.

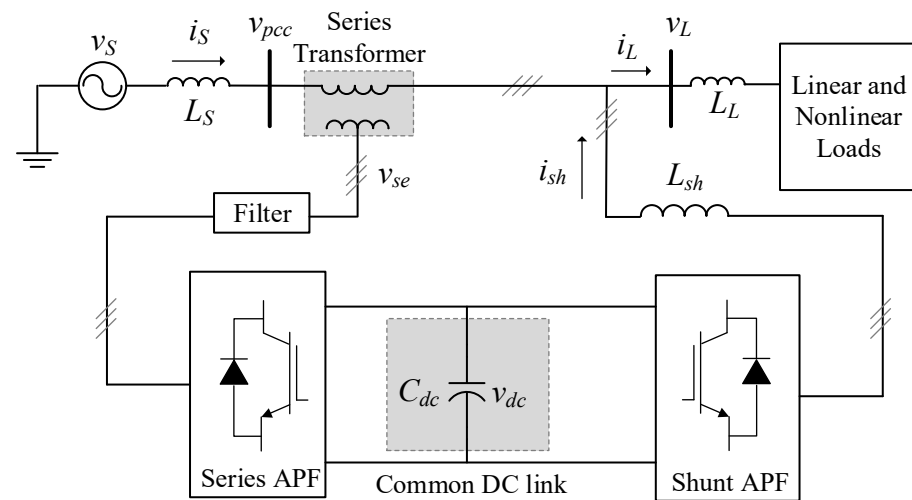


Figure 1. Schematic of a basic UPQC-based system.

This paper focused solely on the reference signal generation process. This process is the first and crucial step to ensure the performance of reference signal tracking control. The reference signal generation process concerns the voltage compensation strategy and harmonic identification methods. There are four main voltage compensation strategies for UPQC, including UPQC-P, UPQC-Q, UPQC-VA_{min}, and UPQC-S. In the UPQC-P strategy, active power is injected through the series transformer for the voltage sag and voltage swell compensation [11]. In the UPQC-Q approach, only voltage sag is mitigated by the reactive power compensation [12,13]. The UPQC-VA_{min} has been developed to compensate for the voltage swell. Moreover, a minimum VA rating of UPQC is considered in this approach [14,15]. Recently, UPQC-S was proposed [16–18]. This approach cooperates with the power angle control (PAC) method. The PAC method can be considered for both voltage sag and voltage swell conditions. Simultaneously, the reactive power compensation is shared between a shunt APF and a series APF. This results in a reduction in the shunt APF rating and its cost. However, in voltage sag/swell conditions, the UPQC with the PAC method cannot share equal reactive power compensation. The variable PAC method [18] has been proposed. The power angle is regulated by the voltage fluctuation factor. Here, this approach can maintain a balanced reactive power compensation between a shunt APF and a series APF. Due to these advantages, the UPQC-S with variable PAC is also adopted in this study.

Apart from the voltage compensation strategy, harmonic identification of the shunt and series APFs is also an important process for reference signal generation. The harmonic identification of UPQC is classified mainly as frequency domain methods [19] and time domain methods [16,17,20–28]. The frequency domain method required a large dataset and high computational capability. This results in a delay in calculation, which is not suitable for the real-time performance of UPQC. Therefore, time-domain methods are more widely

considered for identifying the harmonics. From the literature reviews, the instantaneous p-q theory (PQ) [16,17,20–24], the synchronous reference frame (SRF) or d-q theory [25,26], unit vector template generation (UVTG) [27], and machine learning-based techniques [28] have been presented.

It was found that the PQ method can operate suitably with the UPQC-S approach, leading to simple and fast computation in the digital signal processor implementation. However, in a distorted voltage source condition, a harmonic voltage extraction process for the reference signal generation must be considered. The harmonic voltage on the utility source side can cause an incorrect calculation of the reference signal [29]. This problem also affects the UPQC control performance for power quality improvement. The design and development of the filtering method to obtain the fundamental component of the source voltage has been researched to overcome this condition. In [25], an LPF method was adopted. This filter is simple, but it has limitations, including cut-off frequency tuning and a non-ideal characteristic of filters. Thus, the LPF cannot accurately draw the fundamental component from the distorted source voltage. In [26], under distorted voltage conditions, a modified PLL was applied to track the fundamental frequency and phase angle of the PCC voltage for the SRF method. However, according to the functional block diagram of the modified PLL circuit, the PI controller cannot attenuate the oscillating component of the three-phase power well. The appropriate design of the PI controller parameter is required to avoid instability. In the study in [21], generalized cascaded delay signal cancellation (GCDSC) was proposed to extract the fundamental source voltage. However, this technique can still cause magnitude and phase errors at high frequencies. Thus, additional bandpass filters (BPF) were used to draw these high-frequency components. In [24], the fundamental source voltage was calculated by the limit cycle oscillator–frequency lock loop (LCO-FLL) circuit. To obtain the fundamental source voltage, this technique requires the Jacobian matrix analysis, the Lyapunov theory, and the BPF. From the studies in [21,24], it can be observed that more design procedures, computational complexity, and processing delay must be taken into account in the reference signal generation process when the distorted voltage source is presented.

The sliding window with Fourier analysis (SWFA) as a filter has been applied in the harmonic identification process [30]. The SWFA mechanism can be designed to calculate a signal component at a specific frequency. The considered component is accurately calculated based on the discrete Fourier transform. Here, multiple processes are not required in the harmonic voltage extraction, thereby reducing the complexity and the computational burden of the filtering procedure. In this work, the SWFA method is applied to improve power quality using UPQC.

Based on existing works in the literature, a summary comparison between the related work and the proposed work is presented in Table 1. The main contributions of this work are as follows:

- A distorted voltage source was not studied in many literature [17–20,23,28]. In this work, the reference compensating current calculation with the SWFA is proposed to achieve robustness of harmonic identification in a distorted utility source.
- For the control of UPQC, the use of SWFA in the harmonic voltage extraction process is presented. The use of multiple filters and design complexity are not required in this proposed approach.

As mentioned above, these two points can provide accurate reference signals for the UPQC control. This results in an excellent performance of the power quality improvement under voltage sag, voltage swell, harmonic source voltage, and harmonic current. According to performance indices, the total harmonic distortions ($\%THD_i$, $\%THD_o$) and the RMS voltage magnitude are maintained within the IEEE519-2022 [31] and ANSI C84.1-2016 [32] standards, respectively. Moreover, the PAC method operated with the proposed reference signal generation can still share the load-reactive power compensation between the shunt APF and the series APF. Therefore, this approach can reduce the required VA rating of shunt APF and installation cost.

The rest of this paper is organized as follows: Section 2 describes the structure of the UPQC and the power system investigated in this study. Section 3 explains the proposed methodology, including the principles of harmonic identification and reference signal generation using the SWFA filter. Section 4 explains the processor-in-the-loop (PIL) simulation setup and the testing conditions for the UPQC. The performances of the SWFA and the UPQC operation are presented and discussed in Section 5. Finally, the significant results of this paper are summarized in Section 6.

Table 1. Comparative studies of harmonic identification method for the UPQC control strategy.

