



Article

A Bi-Level Optimization Model for Virtual Power Plant Membership Selection Considering Load Time Series

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Abstract: In order to improve the level of new energy consumption and reduce the dependence of the power system on traditional fossil energy, this paper proposed a bi-level optimization model for virtual power plant member selection by means of coordination and complementarity among different power sources, aiming at optimizing system economy and clean energy consumption capacity and combining it with the time sequence of load power consumption. The method comprises the following steps: (1) The processing load, wind power, and photovoltaic data by using ordered clustering to reflect the time sequence correlation between new energy and load and (2) uses a double-layer optimization model, wherein the upper layer calculates the capacity configuration of thermal power and energy storage units in a virtual power plant and selects the new energy units to participate in dispatching by considering the utility coefficient of the new energy units and the environmental benefit of the thermal power units. The Latin hypercube sampling (LHS) method was used to generate a large number of subsequences and the mixed integer linear programming (MILP) algorithm was used to calculate the optimal operation scheme of the system. The simulation results showed that by reducing the combination of subsequences between units and establishing a reasonable unit capacity allocation model, the average daily VPP revenue increased by RMB 12,806 and the proportion of new energy generation increased by 1.8% on average, which verified the correctness of the proposed method.

Keywords: virtual power plant; ordered clustering; bilevel optimization; Latin hypercube mixed; integer linear programming



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1. Introduction

After 2020, China's total terminal energy demand entered the growth stage of saturation, and the scale of supply side is in excess, and the supporting thermal power units cannot be retired immediately [1]. This makes the total installed capacity in the same area in excess, and more of the same type of power enterprises. Virtual power plants (VPP) aggregate generation side resources with different output characteristics through advanced communication, control, and network technologies to participate in power grid dispatching. Based on the software-based decentralized control structure, each entity can receive, cooperate, and respond to demand according to requirements [2,3]. VPP can take advantage of the current situation of excess resources in the generation side, give full play to the output characteristics of different members, and select the members that are more conducive to meeting the dispatching needs from the existing power plants to complete the dispatching tasks. How to judge which subsequence multiple units are in at the same time and how to select members and dispatch the units in different subsequences will test the rapid response ability of VPP.

The main objective of different VPP member combinations in existing studies is to maximize the economic benefits. Romanos P et al. proposed an operational energy management strategy that uses thermal energy storage tanks to generate electricity in conjunction

with 670 MW nuclear power plants in the United Kingdom [4]. Cavazzini G et al. combined pumped storage and wind power to increase revenue and working hours [5]. In Wei C, Xu J, Liao S, et al., distributed thermostatic control load and intermittent renewable energy were combined to form VPP, which can reduce the most unbalanced power and was not affected by parameter heterogeneity, and was suitable for diversified virtual electricity [6]. Cao J, Zheng Y, Han X, et al. proposed a VPP two-stage scheduling strategy with multi-time scale optimization, which introduced external calculation to coordinate the real-time complementation of regional energy [7]. Some members can decide the unit capacity configuration and system deployment according to the demand side and power plant degradation characteristics [8,9]. Li, Z. et al. took into account the heterogeneous uncertainties from the renewable energy, market prices, and electricity loads through a risk-averse stochastic programming approach [10].

Other studies have also analyzed the characteristics of members of the VPP: Chen Y, Du Q, Wu M, et al. combined the seasonal characteristics of hydropower resources through the signing of medium-term contracts to obtain a certain flexible load reserve to minimize the daily operating cost of the VPP [11]. Sakr W S, EL-Sehiemy R A, Azmy A M, et al. considered the uncertain load demand, renewable energy, and market price of VPP, and determined the optimal capacity and location of the dispatchable load [12]. Rahimi M, Ardakani F J, and Ardakani A J established the windPDF model to speed up the uncertainty and improve the expected net profit of VPP [13]. Z. Li integrated multiple levels of renewable energy to optimize the hourly operation of distributed renewable energy generation [14]. However, the above literature did not take into account the following. (1) The seasonal variation of load in some areas is not obvious. The load curve cannot be simply replaced by the typical load of the season. (2) In the process of capacity allocation, VPP does not notice that some members also undertake the function of making up for the lack of other members while meeting the load demand, and this part of the function is not reflected, which indirectly affects the value of these members.

