



Article

Predictive Modeling Approach for Surface Water Quality: Development and Comparison of Machine Learning Models

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Abstract: Water pollution is an increasing global issue that societies are facing and is threating human health, ecosystem functions and agriculture production. The distinguished features of artificial intelligence (AI) based modeling can deliver a deep insight pertaining to rising water quality concerns. The current study investigates the predictive performance of gene expression programming (GEP), artificial neural network (ANN) and linear regression model (LRM) for modeling monthly total dissolved solids (TDS) and specific conductivity (EC) in the upper Indus River at two outlet stations. In total, 30 years of historical water quality data, comprising 360 TDS and EC monthly records, were used for models training and testing. Based on a significant correlation, the TDS and EC modeling were correlated with seven input parameters. Results were evaluated using various performance measure indicators, error assessment and external criteria. The simulated outcome of the models indicated a strong association with actual data where the correlation coefficient above 0.9 was observed for both TDS and EC. Both the GEP and ANN models remained the reliable techniques in predicting TDS and EC. The formulated GEP mathematical equations depict its novelty as compared to ANN and LRM. The results of sensitivity analysis indicated the increasing trend of input variables affecting TDS as HCO_3^- (22.33%) > Cl^- (21.66%) > Mg^{2+} (16.98%) > Na^+ (14.55%) > Ca^{2+} (12.92%) > SO_4^{2-} (11.55%) > pH (0%), while, in the case of EC, it followed the trend as HCO_3^{-} $(42.36\%) > SO_4^{2-}(25.63\%) > Ca^{2+}(13.59\%) > Cl^-(12.8\%) > Na^+(5.01\%) > pH(0.61\%) > Mg^{2+}(0\%).$ The parametric analysis revealed that models have incorporated the effect of all the input parameters in the modeling process. The external assessment criteria confirmed the generalized outcome and robustness of the proposed approaches. Conclusively, the outcomes of this study demonstrated that the formulation of AI based models are cost effective and helpful for river water quality assessment, management and policy making.

Keywords: river water quality; sustainable environment; soft computing; regression analysis; total dissolved solids; specific conductivity; parametric study; variable importance; external validation



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1. Introduction

Surface water is the most sensitive and vulnerable resource since its demand increases with the rise in population. The surface water bodies are abundantly available which fulfill multiple needs such as industrial processes, drinking, irrigation, agricultural production and hydroelectricity generation. The streams, lakes and rivers are the most susceptible to pollution, receiving more waste load from other sources attributed to their dynamic nature and easy accessibility. Major processes responsible for water quality degradation include urban waste water, non-treatment sewage discharge, industrial processes, hazardous substances, diffuse pollution from agricultural lands, climatic processes and anthropogenic

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activities [1–3]. Polluted water is a major issue threatening human health, agriculture and ecosystems [4].

Estimating the processes pertaining to water quality deterioration is becoming a key hurdle in managing pollution of the marine environment [5,6]. The selected variables for water quality assessment are total dissolved solids (TDS) and specific conductivity (EC). Both TDS and EC depend on organic matter and inorganic salts dissolved in water. A variation in TDS or EC level is a sign of source pollution, hence, elevated values of these parameters indicate contamination in water [7,8]. The field monitoring and manual laboratory tests/calculations methods for water quality assessment are labor-intensive and time-consuming [9]. In order to condense the experimental workload for the calculation of water quality parameters, modeling techniques can be the best alternatives. Employing computer aided models for modeling the significant properties of water are helpful in saving time, cost and also making suitable predictions [10,11]. Modeling and estimation in different fields were carried out with typical and conventional computing methods including numerical, and deterministic models. Although, these models have limited capability and are complex in structure (require in depth details). Therefore, leaves a gap to use alternate and advanced modeling approaches [12,13].

The artificial intelligence (AI) techniques encompassing neural network (ANN), random forest (RF), multi-expression programming (MEP), adaptive neuro-fuzzy inferencebased system (ANFIS) and gene expression programming (GEP) remained the reliable methods for valuable predictions and solving complex problems in various engineering domains [9,10,14–24]. The ANN was defined as enormous parallel spread processors containing simple units [25]. The hidden network between the neurons are adjusted in a way to develop and store the information required for modeling the complex systems [19]. Some drawbacks of ANN include unexplained behavior and difficulty in determining the proper network structure. The ANN does not give information regarding the adopted procedure, thus reducing the trust in the network structure [26,27]. The Genetic Programing (GP) was presented as a simplification of genetic algorithm [28]. In gene expression programming (GEP), which is the enhanced form of GP, the formation of genetic diversity is very simplified because the process works at chromosomes level [29]. The linear regression models (LRM) are the oldest and frequently used models across many fields. These are statistical tools that creates a relation between several independent and a single dependent variable [30].

Various researchers used different models for the estimation of water quality parameters. Palani et al. (2008) [16] used ANN to forecast dissolved oxygen (DO), salinity, temperature and chlorophyll-a in Singapore coastal water. The authors reported excellent prediction capability of the ANN model with correlation coefficient ranging from 0.8 to 0.9. Ahmed et al. (2019) [31] used ANFIS, radial bias function and multi-layer perception neural network models along with wavelet data de-noising technique in predicting pH, suspended solids and ammoniacal nitrogen concentration. The authors reported improved performance of the predictive models with data de-noising technique. Marti et al. (2013) [19] used ANN, GEP and regression for DO prediction in sand media filters utilizing 769 data points from experimental results. EC, pH, dissolved oxygen and head loss remained the most effective parameters. The results exposed better estimation of GEP model than other techniques. Granata et al. (2017) [32] predicted total suspended solids (TSS), biochemical oxygen demand (BOD), chemical oxygen demand (COD) and TDS of wastewater in a drainage basin with the help of support vector regression (SVR) and regression tree (RT) models. The authors reported better performance of SVR than RT in predicting the targeted output. The ANN was used by Sarkar et al. (2015) [14] for DO prediction. The authors reported accurate results of ANN with correlation coefficient close to 0.9. Haghiabi et al. (2018) [33] employed SVM, ANN and group method of data handling (GMDH) models in predicting various water quality parameters. The authors demonstrated suitable performance of both ANN and SVM for water quality prediction. Zhang et al. (2019) [34] used hybrid neural network model to predict water treatment plant production capacity. Sustainability **2021**, 13, 7515 3 of 20

The results of the study demonstrated enhanced performance of the model by using a larger dataset.