Publication Year	Power System	Compensation Strategy	Harmonic Identification Method		Operating Conditions /Disturbances			Sharing of Load Reactive Power
			Series APF	Shunt APF	Voltage Source		Load System	
2007 [19]	3P4W	proposed method	Discrete Wavelet Transform (DWT) and MRA	Discrete Wavelet Transform (DWT) and MRA	-	Frequency change from 50 to 51 Hz	- Nonlinear load - Load change	NO
2008 [16]	3P3W	UPQC-S	UVTG with PAC	Instantaneous pq theory	-	Normal voltage - 5th and 7th harmonic	- Nonlinear load - Load change	YES
2011 [17]	3P3W	UPQC-S	UVTG with PAC	Instantaneous pq theory	-	20% Voltage sag/swell	- Nonlinear load - Load change	YES
2011 [28]	3P4W	UPQC-PSO based ANFIS	State Space Extraction	State Space Extraction	-	Unbalanced sag - Phase jump	- Nonlinear load - Load change	NO
2015 [26]	3P4W	UPQC-S	SRF theory	SRF theory	-	15% Voltage sag - Voltage sag with harmonics - Unbalanced voltage with harmonic	- Nonlinear load - Unbalanced load	YES
2017 [21]	3-phase with PV	UPQC-S	UVTG with PAC	Instantaneous pq theory with GCDSC+BPF	-	Change of irradiation affecting DC bus - 30% Voltage sag/swell - Harmonic	- Nonlinear load - Unbalanced load	YES
2018 [20]	3P3W	UPQC-S	Proposed controllable PAC	Instantaneous pq theory	-	Abrupt phase change - 40% Voltage sag/swell	- Nonlinear load - Load change	YES
2020 [23]	3P3W	Not mentioned	Not mentioned	Proposed Adaptive LSL	-	Normal voltage	- Nonlinear load	NO
2020 [25]	3P3W	Not mentioned	SRF theory with LPF and PLL	Double closed-loop control based	-	20%/ 40% voltage sag - 5th and 7th harmonic	- Nonlinear load - Load change - Unbalanced load	NO
2020 [24]	3P3W	UPQC-S	Instantaneous pq theory with LCO-FLL	Instantaneous pq theory with LCO-FLL	-	20% Voltage sag/swell - 5th and 7th Harmonic	- Nonlinear load - Unbalanced load	YES
This work	3P3W	UPQC-S	UVTG with variable PAC	Instantaneous pq theory with SWFA filtering	-	20%Voltage sag/swell - 5th and 7th harmonic	- Nonlinear load - Load change	YES

2. Structure of the Studied Unified Power Quality Conditioner System

As illustrated in Figure 1, a UPQC consists of a series APF and a shunt APF. The APFs are connected back-to-back through a common DC voltage link. The series APF is used to mitigate load voltage problems such as voltage sag, voltage swell, and harmonic voltages

on the supply utility, whereas the shunt APF is used to compensate for the distorted current due to nonlinear load.

This study focused exclusively on the harmonic identification and reference signal generation of the UPQC in the balanced three-phase three-wire system. To avoid the performance factor of the UPQC control, the ideal voltage sources and the ideal current sources were used as the series APF and the shunt APF, respectively. Hence, the capacitor and DC bus voltage control were excluded. The UPQC topology and the considered power system are presented in Figure 2. In this configuration, the reference compensating currents ($i_{sh,abc}^*$) and the reference compensating voltages ($v_{se,abc}^*$) are injected by the ideal sources. Therefore, the generated reference signals can be taken directly as the compensating signals of the UPQC. It should be noted that the line impedances between the supply and the point of common coupling (PCC) were negligible in the system studied. Therefore, the source voltage (v_s) was assumed to be the same as the PCC voltage (v_{pcc}).

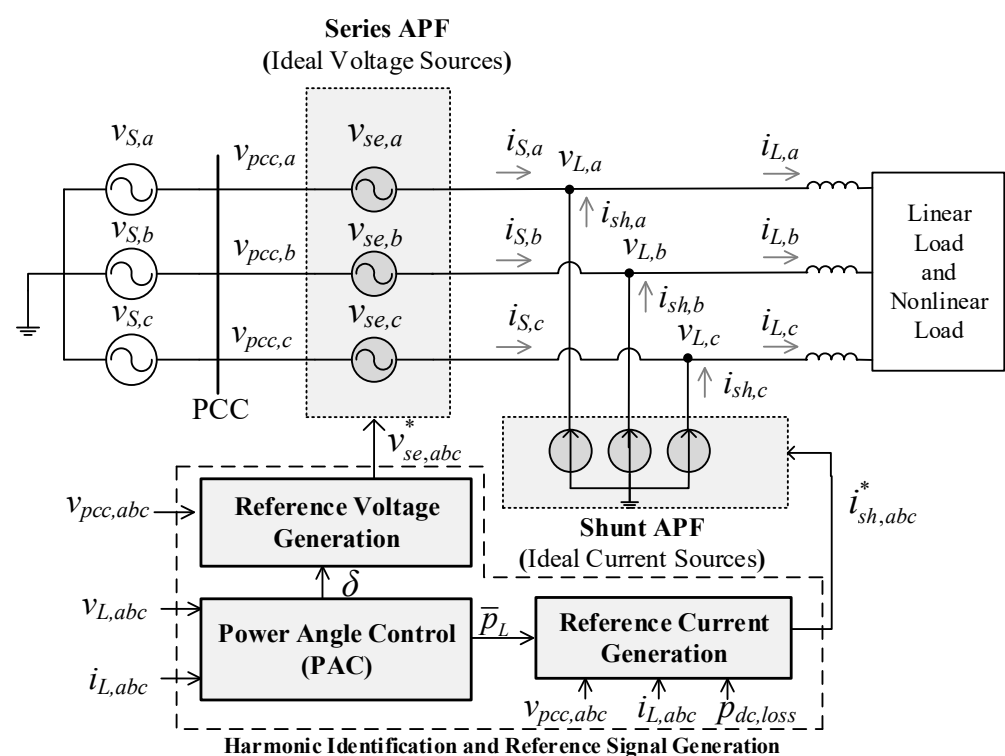


Figure 2. UPQC system with ideal current and voltage sources.

3. Harmonic Identification and Reference Signal Generation

The harmonic identification and the reference signal generation of the UPQC consist of three main processes, including the calculation of the power angle (δ) using the variable PAC method, the calculation of the $v_{se,abc}^*$ and the calculation of the $i_{sh,abc}^*$. The first process is the power angle calculation. This process determines the sharing of the load reactive power (q_L) compensation between the series APF and the shunt APF. The second process is the reference compensating voltage calculation. This process generates the $v_{se,abc}^*$. The third process is the reference compensating current calculation. This process generates the $i_{sh,abc}^*$. The overall procedure is shown in Figure 3.