In order to complete the dispatching tasks of the virtual power plant to the power grid more reliably, the problem of how to design indices to select members among multiple units still needs to be solved. According to the characteristics of distributed generation such as photovoltaic and wind power generation, the index of the uncontrollable member utility coefficient was proposed, and a virtual power plant member selection model considering the time sequence of power consumption was established. First, the sample was divided into different subsequences by using ordered clustering. Then, the upper reference utility coefficient and environmental performance index were used to calculate the capacity configuration of thermal power and energy storage units in VPP and select the wind power and photovoltaic units to participate in the scheduling. The lower optimization used the MILP algorithm to calculate the optimal operation scheme of the system.

2. Data Preprocessing

The data of the load and new energy units are highly uncertain due to seasonal and climatic factors. When forecasting, it is often considered to use collection methods with less interference factors or to consider more interference factors for modeling [15–17]. Some clustering algorithms are also used, but the usual clustering algorithm is to disrupt the clustering samples, and then divide the samples with similar characteristics into one class. Ordered clustering seeks the optimal segmentation method without changing the order of the samples [18]. Zhao J and Liu J (2020) used ordered clustering to analyze the degradation trend of capacitors under different temperatures and humidities, and the proposed degradation fitting function could well fit the degradation trend under different stresses [19]. Ping W and Zhou H (2020) improved the K-means algorithm by using the idea of two orders to reduce the number of binning and improve the efficiency of picking equipment [20]. Gao Chun, Yu Aiqing, and Ding Yu (2021) used the recursive ordered clustering method to reduce the impact of distributed generation on the distribution network reconfiguration [21]. Yuan Tie-jiang and Cao Ji-lei (2022) used a combination

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of the sequential algorithm and clustering algorithm to reduce the wind power–load time sequence subsequence to improve the calculation speed of the subsequent optimal allocation process [22].

Load sample data $L = \{L_1, L_2, ..., L_n\}$, select different number of points p to segment, $p \in (1, n)$, and select the optimal segmentation position P, $P = \{P_1, P_2, ..., P_p\}$. Divide the sample into p + 1 subsequences, the sum of the squares of deviations is defined as shown in Formulas (1) and (2), and finally, the number of optimal segmentation points is determined by using the contour coefficient. The expected value of the segmented load subsequence set is used as a typical load subsequence, and the function of the contour coefficient is defined as shown in Formula (3), wherein the range of the contour coefficient is [-1, 1]. The larger the value, the better the clustering effect.

$$S = \sum_{t=1}^{T} \sum_{i=1}^{K} \sum_{L \in L_{i \times T}} |L - \mu_{i,t}|^2$$
 (1)

$$\mu_{i,t} = \frac{1}{P_i - P_{i-1}} \sum_{n=P_{i-1}+1}^{P_i} L_{(n,t)}$$
 (2)

$$C = \frac{1}{n} \sum_{i=1}^{n} \frac{b_i - a_i}{\max\{a_i, b_i\}}$$
 (3)

where K is the number of centroid samples; $\mu_{i,t}$ is the centroid of the ith centroid sample at time t; n is the number of samples; a_i is the average distance between the ith sample and all other samples in the same cluster; and b_i is the average distance between the ith sample and all samples in the next best cluster. The number of segmentation points p corresponding to the maximum contour coefficient C was selected as the optimal number of segmentation points to determine the load classification scheme. The time series data of the wind power and photovoltaic units were divided into multiple subsequences in units of days according to the p segmentation points obtained by the orderly clustering of electric loads, as shown in Figure 1.

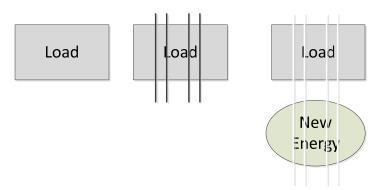


Figure 1. Schematic diagram of new energy and load time node division based on ordered clustering.

3. Research on VPP Member Selection Architecture

3.1. System Structure of Virtual Power Plant

As is shown in Figure 2, the VPP control center exchanges information with thermal power, wind power, photovoltaic, energy storage, and general load, and arranges power output as a whole. Thermal power and energy storage, as the controllable members in the selection of VPP members, play a role in stabilizing the uncertainty of renewable energy output and ensuring the continuous and stable power supply, while wind power and photovoltaic power, as the uncontrollable members in the selection of VPP members, undertake the task of power supply together with thermal power units because of the unstable output due to weather and other factors. Load is considered to be an uncontrollable

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member that must be selected by the VPP because it has similar characteristics to wind and PV.

