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Land Use Optimization for Coastal Urban Agglomerations Based on Economic and Ecological Gravitational Linkages and Accessibility

Tingting Pan ^{1,2,3}, Fengqin Yan ^{1,2}, Fenzhen Su ^{1,2,3,*}, Vincent Lyne ⁴ and Chaodong Zhou ^{1,2}

- State Key Laboratory of Resources and Environmental Information System, Institute of Geographic Sciences and Natural Resources Research, Chinese Academy of Sciences, Beijing 100101, China; pantt@lreis.ac.cn (T.P.); yanfq@lreis.ac.cn (F.Y.); zhoucd@lreis.ac.cn (C.Z.)
- ² College of Resources and Environment, University of Chinese Academy of Sciences, Beijing 100049, China
- ³ Collaborative Innovation Center of South China Sea Studies, Nanjing University, Nanjing 210093, China
- ⁴ IMAS-Hobart, University of Tasmania, Hobart, TAS 7004, Australia; vincent.lyne@utas.edu.au

Correspondence: sufz@lreis.ac.cn

Abstract: Urban agglomerations (UA) are attracting increasing research attention as a global emergent phenomenon, whereby regional collaborative linkages between cities attracts and agglomerates development. However, these studies also acknowledge that ecological values may be negatively impacted by re-development, ecological fragmentation, and proximity or downstream impacts. Sustainable development, therefore, requires balancing forces from economic attraction and ecological repulsion. Forces similar to economic ones may also operate in attracting ecological enhancement towards higher-valued ecological regions; however, research regarding the role of the self-collaborative gravity-like forces shaping UA is limited in land use optimization. To assist planners, this study developed a new multi-objective land use optimization of UA that explored the intensity of economic ties and ecological gradients using the multi-objective NSGA-II algorithm. In this model, economic linkage intensity (ELI) and accessibility were used to calculate a modified GDP (gross domestic product), while the NDVI (normalized difference vegetation index) was used for the modified ESV (ecosystem services value). Spatial allocation with implicit economic accessibility relationships was enhanced through a two-step mutation operator, including a "gravity flip" spatial orientation factor. Compared to the standard NSGA-II algorithm, models of future land use of the Guangdong-Hong Kong-Macao Greater Bay Area (GBA) in 2030 have shown that the modified GDP value in our model increased by 7.41%, while the conversion rate of high-density vegetation reduced by 7.92%. The results highlighted the importance of linkage and accessibility factors in enhancing the clustering of cities. In tandem, the modified ESV also enhances ecosystem services contributions of higher value vegetated land through decentralized built-up developments. The proposed model provides managers with a comprehensive and efficient land use solution model that accounts for intrinsic linkage factors shaping the development of compact urban agglomerations.

Keywords: urban agglomerations; land use optimization; parallel NSGA-II; economic linkage intensity; ecosystem services value

1. Introduction

The emergence of urban agglomerations (UA) globally is thought to improve economic cooperation, livability, and transportation, especially along coastal areas [1–4]. There are more than 20,000 UA in the 151 countries, and research has proved that the urban growth of UA in the 21st century will produce increasingly concentrated cities with high population density [5]. Expansion of these UA is driven not only by the speed of economic development and population growth, but also through collaborative economic linkages between cities, and regional collaborative development has become even more important



Citation: Pan, T.; Yan, F.; Su, F.; Lyne, V.; Zhou, C. Land Use Optimization for Coastal Urban Agglomerations Based on Economic and Ecological Gravitational Linkages and Accessibility. *Land* **2022**, *11*, 1003. https://doi.org/10.3390/ land11071003

Academic Editor: Benedetto Rugani

Received: 1 June 2022 Accepted: 28 June 2022 Published: 1 July 2022

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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). than ever in domestic and foreign competition [1,6]. However, urban expansion in UA is at the expense of limited land resources that increase pressure on the ecological environment and ecosystem services [7]. UA that are sustainable, therefore, need to balance and optimize complex multiple objectives, in order to progress and/or redress development towards balanced integrated ecological sustainability and economic performance.

Future planning for urban agglomerations is evident in China's New Urbanization Strategy, involving the proposed development of five national-level UA [8]. One of these, the Guangdong-Hong Kong-Macau Greater Bay Area (GBA), was strategically initiated in 2015 to strengthen links within the Pearl River Delta (PRD) regions, with countries involved in China's Belt and Road Initiative [4]. GBA's development is, therefore, strategically important to China for economic outcomes, innovation, tourism, and industrial cooperation, as supported by high quality living conditions and environment [1–3,9]. However, GBA is facing major challenges, including serious environmental pollution, social conflicts, and the need for planning options to guide regional collaborative development. Land use optimization strategies for GBA are, therefore, needed to guide collaborative development between cities, as well as for ecological sustainability.

Studies of land use optimization typically focus on the tradeoffs between conflicting objectives, in order to optimize allocations of regional land use using optimization models [10–16]. Sustainable development under constrained land availability invariably leads to conflicts between economic growth and declines in ecosystem services [17]. Increased accessibility and transportation infrastructure can improve regional connectivity, social equity, health, and education [18]; however, they can also lead to regional landscape and habitat fragmentation [19], with flow-on impacts to biodiversity. GDP (gross domestic product) and ESV (ecosystem services value) are often used in the calculation of economic and ecological objectives, respectively; however, the above two objectives do not have the ability to select spatial locations, while compactness has such ability to limit land use fragmentation [20,21].