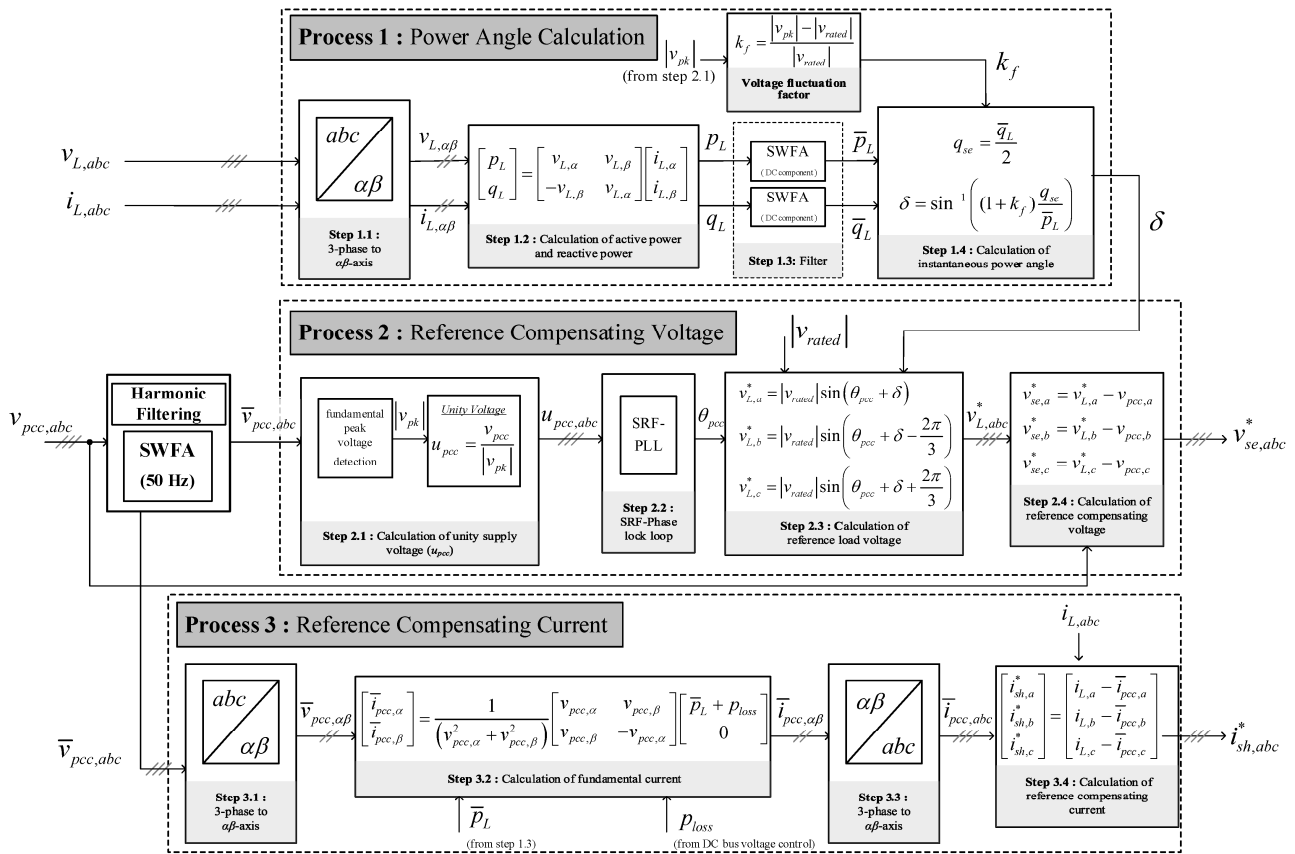


Figure 3. Procedure of the proposed harmonic identification and the reference signal generation of the UPQC system.

3.1. Variable Power Angle Calculation

Power angle control (PAC) was introduced by V. Khadkikar in 2008, cooperating with the apparent power approach of UPQC (UPQC-S). Refs. [16,17] explained PAC with normal supply and sag/swell supply, respectively. The main advantage of PAC over other approaches is that the load reactive power (q_L) can be compensated by both series and shunt APFs. This feature reduces the shunt APF rating needed to compensate for reactive power demand and increases the utilization rate of the series APF.

Process 1 in Figure 3 shows the calculation of the power angle (δ), which enforces the sharing of q_L between the two APFs. The details of this process are as follows:

Step 1: Transform three-phase load voltages ($v_{L,abc}$) and currents ($i_{L,abc}$) into the $\alpha\beta$ -axis using the power-invariant Clarke transform.

Step 2: Calculate the load active power (p_L) and load reactive power (q_L) in $\alpha\beta$ -axis.

Step 3: Filter out any harmonic component in the load power using SWFA. This step extracts the DC component to obtain fundamental instantaneous powers (\bar{p}_L, \bar{q}_L).

In the original PAC [16], low pass filters (LPF) are needed to eliminate the harmonic or AC components of load-active and load-reactive powers (\tilde{p}_L, \tilde{q}_L). However, an optimal cut-off frequency (f_c) of LPF must be determined. Moreover, LPFs cannot perfectly filter out the harmonic contents, leading to inaccurate instantaneous fundamental load-active and load-reactive powers (\bar{p}_L, \bar{q}_L). This could affect the reference signal generation. Therefore, LPFs are replaced by SWFA filters for DC components, as proposed in [33].

Step 4: Calculate reactive power compensation for series APF (q_{se}) and its corresponding power angle (δ). The method used for the determination of the δ is called variable PAC [18]. This method results in a constant sharing of reactive power compensation during

voltage sag/swell by considering the voltage supply condition. The voltage fluctuation factor (k_f) can be calculated using (1).

$$k_f = \frac{|v_{pk}| - |v_{rated}|}{|v_{rated}|} \quad (1)$$

where $|v_{rated}|$ represents the magnitude of the rated value of the desired load voltage and $|v_{pk}|$ represents the magnitude of the supply voltage, which is obtained from step 2.1 of process 2 in Figure 3.

3.2. Sliding Window with Fourier Analysis Filter

Sliding window with Fourier analysis (SWFA) is a filtering method [30]. The signal values at every sampling time in one period are utilized for the computation. Considering the Euler–Fourier formula of a signal $f(kT_s)$ in (2), it consists of a DC component term and an AC component term. To extract a signal at the fundamental frequency from the $v_{pcc,abc}$, only the AC component at the first order ($h = 1$) is considered. Therefore, (2) can be rearranged to (3), where the coefficients A_1 and B_1 are determined as shown in (4) and (5), respectively.

$$f(kT_s) = \frac{A_0}{2} + \sum_{h=1}^{\infty} [A_h \cos(h\omega kT_s) + B_h \sin(h\omega kT_s)] \quad (2)$$

where $h = 1, 2, 3, \dots$

$$f(kT_s) = A_1 \cos(\omega kT_s) + B_1 \sin(\omega kT_s) \quad (3)$$

$$A_1 = \frac{2}{N} \sum_{n=N_0}^{N_0+N-1} f(nT_s) \cos(n\omega T_s) \quad (4)$$

$$B_1 = \frac{2}{N} \sum_{n=N_0}^{N_0+N-1} f(nT_s) \sin(n\omega T_s) \quad (5)$$

where T_s is the sampling time in seconds.

ω is the fundamental angular frequency in rad/s.

N is the number of data points in one period.

n is the index of the data point.

The computation process of a SWFA filter is as follows:

Firstly, receive the data of the considered signal during the first period of N data points and compute the initial A_1 and B_1 coefficients using (4) and (5), respectively. In this step, the data point indices are considered as $n = N_0, N_0 + 1, \dots, N_0 + N - 1$.

Then, compute a new value of A_1 and B_1 coefficients (A_1^{new} , B_1^{new}) using (6) and (7), respectively. A_1^{old} and B_1^{old} denote the coefficient calculated in the previous step. In this step, the first or old data point ($n = N_0$) collected in the first step is removed from the data set, and its index now becomes $n = N_0 - 1$. Then, a new data point ($n = N_0 + N$) is added to the dataset, where its index becomes $n = N_0 + N - 1$ for the coefficient calculations.

$$A_1^{new} = A_1^{old} + \frac{2}{N} f\{(N_0 + N)T_s\} \cdot \cos\{(N_0 + N)\omega T_s\} - \frac{2}{N} f\{(N_0 - 1)T_s\} \cdot \cos\{(N_0 - 1)\omega T_s\} \quad (6)$$

$$B_1^{new} = B_1^{old} + \frac{2}{N} f\{(N_0 + N)T_s\} \cdot \sin\{(N_0 + N)\omega T_s\} - \frac{2}{N} f\{(N_0 - 1)T_s\} \cdot \sin\{(N_0 - 1)\omega T_s\} \quad (7)$$

After that, compute $f(kT_s)$ with A_1^{new} and B_1^{new} using (3) and repeat the SWFA process for the derivation of the new $f(kT_s)$ with the next data point. The calculation mechanism of the coefficients is illustrated in Figure 4.

The SWFA filter for $h = 1$ (50 Hz in the studied power system) is implemented to extract fundamental source voltages at the point of common coupling ($\bar{v}_{pcc,abc}$), which are utilized for the generation of reference signals explained in Sections 3.3 and 3.4.

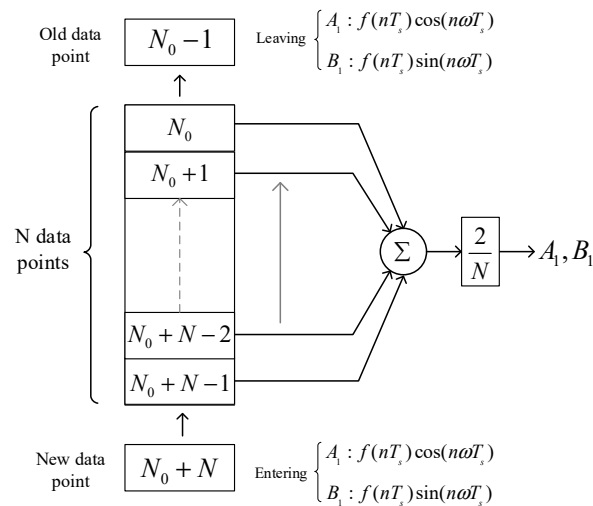


Figure 4. Computation of A_1 and B_1 coefficients.