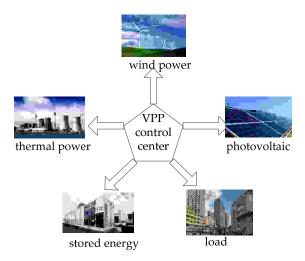


Figure 2. Control diagram of the virtual power plant.

3.2. Bi-Level Programming Structure Design of Virtual Power Plant System

In this paper, a bi-level optimization programming method was used to optimize the member selection of the virtual power plant. The upper level is the capacity optimization module, which is used to find the optimal configuration of the system including the capacity of the controllable members and whether the uncontrollable members participate in the dispatch. This low layer is a scheduling optimization module that is used to calculate the optimal operation scheme of the system.

As shown in Figure 3, the two-level optimization contained two levels. The decision results of the upper level generally affect the objectives and constraints of the lower level, while the lower level feeds back the decision results to the upper level, thus realizing the interaction between the upper and lower levels.

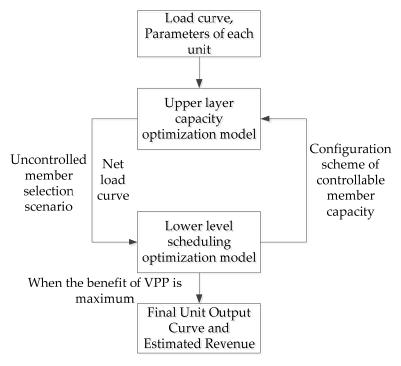


Figure 3. Logic diagram of two-level optimization.

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3.2.1. Upper Layer Capacity Optimization Model Objective Function

The upper layer selects the utility coefficient of the uncontrollable members of the virtual power plant and the environmental performance coefficient of the controllable members as the indices for evaluating the system, which can be described as follows:

$$J_1 = \max(F_1 - F_2) \tag{4}$$

where F_1 is the utility coefficient of the uncontrollable member and F_2 is the environmental performance coefficient of the controllable member.

Utility Coefficient of Uncontrollable Member

Markowitz portfolio theory is often applied to asset allocation, which proposes that investors pursue the maximization of the expected return and the minimization of risk. VPP often faces a similar situation when choosing members, that is, VPP hopes to choose more new energy units to obtain more output, but at the same time, it has to face greater volatility risk. The risk is mainly caused by the uncertainty of the load, wind power, and photovoltaic output. In Figure 4, the solid line is the net load curve, the blue part is the adjustment interval of the net load fluctuation caused by the uncertainty of the actual output of wind power and photovoltaic power, and the dotted line is the adjustment interval of the output of controllable members adjusted by the virtual power plant. It can be seen that: ① From T1 to T2, with the increase in the net load fluctuation, the capacity of the controllable members that needs to be mobilized increases; ② in the stage from T1 to T2, when the output of the uncontrollable member is within the regulation range of the controllable member of the virtual power plant, the virtual power plant can regulate; ③ in the stage from T2 to T3, when the output of the uncontrollable member is beyond the downward regulation range of the virtual plant, the virtual power station needs to adjust the member selection to ensure the downward regulation capability; and (4) from T3 to T4, the uncontrollable members exceed the upstream regulation range of the virtual power plant, and the virtual power plant needs to adjust the member selection to ensure the upstream regulation capability.

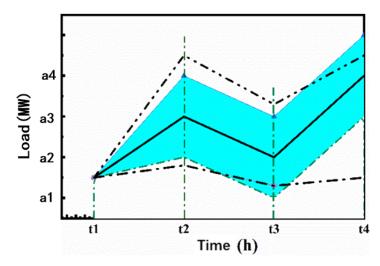


Figure 4. Impact of the uncontrollable members on the capacity configuration of the controllable members.

