

Supplementary Materials: Dynamic Mapping of Evapotranspiration Using an Energy Balance-Based Model over an Andean Páramo Catchment of Southern Ecuador

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1. METRIC_L and METRIC_M Implementation Flowchart

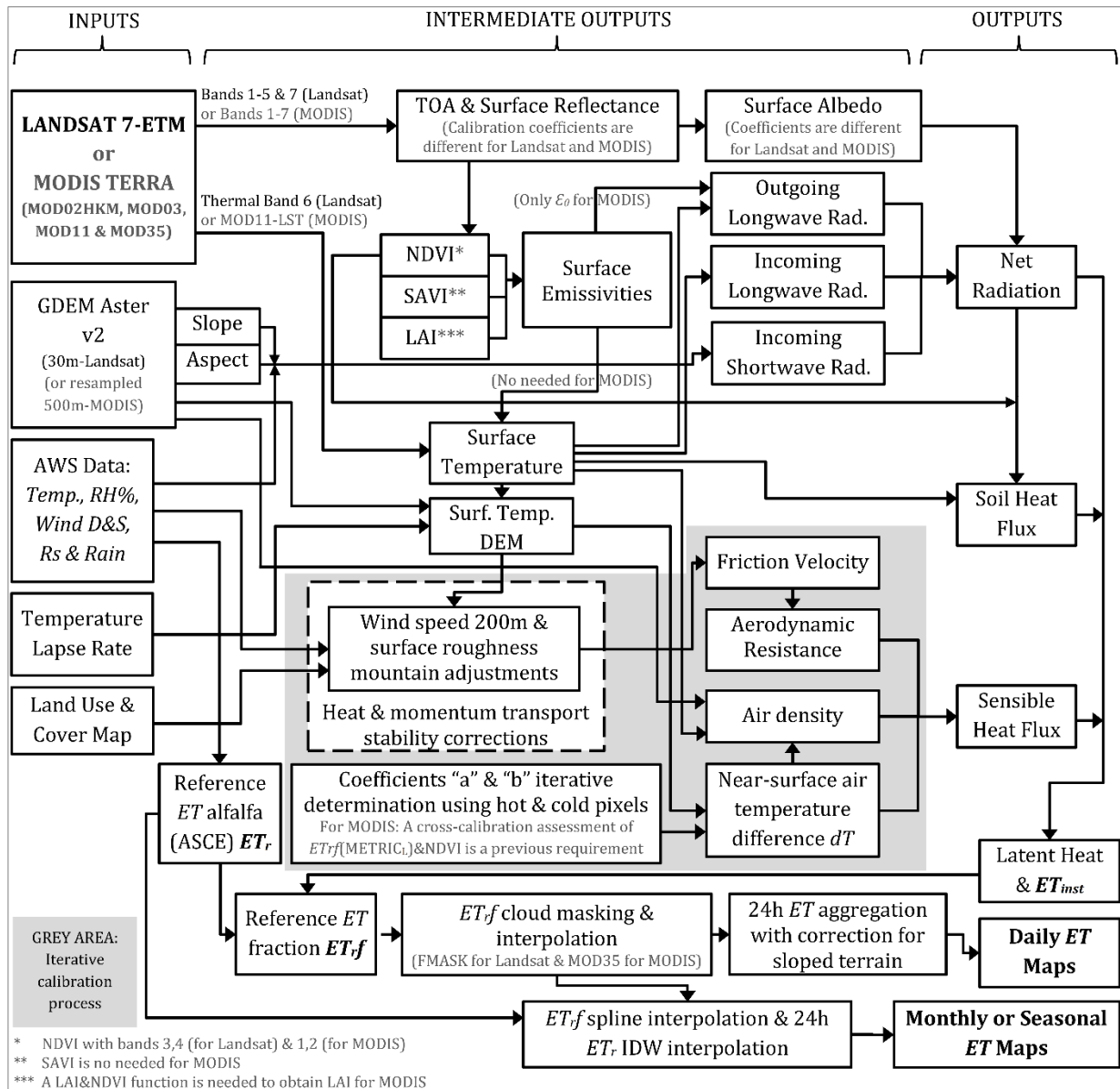


Figure S1. METRIC_L and METRIC_M algorithms flowchart (adapted from equations of Allen *et al.* [1] and Trezza *et al.* [2]).