3.3. Reference Voltage Signal Generation for Series Active Power Filter

In this process, unit vector template generation (UVTG) is implemented due to its simplicity and fast processing time. In addition, a synchronous reference frame phase-locked loop (SRF-PLL) is required for this approach to synchronize the system. The details of this process are as follows:

Step 1: Calculate the unit vector signals ($u_{pcc,abc}$) of the source voltages by dividing the \bar{v}_{pcc} by its peak value. These peak values are obtained by multiplying the RMS value by $\sqrt{2}$, where the RMS values are determined using the moving RMS method.

Step 2: Extract the phase angle (θ_{pcc}) of the unit vector signals using SRF-PLL.

Step 3: Calculate the three-phase reference load voltages ($v_{L,abc}^*$) cooperating the θ_{pcc} and the δ of the previous process.

Step 4: Compare $v_{L,abc}^*$ with $v_{pcc,abc}$ to generate the $v_{se,abc}^*$.

3.4. Reference Current Signal Generation for Shunt Active Power Filter

An indirect control based on the instantaneous pq theory approach is utilized in Process 3 to produce the reference current signals ($i_{sh,abc}^*$).

Step 1: Transform $\bar{v}_{pcc,abc}$ into $\alpha\beta$ -axis using the power-invariant Clarke transformation.

Step 2: Calculate the fundamental currents (\bar{i}_{pcc}) in the $\alpha\beta$ -axis with the use of \bar{p}_L calculated in Process 1.

Step 3: Transform $\bar{i}_{pcc,\alpha}$ and $\bar{i}_{pcc,\beta}$ into the abc -frame to obtain the fundamental currents in a three-phase system ($\bar{i}_{pcc,abc}$) using the inverse Clarke transformation.

Step 4: Compare $\bar{i}_{pcc,abc}$ with the load currents to produce the $i_{sh,abc}^*$.

4. Processor-in-the-Loop (PIL) Simulation

In this section, the proposed harmonic identification with the power system under different test scenarios was implemented to verify the feasibility and the performance of the proposed harmonic identification and reference signal generation of UPQC.

4.1. Processor-in-the-Loop Setup

The PIL simulation model was developed using MATLAB/Simulink R2018a and the eZdsp™ F28335 board to validate the performance of the proposed algorithm of a UPQC with the SWFA filters under linear and nonlinear loads. To record the data, a discrete time domain was implemented at the sampling time of 32 μ s. Figure 5 demonstrates the implementation of PIL. The 'ReferenceSignalGeneration' block is computed by the eZdsp™ F28335 board. This block comprises the three UPQC processes, as shown in Figure 6, while the balanced three-phase, three-wire system is executed by MATLAB/Simulink on the host

computer. The board is connected to a host computer via a USB port. The parameters of the simulation model are specified in Table 2.

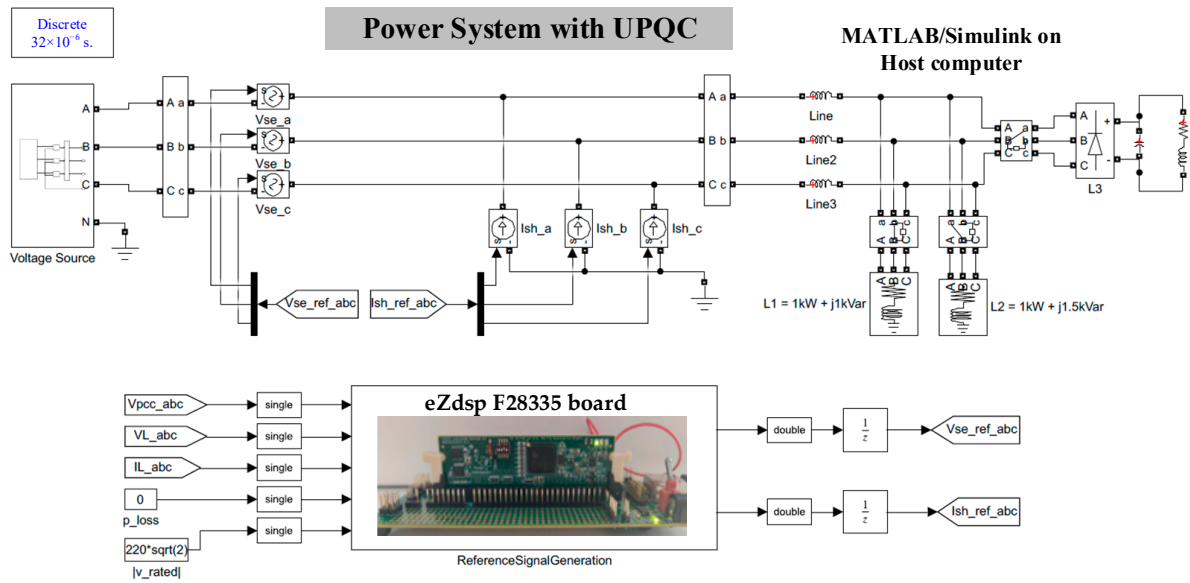


Figure 5. The proposed UPQC model with the eZdsp™ F28335 board.

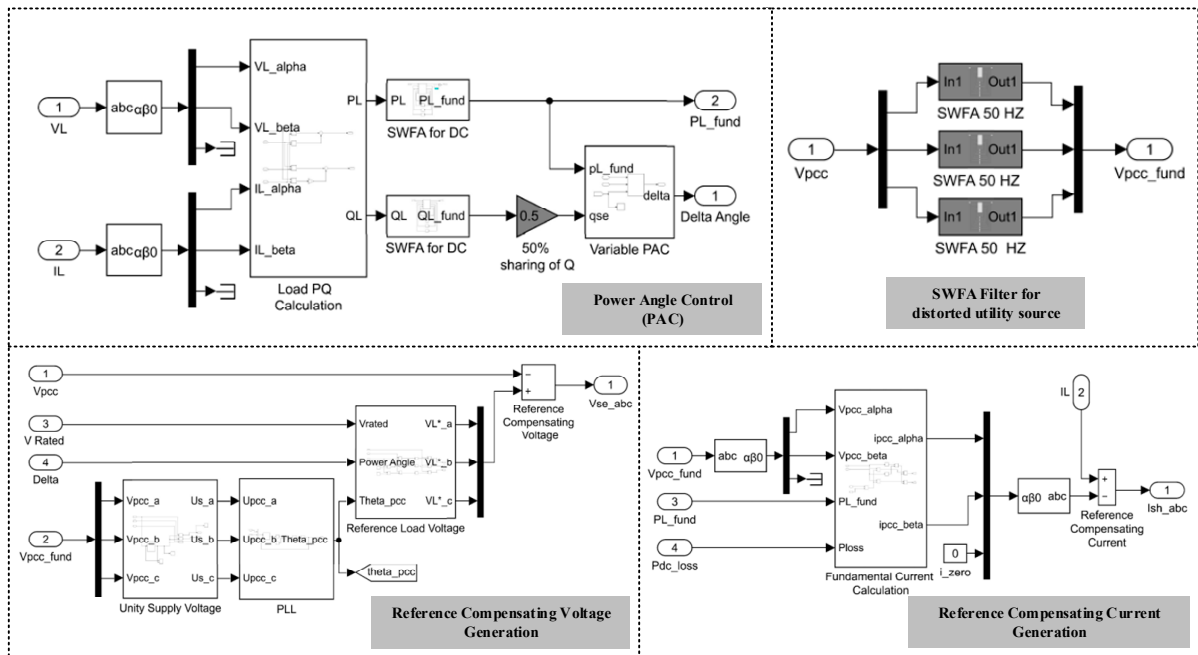


Figure 6. MATLAB/Simulink model of the proposed harmonic identification and the reference signal generation.

Table 2. System parameters for the simulation model.