The AI and machine learning modeling techniques were successfully employed in the aforementioned studies. A literature survey demonstrated that most of the modeling studies rely only on limited duration data and/or limited number of data points. Therefore, a systematic and detailed analysis is needed to consider the behavior of AI and regression-based techniques using a large dataset. Most of the modeling methodologies reported in literature have low and uneven prediction capacity due to the use of inadequate dataset. Moreover, limited research is available that focuses on the use of models that are efficient to provide empirical expressions. Such modeling approaches will ultimately reduce the experimental workload in predicting important water quality variables.

A study conducted by Shah et al. (2021) [8], where ANFIS modeling was applied in predicting the monthly TDS and EC in upper Indus river basin (UIB) measured at Bisham Qilla gauging station. The ANFIS model was coupled with data preprocessing and input optimization routine to remove the outliers and to select the most influential input combination. The authors reported an excellent result of the ANFIS model in TDS and EC prediction. In comparison to the aforementioned study, the present study is mainly devoted to applying AI and regression methods for modeling TDS and EC in the expanded study region. The dataset, simultaneously measured at both Doyian and Bisham Qilla outlets, were utilized for models training and testing. Thereafter, a comparative assessment is conducted in selecting the best model. The employed techniques included artificial neural network (ANN), gene expression programming (GEP) and linear regression model (LRM) utilizing monthly historical data. Models were developed for TDS and EC and performance was assessed by computing statistical indicators. Variable importance and a parametric study were conducted to figure out the influence of modeling inputs on the targeted output. The results of the present study might provide a valuable insight to authorities to devise a strategy for the effective management of river water quality.

2. Material and Methods

2.1. Genetic Base Algorithm

The enhanced variant of genetic programming (GP) was developed by Ferreira, C. [35], which is known as gene expression programming (GEP). A parse tree structure is coded in GEP which overcome the limitations of the GP [36]. Due to multigenic behavior, GEP uses unpretentious criteria for genetic variety formation which enable them to develop nonlinear and complex programs. GEP process is composed of various sets such as parameter set, fitness measure set, function set, criteria set and terminal set. The two main components of GEP are the chromosomes and expression trees (ETs). The ETs are used to express different nonlinear individuals and the genetic information encoded in the chromosomes. ETs are an excellent way to represent an expression in a computer because ET can be easily evaluated as compared to genetic information and equations [37]. A typical example of ET is shown in Figure 1. Furthermore, during the reproduction stage, the genetic operators are commonly used to modify the chromosomes [38,39]. GEP can represent any parse tree because of the capability of producing chromosomes. For such purpose, a new language called Karwa language is used to decode the information in the chromosomes [40,41]. An empirical relationship between the chromosomes and sets can be develop using the expression called Karva notation. The K expression from Karwa notation can be converted into mathematical equations that have the proficiency to forecast the output as a function of input variables and are applicable with high accuracy [21]. For GEP model development, the GeneXpro software tool was used and the GEP modeling parameters are listed in Table 1.

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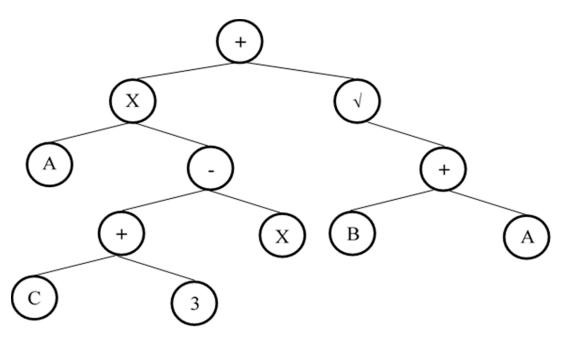


Figure 1. Typical example of expression tree (ET).

Table 1. Best fitted parameters for GEP algorithm run.

Parameter	Setting
Number of Chromosomes	30
Number of Genes	4
Head size	10
Gene size	26
Linking function	Addition
Function set	$+$,-, \times , \div , 2 , 3 \checkmark
Mutation rate	0.0138
Inversion rate	0.00546
Constants per gene	10
Maximum complexity	10
Data type	Floating type
Lower bound	-10
Upper bound	10

2.2. Artificial Neural Network (ANN)

The artificial neural network (ANN) was introduced by McCulloch et al. (1943) [42]. The use of ANN in modeling studies begins with the development of back propagation training algorithm in 1986 [43]. The artificial neuron is the basic element for simulation of biological nervous system microstructures. ANN has the ability to portray the nonlinear and complex functionalities in term of some variables to train the structure [16]. Figure 2 shows the architecture of typical ANN with different form of layers. Based on agreeable training, the ANN replicate the output based on unseen input data. Recently, the applications of ANN have been extended to many fields including water quality modeling, temperature prediction, ground water and hydrologic processes modeling [7,15,44]. In this study, the ANN model i.e., feed forward neural network type, was developed in the MATLAB environment. The final optimum parameters set for ANN modeling employed in the current study, are listed in Table 2.

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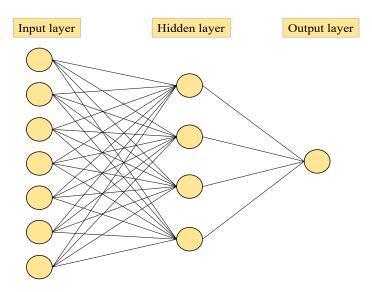


Figure 2. Architecture of the ANN model.

Table 2. Parameters of ANN for optimal network configuration.