Assuming that there are L uncontrollable members that can be selected by VPP, the expected expectation and variance after the combination of uncontrollable members are:

$$E_{\sum_{t=1}^{T}(t,p)}^{NE(i)} = \sum_{i=1}^{L} v_p^i \times E_{(t,p)}^{NE(i)}$$
(5)

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$$Var_{\sum_{t=1}^{T}(t,p)}^{NE(i)} = \sum_{t=1}^{L} v_{p}^{i} \times Var_{(t,p)}^{NE(i)} + \sum_{i=1}^{L} v_{p}^{i_{1}} \times v_{p}^{i_{2}} \times cov(i_{1}, i_{2})$$

$$i = 1$$

$$i_{1} \neq i_{2}$$

$$(6)$$

where $E_{(t,p)}^{NE(i)}$ and $Var_{(t,p)}^{NE(i)}$ are the expectation and variance of the output of the ith uncontrollable member at time t under the subsequence p; v_p^i is the 0–1 variable of whether the ith unit is selected by VPP under the subsequence p; 1 represents selection; and 0 represents elimination. $cov(i_1,i_2)$ is the correlation coefficient of member i_1 and i_2 is the output. $E_{\sum\limits_{t=1}^{NE(i)}}^{NE(i)}$ and $Var_{\sum\limits_{t=1}^{NE(i)}}^{NE(i)}$ are the sum of the expectation and variance of the ith generator at $\sum\limits_{t=1}^{NE(i)} (t,p)$

all times under the subsequence p.

To this end, the investment utility function F_1 is used to represent the portfolio return rate:

 $F_{1} = E_{T}^{NE(i)} - 0.5 \times A \times Var_{T}^{NE(i)} \sum_{t=1}^{T} (t,p)$ (7)

among them, A is the degree of risk aversion, which reflects the degree of the risk aversion of investors. It is generally a subjective setting variable, and the value is between [0, 4] [23]. In this paper, the value of A was selected to maximize the expected total return of VPP.

Environmental Performance Indicators of Controllable Members

The flue gas discharged in the process of thermal power plant production contains harmful substances such as CO_2 , SO_2 , and NO_x , which pollute the surrounding environment. The emission of pollutants is directly proportional to the power generation of thermal power units:

$$F_2 = (\delta^{SO_2} + \delta^{CO_2} + \delta^{NO_x}) \times \sum_{t=1}^{T} P_{(t,p)}^G$$
 (8)

where δ^{SO_2} , δ^{CO_2} , δ^{NO_x} represent the emission coefficient of each pollutant, respectively, and $\sum_{t=1}^T P^G_{(t,p)}$ is the total power generation of the thermal power unit under the condition of subsequence p.

Controllable Member Capacity Configuration Constraint

VPP will determine the capacity of controllable members according to the output fluctuation of the selected uncontrollable members. In addition to meeting the net load demand, the thermal power will also cooperate with energy storage to increase the output to make up for the shortage of the output of uncontrollable members or reduce the output to ensure new energy consumption. When the output of the new energy unit exceeds the expected output, the thermal power unit reduces the output, in addition to meeting the output demand of the net load part, and the energy storage is used for charging when the reducing capacity is insufficient. When the output of the new energy unit fails to meet the expected output, the thermal power unit increases the output, in addition to meeting the output demand of the net load part, and the energy storage is used for supplementing the power generation for the insufficient part.

$$-R_{\min}^{G} + ES_{\max} - ES_{(t,p)}^{store} \le P_{(t,p)}^{G} - P_{(t-1,p)}^{G} + \sqrt{Var_{(t,p)}^{NE(i)}} \le P_{\max}^{G} + ES_{\max}$$

$$R_{\min}^{G} + ES_{\min} \le P_{(t,p)}^{G} - P_{(t-1,p)}^{G} + \sqrt{Var_{(t,p)}^{NE(i)}} \le R_{\max}^{G} + ES_{(t,p)}^{store} - ES_{\min}$$
(9)

where $P_{(t,p)}^G$ is the actual output of the thermal power generating unit at time t of the p subsequence; P_{\max}^G and P_{\min}^G are the upper and lower limits of the output of the thermal power generating unit; and R_{\max}^G and R_{\min}^G are the upper and lower limits of the climbing

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of thermal power generating units. $E_{(t,p)}^{store}$ is the stored energy of energy storage at time t under the condition of subsequence p; ES_{\max} and ES_{\min} are the upper and lower limits of the stored energy of energy storage; $\sqrt{Var_{(t,p)}^{NE(i)}}$ is the standard deviation of the net load, representing the power fluctuation of the uncontrollable member at time t of the p subsequence.