Parameters	Value
Supply Voltage Frequency	$v_s = 380 \text{ V}_{L-L}, f_s = 50 \text{ Hz}$
Line Impedance	$L_L = 10 \text{ mH}$
Linear Loads (L1, L2)	$S_{L1} = 1 \text{ kW} + j1 \text{ kVar}, S_{L2} = 1 \text{ kW} + j1.5 \text{ kVar}$
Nonlinear Load (L3)	Diode Bridge Rectifier with $R_{L3} = 160 \Omega, L_{L3} = 0.5 \text{ H}, C_{L3} = 40 \mu\text{F}$
Series APF	Ideal voltage sources
Shunt APF	Ideal current sources

4.2. Test Scenarios

The simulation was divided according to the situations shown in Table 3. At $t = 0$ s, an ideal three-phase balanced supply was connected to a load system consisting of linear load (L1). At $t = 0.1$ s, the UPQC was then ON. This step was carried out to verify that the UPQC system operated successfully during ideal waveforms of current and voltage. Subsequently, disturbances, including load changes, voltage sag, voltage swell, and harmonics of the supply, were introduced individually.

The details of each disturbance are as follows:

- Load Change—two stages of load changes. Firstly, an increase in the reactive power demand by switching to load (L2). Secondly, a nonlinear load (L3) was connected, resulting in a 25.3%THD of the load current.
- Voltage Sag—a decrease in supply voltage magnitude by 20%.
- Voltage Swell—an increase in supply voltage magnitude by 20%.
- Harmonic Voltage—20V of the 5th harmonics and 20V of the 7th harmonics are added to the source voltage, resulting in a 9.09%THD of the source voltage.

Table 3. Simulation time and situations of the system.

Time (s)	Situations
0–0.1	Normal supply system connected to Load L1
0.1–0.3	Shunt and Series APFs ON
0.3–0.5	Switch to Load L2 (L1 disconnected)
0.5–0.7	Nonlinear Load L3 added (Load = L2 + L3)
0.7–0.9	20% Voltage Sag
0.9–1.1	20% Voltage Swell
1.1–1.3	Harmonic Voltage

4.3. Performance Evaluation

The RMS values and the percent of total harmonic distortion (%THD) of the source current and the load voltage were used as performance evaluation metrics. The Fast Fourier Transform (FFT) analysis was applied to obtain the peak values of the signals at each harmonic order. These peak values are then converted to RMS values to calculate the corresponding %THD.

According to the IEEE519-2022 standard, the percent of total harmonic voltage distortion (%THD_v) of a low voltage system (<1.0 kV) limit is 8.0%, and the percent of total harmonic current distortion (%THD_i) should not exceed 5.0%. The voltage fluctuation range is normally between 0.95 pu and 1.05 pu, as specified by ANSI C84.1-2016. Therefore, the RMS value of the voltage supply in a 220 V supply system should be kept in the range of 209–231 V.

5. Results and Discussion

As the simulation study was conducted with a balanced three-phase, three-wire system, the simulation results of only one phase (i.e., phase a) are illustrated in this section.

5.1. Filter Performance

To mitigate the effects of harmonic voltage (1.1–1.3 s), a filter was placed before the voltage reference and current reference processes, as explained in Section 3. The performance of the proposed SWFA filtering was compared with an LPF. A suitable cut-off frequency (f_c) of the LPF had to be determined. As the supply voltage had the 5th and 7th harmonic components, the f_c of under 250 Hz were experimented to determine the most suitable value of f_c . The %THD_v and RMS values of the filtered signals ($\bar{v}_{pcc,abc}$) were measured. It was found that LPF reduced both the %THD_v and RMS values of the $\bar{v}_{pcc,abc}$ when f_c decreased, as shown in Table 4. In compliance with the IEEE519-2022 and ANSI

C84.1-2016 standards, a cut-off frequency of 160 Hz was chosen because the $\%THD_v$ of the filtered signal was minimal while staying within the RMS limit of the normal supply range.

Table 4. LPF performance at different cut-off frequencies.

f_c	v_{RMS}	$\%THD_v$
140	207.54	4.23
160	210.29	4.64
180	212.27	5.01
200	213.69	5.35
220	214.75	5.67
240	215.60	5.95

Considering only the filter performance, the $\%THD_v$ of the signal filtered by LPF ($f_c = 160$ Hz) is equal to 4.64% and the RMS value is equal to 210.29 V. In comparison with the SWFA, the $\%THD_v$ is equal to 0% and the RMS value is equal to 220.76 V.

Figure 7 shows the waveforms of the $v_{pcc,a}$ before and after the filtering process. The $v_{pcc,a}$ waveforms from the LPF and the SWFA filtering were compared with the reference signal. Considering the transient response of the filters, the LPF signal reached the steady state immediately in the first cycle with a slight phase shift compared to the reference signal. In contrast, the SWFA filter required one period (0.02 s) of computation to reach a steady state. The resulting signal matched perfectly with the reference signal without any phase shift. Furthermore, the selection of f_c is not required by the SWFA approach. The harmonic content of $v_{pcc,a}$ before and after the filtering process are shown in Figure 8. Both the fifth and seventh harmonic components still appeared after the LPF process, even though their magnitudes decreased. In comparison, all harmonic components were eliminated after the SWFA process. Furthermore, the magnitude of the fundamental component remained the same as the fundamental component of the input $v_{pcc,a}$.

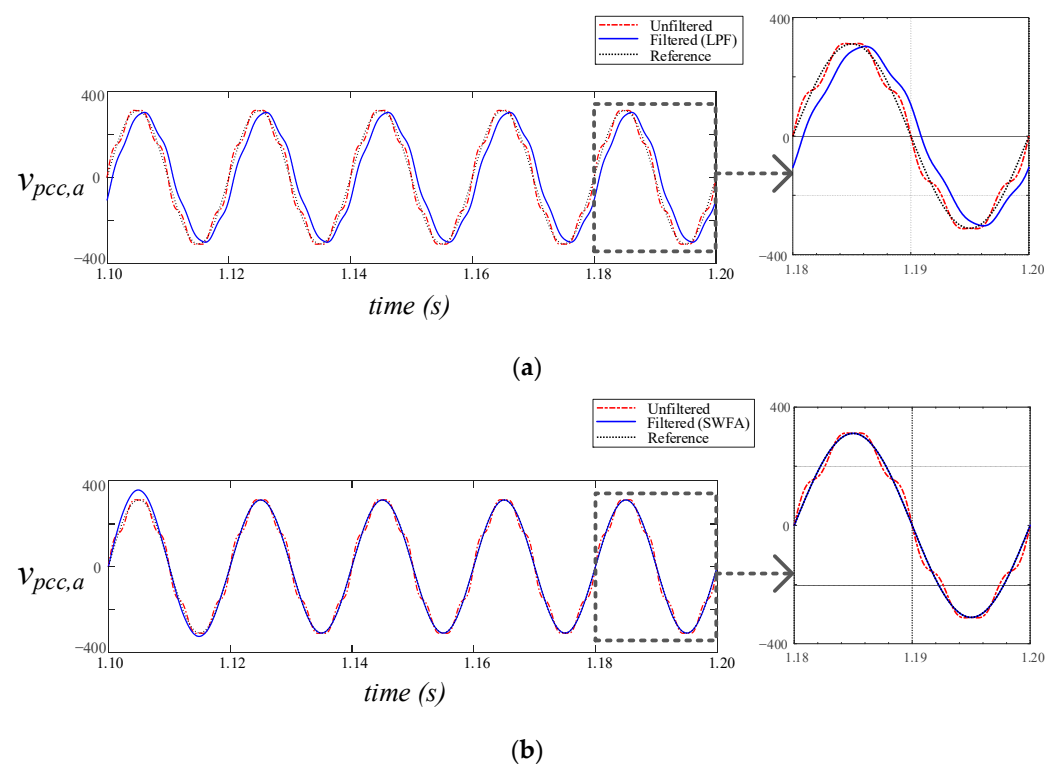


Figure 7. Waveforms of $v_{pcc,a}$ in the filtering process. (a) LPF (b) SWFA.