UA involve similar tradeoffs, but additional polycentric spatial structures arise from correlated attraction forces that increase towards the core of cities, and as well as linkages with neighboring cities [22–25]. The degree of economic linkage affects the capacity of collaborative development among cities, which, in turn, affects the extent of regional synergy and urban expansion [6,26,27]. Analytical studies of economic linkage include network analysis, gravity models, and hierarchical structures. Zhao et al. (2017) used network analysis to show that the Pearl River Delta region was characterized by cross-regional interactions between market-oriented sectors [28]. Shen et al. (2019) found significant east-west gradient differences between counties in Zhejiang [29], and Meng et al. (2021) used gravity models to illustrate barycentric expansion of urbanization, industrialization, and carbon emissions in China [26]. Despite analytical differences, these findings show that UA involve integration and development across regional disparities and gradients. A unifying theme maybe economic linkage intensity (ELI), which has been shown to influence urban expansion [6,30]. However, Chen et al. (2020) found that this relationship between urban expansion and economic linkage is indirect and variable [6]. Further, this aspect is often overlooked in land use optimization models of UA, where ELI between cities may affect collaborative development within regions, and accessibility can effectively strengthen the ties between cities [31]. Hence, this aspect requires further investigation in the land use optimization models of UA.

Optimization of land resources, under multiple conflict objectives, can be modelled using mature intelligent algorithms, such as genetic [21,32–34], simulated annealing [35,36], ant colony [37,38], and particle swarm [15] algorithms. Due to nonlinear tradeoffs between objectives, the overall fitness, representing the balance between objectives, is typically calculated using one of two methods: the weighted-sum method and Pareto frontier. The weighted-sum method set weights for each normalized objective before calculating the weighted sum across objectives, in order to obtain an overall fitness measure. The Pareto frontier obtains a set of preferred solution sets by non-dominated sorting and selects the

results according to the planner's needs [39]. The non-dominated sorting genetic algorithm II (NSGA-II) is a classic metaheuristic algorithm based on GA, and it can obtain Pareto set by non-dominated sorting; it has been widely used for optimizations, due to its good robustness and global search capability [40–42]. For example, it has been successfully applied to land use planning and integrated optimization using system dynamics models [43–45]. However, the complexity of NSGA-II problems often leads to long calculation times, especially in land use optimization. Significant time reductions can be achieved with computationally parallelized NSGA-II [46,47]. Even small computational speedup across numerous repetitive calculations in NSGA-II can provide substantial overall benefits, and parallel processing is a reliable method for achieving computational improvements.

Most previous urban land use optimization studies considered the conflicting relationship between economy and ecology but ignored the role of ecological gradients and economic linkage between cities [13]. This paper assumes that the economic linkages and ecological gradients can play a positive role in the future regional optimization. To simplify the model and emphasize the collaborative development demands of UA, we do not consider the effects of factors such as food security [16,48], environmental deterioration [49], or climate risk [50] on land use optimization and propose a new multi-objective land use optimization of UA that explored the intensity of economic ties and ecological gradients using the multi-objective NSGA-II algorithm. In the rest of this paper, a description of the land use optimization model, consisting of three conflicting objectives, is described first, followed by details of the parallel NSGA-II algorithm used. Subsequently, the model is applied to the Guangdong-Hong Kong-Macao Greater Bay Area (GBA) to assess its agglomeration capabilities, and the results and conclusions are discussed.

2. Materials and Methods

2.1. Materials

Our case study is the Guangdong-Hong Kong-Macao Greater Bay Area (GBA), situated in the Pearl River Delta in China, which includes nine mainland cities and two special administrative regions, namely Guangzhou (GZ), Shenzhen (SZ), Zhuhai (ZH), Zhaoqing (ZQ), Huizhou (HZ), Jiangmen (JM), Dongguan (DG), Foshan (FS), Zhongshan (ZS), Hongkong (HK), and Macao respectively (Figure 1). Covering a total area of 64,823 km², and with a total population of over 66 million at the end of 2015, it is one of the most economically dynamic regions in China. As of 2015, the total GDP reached 6745 billion CNY, where the economic volume and population density are mainly concentrated in HK, SZ, and GZ, and the regional land use shows a spatial gradient of decreasing built-up development from the bay area to the hinterland.

Economic and demographic data were obtained from the statistical yearbooks of each city, which contained the total GDP of primary, secondary, and tertiary industries (Table 1). The ecological control areas data of the GBA were obtained from the website of the Ministry of Natural Resources of the People's Republic of China (http://g.mnr.gov.cn/ (accessed on 21 February 2022)). Land use data (Figure 1), and NDVI data (Figure 2a) were obtained from the Resource and Environmental Science and Data Center, with a resolution of 1×1 km (https://www.resdc.cn/ (accessed on 5 December 2021)). The intensity of urban economic linkage data were obtained from Peng's paper [51], while the road network was obtained from Open Street Map (https://www.openstreetmap.org accessed on 2 December 2021). DEM data (Figure 2b) were obtained from the Shuttle Radar Topography Mission (SRTM, http://srtm.csi.cgiar.org/SELECTION/inputCoord.asp (accessed on 2 December 2021)).

