

Article

Periodicity on Neutral-Type Inertial Neural Networks Incorporating Multiple Delays

Jian Zhang ^{1,2} , Ancheng Chang ^{3,*} and Gang Yang ⁴

¹ School of Mathematics and Statistics, Changsha University of Science and Technology, Changsha 410114, China; zhangjian@stu.csust.edu.cn

² Hunan Provincial Key Laboratory of Mathematical Modeling and Analysis in Engineering, Changsha 410114, China

³ Department of Mathematics, Hunan University of Information Technology, Changsha 410151, China

⁴ School of Science, Hunan University of Technology and Business, Changsha 410205, China; yanggangmath@hutb.edu.cn

* Correspondence: webmaster@hnuit.edu.cn

Abstract: The classical Hopfield neural networks have obvious symmetry, thus the study related to its dynamic behaviors has been widely concerned. This research article is involved with the neutral-type inertial neural networks incorporating multiple delays. By making an appropriate Lyapunov functional, one novel sufficient stability criterion for the existence and global exponential stability of T -periodic solutions on the proposed system is obtained. In addition, an instructive numerical example is arranged to support the present approach. The obtained results broaden the application range of neutral-types inertial neural networks.

Keywords: neutral-type inertial neural networks; periodic solution; exponential stability; multiple delays



Citation: Zhang, J.; Chang, A.; Yang, G. Periodicity on Neutral-Type Inertial Neural Networks Incorporating Multiple Delays. *Symmetry* **2021**, *13*, 2231. <https://doi.org/10.3390/sym13112231>

Academic Editors: Quanxin Zhu, Fanchao Kong and Zuwei Cai

Received: 23 October 2021
Accepted: 12 November 2021
Published: 22 November 2021

Publisher's Note: MDPI stays neutral with regard to jurisdictional claims in published maps and institutional affiliations.



Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (<https://creativecommons.org/licenses/by/4.0/>).

1. Introduction

The well-known inertial neural networks (INNs) were first introduced by Babcock and Westervelt [1,2], and can be expressed as the following functional differential equations:

$$s_j''(t) = -a_j s_j'(t) - b_j s_j(t) + \sum_{k=1}^n c_{jk} f_k(s_k(t)) + \sum_{k=1}^n d_{jk} f_k(s_k(t - \tau_{jk})) + I_j, \quad t \geq 0, \quad (1)$$

with the initial value conditions:

$$s_j(v) = \varphi_j(v), \quad s_j'(0) = \psi_j, \quad -\tau_j^+ \leq v \leq 0, \quad \varphi_j \in C([- \tau_j^+, 0], \mathbb{R}), \quad \psi_j \in \mathbb{R}, \quad (2)$$

where $\tau_j^+ = \max_{1 \leq k \leq n} \{\tau_{jk}\}$, $s(t) = (s_1(t), s_2(t), \dots, s_n(t))$ represents the state vector, $s_j''(t)$ is referred to an inertial item of the j -th neuron on (1), the parameters $a_j > 0$, $b_j > 0$, c_{jk} , d_{jk} and time delay $\tau_{jk} \geq 0$ are real numbers, I_j is the external input, f_k is a continuous activation function, $j, k \in \mathfrak{N} := \{1, 2, \dots, n\}$.

During the past thirty decades, by utilizing the reduced-order transformation, numerous studies have been conducted on the stability and synchronization of system (1) and its generalizations, such as [3–11]. However, the reduced-order method will affect the dimensions of systems, thereby increasing a large amount of calculation, which will make it difficult to achieve in practice. For the sake of avoiding the traditional reduced-order method, the authors proposed several new criteria for the stability and synchronization of the system (1) in [12,13] through making a new Lyapunov functional. On this basis, references [14–21] extensively studied various dynamic behaviors of system (1) and its generalizations via applying the non-reduced order approach.