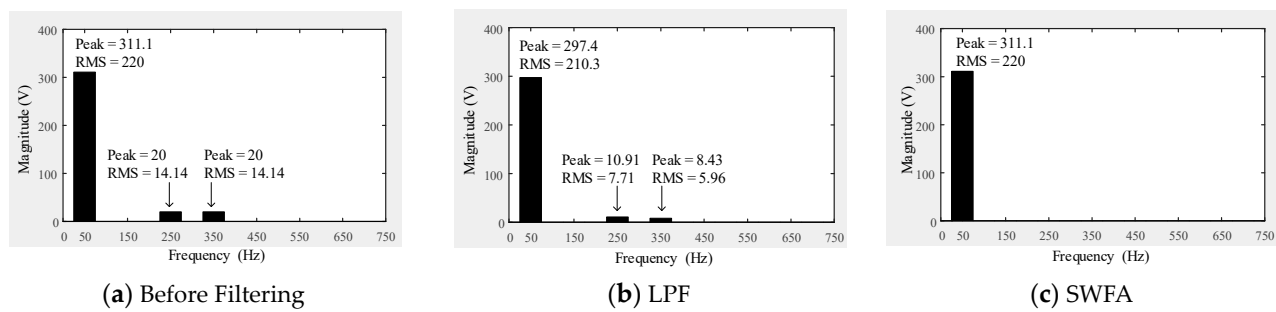


Figure 8. Harmonic Spectrum of the signal (a) before filtering and after being filtered by (b) LPF and (c) SWFA.

The results suggested that the utilization of SWFA for the reference signal generation should lead to a better performance of UPQC under the harmonic voltage.

5.2. Unified Power Quality Conditioner Performance

The simulation results of the UPQC performance between the use of LPF, SWFA, and without filter in the reference signal generation are shown in Tables 5 and 6. Table 5 shows the %THD_v and RMS values of the load voltage (v_L), and Table 6 shows the %THD_i and RMS values of the source current (i_S). These tables compared the %THD and RMS values of the signals in different situations, including the load changes and the supply disturbances. Moreover, the comparison of UPQC performance between three approaches of filtering (no filter, LPF, and SWFA) is presented in these tables.

Table 5. Performance of UPQC considering load voltage waveform.

Case	Index	Load/Supply Situation					
		Normal Voltage		Normal Voltage	Voltage Sag	Voltage Swell	Harmonic Voltage
		L1	L2	L2 and L3			
Before Compensation	%THD _v	0.00	0.00	0.00	0.00	0.00	9.09
	RMS	220	220	220	176	264	220
After Compensation	Without Filter [16]	%THD _v	0.00	0.00	0.00	0.00	3.67
		RMS	221.1	221.6	220.9	220.6	220.7
	LPF ($f_c = 160$ Hz)	%THD _v	0.02	0.05	0.00	0.00	1.67
		RMS	220.4	221.1	220.2	220	220.90
With SWFA	%THD _v	0.03	0.04	0.00	0.01	0.00	0.55
	RMS	221.1	221.6	220.9	220.5	221.3	220.9

Table 6. Performance of UPQC considering source current waveform and power factor.

Case	Index	Load/Supply Situation					
		Normal Voltage		Normal Voltage	Voltage Sag	Voltage Swell	Harmonic Voltage
		L1	L2	L2 and L3			
Before Compensation	%THD _i	0.00	0.00	25.31	25.31	25.31	22.16
	RMS	2.15	2.69	4.76	3.81	5.71	4.75
After Compensation	Power Factor	0.709	0.556	0.760	0.760	0.760	0.758
	Without Filter [16]	%THD _i	0.00	0.07	1.91	1.53	9.59
		RMS	1.55	1.52	3.77	4.70	3.77
	LPF ($f_c = 160$ Hz)	%THD _i	0.00	0.05	1.83	1.47	4.78
		RMS	1.61	1.58	3.92	4.89	3.93
	With SWFA	%THD _i	0.00	0.07	1.91	1.53	1.93
		RMS	1.55	1.52	3.77	4.70	3.76
Power Factor		1.00	0.999	0.999	0.999	0.999	0.996

In the process of reference voltage signal generation for series APF, peak voltage detection using the moving RMS method is performed. For the first period, this method requires the data in one period (0.02 s) to calculate the magnitude of v_{pcc} . Then, the peak value is updated at every sampling time. The performance of the moving RMS method for the magnitude detection of $v_{pcc,a}$ is shown in Figure 9a.

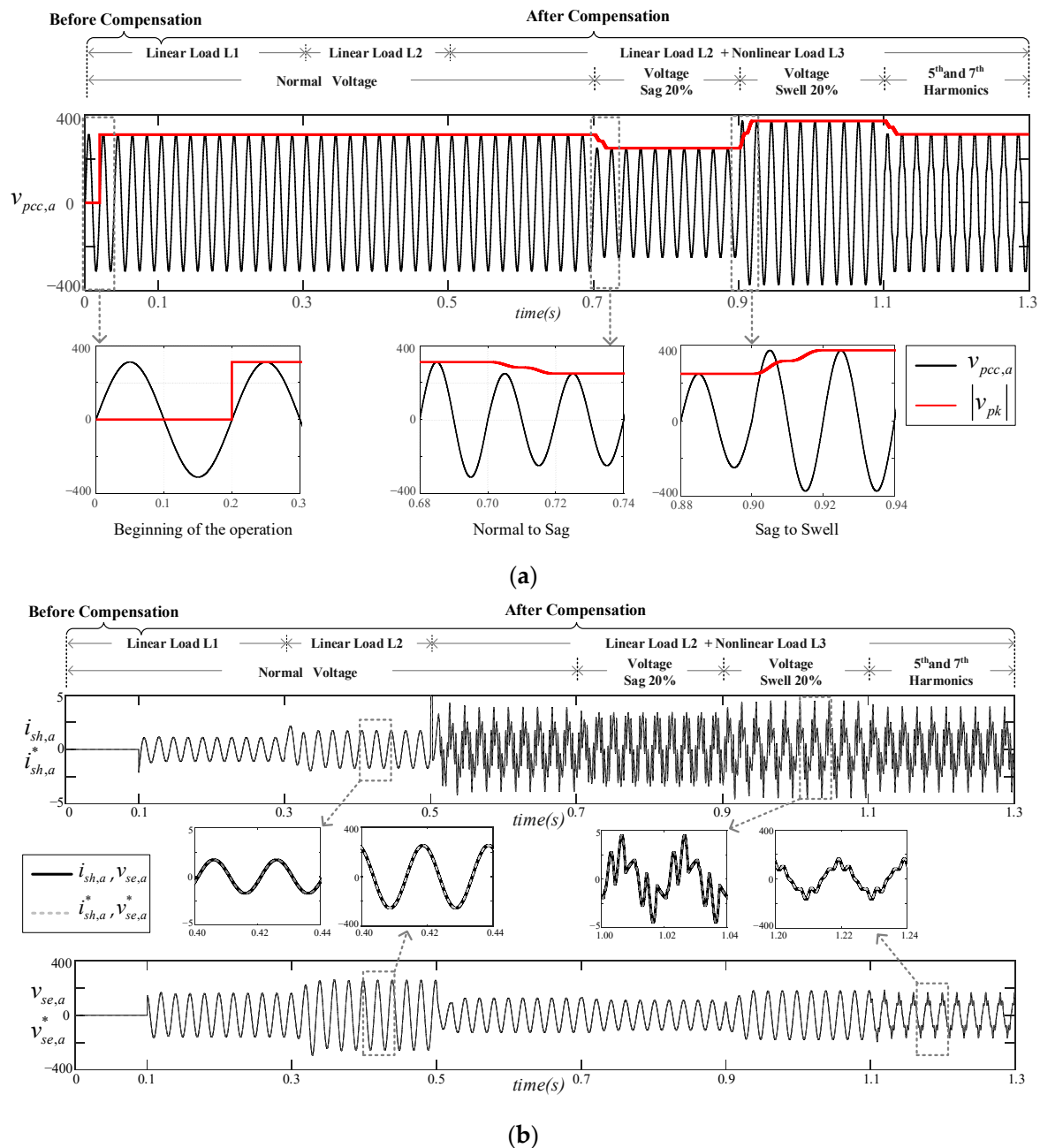


Figure 9. The performance of moving RMS method and the tracking performance of the compensating values. (a) The magnitude detection of $v_{pcc,a}$. (b) The actual compensating signal and the reference compensating signal.