D	Fitted Value				
Parameter —	TDS	EC			
Training dataset	252 (70%)	252 (70%)			
Testing dataset	108 (30%)	108 (30%)			
	General				
Network type	Feed forward neural network				
Data division	Random				
Number of hidden neurons	10				
Training algorithm	Levenberg	-Marquardt			
Transfer function for hidden layer	TAN	NSIG			
Transfer function for output layer	PURELIN				
Number of nonlinear parameters	18				
Number of epochs	35				
Learning rate	0.	.01			

2.3. Linear Regression Model (LRM)

Linear regression modeling (LRM) applies a linear approach to model the relationship between a scalar and one or more explanatory variables. In linear regression modeling, a linear predictor function is used, whose unknown parameters are estimated from the given data. In this method, one variable is considered as explanatory variable, while the other one is considered to be a dependent variable. It is a frequently used method with practical applications in various fields of engineering. The generated regression-based equations can further be used specifically for water related problems [45]. Below, Equations (1) and (2) representing the mathematical form of linear regression analysis [46,47].

$$Y = a + \beta_1 X_1 + \beta_2 X_2 + \dots + \beta_i X_i$$
 (1)

$$Y = a + \beta_1 X_i + \beta_2 X_i + \beta_3 X_i^2 + \beta_4 X_i^2 + \dots + \beta_k X_i X_i$$
 (2)

In both the Equations, a is the intercept, β is the slope or coefficient and k is the number of observations. The linear regression fit an estimated model to a dataset of Y and X values and the fitted model may be used to estimate Y with the addition of known X values [46]. The LRM employed in this study was developed using statistical package for social sciences (SPSS).

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3. Study Area, Datasets and Modeling

3.1. Description of the Study Area

The Indus River is 2880 km long and the Upper Indus river basin (UIB) is one of the glacierized, mountainous and snow-fed catchment [48]. The UIB, a part of the Indus basin system, situated upstream of Tarbela dam with 1150 km total length, 165,400 km² drainage area and ice reserves of 2174 km³. The elevation in UIB varies from 455 m to 8611 m and the climate fluctuates considerably inside the basin due to variation in altitude [49–51]. The average yearly precipitation varies from 100 to 200 mm [52,53]. The detailed description of the study area is given in Figure 3.

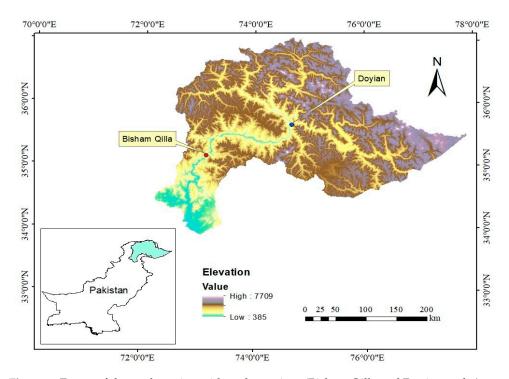


Figure 3. Extent of the study region with outlet stations (Bisham Qilla and Doyian outlet).

3.2. Modeling and Water Quality Dataset

The water quality modeling using AI methods were carried out using four main steps: (1) Data preparation; (2) Model development; (3) Model assessment and validation; and (4) Robustness analysis. The water quality dataset used in this study was obtained from WAPDA, Pakistan. The final data contained 360 monthly data points collected from 1975 to 2005 measured at Doyian and Bisham Qilla outlets. The dataset included nine parameters, namely, calcium (Ca), magnesium (Mg), sodium (Na), chloride (Cl), sulphate (SO₄), pH, bicarbonates (HCO₃), TDS and EC. The statistical parameters of the water quality data are shown in Table 3. The typical values of TDS in the study area ranges from 60 ppm to 260 ppm, while, the EC values lies between 92 $\mu S/cm$ to 450 $\mu S/cm$. The WHO guidelines suggested the permissible range of TDS in drinking water is 300-600 mg/L, while the allowable limit for agriculture water is 450–2000 mg/L [54,55]. The concentration of both the TDS and EC lies within the permissible limit; however, it is the need of time to measure important water quality indicators accurately with minimum efforts. The correlation matrix between the input parameters and modeling output (TDS and EC) is tabulated in Tables 4 and 5, respectively. According to available literature, adding too much input parameters that have a weak correlation with the model output adversely affects the performance of the model and increases the complexity and computational time [50]. Keeping in view the water quality dataset and the correlation among inputs and the targeted TDS and EC levels, seven parameters (Ca, Mg, Na, Cl, SO₄, pH, and HCO₃) were selected as significant inputs for GEP, ANN and LRM model development. As a usual

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practice, the dataset was randomly separated into 70% (252 records) and 30% (108 records) for models training and testing, respectively.

Variable	Unit	Range	SD	Mean	Minimum	Maximum	Skewness	Kurtosis
INPUTS								
Calcium (Ca)	meq/L	1.80	0.31	1.49	0.65	2.45	0.94	3.01
Magnesium (Mg)	meq/L	2.60	0.33	0.66	0.04	2.64	0.44	0.51
Sodium (Na)	meq/L	8.95	0.67	0.51	0.05	9.0	2.10	3.92
Chloride (Cl)	meq/L	4.15	0.20	0.27	0.05	4.2	1.43	3.15
Sulphate (SO ₄)	meq/L	3.11	0.34	0.51	0.1	3.2	0.83	0.55
Bicarbonate (HCO ₃)	meq/L	7.10	0.61	1.82	0.3	7.4	0.76	0.89
PH	-	1.22	0.65	7.83	7.08	8.3	-0.47	0.23
OUTPUTS								
TDS	ppm	200	38.64	138.17	60	260	0.86	1.19
EC	μS/cm	358	67.49	244.65	92	450	0.71	0.91

Total number of data points (n) = 360.

Table 4. Correlation matrix of TDS (Bold values show the significant correlation with other parameters).