It is well known that the classical Hopfield neural networks have obvious symmetry, numerous researchers have carried out extensive research on its related dynamic behaviors [16,22–24]. In particular, the authors in [25] investigate the exponential stability and the almost sure exponential stability for a class of stochastic fuzzy Cohen-Grossberg neural networks by fabricating an appropriate Lyapunov functional. In practical application, owing to the finite switching and transmission speeds of signals in the networks, the existence of time delays is inevitable in the working networks. It should be pointed out that in addition to the state itself, there are also time delays in the derivatives of the state related to the networks. This kind of delay is deemed as neutral delay, which not only appears in the field of automatic control and population ecology [26,27], but also occurs in many physical systems, including transmission lines, Lotka–Volterra systems, chemical reactors, and others [23,24,28,29]. Particularly, if we use differential equations to model neural networks (NNs) for the realization of electronic circuits, the influence of neutral delay often exists. The authors in [24,29] investigated the effect of neutral delays on the partial element equivalent circuit. The circuit was represented to a neutral-type functional differential equation, and some new sufficient stability assertions were given by Lyapunov theory. Furthermore, the dynamic behaviors of neutral-type inertial neural networks (NTINNs) have been extensively studied by exploiting the reduced-order approach. For example, the authors in [30] used the finite-time stability theory, inequality techniques and analysis approaches to research the finite-time synchronization on fuzzy NTINNs. In [31], the stability of NTINNs is studied via utilizing the Lyapunov–Krasovskii functional approach and Linear Matrix Inequality (LMI) analysis.

On the other hand, periodic phenomena are widespread in biological systems. For instance, seasonal influences of weather and food supplies, electronic systems, NNs etc. Especially in the application of NNs, periodic phenomenon is one of the most important dynamic behaviors to describe the symmetry of the Hopfield neural networks model, and the existence and stability of periodic solutions will help us to understand the asymptotic behavior of mathematical biological systems. Therefore, it is a very meaningful thing to research the existence and stability of periodic solutions [24,32]. However, few researches have discussed the periodic problem of the following NTINNs involving multiple delays:

$$s_j''(t) - \sum_{k=1}^n e_{jk} s_k''(t - \zeta_{jk}) = -a_j s_j'(t) - b_j s_j(t) + \sum_{k=1}^n c_{jk} f_k(s_k(t)) + \sum_{k=1}^n d_{jk} f_k(s_k(t - \tau_{jk})) + I_j(t), \quad t \geq 0, \quad (3)$$

with the initial conditions:

$$s_j(v) = \varphi_j(v), \quad s_j'(v) = \psi_j(v), \quad s_j''(v) = \zeta_j(v), \quad -\sigma_j \leq v \leq 0, \quad \varphi_j, \psi_j, \zeta_j \in C([- \sigma_j, 0], \mathbb{R}), \quad (4)$$

where $\zeta_j^+ = \max_{1 \leq k \leq n} \{\zeta_{jk}\}$, $\sigma_j = \max\{\tau_j^+, \zeta_j^+\}$, e_{jk} and the multiple neutral delays $\zeta_{jk} \geq 0$ are constants, $I_j(t)$ is a continuous periodic function involving period $T > 0$, and $j, k \in \mathfrak{N}$.

Enlightened by the above arguments, our major purpose in this article is to investigate the existence and stability of periodic solutions on NTINNs involving multiple delays through constructing a new and appropriate Lyapunov functional to replace the traditional reduced-order approach. Briefly speaking, the innovative contents of this article can be presented as below. (1) A class of NTINNs involving multiple delays is proposed; (2) Under certain assumptions, by exploiting the non-reduced order approach, one new sufficient stability criterion to guarantee the existence and stability of the T -periodic solutions on system (3) is gotten for the first time; (3) NTINNs here are second-order and involve multiple neutral delays, which are different from the traditional NNs [33–40] or INNs [3–9,11–15,17–21,30–32]. Compared with the results on exponential stability for the neutral-type neural networks (NTNNs) [26,29,39,41] and INNs [13,14,18,19], we give the exponential stability of the T -periodic solution for the NTINNs. (4) An instructive

numerical simulation including comparisons is afforded to demonstrate the obtained theoretical results.

This article is systematized as below. In Section 2, a few indispensable lemmas, definitions and assumptions are given. In Section 3, the global exponential stability on the T -periodic solutions of the NTINNs (3) is proved. In Section 4, an instructive numerical simulation is afforded to evidence the validity and feasibility of the analytical results. A concise conclusion is offered in Section 5.