To ensure that the compensation of v_L and i_S was conducted correctly, the actual compensating signal and the reference compensating signal were compared. As seen in Figure 9b, $i_{sh,a}$ and $v_{se,a}$ were identical with $i_{sh,a}^*$ and $v_{se,a}^*$, respectively. This conformed with the use of ideal current sources and ideal voltage sources as the shunt APF and the series APF.

During normal, sag, and swell supply, the three filtering methods resulted in a similar performance of i_S and v_L compensation. However, the harmonic voltage source resulted in the different %THD_i levels of i_S in which the SWFA significantly outperformed the other options. Therefore, the waveform performances of UPQC presented in this section are only the simulation results with the SWFA integration.

5.2.1. Load Changes

During $t = 0.1$ to 0.7 s, the loads were varied to demonstrate the behavior of the UPQC compensation when there was a change in linear load by increasing reactive power demand and an addition of a nonlinear load under normal supply conditions. It can be seen in Figure 10 that the voltage across the load (v_L) maintained a pure sine waveform with a relatively constant RMS value. At $t = 0.5$ s, a nonlinear load (L2 and L3) was connected, resulting in an increase in the load active power and a harmonic load current of 25.31%. The i_S was increased as expected to supply the increase of p_L . UPQC successfully compensated the harmonic content, reducing the %THD_i to 1.91%.

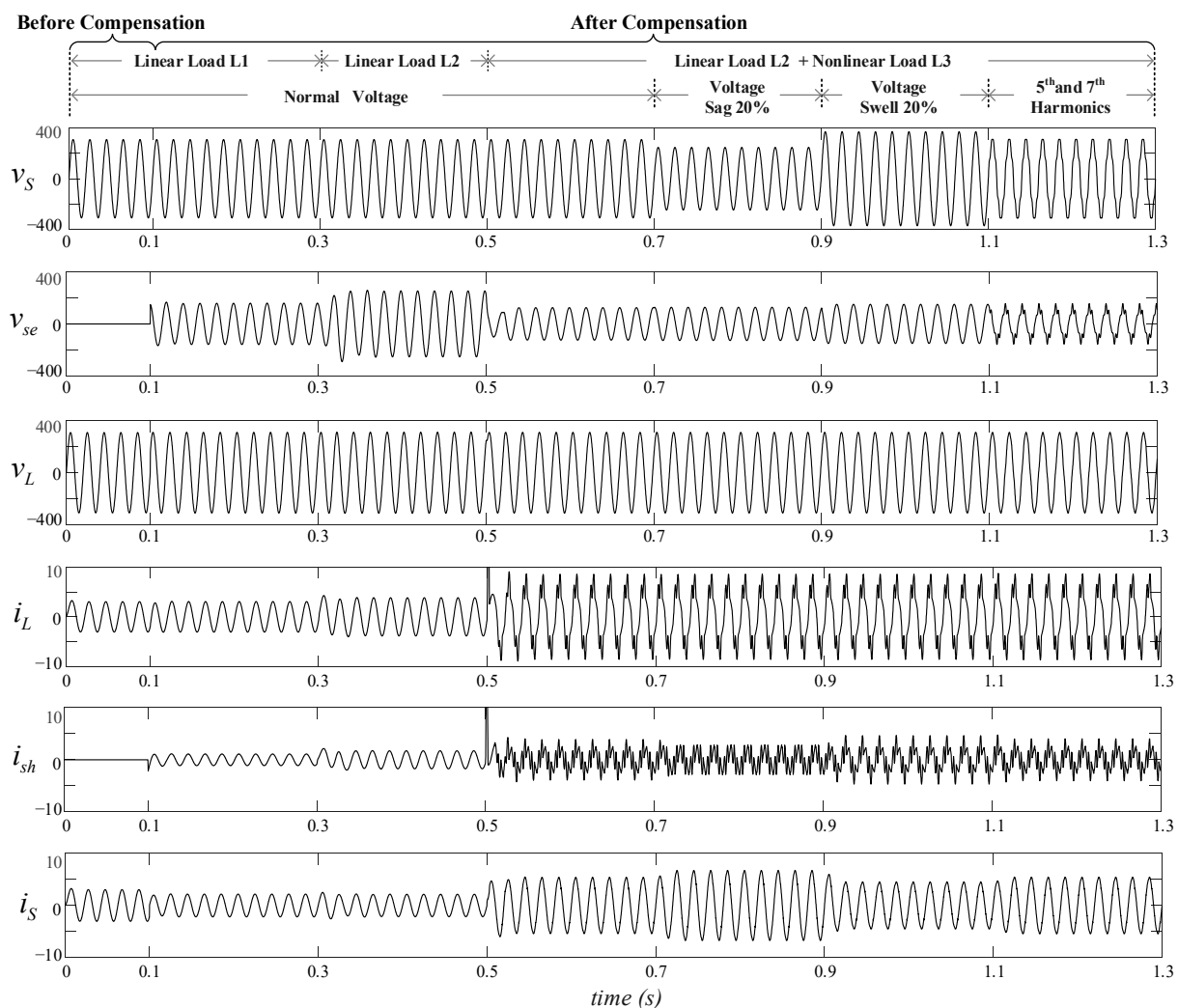


Figure 10. Voltage and current waveforms of phase a during different test scenarios.

5.2.2. Supply Disturbances

After $t = 0.7$ s, the load was fixed as a combination of L2 and L3, while supply conditions were varied, as stated in Table 3. During voltage sag and voltage swell conditions, the RMS values of v_L could be maintained close to the nominal value of 220 V while keeping the pure sine waveform. The i_S was adjusted to supply the load active power, where i_S

increased during the voltage sag and decreased during the voltage swell, and the $\%THD_i$ was kept to 1.53% and 2.29%, respectively. At $t = 1.1\text{--}1.3\text{ s}$, the harmonic supply condition was introduced, the $\%THD_v$ of v_L was decreased from 9.09% to 0.55% and the $\%THD_i$ of i_S was reduced to 1.93%. The waveforms of these signals are illustrated in Figure 10. The $\%THD$ and RMS values presented in Tables 5 and 6 were within the IEEE standard limits.

It can be concluded that the proposed harmonic identification and reference signal generation of the UPQC system with the SWFA filters responded successfully under different operating conditions of supply and loads.

5.3. Power Flow Analysis

This section reported the active power and reactive power flow of the studied system, including the source side, load side, and the series and shunt APFs of the UPQC. It should be noted that the harmonic supply could be considered as a small voltage swell in the power flow analysis.

5.3.1. Active Power

Typically, the series and shunt APFs provide the active power for the compensation of voltage sag, voltage swell, and any losses associated with transmission lines, DC link, and active power filter operation. However, in this study, only the transmission line losses were accounted for, as the ideal sources were used as the APFs, and the DC link was not included in the system. During the normal supply $t = 0.1\text{--}0.7\text{ s}$, the active power of the series APF and shunt APF in the UPQC system were only responsible for compensating the power losses in the transmission lines.

However, during voltage sag ($t = 0.7\text{--}0.9\text{ s}$), the series APF injected additional p_{se} to maintain the level of v_L ; therefore, the shunt APF drew an equal amount of active power p_{sh} from the system to maintain the operation of the UPQC. In comparison, during voltage swell, the active power was absorbed from the system by the series APF to maintain the level of v_L while the shunt APF injected an equal amount of active power p_{sh} back into the system to maintain the operation of the UPQC. The power flow of active power is shown in Figure 11.