Optimization Variables

The thermal power unit capacity P_{\max}^G , the energy storage capacity ES_{\max} , and the decision variable v_p^i of each uncontrollable member in the VPP member were selected as the optimization variables.

3.2.2. Lower Dispatching Optimization Model Objective Function

The dispatching optimization model selects 24 h as the dispatching scale, takes the maximization of the VPP's daily net revenue as the objective function, includes the net revenue of each unit, and considers the cost of the signing medium and long-term contracts between VPP and thermal power.

$$J_2 = \max(\text{Profit}_{VPP(p)}) \tag{10}$$

$$Profit_{VPP(P)} = Profit_{gen(p)} + Profit_{NE(p)} + Profit_{ES(p)} - C_{gen(p)}^{s \tan dby}$$
(11)

The net income of thermal power unit can be expressed as:

$$\operatorname{Profit}_{gen(p)} = \sum_{t=1}^{T} P_{(t,p)}^{G} \times (\rho_{VPP} - \rho_{gen})$$
(12)

The net income of new energy units can be expressed as:

$$Profit_{NE(p)} = \sum_{t=1}^{T} P_{T}^{NE(i,i\neq load)} \times (\rho_{VPP} - \rho_{NE})$$

$$(13)$$

The net income of the energy storage unit can be expressed as:

$$Profit_{ES(p)} = (\eta_D \times \sum_{t=1}^{N} P_t^{charge} - \sum_{t=1}^{N} P_t^{discharge} \div \eta_D) \times (\rho_{VPP} - \rho_{ES})$$
(14)

The cost of VPP signing a medium- and long-term contract with thermal power can be expressed as:

$$C_{gen(p)}^{s \tan dby} = 2 \times \sum_{t=1}^{T} \sqrt{Var_{T}^{NE(i)} \times (\rho_{s \tan dby} - \rho_{gen})}$$
 (15)

where ρ_{VPP} is the on-grid price of VPP, and ρ_{gen} , ρ_{NE} , and ρ_{ES} are the cost per kilowatt-hour of thermal power units, new energy units, and energy storage, respectively. $\operatorname{Profit}_{gen(p)}$, $\operatorname{Profit}_{ES(p)}$, and $\operatorname{Profit}_{VPP(p)}$ are the net profits of the thermal power units, new energy units, energy storage units, and VPP under the condition of subsequence p, respectively. $C_{gen(p)}^{s \tan dby}$ is the cost generated by the medium- and long-term contract signed between the VPP and the thermal power unit under the condition of subsequence p to ensure the energy consumption of the system. In the formula, 2 is multiplied to represent the increase and decrease of the reserve cost, respectively. $\rho_{S \tan dby}$ is the electricity price of the medium- and long-term contract signed between the VPP and the thermal power unit. $P_{(t,p)}^G$ is the output of the thermal power unit at time t of the p subsequence, and

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 $P_T^{NE(i,i\neq load)}$ is the actual output of the ith uncontrollable member excluding the load at $\sum_{t=1}^{T} (t,p)$

time t under the condition of subsequence p.

Constraints

(1) Controllable member model

The thermal power unit scheduling constraints:

$$P_{\min}^G \le P_{(t,p)}^G \le P_{\max}^G \tag{16}$$

$$-R_{\min}^{G} \le P_{(t,p)}^{G} - P_{(t-1,p)}^{G} \le R_{\max}^{G}$$
(17)

The SOC constraint of the energy storage unit is:

$$ES_{\min} \le ES_{(t,p)}^{charge} \le ES_{\max}$$
 (18)

$$E_{t+1}^{store} = E_{(t,p)}^{charge} + \triangle T \times \eta_D \sum_{t=1}^{N} x_{(t,p)} \times P_{(t,p)}^{discharge} - \Delta T \times \sum_{t=1}^{N} (1 - x_{(t,p)}) \times P_{(t,p)}^{charge} \div \eta_D \quad (19)$$

where $P_{(t,p)}^{charge}$ and $P_{(t,p)}^{discharge}$ are the charge and discharge power of the energy storage at time t of the p subsequence, respectively; $x_{(t,p)}$ is the 0–1 variable that controls the energy storage not to be charged and discharged at the same time; and η_D is the charge and discharge efficiency of the energy storage.