Parameters	Ca	Mg	Na	HCO ₃	Cl	SO ₄	PH	TDS
Ca	1							
Mg	0.0194	1						
Na	-0.0037	0.4712	1					
HCO_3	0.0363	0.5324	0.7414	1				
Cl	0.0239	0.5035	0.7041	0.5296	1			
SO_4	0.0212	0.5415	0.4853	0.2749	0.3698	1		
PH	0.0025	0.0737	0.0415	0.0545	0.0561	-0.0445	1	
TDS	0.7452	0.7001	0.8629	0.8176	0.7411	0.6297	0.6210	1

Table 5. Correlation matrix of EC (Bold values show the significant correlation with other parameters).

Parameters	Ca	Mg	Na	HCO_3	Cl	SO_4	PH	EC
Ca	1							
Mg	0.0194	1						
Na	-0.0037	0.4712	1					
HCO_3	0.0363	0.5324	0.7414	1				
Cl	0.0239	0.5035	0.7041	0.5296	1			
SO_4	0.0212	0.5415	0.4853	0.2749	0.3698	1		
PH	0.0025	0.0737	0.0415	0.0545	0.0561	-0.0445	1	
EC	0.7539	0.8632	0.7672	0.8545	0.8951	0.7954	0.6202	1

3.3. Models Performance Evaluation

The efficiency of the developed GEP, ANN and LRM models was determined using selected indicators such as Root Mean Squared Error (RMSE), Nash Sutcliff efficiency (NSE), correlation coefficient (R^2), and Mean Absolute Error (MAE) [56]. The NSE ranges between negative infinity to 1 with value over 0.65 represents a reasonable estimation [57,58]. The value of R^2 varies between 0 and 1 [57]. The RMSE and MAE are error type parameters mostly followed in modeling studies. Lesser value of RMSE and MAE are ideal. The mathematical formulae for the aforementioned indicators are illustrated below as Equations (3)–(6), respectively.

$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (P_i - M_i)^2}{N}}$$
 (3)

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$$NSE = 1 - \frac{\sum_{i=1}^{n} (M_i - P_i)^2}{\sum_{i=1}^{n} (M_i - \overline{M}_i)^2}$$
 (4)

$$R^{2} = \frac{\sum_{i=1}^{n} \left(M_{i} - \overline{M}_{i} \right) \left(P_{i} - \overline{P}_{i} \right)}{\sqrt{\sum_{i=1}^{n} \left(M_{i} - \overline{M}_{i} \right)^{2} \sum_{i=1}^{n} \left(P_{i} - \overline{P}_{i} \right)^{2}}}$$
(5)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |P_i - M_i|$$
 (6)

where n represents the data points; M_i and P_i are actual and model simulated values, respectively, and \overline{M}_i and \overline{P}_i are mean actual and model mean simulated values, respectively.

4. Results and Discussion

4.1. Formulation of TDS and EC Using GEP

For the GEP model for TDS and EC formulation, the Equations (7) and (8) are developed to forecast the TDS and EC level on monthly basis. These Equations were formulated using seven parameters as significant inputs for GEP model and highlighted its novelty in the accurate prediction of the desired output. Moreover, the modeling results for TDS and EC estimation, as predicted by GEP, are graphically presented in Figures 4 and 5, respectively, for both training and testing.

$$TDS(ppm) = A + B + C - D \tag{7}$$

where

$$A = \left(\left(\frac{20390}{Ca} \right)^{\frac{1}{3}} - 22HCO_3 \right) \times \left(SO_4 - HCO_3 \right)^{\frac{1}{3}}$$

$$B = \frac{1}{HCO_3^{\frac{1}{3}} \times \ln(8.14Cl - 1.11)^2}$$

$$C = (4.15 + Na) \times 25 - Na \times HCO_3$$

$$D = \frac{28}{Ca} \left(Mg \times Cl \times 1.17 + \frac{SO_4}{1.03} \right) \times (51 - 7.33Cl)$$

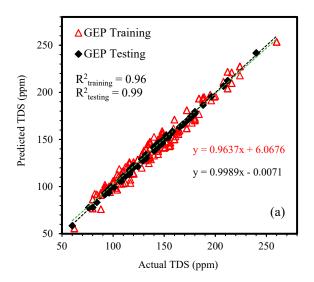
$$EC \left(\mu S/cm \right) = A + B + C$$
(8)

where

$$A = (9.6Cl + 5.1SO_4 - \ln HCO_3) \times (4.9 - HCO_3)^2$$

$$B = \{ (SO_4 \times PH \times 2.6 - \frac{32.7}{CA}) - 5.8 \} \times HCO_3$$

$$C = (Na + HCO_3 \times 10.4 - SO_4 \times Cl) \times 12.12$$



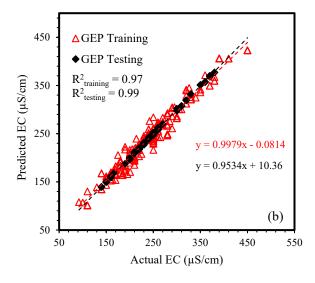
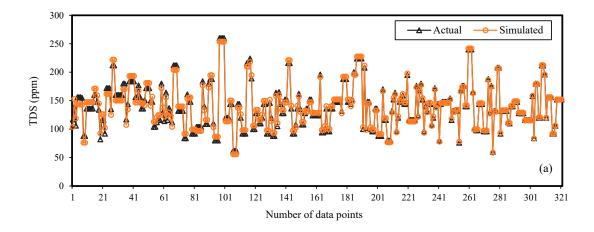


Figure 4. Scattered plots of actual and simulated results for (a) TDS and (b) EC, using gene expression programming (GEP).

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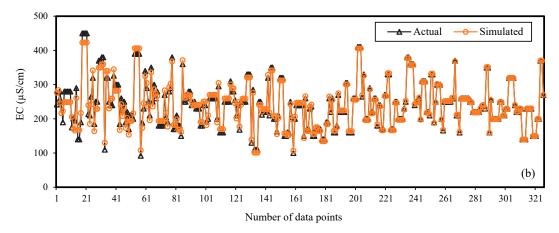


Figure 5. Comparison of actual and simulated results for (a) TDS and (b) EC, using gene expression programming (GEP).