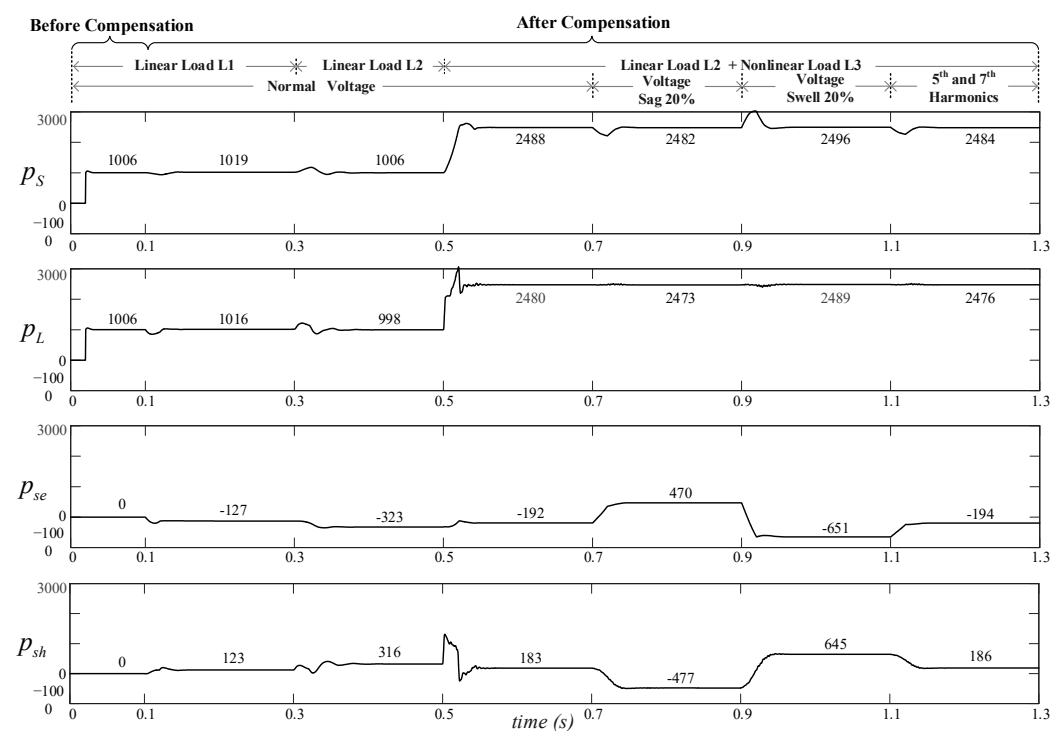


Figure 11. Active power flow of the UPQC system during different test scenarios.

5.3.2. Reactive Power

Apart from the current and voltage compensations, the other main characteristic of UPQC operation is the power factor correction. It can be seen in Figures 11 and 12 that after the UPQC is operating at $t = 0.1$ s, the distribution system only supplied the active power to the load as the reactive power of the supply became close to zero as the two APFs were responsible for the reactive power compensation in all scenarios. As shown in Table 6, the power factor of the worst case was improved from 0.556 to 0.999 after the compensation. This power factor correction achieved a value close to 1 in every test scenario.

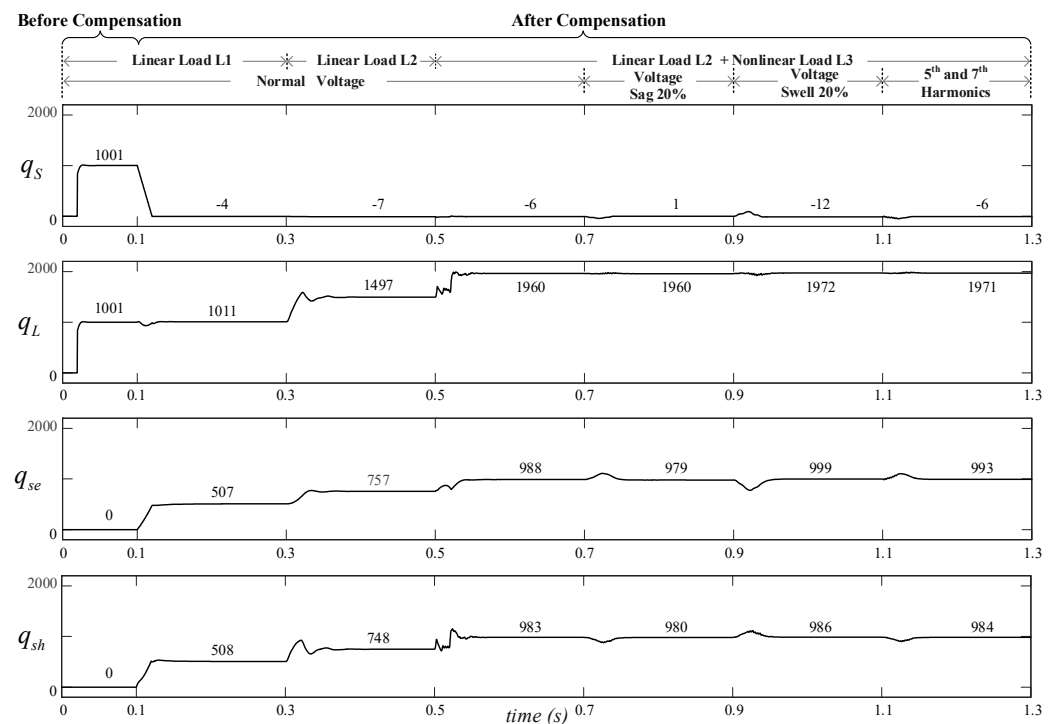


Figure 12. Reactive power flow of the UPQC system during different test scenarios.

As the proposed method cooperated with the UPQC-S system with the PAC approach, the simulation results confirmed that the series APF shared the reactive power compensation burden from the shunt APF. It can be observed that half of the reactive power is compensated by the series APF, as the proposed model was designed for a 50% sharing of reactive power demand compensation between the two APFs. Moreover, the variable PAC approach automatically adjusts the power angle and its corresponding reactive power compensation during the disturbances of the source voltage. As illustrated in Figure 12 at $t = 0.7$ – 1.3 s, the reactive power provided by both APFs remains relatively constant. It can be observed that in any condition, the sum of the reactive power supplied by the two APFs is always equal to the reactive power demand. The feature of applying the variable PAC approach is for better management and installation of the UPQC, where the rating of the shunt APF and the series APF can be the same and also have a high utilization rate.

6. Conclusions

In this work, harmonic identification and reference signal generation, which is an important process for power quality improvement using the UPQC, are intensively studied. A modified harmonic identification based on SWFA with the utilization of instantaneous pq theory, variable PAC, and UVGT is proposed to mitigate the power quality problems, including voltage sag, voltage swell, harmonic supply voltage, and harmonic current due to nonlinear loads. The utilization of SWFA can notably suppress the effect of the distorted utility source in three-phase, three-wire systems. Additionally, the performance

comparison of the proposed SWFA and LPF showed that SWFA could accurately extract the fundamental component of the supply voltage after one time period of the signal. The performance verification of the modified harmonic identification is performed based on the PIL technique. The proposed algorithm was implemented on an eZdsp™ F28335 board and the MATLAB/Simulink program. During the harmonic supply voltage, the THD of the source current was reduced from 22.16% to 1.93% when SWFA was implemented. This performance is superior to the compensation without any filter and with LPF, which reduced the THD to 9.59% and 4.78%, respectively. Moreover, the use of SWFA provides a less complex calculation and requires a smaller number of filters compared to the method in the existing literature. The testing results confirm that the total harmonic distortion and RMS values were maintained within the IEEE519-2022 and ANSI C84.1-2016 standards. The power flow analysis also showed that the load reactive power compensation was shared by a series of APFs as the PAC method was implemented. This resulted in an equal rating of the UPQC, which may lessen the burden on the UPQC installation and cost.

Author Contributions: Conceptualization, P.S. and K.A.; methodology, K.C.; software, K.C.; validation, P.S., K.C. and K.A.; formal analysis, P.S.; investigation, P.S. and K.A.; resources, P.S. and K.A.; data curation, K.C.; writing—original draft preparation, P.S. and K.C.; writing—review and editing, K.A.; visualization, K.C.; supervision, P.S.; project administration, P.S.; funding acquisition, P.S. All authors have read and agreed to the published version of the manuscript.

Funding: This research was supported by the National Science Research and Innovation Fund (NSRF) and the Prince of Songkla University (Grant No ENG6601105S).

Data Availability Statement: No new data were created.

Conflicts of Interest: The authors declare no conflicts of interest.

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