2. Abbreviations

Table S1. Abbreviations used in this supplementary information (Equations (S1)–(S32)).

Abbreviation	Full Name	Units
ET	Evapotranspiration	mm
LE	Latent heat flux	$W \cdot m^{-2}$
R_N	Net radiation	$W \cdot m^{-2}$
G	Soil heat flux	$W \cdot m^{-2}$
H	Sensible heat flux	$W \cdot m^{-2}$
$R_{S,in}$	Incoming shortwave radiation	$W \cdot m^{-2}$
$R_{L,in}$	Incoming longwave thermal radiation from the atmosphere	$W \cdot m^{-2}$
$R_{L,out}$	Outgoing longwave thermal radiation	$W \cdot m^{-2}$
ε_0	Broad-band surface emissivity	dimensionless
T_s	Temperature of the surface	K
LAI	Leaf Area Index	$m^2 \cdot m^{-2}$
$SAVI$	Soil Adjusted Vegetation Index	dimensionless
$NDVI$	Normalized Difference Vegetation Index	dimensionless
r_{ah}	Aerodynamic resistance to heat transfer	$s \cdot m^{-1}$
dT	Near surface temperature difference	K
AWSs	Automatic weather stations	-
u^*	Friction velocity	$m \cdot s^{-1}$
u_{200}	Wind speed at a blending height (200 m)	$m \cdot s^{-1}$
z_{om}	Momentum roughness length	m
$z_{om(mtn)}$	Mountain adjusted roughness length	m
ω	Wind speed weighting coefficient	dimensionless
T_{sDEM}	Lapse rate corrected surface temperature	K
L	Monin-Obukhov Length	m
ET_r	ASCE-ERWI Standardized Reference Evapotranspiration for alfalfa	$mm \cdot h^{-1}$
ET_{inst}	Instantaneous actual ET	$mm \cdot h^{-1}$
λ	Latent heat of vaporization of water	$J \cdot kg^{-1}$
ET_{rf}	Reference Evapotranspiration fraction (crop coefficient at reference alfalfa basis)	dimensionless
ET_{day}	ET at a daily basis (24 h)	$mm \cdot day^{-1}$
K_c	Grass-based crop coefficient	dimensionless
K_{ratio}	Conversion value for ET_{rf} to K_c	dimensionless

3. Description of the METRIC Landsat-Based Implementation

According to the methodology of Allen *et al.* [1] METRIC delivers the instantaneous latent heat flux (LE) on a pixel-by-pixel basis as a residual of the energy balance Equation (S1):

$$LE = R_N - G - H \quad (W \cdot m^{-2}) \quad (S1)$$

Here LE can be expressed as actual evapotranspiration ET by dividing it by the latent heat of vaporization. We calculated R_N considering: $R_{S,in}$, the outgoing shortwave radiation retrieved by multiplying $R_{S,in}$ with Albedo (α), $R_{L,in}$, $R_{L,out}$, and ε_0 . Equation (S2) describes this calculation.

$$R_N = R_{S,in} - \alpha \times R_{S,in} + R_{L,in} - R_{L,out} - (1 - \varepsilon_0) \times R_{L,in} \quad (W \cdot m^{-2}) \quad (S2)$$

$R_{S,in}$ was calculated using Equation (S3).

$$R_{S,in} = \frac{G_{sc} \times \cos\theta_{rel} \times \tau_{sw}}{d^2} \quad (W \cdot m^{-2}) \quad (S3)$$

where G_{sc} is the solar constant ($1367 \text{ W}\cdot\text{m}^2$), $\text{Cos}\theta$ considers the slope and aspect terrain adjustments according [1,3]. τ_{sw} is the atmospheric transmissivity obtained with the ASCE-ERWI method [4], and d^2 is the square of the relative earth-sun distance at the day of the image. α was calculated by integrating satellite spectral reflectance values from bands 1 to 5 and 7 of Landsat image according [5]. $R_{L,out}$ was calculated using the Stephan-Boltzmann equation (Equation (S4)).