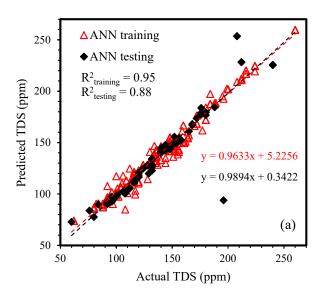
It is evident from Figures 4 and 5 that the proposed GEP model had successfully took the effect of all the modeling inputs. The developed GEP model for both TDS and EC was selected after running a set of algorithms. The performance measure indicators of all the models are listed in Table 6. Considering the TDS estimated by GEP, the NSE, R^2 , MAE and RMSE were found to be 0.96, 0.96, 6.58, 7.10 for model training data and 0.99, 0.99, 1.38, 1.57 for the testing data, respectively. Similarly, GEP results for EC during model training, the NSE, R^2 , MAE and RMSE were observed to be 0.96, 0.97, 12.2 and 14.4. For EC model testing, the goodness of fit was found to be 0.99, 0.99, 1.51 and 1.74, respectively. According to available literature, the R^2 value above 0.8 is reasonable [59], while, low MAE, RMSE and higher R^2 and NSE demonstrate adequate estimation of the model as compared with the actual data [36]. In our study, the R^2 is above 0.9 for both TDS and EC data, therefore, emphasized the reliable and accurate results of the developed GEP technique.

Table 6. Summary of statistical results for GEP, ANN, and LRM models.

Output	N.C. 1.1	Training			Testing				
Output	Model -	NSE	R ²	MAE	RMSE	NSE	R ²	MAE	RMSE
TDS	GEP	0.96	0.96	6.58	7.10	0.99	0.99	1.38	1.57
	ANN	0.95	0.94	4.80	6.37	0.85	0.88	5.50	13.1
	LRM	0.97	0.93	5.22	6.69	0.90	0.91	3.83	10.8
EC	GEP	0.96	0.97	12.2	14.4	0.99	0.99	1.51	1.74
	ANN	0.93	0.95	6.67	10.81	0.90	0.90	13.1	13.5
	LRM	0.95	0.92	11.93	16.37	0.94	0.92	11.0	26.70

4.2. ANN Modeling Output

Figures 6 and 7 shows the ANN estimated results against the measured data for both TDS and EC data. A trial-and-error method with optimization routine was employed to select the best ANN architecture. During the ANN model training period on TDS data, the values of NSE, R², MAE and RMSE were observed to be 0.95, 0.94, 4.80 and 6.37, respectively. For TDS testing dataset, the values of statistical indicators were found to be 0.85, 0.88, 5.50 and 13.1, respectively.



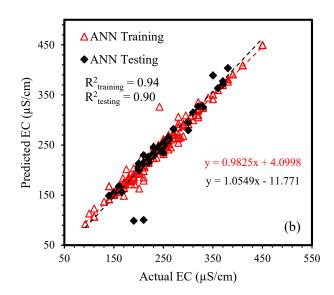


Figure 6. Scattered plots of actual and simulated results for (a) TDS and (b) EC, using artificial neural network (ANN).

Similarly, the ANN model performance for training data in EC prediction was assessed by mean of statistical measures. The statistical variables (NSE, R^2 , MAE and RMSE) were found to be 0.93, 0.95, 6.67 and 10.81, respectively for training data and 0.90, 0.90, 13.1 and 13.5 for EC testing data. The ANN modeling outcome (in term of R^2) indicated that the performance of the ANN on training dataset is accurate than on the testing data. The values of NSE and R^2 decreased and RMSE increased for the testing data. This may be considered as one of the drawbacks of the ANN model and can be attributed to the black box nature and inexplicable behavior of ANN, in comparison with other modeling techniques.

4.3. Linear Regression Modeling for TDS and EC

The results for linear regression model (LRM) are presented in Figures 8 and 9 for both TDS and EC with a satisfactorily estimated output. For LRM, the NSE and R² values were found to be 0.97 and 0.93 for training data and 0.90 and 0.91 for testing dataset, respectively, in modeling the TDS. Similarly, the EC modeling output estimated by LRM, the NSE and R² were equal to 0.95 and 0.92 for model training data and 0.94 and 0.92 for model testing data, respectively. The LRM results shows the declining accuracy (in term of statistical indicators) during the model testing phase which is one of the main drawback of regression-based modeling techniques [50].

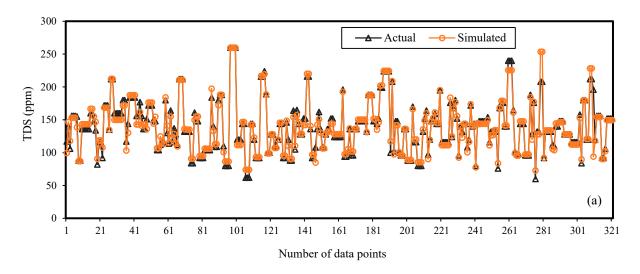
4.4. Models Comparative Analysis and Error Assessment

The output of all the developed models is compared to draw a comparative analysis pertaining to the prediction capability of AI and regression techniques. Considering the performance of the GEP technique, it outclasses other models (ANN and LRM) during training as well as testing phase and remained the accurate one. The lowest RMSE values was also attained by GEP which highlighted its overall supremacy. Keeping in view the performance of the ANN model, it showed good prediction capability during training but its performance reduced on testing dataset. The declined performance may be considered

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a limitation of the ANN model and can be attributed to the inexplicable behavior and the difficulty in the network structure of ANN [26,27]. As far as the performance of LRM is concerned, behavior (reduced performance during model training) similar to ANN was observed. The results of the observed and LRM simulated data tend to deviate largely as compared to GEP and ANN, which exposed the overall enhanced prediction capacity of AI based modeling techniques. The comparative performance indicators of the models are listed in Table 6.