2. Preliminaries

Throughout this article, a few indispensable lemmas, definitions and assumptions are provided, which are useful in the following proving process.

Assumption 1. *There is a nonnegative real number L_j obeying*

$$|f_j(p) - f_j(q)| \leq L_j|p - q|, \text{ for all } p, q \in \mathbb{R} \text{ and } j \in \mathfrak{N}.$$

Assumption 2. *For $j \in \mathfrak{N}$, there remain three real numbers $\bar{\delta}_j \geq 0, \bar{\beta}_j \geq 0$ and $\bar{\alpha}_j > 0$ agreeing with that*

$$\mathcal{X}_j < 0, \quad 4\mathcal{Y}_j\mathcal{X}_j > \mathcal{Z}_j^2, \tag{5}$$

where

$$\begin{aligned} \mathcal{X}_j &= \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| + 2\bar{\alpha}_j\bar{\beta}_j + \sum_{k=1}^n \bar{\alpha}_j\bar{\beta}_j |e_{jk}| - 2a_j\bar{\alpha}_j^2 + \sum_{k=1}^n \bar{\alpha}_j^2 |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j^2 |d_{jk}| \\ &\quad + \sum_{k=1}^n a_j\bar{\alpha}_j^2 |e_{jk}| + \sum_{k=1}^n a_j\bar{\alpha}_j\bar{\beta}_j |e_{jk}| + \sum_{k=1}^n B_{kj}^1 + \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^1, \\ \mathcal{Y}_j &= \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| + \sum_{k=1}^n b_j\bar{\alpha}_j^2 |e_{jk}| - 2b_j\bar{\alpha}_j\bar{\beta}_j + \sum_{k=1}^n \bar{\alpha}_j\bar{\beta}_j |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j\bar{\beta}_j |d_{jk}| \\ &\quad + \sum_{k=1}^n b_j\bar{\alpha}_j\bar{\beta}_j |e_{jk}| + (\sum_{k=1}^n \bar{\alpha}_k^2 |c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l^2 |e_{lk}| |e_{lj}| + \sum_{k=1}^n \bar{\alpha}_k\bar{\beta}_k |c_{kj}| \\ &\quad + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l\bar{\beta}_l |e_{lk}| |c_{lj}|) L_j^2 + \sum_{k=1}^n A_{kj}^1 + \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^1 + (\sum_{k=1}^n C_{kj} + \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl}) L_j^2, \\ \mathcal{Z}_j &= 2(\bar{\delta}_j + \bar{\beta}_j^2) - 2b_j\bar{\alpha}_j^2 - 2a_j\bar{\alpha}_j\bar{\beta}_j, \end{aligned}$$

and

$$\begin{aligned} A_{kj}^1 &= [\bar{\delta}_k + \bar{\beta}_k^2 + (a_k + b_k)\bar{\alpha}_k\bar{\beta}_k] |e_{kj}|, \quad \tilde{A}_{kjl}^1 = \bar{\alpha}_k\bar{\beta}_k (|c_{kl}| + |d_{kl}|) |e_{kj}|, \\ B_{kj}^1 &= (\bar{\delta}_k + \bar{\beta}_k^2 + 2\bar{\alpha}_k\bar{\beta}_k + a_k\bar{\alpha}_k^2 + b_k\bar{\alpha}_k^2) |e_{kj}|, \\ \tilde{B}_{kjl}^1 &= ((\bar{\delta}_k + \bar{\beta}_k^2 + 2\bar{\alpha}_k\bar{\beta}_k) |e_{kl}| + \bar{\alpha}_k^2 (|c_{kl}| + |d_{kl}|)) |e_{kj}|, \\ C_{kj} &= (\bar{\alpha}_k^2 + \bar{\alpha}_k\bar{\beta}_k) |d_{kj}|, \quad \tilde{C}_{kjl} = (\bar{\alpha}_k + \bar{\beta}_k)\bar{\alpha}_k |e_{kl}| |d_{kj}|, \quad j, k, l \in \mathfrak{N}. \end{aligned}$$