$$R_{L,out} = \sigma \times \varepsilon_0 \times T_s^4 \quad (\text{W} \cdot \text{m}^{-2}) \quad (\text{S4})$$

where σ is the Stephan-Boltzmann constant ($5.67 \times 10^{-8} \text{ W}\cdot\text{m}^{-2}\cdot\text{K}^{-4}$). ε_0 was computed using an empirical equation developed by Tasumi [6] (Equation (S5)).

$$\varepsilon_0 = 0.95 + 0.01 \times LAI \quad \text{for } LAI \leq 3 \quad (\text{S5})$$

The equation is limited to $\varepsilon_0 = 0.98$ when $LAI > 3$. LAI was computed using the equation from Bastiaanssen [7] (Equation (S6)).

$$LAI = -\frac{\ln\left(\frac{0.69 - SAVI}{0.59}\right)}{0.91} \quad (\text{S6})$$

$SAVI$ considers the top-of-atmosphere reflectance bands number 3 and 4 of the images (Equation (S7)).

$$SAVI = \frac{(1 - L_{const}) \times (\rho_{\lambda,4} - \rho_{\lambda,3})}{(\rho_{\lambda,4} + \rho_{\lambda,3})} \quad (\text{S7})$$

L_{const} constant value represents the soil-brightness dependent factor. We calibrated L_{const} for our study area and a value of 0.05 was found after processing the images according to the method recommended by Huete [8]. T_s was estimated for Landsat imagery using the methodology proposed by Markham and Barker [9] which accounts for emissivity and atmospheric specific corrections (Equation (S8)).

$$T_s = \frac{K_2}{\ln\left[\left(\varepsilon_{NB} \times \frac{K_1}{L_{C\lambda,6}}\right) + 1\right]} \quad (\text{K}) \quad (\text{S8})$$

Here, K_1 and K_2 constants were 666.09 and $1282.71 \text{ W}\cdot\text{m}^{-2}\cdot\text{sr}^{-1}$ respectively for Landsat, and the corrected thermal radiance $L_{C\lambda,6}$ was calculated using the approach from Wukelic *et al.* [10]. In this calculation we applied the default values recommended by Allen *et al.* [1] for the path radiance ($R_p = 0$), downward thermal radiation from clear sky ($R_{sky} = 0$), and narrow band transmissivity or air ($\tau_{NB} = 1$) due to the lack of radio sounding data for the study area.

The T_s was internally adjusted during the creation of the dT function according Allen *et al.* [1]. The narrow-band surface emissivity (ε_{NB}) was calculated using the approach from Tasumi [6] similarly to ε_0 . The $R_{L,in}$ was calculated by Equation (S9).

$$R_{L,in} = \sigma \times \varepsilon_a \times T_a^4 \quad (\text{W} \cdot \text{m}^{-2}) \quad (\text{S9})$$

where ε_a is the effective atmospheric emissivity and T_a is the air temperature. The ε_a was obtained according Allen *et al.* [1] and Bastiaanssen [11]. METRIC applications generally use T_s as a surrogate of T_a in the calculation of $R_{L,out}$ and $R_{L,in}$. This assumption was appropriate considering the high altitude and predominant wet conditions of the Andean páramo, where differences between the surface and near-surface air temperatures tends to be small [1]. G in $\text{W}\cdot\text{m}^{-2}$ was calculated using the approach of Bastiaanssen *et al.* [12] (Equation (S10)).

$$G = (T_s - 273.15) \times (0.0038 + 0.0074 \times \alpha) \times (1 - 0.98 \times NDVI^4) \times R_N \quad (\text{S10})$$