(2) Uncontrollable member constraint

$$0 \le v_i^p \times P_{(t,p)}^{NE(i)} \le v_p^i \times P_{\max}^{NE(i)}$$
(20)

$$0 \le P_{(t,p)}^{load} \tag{21}$$

where $P_{\max}^{NE(i)}$ is the maximum installed capacity of the ith new energy unit and $P_{(t,p)}^{load}$ is the load at time t under the subsequence p.

(3) Power balance constraint

$$P_{(t,p)}^{load} = P_{(t,p)}^G + \eta_D \times P_{(t,p)}^{discharge} - P_{(t,p)}^{charge} \div \eta_D + sum(v_p^i \times P_{(t,p)}^{NE(i)})$$
 (22)

Optimization Variables

The lower layer selects the output $P_{(t,p)}^G$ of the thermal power unit, the charge and discharge power $P_{(t,p)}^{charge}$, $P_{(t,p)}^{discharge}$ of the energy storage, and the risk aversion coefficient A as the optimization variables.

4. System Solution Method

4.1. Latin Hypercube Scenario Generation and Reduction

A multi-scenario approach is used to describe the uncertainty of the load and the output of the uncontrollable members. The scene generated according to ordered clustering is not as representative as a traditional typical curve such as the typical seasonal load curve, so this paper used the LHS method to generate the scene [24]. The LHS method was used to generate 1000 load scenarios and uncontrollable member output scenarios, and then the scenario reduction method considering the Kantorovich distance was used to reduce the scenarios to 10, and the two were randomly matched [25].

$$Prifit_{VPP(p)} = \sum_{i=1}^{10} P_i \times Profit_{VPP(P,j)}$$
 (23)

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where P_j is the probability of the scenario, and $Profit_{VPP(P,j)}$ is the net profit of VPP in the jth scenario under the condition of subsequence p.

4.2. MILP Algorithm to Solve the Lower Scheduling Optimization Problem

MILP is a kind of important mathematical programming problem that is used to solve the scheduling problem at the lower level of the model. The difference between MILP and the general programming problem is that the mathematical model of this kind of problem can be expressed by a linear relationship. A complete mathematical description of a mixed integer linear programming problem including a linear objective function for solving a maximum or minimum, a system of simultaneous linear equations, and constraints on the optimization variables is as follows:

$$\min(cx)$$

$$s.t.Bx \begin{cases} \geq \\ \leq \\ \leq \\ \end{cases} b$$

$$x_{\min} \leq x_i \leq x_{\max}$$

$$x_j \in (0, 1)$$
(24)

where cx is the objective function; B is the coefficient matrix of the simultaneous linear equations; b is the value of the simultaneous linear equations; x_i and x_j are continuous variables and shaped variables, respectively.

5. Example Analysis

5.1. Results of Data Preprocessing

The annual load data of a region in 2021 were selected, the data time interval was 1 h, the capacity of three wind turbines was 20 MW, 30 MW, and 40 MW, respectively, and the capacity of the three photovoltaic units was 20 MW, 30 MW, and 40 MW, respectively. Formulas (1) and (2) were used to calculate the contour coefficient and find the segmentation point. The contour coefficient calculation results are shown in Table 1.

Table 1.	The contour	coefficient c	calculation	results.
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Number of Split Points (p)	Contour Factor (c)				
2	0.545				
3	0.2936				
4	0.3284				
5	0.2801				
6	0.2702				
7	0.2316				
8	0.2027				
9	0.1801				

As shown in Figure 5 and Table 2, the red part of the figure is the expectation of each subsequence, and the clustering results show that the differences between the subsequences are obvious and cannot simply be distinguished by seasons. The results of the contour coefficient calculation are shown in Table 3.

Table 2. Load sequence segmentation.

Subsequence Number	Time/h
1	1–742
2	742–5326
3	5326-6870
4	6870–7591
5	7591–8760

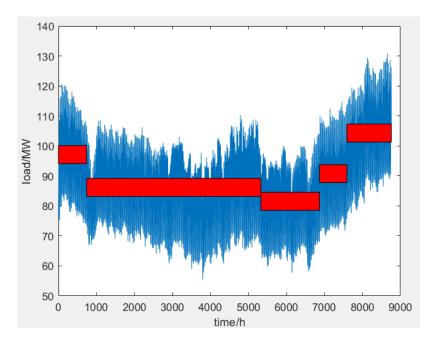


Figure 5. Load data and ordered clustering results.