The average absolute error between the model simulated and actual data are graphically illustrated in Figures 10–12 for GEP, ANN and LRM models, respectively. For GEP, the mean absolute error was 2.3 ppm and 3.01 $\mu S/cm$ in predicting TDS and EC levels, respectively. The maximum and minimum error in GEP predicted results for TDS (3.3 ppm and 0.23 ppm) and EC (2.9 $\mu S/cm$ and 0.4 $\mu S/cm$) was observed. The error graphs between the simulated and actual data are illustrated in Figure 11a,b for ANN. The average respective absolute error was observed to be 5.3 ppm and 6.9 $\mu S/cm$ for TDS and EC modeling simulated by ANN. Lastly, Figure 12a,b demonstrated the average error values predicted by LRM. The mean absolute error for TDS and EC data was found to be 8.9 ppm and 10.5 $\mu S/cm$, respectively, predicted by LRM. The result shows the accurate performance, reduced error and high correlation of GEP model as compared with other developed techniques (ANN and LRM). Conclusively, the performance of the models follows the order of GEP > ANN > LRM in predicting both the TDS and EC.



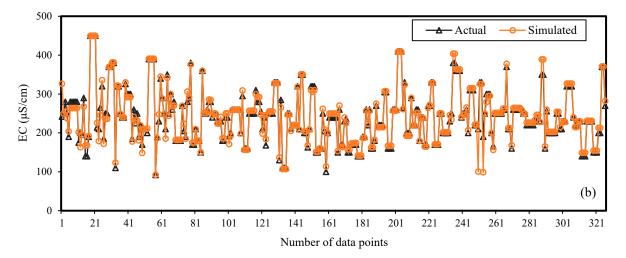


Figure 7. Comparison of actual and simulated results for (a) TDS and (b) EC, using artificial neural network (ANN).

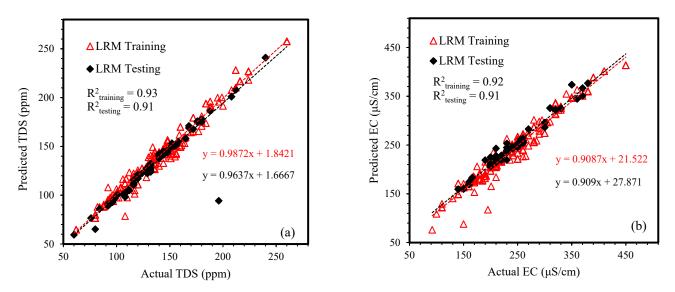


Figure 8. Scattered plots of actual and simulated results for (a) TDS and (b) EC, using linear regression model (LRM).

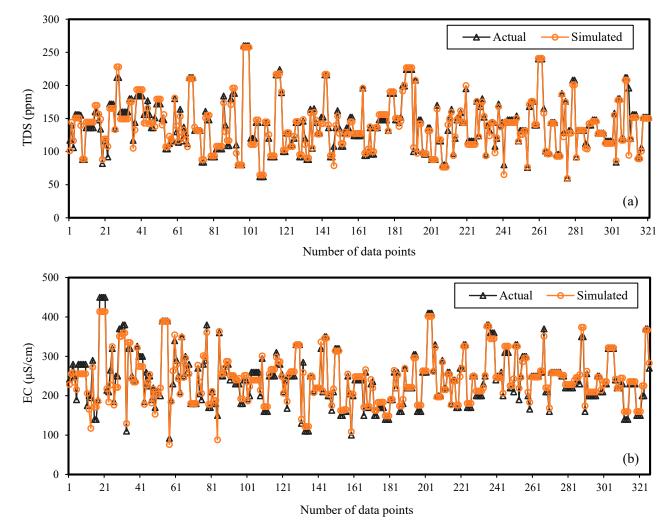


Figure 9. Comparison of actual and simulated results for (a) TDS and (b) EC, using linear regression model (LRM).

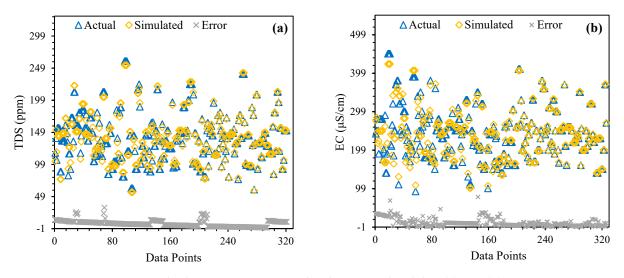


Figure 10. Absolute error among actual and GEP simulated data (a) TDS (b) EC.

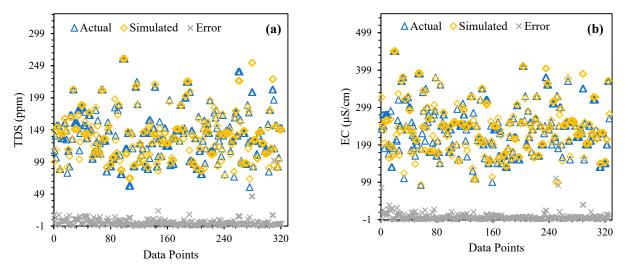


Figure 11. Absolute error among actual and ANN simulated data (a) TDS (b) EC.

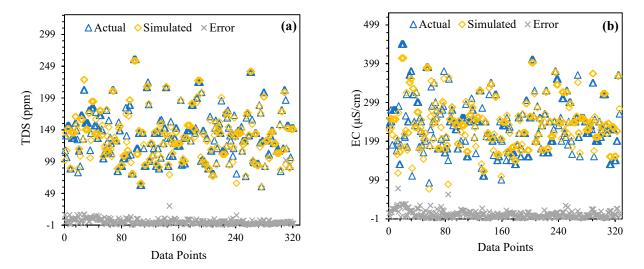


Figure 12. Absolute error among actual and LRM simulated data (a) TDS (b) EC.