This approach was considered because $NDVI$ input is more appropriate for heterogeneous terrain instead of LAI when estimating G [13]. The $NDVI$ was calculated according to Equation (S11).

$$NDVI = \frac{(\rho_{\lambda,4} - \rho_{\lambda,3})}{(\rho_{\lambda,4} + \rho_{\lambda,3})} \quad (\text{S11})$$

where $\rho_{\lambda,4}$ and $\rho_{\lambda,4}$ are the Landsat reflectances from near-infrared and red bands respectively. We estimated H employing an aerodynamic function (Equation (S12)):

$$H = \rho_{air} \times C_p \times \frac{dT}{r_{ah}} \quad (\text{W} \cdot \text{m}^{-2}) \quad (\text{S12})$$

where ρ_{air} is the air density ($\text{kg} \cdot \text{m}^{-3}$), C_p is the specific heat of air at constant pressure ($\text{J} \cdot \text{kg}^{-1} \cdot \text{K}^{-1}$), r_{ah} in $\text{s} \cdot \text{m}^{-1}$ was retrieved between two near surface heights $z_1 = 0.1$ m and $z_1 = 2$ m, and dT in Kelvin was retrieved similarly between z_1 and z_2 . In Equation (S12) both r_{ah} and dT were unknown and required an iterative process to solve it.

The r_{ah} was calculated by extrapolating wind speed to some blending heights above the surface (usually 100 to 200 m) and corrected with an iterative stability scheme based on the Monin-Obukhov functions (Equation (S13)):

$$r_{ah} = \frac{\ln\left(\frac{z_1}{z_2}\right)}{k \times u^*} \quad (\text{S13})$$

k is Von Karman's constant (0.41). u^* in $\text{m} \cdot \text{s}^{-1}$ was applied for neutral atmospheric conditions and was computed during the first iteration using Equation (S14).

$$u^* = \frac{k \times u_{200}}{\ln\left(\frac{200}{z_{om}}\right)} \quad (\text{S14})$$

The term u_{200} was calculated using Equation (S15).

$$u_{200} = \frac{u_{AWS} \times \ln\left(\frac{200}{z_{omAWS}}\right)}{\ln\left(\frac{z_{AWS}}{z_{omAWS}}\right)} \quad (\text{S15})$$

In the equation, u_{AWS} is wind speed measured at z_{AWS} height (m) above the surface, and z_{omAWS} is the estimated roughness length (m) at the same place. To represent z_{om} we employ a land use and land cover map (LULC) where we assigned z_{om} values according to land use type and vegetation cover. The assigned z_{om} values were: Water (0.0005 m), páramo grasslands (0.020 m), páramo flooded grasslands (0.020 m), evergreen shrublands with grasslands (0.125 m), high montane evergreen forest (0.20 m) and inter-Andean montane evergreen forest (0.25 m). These values were selected according to several studies [14–17].

To account for mountainous effects we implemented the empirical methodology recommended by Allen *et al.* [18] where an adjustment of z_{om} was applied using Equation (S16).

$$z_{om(mtn)} = z_{om} \times \left(1 + \frac{s_d - 5}{20}\right); \quad \text{for } s_d \geq 5 \quad (\text{S16})$$

where s_d is the slope of each pixel in degrees. In the same way, the term u_{200} for mountainous image pixels was multiplied by a wind speed weighting coefficient (ϖ), before computations of u^* and r_{ah} . The function is on Equation (S17).

$$\varpi = 1 + 0.1 \times \left(\frac{E_{DEM} - E_{AWS}}{1000}\right) \quad (\text{S17})$$

In this equation, E_{DEM} and E_{AWS} are the elevation of each pixel and elevation of the AWSs respectively. T_s was corrected using the difference in elevation in relation to an arbitrary point in the image where $T_{sDEM} = T_s$ according Allen *et al.* [18] (Equation (S18)).

$$T_{sDEM} = T_s - CT_{lr} \times \Delta z \quad (\text{S18})$$

Specific calibration of the temperature lapse rate CT_{lr} was performed using the methodology proposed by Allen *et al.* [18] and was applied for each image date (CT_{lr} mean = 0.68 °C each 100 m).