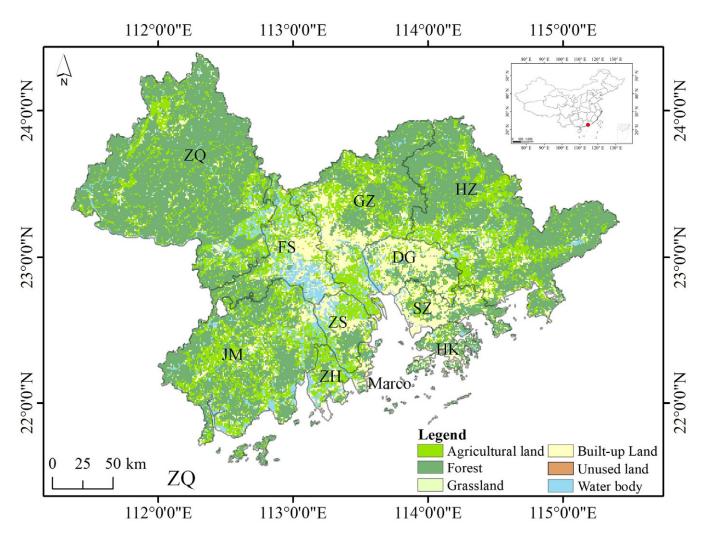


Figure 1. Land use map of the GBA in 2015. For modeling purposes, the land-use map is divided into 509×417 cells, with each cell being 1×1 km in size.

City\Industry (100 Million CNY)	Primary Industry	Secondary Industry	Tertiary Industry
SZ	7.21	7678.10	10,328.76
ZH	48.30	1037.97	980.08
GZ	206.52	5873.54	12,233.74
ZQ	288.22	647.20	342.28
FS	127.29	4975.83	3030.55
HZ	146.13	1768.08	1264.48
DG	19.92	3007.87	3346.51
ZS	59.56	1680.96	1312.27
JM	170.46	1110.76	982.97
HK	1.13	129.23	1547.69
Marco	0.00	207.53	2888.67

Table 1. The GDP of different cities in the Great Bay Area.

Based on the land use data from 1995–2015 (five years for one period), linear regression was used to predict the total built-up land area in 2030 to be 12,371 km². To ensure that the future agricultural land conforms to government planning requirements, we used the data from the 2010–2020 master plan of Guangdong Province for the agricultural land retention projection to estimate agricultural land retention of 8299 km² in 2030, excluding Hong Kong and Macao.

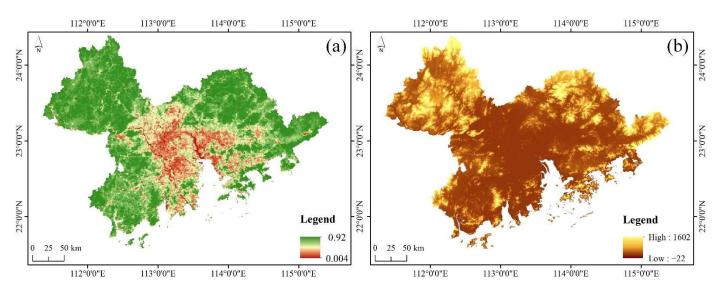


Figure 2. The distribution of NDVI (a) and DEM (b) in the GBA.

2.2. Method

The steps in applying the NSGA-II optimization algorithm are shown in Figure 3. The first step was to derive future land use area constraints for the optimization case study by predicting the future land use structure using a linear model of past trends. Using NSGA-II, we incorporated accessibility and ELI as modification factors and used parallel computational processing to speed up the model.

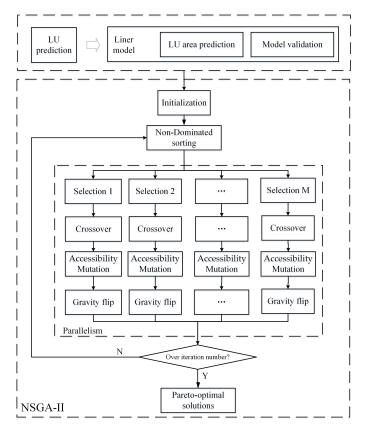


Figure 3. Workflow procedure of the multi-objective NSGA-II land use optimization framework to derive Pareto-optimal solutions. A linear prediction of past land use was used to provide future land use initialization constraints. The NSGA-II algorithm was then applied using non-dominated sorting, cross-over, accessibility mutation, and gravity flip operators, which are described in the main text.

We assumed that the study area was a two-dimensional regular grid (rasterized region). The land use allocation problem was to determine how to assign future (changed) land uses to specific locations, so that the optimal land use pattern balanced the conflicting objectives, based on Pareto front solutions.

To determine constrains for the overall areas of future land use, a linear model was used to extrapolate past trends of land use. In the case study area (described below), we used data of land use from every five years of the past twenty years to forecast land use constraints 15 years into the future. The modified NSGA-II algorithm was then used to determine Pareto front solutions using modified objectives and genetic algorithm procedures described in the next section.

2.2.1. Objectives

(a) Modified GDP

GDP is widely used to measure the level of regional development, and many scholars have adopted this objective in land use optimization [13,20,21,52]. Since different land uses correspond to different industries, the study uses the sector-based classification designed by Cao to calculate the GDP per unit area for different land uses [13], as shown in Table 2.