Table 3. Member selection scheme based on order-bilevel optimization.

	A	TANN	Member Selection								Dunnetten of
Subsequence		VPP Revenue (RMB)	Wind1	Wind2	Wind3	PV1	PV2	PV3	Energy Storage (MWh)	Thermal Power (MWh)	Proportion of New Energy Generation
1	0.2	481,720	0	1	1	1	0	1	8	108	27.57%
2	0.1	534,550	0	1	1	1	1	1	12	81	33.40%
3	0.1	523,580	1	1	1	0	1	1	17	67	43.54%
4	0.1	563,410	1	1	1	1	1	1	20	83	37.20%
5	0.1	593,910	1	1	1	1	1	1	20	102	37.72%

5.2. Comparison of Member Selection Schemes of Two Calculation Methods

Table 3 shows the member selection scheme obtained by using the method in this paper to evaluate each member.

Table 4 shows the results of member selection by using the MILP method to maximize the total revenue of VPP after ordered clustering.

Table 4. Member selection scheme based on the ORDING-MILP method.

Subsequence	VPP Revenue (RMB)		Member Selection							
		Wind1	Wind2	Wind3	PV1	PV2	PV3	Energy Storage (MWh)	Thermal Power (MWh)	New Energy Generation
1	548,290	0	0	1	1	1	1	20	110	30.38%
2	502,560	0	1	1	1	1	1	20	110	33.40%
3	473,820	1	1	1	1	1	0	20	110	45.90%
4	516,450	0	1	1	1	1	1	20	110	33.36%
5	592,020	0	1	1	1	1	1	20	110	33.04%

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Compared with the member selection of the two groups, it can be found that under the condition of sufficient consumption capacity, the bi-level optimization method proposed in this paper tended to select more clean energy unit output, which takes into account both the clean energy consumption and environmental benefits while pursuing the maximization of the VPP economic benefits. Comparing the VPP benefits of the two groups, it can be found that, except for subsequence 1, the benefits of the bi-level optimization method were higher, because this method optimized the capacity allocation of controllable members, indirectly reduced the operation and maintenance costs of thermal power and energy storage units, and increased the benefits of VPP. From the perspective of the proportion of new energy generation, comparing the two groups of subsequence 2, it can be found that when the selection scheme of uncontrollable members was the same, the proportion of new energy generation did not change significantly, which shows that the method proposed in this paper is reasonable for the capacity allocation of controllable members, and saves the operation and maintenance costs for virtual power plants while ensuring the new energy consumption capacity. Comparing subsequences 4 and 5 of the two groups, it can be found that when the uncontrollable members chose to increase one group, the method proposed in this paper could improve the overall revenue of VPP while increasing the proportion of new energy generation.

Taking subsequence 1 as an example, Figure 6 shows the 10 groups of the load subsequence generated by the LHS method, Figures 7 and 8 show the output subsequence of uncontrollable members of the LHS method, and the dashed line in the figure shows the load in subsequence 1 and the output expectation of the uncontrollable members. It can be found that the peak value of the output of new energy units generally decreased between 10 o'clock and 15 o'clock. Figures 9 and 10 are the output results of typical days under the two optimization methods, respectively. The red part is the thermal power output. It can be found that the output of thermal power units was smoother between 10 o'clock and 15 o'clock. This shows that the output of the uncontrollable member optimized by the bi-level optimization model proposed in this paper was smoother, which is convenient for VPP coordination.

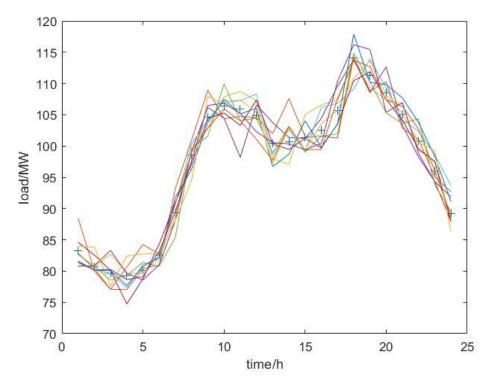


Figure 6. LHS randomly generated load data.