Definition 1. *Given $x(t) = (x_1(t), x_2(t), \dots, x_n(t))$ and $y(t) = (y_1(t), y_2(t), \dots, y_n(t))$ as two solutions of the NTINNs (3) to satisfy*

$$\begin{aligned} x_j(v) &= \varphi_j^x(v), \quad x_j'(v) = \psi_j^x(v), \quad x_j''(v) = \zeta_j^x(v), \\ y_j(v) &= \varphi_j^y(v), \quad y_j'(v) = \psi_j^y(v), \quad y_j''(v) = \zeta_j^y(v), \quad j \in \mathfrak{N}, \end{aligned} \tag{6}$$

where $\varphi_j^x, \psi_j^x, \zeta_j^x, \varphi_j^y, \psi_j^y, \zeta_j^y \in C([- \sigma_j, 0], \mathbb{R})$. The NTINNs (1.3) is said to have global exponential stability when there are constants $\lambda > 0$ and $\Lambda = \Lambda(\varphi^x, \psi^x, \zeta^x, \varphi^y, \psi^y, \zeta^y) > 0$ obeying that

$$|x_j(t) - y_j(t)| \leq \Lambda e^{-\lambda t}, \quad |x_j'(t) - y_j'(t)| \leq \Lambda e^{-\lambda t}, \quad \text{for all } t \in [0, +\infty) \text{ and } j \in \mathfrak{N}.$$

Lemma 1. Under the Assumptions 1 and 2, every solution of NTINNs (3) incorporating initial values (4) exists and is unique on $[0, +\infty)$.

Proof. At first, set

$$\iota = \min_{1 \leq j \leq n} \{ \tau_j^-, \zeta_j^- \}, \quad w_j(t) = s_j(t) - \sum_{k=1}^n e_{jk} s_k(t - \zeta_{jk}),$$

where $\tau_j^- = \min_{1 \leq k \leq n} \{ \tau_{jk} \}$, $\zeta_j^- = \min_{1 \leq k \leq n} \{ \zeta_{jk} \}$ and $j \in \mathfrak{N}$. Now, we prove that $s_j(t)$ exists and is unique on $[0, \iota]$. Actually, for all $t \in [0, \iota]$ and $j \in \mathfrak{N}$,

$$\begin{aligned} w_j''(t) &= s_j''(t) - \sum_{k=1}^n e_{jk} s_k''(t - \zeta_{jk}) \\ &= -a_j s_j'(t) - b_j s_j(t) + \sum_{k=1}^n c_{jk} f_k(s_k(t)) + \sum_{k=1}^n d_{jk} f_k(s_k(t - \tau_{jk})) + I_j(t) \\ &= -a_j w_j'(t) - b_j w_j(t) - a_j \sum_{k=1}^n e_{jk} \psi_k(t - \zeta_{jk}) - b_j \sum_{k=1}^n e_{jk} \varphi_k(t - \zeta_{jk}) \\ &\quad + \sum_{k=1}^n c_{jk} f_k(w_k(t)) + \sum_{j=1}^n e_{kj} \varphi_j(t - \zeta_{kj}) + \sum_{k=1}^n d_{jk} f_k(\varphi_k(t - \tau_{jk})) + I_j(t). \end{aligned} \tag{7}$$

From the Assumption 1, one can discover that the solution $w(t)$ of the second order ordinary differential Equation (7) with initial conditions $w(0) = \{ \varphi_j(0) - \sum_{k=1}^n e_{jk} \varphi_k(-\zeta_{jk}) \}$ and $w'(0) = \{ \psi_j(0) - \sum_{k=1}^n e_{jk} \psi_k(-\zeta_{jk}) \}$ exists and is unique on $[0, \iota]$. Consequently, $s(t) = w(t) + \{ \sum_{k=1}^n e_{jk} \varphi_k(t - \zeta_{jk}) \}$ exists and is unique on $[0, \iota]$. Using the same method, one can discover $s(t) = w(t) + \{ \sum_{k=1}^n e_{jk} \varphi_k(t - \zeta_{jk}) \}$ exists and is unique on $[\iota, 2\iota], [2\iota, 3\iota], \dots$. Hence, every solution of NTINNs (3) incorporating initial values (4) exists and is unique on $[0, +\infty)$. \square

Lemma 2. Under the Assumptions 1 and 2, NTINNs (3) possess global exponential stability.