GDP Group by Sector			Corresponding Land Use
	Farming	-	Agricultural land
Primary industry	Forestry	-	Forest
	Animal husbandry	Cattle, sheep,	Grassland, Agricultural
		chickens, pigs	land
	Fishery	-	Water
Secondary industry	-	-	Built-up land
5	Service on farming	-	Agricultural land
	Service on forestry	-	Forest
Tertiary industry	Service on animal husbandry	-	Agricultural land
	Service on Fishery	-	Water
	Other	-	Built-up land

Table 2. GDP grouped by sector and corresponding land uses (Cao et al. (2019)).

Uneven development reflects complex linkages between, and drivers of, regional and local policies, trade, and market. Rapid urbanization in UA can lead to uneven development, and the strength of economic linkages between cities reflects the potential for regional economic collaborative development, which is closely related to distance, population size, and the level of economic development [1]. The greater the economic linkage intensity (ELI) between cities, the greater the region's capacity for collaborative development. ELI is, therefore, a potential factor that drives change and integrated development in UA. In our study, we tested its incorporation as a spatial modification factor for GDP, in order to guide the direction of collaborative land use change towards regions of higher ELI.

Accessibility, in relation to regional commuting time and reduction in environmental impacts, such as CO₂ emissions, has significant impact on land use status and socioeconomic development [53]. Within a region of several cities, accessibility is a core issue affecting connectivity, livability, and the shaping of UA [31]. Accessibility was, therefore, used as a spatial modification factor for GDP, calculated according to the formula:

Modified GDP =
$$\sum_{k=1}^{K} ELI_k \times GDP_k \times Acc_k$$
 (1)

where ELI_k represents the ELI value in cell k. GDP_k and Acc_k represent the unit GDP value and accessibility value in cell k, respectively. K represent the total number of changed cells.

Factors included in calculating ELI were: total population, GDP, total import and export, and tourism income, based on the gravity model of urban economic linkage data obtained from Peng's paper [51]. ELI data can present the economic influence degree between each city, which have high spatial autocorrelation. Considering that ELI is a function of city quality and spatial distance between cities, which decays exponentially with increasing distance. Kringing is the method use the spatial correlation between sampled point data to interpolate the value in the spatial field. Compared with other interpolation methods, Kringing can preserve spatial variability and generate estimates of uncertainty surrounding interpolated value. Thus, in this paper, Kringing was used in this paper to get the spatial distribution map of ELI.

(b) Modified ESV

ESV is a main factor determining the livability, attractiveness, and ecological health of a region. Obtaining greater economic value with minimal ESV loss is often one of the main goals of land use management. Conventionally, the same land use type is regarded as having the same ESV value, thereby ignoring differences in ESV due, for example, to vegetation densities, which could be used to temper the direction of urban expansion. Therefore, in this paper, the NDVI was used as modified index to identify the vegetation density of the selecting cells. With higher NDVI, there will be a lower chance of change. The modified ESV objective change was calculated by multiplying the unit ESV by the NDVI, using the formula:

Modified ESV =
$$\sum_{k=1}^{K} ESV_k \times NDVI_k$$
 (2)

where *k* represents the changed cell. *K* represent the total number of changed cells. $NDVI_k$ is the value of NDVI in cell *k*. ESV_k is the unit ESV in cell *k*.

(c) Compactness

Compactness is a measure of urban intensification and land use efficiency [14,54]. For any cell, compactness is the number of cells with the same land use type in its eight neighborhoods, i.e., the more cells with the same value in its neighborhood, the higher the compactness. The formula is as follows:

$$Compactness = \sum_{i=1}^{I} (N_i - N'_i)$$
(3)

where N_i and N'_i are the number of cells with the same land use type in *i* cell's eight neighborhoods in the solution and initial pattern, respectively. I represents the total number of cells in the region.

2.2.2. Constraints

Constraints on the regional optimization, detailed later in the case study, are set by the ecological control zone, slope constraint, total agricultural land area constraint, and built-up land area constraint. Additionally, each cell's land use type is unique and, therefore, cannot be converted to another land use type.

2.2.3. Parallel NSGA-II

The NSGA-II algorithm, widely used in land use optimization, was used to obtain the Pareto solution set from multiple non-linear objectives through non-dominated sorting. As shown in Figure 1, improved NSGA-II involved five steps: initialization, non-dominated sorting, selection, crossover, accessibility mutation, and gravity flip. These steps are described below, bearing in mind that a land use pattern represents a chromosome, and each land use cell is called a gene. To reflect economic attraction between cities shaping UA,

we modified the algorithm with a two-step mutation operator and improved the overall computational efficiency through parallel processing.

Initialization: Based on the projected area of each land use in future (2030 in the case study), the land use that needs to be increased is randomly assigned to other land uses, and 100 initial chromosomes are set to form the initial population.

Non-dominated sorting and crowing distance: A selected solution in the search space is a non-dominated solution [55] only if there are no other solutions that are equal in all objectives or better than that solution in at least one objective. Crowding distance is used to choose the better solution on a front shown in Figure 4, which represents the non-dominated sorting of NSGA-II, based on the following process. Assume that the parent is Pi and population after crossover and mutation is T. There are M solutions within the population. First, P and T are combined and then sorted non-dominantly from shortest to longest crowding distance, and the top M chromosomes are selected as the new offspring P_{i+1} .