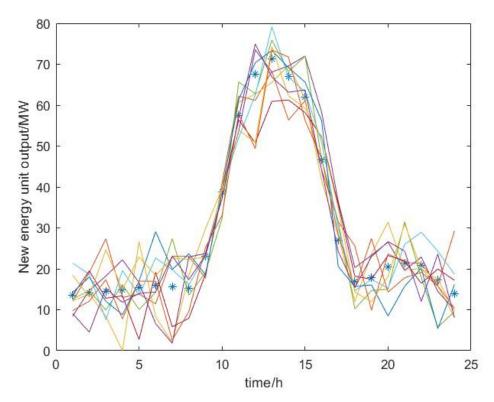


Figure 7. The uncontrollable member effort of the order-MILP method.

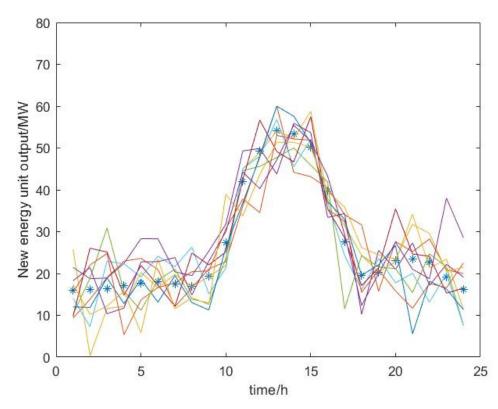


Figure 8. Uncontrollable member effort of the order-bilevel optimization method.

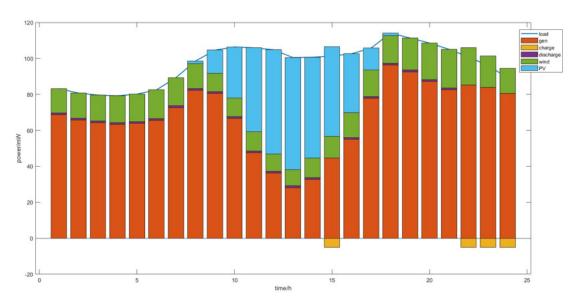


Figure 9. Scheduling results of the order-MILP method.

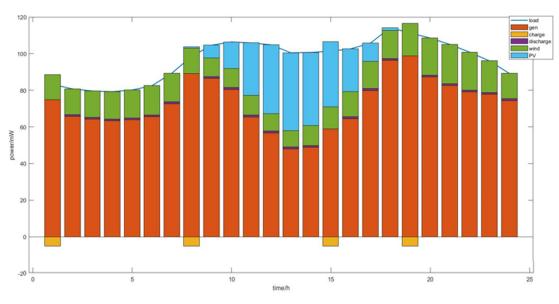


Figure 10. Scheduling results of the order-bilevel optimization method.

6. Conclusions

With the excess power supply on the supply side, the assembled thermal power units cannot be retired immediately. By taking advantage of the output characteristics of different members of VPP, the existing power plants can choose members that can easily meet the dispatching requirements. First, the load timing was utilized to solve the problem that the load curve in some areas does not change obviously with the season. It is more reliable to divide the load curve into different subsequences by using ordered clustering. Second, the utility function of uncontrollable members was proposed to describe the risks and benefits of the uncontrollable members in VPP. It provides a basis for the capacity configuration of controllable members in VPP, reflects the value of controllable members to maintain the reliability of the VPP output, and provides a basis for the signing of medium- and long-term standby contract between the VPP and controllable members. The double-layer optimization scheme proposed by this model was compared with the method considering only the economic benefits of VPP. The average daily income of VPP was increased by RMB 12,806, and the proportion of new energy generation was increased by 1.8% on average, which verified the correctness of the proposed method. It can be found

that the economic benefit, environmental benefit, and scheduling reliability are a pair of contradictory objectives. The optimization results show that there is a strong coupling relationship between the capacity of each equipment. The method proposed in this paper is suitable for the future situation of abundant data and abundant power generation resources, and provides a new idea for the VPP capacity configuration problem. It should be pointed out that this method relies on accurate prediction of the output of uncontrollable members. With the development of prediction technology, the improvement in the output prediction accuracy of new energy units is a direct optimization of this method.

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