Proof. Label $u_j(t) = x_j(t) - y_j(t)$, then

$$\begin{aligned} u_j''(t) - \sum_{k=1}^n e_{jk} u_k''(t - \zeta_{jk}) &= -a_j u_j'(t) - b_j u_j(t) + \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) \\ &\quad + \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})), \end{aligned} \tag{8}$$

where

$$\tilde{f}_k(u_k(t)) = f_k(x_k(t)) - f_k(y_k(t)), \quad \tilde{f}_k(u_k(t - \tau_{jk})) = f_k(x_k(t - \tau_{jk})) - f_k(y_k(t - \tau_{jk})).$$

In view of the Assumption 2 and the boundedness of NTINNs (3), one can select a real number $\lambda > 0$ such that

$$\mathcal{X}_j^\lambda < 0, \quad 4\mathcal{Y}_j^\lambda \mathcal{X}_j^\lambda > (\mathcal{Z}_j^\lambda)^2, \tag{9}$$

where

$$\begin{aligned} \mathcal{X}_j^\lambda &= \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| + \lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j + \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + \bar{\alpha}_j \bar{\beta}_j) |e_{jk}| \\ &\quad - 2a_j \bar{\alpha}_j^2 + \sum_{k=1}^n \bar{\alpha}_j^2 |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j^2 |d_{jk}| + \sum_{k=1}^n a_j \bar{\alpha}_j^2 |e_{jk}| + \sum_{k=1}^n a_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| \\ &\quad + \left(\sum_{k=1}^n B_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^2 \right) e^{\lambda \xi_{kj}}, \\ \mathcal{Y}_j^\lambda &= \lambda (\bar{\delta}_j + \bar{\beta}_j^2) + \lambda \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| + \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| \\ &\quad + \sum_{k=1}^n b_j \bar{\alpha}_j^2 |e_{jk}| - 2b_j \bar{\alpha}_j \bar{\beta}_j + \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |d_{jk}| + \sum_{k=1}^n b_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| \\ &\quad + \left(\sum_{k=1}^n \bar{\alpha}_k^2 |c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k^2 |e_{lk}| |e_{lj}| + \sum_{k=1}^n \bar{\alpha}_k \bar{\beta}_k |c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l \bar{\beta}_l |e_{lk}| |c_{lj}| \right) L_j^2 \\ &\quad + \left(\sum_{k=1}^n A_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^2 \right) e^{\lambda \xi_{kj}} + \left(\sum_{k=1}^n C_{kj} + \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl} \right) L_j^2 e^{\lambda \tau_{kj}}, \\ \mathcal{Z}_j^\lambda &= 2(\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) - 2b_j \bar{\alpha}_j^2 - 2a_j \bar{\alpha}_j \bar{\beta}_j \end{aligned}$$

and

$$\begin{aligned} A_{kj}^2 &= \lambda (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kj}| + (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2 + (a_k + b_k) \bar{\alpha}_k \bar{\beta}_k) |e_{kj}|, \\ \tilde{A}_{kjl}^2 &= (\bar{\alpha}_k \bar{\beta}_k (|c_{kl}| + |d_{kl}|) + \lambda (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kl}|) |e_{kj}|, \\ B_{kj}^2 &= (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2 + \lambda \bar{\alpha}_k^2 + 2\bar{\alpha}_k \bar{\beta}_k + a_k \bar{\alpha}_k^2 + b_k \bar{\alpha}_k^2) |e_{kj}|, \\ \tilde{B}_{kjl}^2 &= ((\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2 + \lambda \bar{\alpha}_k^2 + 2\bar{\alpha}_k \bar{\beta}_k) |e_{kl}| + \bar{\alpha}_k^2 (|c_{kl}| + |d_{kl}|)) |e_{kj}|, \quad j, k, l \in \mathfrak{N}. \end{aligned}$$