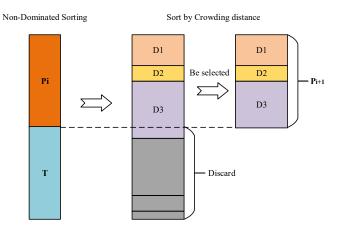


Figure 4. Non-dominated sorting in NSGA-II, where Pi is the parent population while T is the result population after crossover and mutation. P_{i+1} represents the result after non-dominated sorting.

Selection: After non-dominated sorting of the parent population, roulette is performed, based on the crowding distance. The smaller the distance, the higher the probability of being selected.

Crossover: Crossover operator is used to preserve relatively better land-use change patterns under multi-objective constraints and reduce the generation of duplicate individuals. In original NSGA-II, the selected cell in the two parents will be exchanged to form the offspring. Different to the original NSGA-II, the selected cells in our model use maximum count of neighbors' land use to choose whether to change. The procedure for crossover is as follows: after determining the crossover probability, if the number of cells amongst the eight neighbors that are the same as the central cell in Parent1 is less than that in Parent2, crossover is performed by replacing the center cell in Parent1 with the central cell land use in Parent2, as illustrated in Figure 5.

Mutation operator is used to enhance population diversity and prevent the optimization results from falling into a local optimum trap. Original NSGA-II only has one mutation operator. For the selected cell, the land use type of the selected cell is replaced by calculating the highest number of land use types in its eight neighborhoods. Unlike the original NSGA-II, two mutations with implicit economic relationships were set for enabling agglomeration and limiting fragmentation in our model, the procedure for two-step mutation operator is as follows.

Accessibility Mutation: We developed a new mutation operator that used accessibility as a modification factor. Referring to the example in Figure 6, after determining the mutation probability, cell AA (with land use type of built-up land) was selected, and its accessibility value was 0.2, while cell BB was random selected, and its accessibility value was 0.4. Since the accessibility value of BB was higher than AA, the land use type shifted between AA and BB.

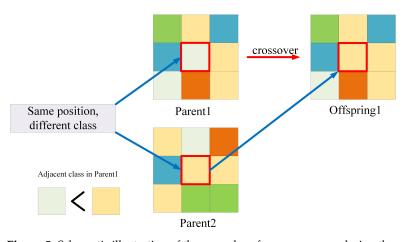


Figure 5. Schematic illustration of the procedure for crossover: replacing the center cell in Parent1 if the new center cell type in Parent2 results in neighbors of the same class that outnumbers those in Parent1.

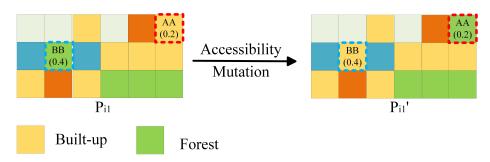


Figure 6. Procedure of mutation, where the selected cell in the parent is changed according to the accessibility value.

Gravity flip: ELI is calculated from the gravity model, and its spatial distribution has a structure similar to a gravity field. Areas with strong gravity attract areas from weak gravity. The spatial linkage of cities can be optimized by gravity flip, which is used to determine if spatial flipping results in an overall stronger impact of the gravity field on modified GDP. As a simple example, where weight = mass × gravity, moving a mass closer to a stronger gravity field results in greater weight. Likewise, moving an area producing GDP closer to a stronger ELI field results in potentially higher GDP generated = original GDP × ELI. Using 3×3 window as unit, the total modified GDP in the original window and solution after gravity flip, which, in this case, corresponds to a transposition, are compared. If the total modified GPD after flipping is higher, then the window will be flipped (Figure 7). Note that vertical and horizontal flipping are possible as options.

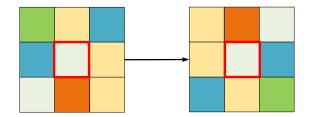


Figure 7. Gravity flip—rotate the 3×3 windows 180 degrees clockwise if it enhances modified GDP.

To summarize, accessibility mutation determines whether the location of a random builtup land cell and another randomly selected non-built-up land cell are exchanged, based on the accessibility value, while gravity flip is implemented if the total modified GDP is higher than the original value when the cells in the 3×3 window are rotated 180 degrees clockwise.

3. Results

3.1. Objective Quantification and Constraints

The spatial constraints were set, based on following restrictions: (1) the total arable land area to be no less than 8299 km² and according to the overall development plan of each city; (2) all changeable cells could not be changed to unused land; (3) slopes less than 15 degrees can be built-up land, less than 25 degrees can be cropland, and more than 25 degrees can only be forest; (4) all ecological control area and water could not be changed (Figure 8). All the restrictions are not only applied in the initialization process, but also play an important role in constraining the global situation.