During ten iterations corrected values for u^* were computed using Equation (S19). We choose this number of iterations to ensure that the change in r_{ah} is less than 0.1% at the end of the process.

$$u^* = \frac{k \times u_{200}}{\ln\left(\frac{200}{z_{om}}\right) - \Psi_{M(200)}} \quad (S19)$$

Herein, $\Psi_{m(200)}$ is the stability correction for momentum transport at 200 m. Then r_{ah} was recalculated using Equation (S20):

$$r_{ah} = \frac{\ln\left(\frac{z_1}{z_2}\right) - \Psi_{H(z_2)} + \Psi_{H(z_1)}}{k \times u^*} \quad (S20)$$

where $\Psi_{H(z_2)}$ and $\Psi_{H(z_1)}$ are stability corrections for the heat transport at heights z_2 & z_1 . The terms $\Psi_{M(200)}$, $\Psi_{H(z_2)}$ and $\Psi_{H(z_1)}$ were updated in the iterative process following the approaches outlined by Paulson [19] and Webb [20], which employ the Monin-Obukhov length L defined by Equation (S21).

$$L = -\frac{\rho_{air} \times C_p \times u^{*3} \times T_s}{k \times g \times H} \quad (S21)$$

This function contemplates the variables mentioned above, and also the gravitational acceleration g ($9.807 \text{ m}\cdot\text{s}^{-2}$) and the air density ρ_{air} at the pixel elevation (kPa). A comprehensive explanation of this process is available in Allen *et al.* [1].

The dT function assumes a linear relationship with T_s where coefficients a and b were used to correct the function in an iterative computation.

$$dT = a + b \times T_s \quad (S22)$$

In Equation (S22) the a and b coefficients have an empirical determination based on two extreme conditions in the image. The named hot and cold pixels were selected by two specific criteria: the hot pixel was a relative dry, non-vegetated, and with higher temperature pixel, and the cold pixel was a wet and fully vegetated pixel, both located in the proximity of the three AWSs. The selection of these pixels for each image was based on a rigorous process of visual and software assisted selection of pixels in T_s , α , $NDVI$, LAI , and slope images. Most of the hot pixels were located on non- or sparsely-vegetated areas in the mid and high areas of the grasslands, and the wet pixels were mostly selected from the *Polylepis* sp. tree patches near wetlands. Temperature differences between the cold and hot pixels ranged in 5 to 7 °C for our study. Hence, the estimations for dT were assessed using Equations (S23) and (S24):

$$dT_{hot} = \frac{(R_N - G) \times r_{ah,hot}}{\rho_{air,hot} \times C_p} \quad (S23)$$

$$dT_{cold} = \frac{(R_N - G - 1.05 \times ET_r) \times r_{ah,cold}}{\rho_{air,cold} \times C_p} \quad (S24)$$

In the Equation (S24), an adjustment with the instantaneous ET_r obtained according the methodology of ASCE-ERWI [4] accounts for an increased condition of ET in the cold pixel (5% greater) [1]. The Equation (S25) calculates H for the hot and cold pixels.

$$H_{hot} = (R_N - G)_{hot} - LE_{hot} ; H_{cold} = (R_N - G)_{cold} - LE_{cold} \quad (S25)$$

At the end of the iterative process, a and b coefficients were determined using Equations (S26) and (S27).

$$a = \frac{dT_{hot} - dT_{cold}}{T_{sDEM,hot} - T_{sDEM,cold}} \quad (S26)$$

$$b = \frac{dT_{hot} - a}{T_{sDEM,hot}} \quad (S27)$$

where $T_{sDEM,hot}$ and $T_{sDEM,cold}$ are the lapse rate corrected surface temperatures for the hot and cold pixels. These two conditions tie the calculations for all pixels in the image.