4.5. Models External Validation

The effectiveness of a model significantly depends on input data [11]. In order to check the correctness of a dataset for establishing a linkage among variables, Frank and Todeschini [60] suggested that five should be the ratio between data points and input variables. In our study, the aforementioned ratio is 36.0 (252/7) and 18.0 (108/6) for train and test data, respectively, which satisfies the requirement of dataset selection. Golbraikh and Tropsha [61] recommended that slope of line passing through the origin must be close to unity. Roy (2008) [62] presented an indicator (R_m) and suggested that value of R_m should be above 0.5. Alavi et al. (2011) [63] proposed that R_0^2 and $R_0^{\prime 2}$ among actual and projected values must be nearly 1. In our study, the performance of the adopted techniques (GEP, ANN and LRM) was assessed by the aforementioned criteria and the results are summarized in Table 7.

S. No.	Equation	Criteria	Technique	Value	Suggested by
	$\nabla^n \left(M_{-} \overline{M}_{-} \right) \left(D_{-} \overline{D}_{-} \right)$		GEP	0.96	
1	$R = \frac{\sum_{i=1}^{n} (M_i - \overline{M}_i) (P_i - \overline{P}_i)}{\sqrt{\sum_{i=1}^{n} (M_i - \overline{M}_i)^2 \sum_{i=1}^{n} (P_i - \overline{P}_i)^2}}$	R > 0.8	ANN	0.98	[60]
	$V \sum_{i=1}^{n} (M_i - M_i) \sum_{i=1}^{n} (P_i - P_i)$		LRM	0.97	
			GEP	1.004	
2	$k = \frac{\sum_{i=1}^{n} (M_i - P_i)}{M \cdot 2}$	0.85 < k < 1.15	ANN	0.997	[61]
	1V1 _i -		L	0.992	
			GEP	0.995	
3	$k' = \frac{\sum_{i=1}^{n} (M_i - P_i)}{P_i \cdot 2}$	0.85 < k' < 1.15	ANN	1.002	[61]
	r_i		LRM	1.007	
			GEP	0.799	
		$R_m > 0.5$	ANN	0.820	
	$R_m = R^2 \times (1 - \sqrt{ R^2 - R_0 ^2})$		LRM	0.811	
	$\sum_{i=1}^{n} (P_i - M_i^0)^2$		GEP	0.999	
4	$R_0^2 = \frac{1}{\sum_{i=1}^{n} (P_i - \overline{P_i^0})^2}, M_i^3 = K \times P_i$	$R_0^2 \cong 1$	ANN	0.999	[62]
	$R_{0}^{2} = \frac{\sum_{i=1}^{n} (P_{i} - M_{i}^{0})^{2}}{\sum_{i=1}^{n} (P_{i} - \overline{P_{i}^{0}})^{2}}, M_{i}^{0} = k \times P_{i}$ $R_{0}^{2} = \frac{\sum_{i=1}^{n} (M_{i} - P_{i}^{0})^{2}}{\sum_{i=1}^{n} (M_{i} - \overline{M_{i}^{0}})^{2}}, P_{i}^{0} = k' \times M_{i}$		LRM	099	
	$\sum_{i=1}^{n} \left(M_i - \overline{M_i^0} \right)^2, I_i = \kappa \wedge IVI_i$		GEP	0.999	_
		$\hat{R_0^2} \cong 1$	ANN	0.999	
		0 -	LRM	999	

Table 7. Statistical indicators for external validation of GEP, ANN and LRM models.

4.6. Sensitivity and Parametric Study

In AI modeling, it is important to carry out some analysis and checks to confirm the accuracy of the models. A reliable performance of a model on training and testing dataset does not guarantee the generalized accuracy and robustness. To find out the effective parameters and ensure that the model has incorporated the effect of all the inputs, the sensitivity and parametric analysis has been proposed in literature [39,50]. For a known dataset and input parameters, a model could provide a desirable outcome but it is not certain to provide the same accuracy for unknown data. Though, it is obligatory to carry out the sensitivity and parametric study to determine the involvement of inputs for predicting output. In the present research, the techniques proposed by Gandomi et al. (2013) [64] was used. The researchers developed the Equations (9) and (10) for finding out the effect and sensitivity of input variables on the modeling output.

$$N_i = f_{max}(x_i) - f_{min}(x_i) \tag{9}$$

$$S_i = \frac{N_i}{\sum_{j=i}^n N_j} \times 100 \tag{10}$$

The $f_{max}(x_i)$ and $-f_{min}(x_i)$ are the maximum and minimum of the estimated output over the *i*th *output*.

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Various sensitive parameters were identified effecting the targeted output and the results are illustrated in Figure 13 for both TDS and EC output. The graphs indicated that bicarbonates (HCO₃) is the most significant parameter with 22.3% and 42.3% relative contribution to TDS and EC concentration, respectively. Similarly, the second influencing parameter is Cl for TDS and SO₄ for EC with 21.6% and 25.6% respective contribution. The results further demonstrated that the targeted output (TDS and EC) is likely to be least effected by pH. Moreover, Mg is contributing 16.98% to TDS and almost 0% to EC (least significant for EC).

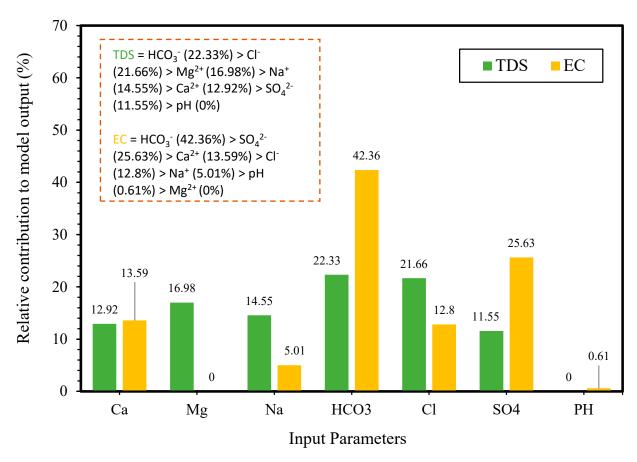


Figure 13. Sensitivity and importance of input parameters with regards to model output.