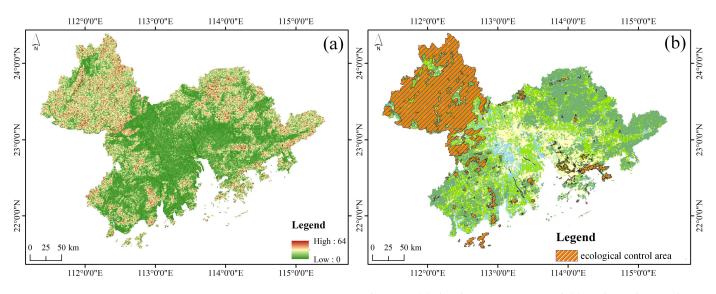


Figure 8. Constraints in GBA, in relation to (**a**) the slope constraint and (**b**) ecological control area, that cannot be changed.

Parameters were set as follows: the unit ESV of each land use is derived from the results of Xie's assessment, as shown in Table 3 [56]. GDP is calculated, with reference to Cao's study, and the unit GDP values of each land use are shown in Table 3 [13]. The initial spatial distributions of GDP and ESV (Figure 9) were obtained using ArcGIS. This paper uses Peng's results of ELI for the Greater Bay Area [51]. Accessibility is expressed by road network density, and its spatial distribution was obtained in arcGIS (Figure 10) after applying the normalization method in Pan's model [21].

Table 3. The unit ESV and GDP in each land use type.

Land Use	ESV (Million CNY $ imes$ km ⁻² $ imes$ a ⁻¹)	GDP (100 Million CNY \times km^-2)
Cropland	0.355	0.104
Forest	0.524	0.004
Grassland	1.263	0.012
Water	2.037	0.137
Built-up land	0	8.4

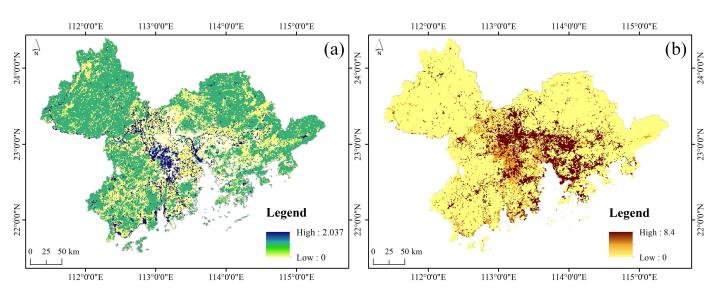


Figure 9. The initial spatial distribution of ESV (a) and GDP (b).

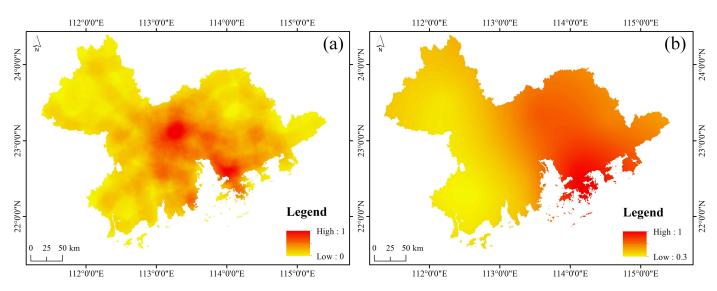


Figure 10. The spatial distribution of normalized accessibility (a) and ELI (b).

3.2. Implementation and Evaluation

A total of 100 random patterns were used as the initial population, based on probabilities of crossover, accessibility mutation, and gravity flip of 0.06, 0.1, and 0.1, respectively. A total of 600 iterations were simulated, in order to optimize the three conflicting objectives under constraints on the agricultural land total and ecological control areas. We found that parallel NSGA-II outperformed classical NSGA-II in execution, taking 16.71 s in each iteration, while classical NSGA-II took 151.63 s.

The progress of iterations (Figure 11a) shows that the solutions achieved a better spread across the three objectives, with the respect to the overall optimization, but improvements become smaller and smaller. To illustrate the convergence trend in the model, we use minimum modified ESV, shown in Figure 11b, which showed a rapid decrease up to 90 iterations and then an almost static phase through successive iterations. The curve appears stable after 212 iterations, implying the solution process efficiently approaches near-optimality relatively quickly.

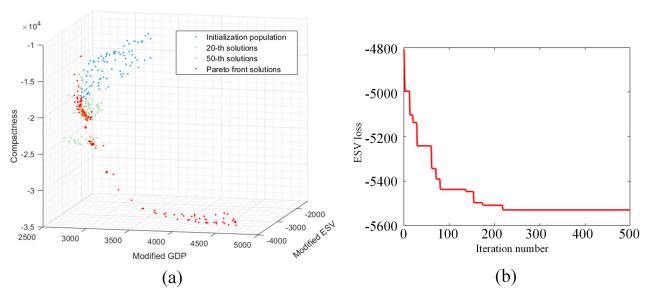


Figure 11. The joint distribution of three objectives (**a**), and the convergence curve of modified ESV change (**b**) with iteration. In (**a**), the objective values are shown at different iteration stages: the blue points represent the initial random population; the green and orange points represent the 20-th and 50-th generation solutions, respectively; the red points are the final result.