Once R_N , H , and G were calculated, we applied the Equation (S1) to obtain LE as the residual of the balance. Hereafter, we divided LE by the λ to obtain the instantaneous actual ET (ET_{inst}) at the satellite image time. Equation (S28) describes this:

$$ET_{inst} = 3600 \frac{LE}{\lambda \times \rho_w} \quad (\text{mm} \cdot \text{h}^{-1}) \quad (\text{S28})$$

where 3600 is the conversion from seconds to hours and ρ_w is the density of water ($1000 \text{ kg} \cdot \text{m}^{-3}$). λ was calculated using the Equation (S29).

$$\lambda = [2.501 - 0.00236 \times (T_s - 273.15)] \times 10^6 \quad (\text{J} \cdot \text{kg}^{-1}) \quad (\text{S29})$$

A requirement to convert hourly ET_{inst} into a daily basis is to obtain ET_{rf} . This variable was calculated dividing ET_{inst} by the ET_r (Equation (S30)). ET_{rf} is also the equivalent of the crop coefficient (K_c) when used with an alfalfa reference basis [1,4]. The advantage of this calibration via ET_r is that each pixel of the ET_{rf} image retains a unique value for ET_{inst} which can be interpolated in the time using representative dataset from the weather stations.

$$ET_{rf} = \frac{ET_{inst}}{ET_r} \quad (\text{S30})$$

Prior to the calculation of daily evaporation the minor areas of the ET_{rf} images had to be masked to avoid contamination due to clouds [1,21,22]. This was done in two steps: (1) identification and masking of clouds and cloud-shadows (considering a buffer of 200 m surrounding the cloud/shadow) with the application of the FMASK algorithm proposed by Zhu and Woodcock [23] and (2) implementing the methodology recommended by Kjaersgaard *et al.* [24] which fills in the masked areas using a time weighted interpolation of the ET_{rf} values from the precedent and following satellite images containing valid ET_{rf} estimates. This method considers an adjustment for vegetation (using $NDVI$) to account for reflectance changes over the time.

Equation (S31) shows calculation of ET_{day} . It was obtained by multiplying ET_{rf} times hourly aggregated ET_r in 24-h periods times a correction term $C_{solar24}$ to account for the variation of solar radiation over sloping terrain in 24 h.

$$ET_{day} = ET_{rf} \times \sum_{i=1}^{24} ET_{r,(i)} \times C_{solar24} \quad (\text{mm} \cdot \text{day}^{-1}) \quad (\text{S31})$$

$C_{solar24}$ was calculated using daily extraterrestrial and clear-sky solar energy using the methodology suggested by Allen *et al.* [25].

Monthly ET was calculated assuming that ET changes in proportion to the change in ET_r at the AWSs. Last, according to Kjaersgaard *et al.* [26], a cubic spline interpolation of the daily ET_{rf} maps over the study period was implemented, as well as an spatial inverse weighted interpolation (IDW) to recreate maps of ET_r using the information of the three AWSs in the same period.

4. The K_{ratio} Conversion Factor Methodology

According to the methodology of Allen *et al.* [26] a crop coefficient based on the alfalfa reference (in our case ET_{rf}) can be converted to a crop coefficient with a grass reference (K_c) by multiplying it by a conversion value (K_{ratio}) which usually ranges between 1.0 to 1.3. The Equation (S32) uses averaged climate data for the period of study and a constant value of the alfalfa crop coefficient for the mid-season stage ($K_{c\ mid}$):

$$K_{ratio} = K_{c\ mid} + [0.04 \times (u_{AWS\ mean} - 2) - 0.004 \times (RH_{min} - 45)] \times \left(\frac{h}{3}\right)^{0.3} \quad (\text{S32})$$

Herein $K_{c\ mid} = 1.20$ was obtained from tables in [27], $u_{AWS\ mean}$ was the daily mean value for wind speed during the study period, RH_{min} was the mean value for daily minimum relative humidity (%) during the study period, and h is the height for alfalfa reference crop ($h = 0.5$).

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