Parametric analysis was performed by keeping all the variables constant at their mean values and changing a single parameter at a time. Figures 14 and 15 graphically demonstrate the respective prediction capacity of the proposed techniques for TDS and EC modeling with a variation in the input parameters. The output of the parametric study exposed that the concentration of TDS and EC follows an increasing tendency with a variation in each input except for PH (where its concentration is constant). According to available literature, both the outputs (TDS and EC) are associated with the salts/ions, and consequently, a fluctuation in the concentration of ions affect the TDS and EC level [55]. The same trend was observed in our study, because most of the input parameters are inorganic and organic salts. Hence the increasing trend of TDS and EC with a variation in model input parameters may be attributed to the salty concentration in surface water. Only one parameter (Mg) remained the least significant one, which did not have a momentous effect on EC level as compared to other modeling inputs.

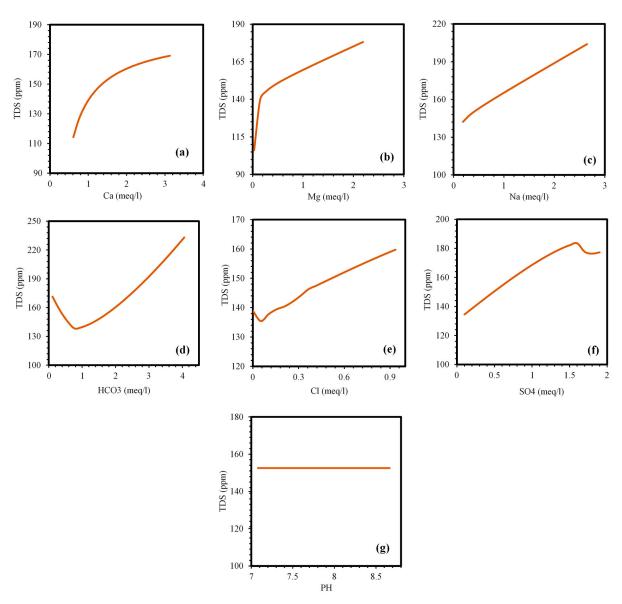


Figure 14. Variation of Total Dissolved Solids (TDS) with individual modeling inputs (a) Ca, (b) Mg, (c) Na, (d) HCO₃, (e) Cl, (f) SO₄, (g) pH.

4.7. Environmental Aspects of Water Quality Modeling

The AI-based models are very useful tools in predicting the concentration, distribution and risk of chemical pollutants in a given surface water body. The modeling outcome from these models are crucial for environmental impact assessment and might provide a supportive technique to environmental management agencies for decision making pertaining to rising water pollution [8]. Moreover, models are helpful in providing objective means of processing the complex information related to water quality condition. In this study, the predictive capacity of the well-known GEP, ANN and LRM models was assessed in predicting the TDS and EC concentration in a highly glacierized and mountainous catchment, the Upper Indus River Basin (UIB). UIB is a major source of contributing water to downstream areas where the water is used for drinking as well as agricultural production. The direct and in-situ measurement of water quality parameters is almost impossible in such a complicated watershed. Therefore, the use of modeling technique is indispensable to provide a deep insight regarding the water pollution. Furthermore, the GEP model provides mathematical expressions which will be very helpful for government organizations

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and environmental pollution control agencies in accessing the condition of water by using minimum number of input parameters.

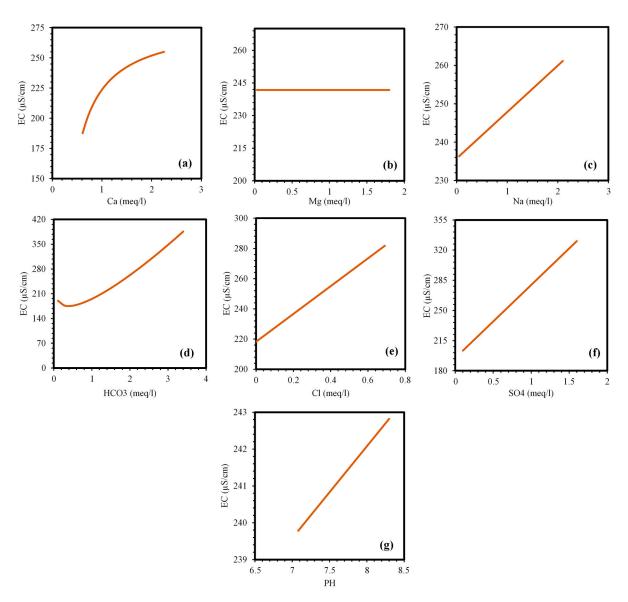


Figure 15. Variation of specific conductivity (EC) with individual modeling inputs (**a**) Ca, (**b**) Mg, (**c**) Na, (**d**) HCO₃, (**e**) Cl, (**f**) SO₄, (**g**) pH.

5. Conclusions

The present study was mainly dedicated in applying AI and regression methods for EC and TDS prediction in the expanded part of the glacierized and mountainous catchment i.e., upper Indus river basin. The dataset, acquired from both Doyian and Bisham Qilla outlets, was utilized for the models' development. Secondly, the accuracies of the artificial neural network (ANN), gene expression programming (GEP) and linear regression model (LRM) were compared and a robustness analysis was performed to determine the most reliable model. Regardless of several factors that have influence on water quality, the models were effectively developed utilizing monthly TDS and EC data measured historically. The modeling outcome for the resolved overfitting issue and generalized results was confirmed by external criteria. The sensitivity and parametric analyses were carried out to ensure a robust relation between inputs and desired output. An excellent correlation exhibited among actual and model simulated results for both training and testing data. The performance of the GEP turned out to be the most accurate followed by ANN technique.

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Both GEP and ANN have the capability to model water quality parameters for a given set of inputs. The GEP mathematical expressions for TDS and EC level could be easily used in predicting monthly TDS and EC. The GEP evaluates suitable association mandatory for representation of the physical processes. The accuracy of the ANN model decreased on testing data and may be attributed to the difficult network structure of ANN. Conclusively, the outcome of the present study will be helpful in assessing the performance of AI models using big dataset for water quality prediction. Moreover, the modeling techniques applied in this study could assist the water quality managers and engineers in developing an effective strategy for successful management of surface water bodies.

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