In Figure 11a, modified ESV and compactness both change negatively to modified GDP, and the pattern with smallest compactness loss also has smallest modified ESV loss. Taking each preferred solution as an example of the optimal solution set, the following specific solutions are possible: Solution I (SI)-the pattern with the highest modified GDP; Solution II (SII)-the pattern with minimal modified ESV loss; Solution III (SIII)-the pattern with minimal compactness loss. To demonstrate the superiority of our model, solutions from the classic NSGA-II approach were also simulated. In this approach, the GDP and ESV were not affected by their spatial location, and cells selected in mutation changed their land use values randomly. Solution IV (SIV)-was obtained from the classic NSGA-II for comparison with SI, due to the almost identical increments of build-up land, ESV loss, and compactness loss. The objective values in SIV were recalculated according to our proposed method to facilitate the comparison. The comparative results from the different solutions are shown below (Figure 12, Tables 4 and 5). We did not count the percentage change in unused land because the total area of unused land is almost zero. For comparison purposes, the spatial distribution of land use and built-up land increment for each scenario are shown in Figure 12.

Scenario\Objective Value	Modified GDP Change	Modified ESV Change	Compactness Change
SI (GDP)	19.22%	-11.48%	-8.67%
SII (ESV)	9.28%	-8.03%	-4.75%
SIII (Compactness)	9.17%	-9.18%	-4.69%
SIV (NSGA-II)	11.81%	-10.94%	-8.67%

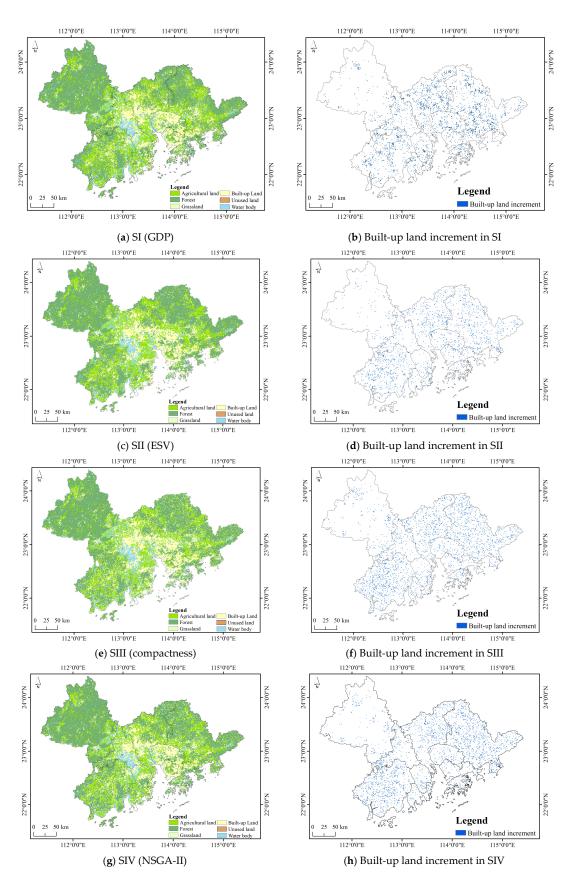


Figure 12. Distribution of land use for simulation scenarios: SI (GDP)—optimal GDP objective; SII (ESV)—optimal ESV objective; SIII (compactness)—optimal compactness objective; SIV (NSGA-II)— baseline NSGA-II algorithm, without ELI, accessibility, or NDVI. Left panels show final simulated land use patterns, while right side panels show the corresponding built-up land increment changes.

Scenario\Area Change (%)	Cropland	Forest	Grassland	Built-Up Land
Initial Pattern	14929	35004	1472	8806
SI (GDP)	1.36%	-8.84%	0.34%	32.88%
SII (ESV)	0.07%	-6.38%	-8.63%	26.89%
SIII (Compactness)	-0.13%	-7.52%	-7.88%	31.56%
SIV (NSGA-II)	-4.88%	-9.00%	54.48%	33.08%

Table 5. The Area change of land use under different scenarios.

SI (GDP), SII (ESV), and SIII (compactness) achieved better scores, with respect to their preferred objectives. In SI (GDP), built-up land increased by 32.88%, forest and cropland decreased 8.84% and 1.36%, respectively, while grassland increased by 0.34%. Compared to SII (ESV), more built-up land increment in SI (GDP) led to a greater decline in modified ESV and compactness. In SII (ESV), although most of the built-up land increment comes from forest, grassland is used more for land use transfer thereby reducing the amount of forest transfer, in a way that minimizes the modified ESV reduction while built-up land increased. Almost identical ESV and compactness value in SI and SIV with the same built-up land increased increment, the modified GDP value in SI was significantly higher than SIV (7.41%), which illustrates the superiority of our model in getting better pattern with higher economic output.

Comparing the spatial distribution of built-up land increments across scenarios, the inclusion of ELI, accessibility and NDVI as modifying factors appears to positively affect the trend of urban expansion. The cluster of built-up land increments in SII (ESV) is worse than SI (GDP), reflecting that modified ESV increased for more decentralized patterns of built-up land increments. Although SIII (Compactness) have the least loss of compactness, the cluster of built-up land increments is worse than SI (GDP), reflecting the limited role of compactness objective on the distribution of built-up land clustering. In addition, the built-up land increment in SIV is spatially evenly distributed without clustering, this phenomenon arises because spatial agglomeration can only be controlled through the compactness objective, without influences from gravitation attraction of ELI, accessibility, and ESV.

The ELI increments were 1072 and 993 for SI and SIV and the accessibility increments were 773 and 565 for SI and SIV, respectively; implying that SI has higher ELI and accessibility with the same built-up land increment. Compared with SIV, the spatial distribution of built-up land increment is more clustered in SI, reflecting the role of modified GDP in spatial agglomeration proposed by our model. To explore the advantages of the modified ESV, we divided NDVI into three level by natural break method, and analyzed the amount of vegetation transfer at different levels in SI and SIV (Table 6). The total changed percent of vegetation (cropland, grassland, and forest) of high level in SIV was 7.92% higher than SI, indicating the effectiveness of our model in optimizing selection of low value vegetation for changes.

Table 6. The change of vegetation transfer at different levels in SI and SIV.

Scenario\Change of Vegetation (%)	Low	Medium	High
SI	3.81%	24.25%	71.94%
SIV	2.43%	17.71%	79.86%

4. Discussion

In the past decades, many scholars have conducted regional land use optimization studies and focused on multi-objective trade-offs, as well as model improvements [20,57–59]; however, few studies take the effect of inner-city economic linkages and ecological gradient on land use changes in UA into account [13,60]. Cao have proposed land use optimization for urban agglomerations, but he focused on the intermediate process of change between

the initial and future patterns and ignored the intrinsic characteristics of urban agglomerations [13]. Some scholars have discussed the role of economic linkages for regional collaborative development [31], these studies cannot identify the spatial location preferences of land use. Meanwhile, although objectives, such as soil erosion and climate risk are still important factors for high quality development of UA [49,50], this model argues that using too many objectives would confuse the focus of the study, so only the three objectives with the highest universality are chosen (GDP, ESV, and compactness) and modified to meet the regional collaborative development needs.

In this model, ELI and accessibility were introduced into modified GDP, while NDVI was used in modified ESV; the modification not only give economic and ecological objective a quantitative meaning, but also the ability of spatial location preference for enabling agglomeration, whereas the above objectives had only a quantitative function in the previous study [13,20]. Additionally, original NSGA-II used a neighbor-change method to reduce the fragmentation [40,42]. In our model, spatial allocation with implicit economic relationships was enhanced through a two-step mutation operator to limit fragmentation. The results show that our model is able to promote agglomeration and optimize ecological objectives around higher value vegetation. Our framework appears to provide more relevant future land use planning solutions that can comprehensively and efficiently simulate UA around different objective priorities.

Although this paper establishes a land use optimization framework applicable to UA, it still has some limitations. Firstly, the raster-based optimization could be more practical if we adopt land use zones or patches as optimization units. Additionally, UA are complex, and the variety of urban development across regions is more pronounced than inland UA—for example, from regional linkages. Computationally, vertical and horizontal gravity flips should be tested, in addition to the rotation used, and more continuous measures of vegetation density could be used. Additionally, risk objectives, such as heat risk and soil erosion risk, may be required in the optimization process, in order to determine the long-term livability of regions. Despite shortcomings, our study provides a good reference and strategy for future planning of UA.

5. Conclusions

This study established a new multi-objective land use optimization of UA that explored the intensity of economic ties and ecological gradients using the multi-objective NSGA-II algorithm. Three conflicting objectives (modified GDP, modified ESV, and compactness) were proposed. ELI and accessibility factors were proposed as modifying factors for GDP. NDVI were used to modify ESV and limit development within high-value vegetation. Accessibility mutation and gravity flip mutation were constructed for enabling agglomerations. The parallel process was applied in NSGA-II by making eight chromosomes run simultaneously in each iteration, which improved the model efficiency in execution. On this basis, the model was used to optimize the land-use layout in GBA in 2030. A Pareto set was obtained, and its optimization performance was evaluated.

The optimization results showed that the performance of our model was better than original NSGA-II. The value of modified GDP of our model was 7.41% higher than the original NSGA-II for almost the same built-up land increment. Anyway, the comparison showed that our model reduced the conversion rate of high-density vegetation (7.92%) and select relatively low- and medium-density vegetation for built-up land development. The reason for these improvements is that ELI and accessibility caused the clustering of cities, which enhanced modified GDP performance, and the modified ESV preferentially optimized ecological objectives around higher value vegetation. However, prioritizing planning around the modified ESV favored decentralized built-up development.

Our model provided a set of relative optimum land-use arrangements that meet the requirements of the ecological red line, and it has shown high robustness and flexibility in multiple-objective land-use optimization problems. It could simultaneously optimize the land-use spatial layout and improve the economic benefits, without negative effects on

ecological benefits and spatial compactness. In 2030, the newly-developed built-up land was reasonably deployed. Decision makers can observe the optimal land-use allocation schemes and select one according to their priorities. Considering collaborative development and ecological sustainability, in 2030, the increment of built-up land in GBA mainly comes from forest. Guangzhou has the largest increase in built-up land. The GBA's spatial optimization needs to adjust measures according to local conditions, adopt strategies according to the categories, cooperate as a whole to promote the core drive capability of Guangzhou, Shenzhen, push the coordinated development of all cities to improve the overall competitiveness of the region, and achieve high quality development.

Author Contributions: All authors contributed to this manuscript. T.P. conceived the research and collected all the data; F.S. and T.P. designed the experiment and drafted the manuscript; V.L., F.Y. and C.Z. provided help with the language and reviewed the manuscript. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by the National Natural Science Foundation of China, grant number 41890854.

Institutional Review Board Statement: No applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: To access the data please contact the authors.

Conflicts of Interest: The authors declare no conflict of interest.

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