Set

$$z_j(t) = u_j(t) - \sum_{k=1}^n e_{jk} u_k(t - \xi_{jk}),$$

then

$$z'_j(t) = u'_j(t) - \sum_{k=1}^n e_{jk} u'_k(t - \xi_{jk}),$$

and

$$z''_j(t) = u''_j(t) - \sum_{k=1}^n e_{jk} u''_k(t - \xi_{jk}),$$

which yield that

$$z''_j(t) = -a_j u'_j(t) - b_j u_j(t) + \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) + \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})). \tag{10}$$

Construct the Lyapunov functional:

$$W(t) = \sum_{j=1}^4 W_j(t), \tag{11}$$

where

$$\begin{aligned}
 W_1(t) &= \sum_{j=1}^n \bar{\delta}_j z_j^2(t) e^{\lambda t} + \sum_{j=1}^n (\bar{\alpha}_j z_j'(t) + \bar{\beta}_j z_j(t))^2 e^{\lambda t}, \\
 W_2(t) &= \sum_{j=1}^n \sum_{k=1}^n \int_{t-\zeta_{kj}}^t A_{kj}^2 u_j^2(v) e^{\lambda(v+\zeta_{kj})} dv + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \int_{t-\zeta_{kj}}^t \tilde{A}_{kjl}^2 u_j^2(v) e^{\lambda(v+\zeta_{kj})} dv, \\
 W_3(t) &= \sum_{j=1}^n \sum_{k=1}^n \int_{t-\zeta_{kj}}^t B_{kj}^2 (u_j'(v))^2 e^{\lambda(v+\zeta_{kj})} dv + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \int_{t-\zeta_{kj}}^t \tilde{B}_{kjl}^2 (u_j'(v))^2 e^{\lambda(v+\zeta_{kj})} dv, \\
 W_4(t) &= \sum_{j=1}^n \sum_{k=1}^n \int_{t-\tau_{kj}}^t C_{kj} \tilde{f}_j^2(u_j(v)) e^{\lambda(v+\tau_{kj})} dv + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \int_{t-\tau_{kj}}^t \tilde{C}_{kjl} \tilde{f}_j^2(u_j(v)) e^{\lambda(v+\tau_{kj})} dv.
 \end{aligned}$$

Firstly, the derivative of $W_1(t)$ along the trajectories of NTINNs (10) is obtained as follows:

$$\begin{aligned}
 W_1'(t) &= \lambda \sum_{j=1}^n \bar{\delta}_j z_j^2(t) e^{\lambda t} + 2 \sum_{j=1}^n \bar{\delta}_j z_j(t) z_j'(t) e^{\lambda t} + \lambda \sum_{j=1}^n (\bar{\alpha}_j z_j'(t) + \bar{\beta}_j z_j(t))^2 e^{\lambda t} \\
 &\quad + 2 \sum_{j=1}^n (\bar{\alpha}_j z_j'(t) + \bar{\beta}_j z_j(t)) (\bar{\alpha}_j z_j''(t) + \bar{\beta}_j z_j'(t)) e^{\lambda t} \\
 &= \lambda \sum_{j=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) z_j^2(t) e^{\lambda t} + 2 \sum_{j=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) z_j(t) z_j'(t) e^{\lambda t} \\
 &\quad + \sum_{j=1}^n (\lambda \bar{\alpha}_j^2 + 2 \bar{\alpha}_j \bar{\beta}_j) (z_j'(t))^2 e^{\lambda t} + 2 \sum_{j=1}^n \bar{\alpha}_j (\bar{\alpha}_j z_j'(t) + \bar{\beta}_j z_j(t)) z_j''(t) e^{\lambda t} \\
 &= \lambda \sum_{j=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) u_j^2(t) e^{\lambda t} - 2 \lambda \sum_{j=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) u_j(t) \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}) e^{\lambda t} \\
 &\quad + \lambda \sum_{j=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}) e^{\lambda t} \\
 &\quad + 2 \sum_{j=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) (u_j(t) - \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk})) \\
 &\quad \times (u_j'(t) - \sum_{k=1}^n e_{jk} u_k'(t - \zeta_{jk})) e^{\lambda t} \\
 &\quad + \sum_{j=1}^n (\lambda \bar{\alpha}_j^2 + 2 \bar{\alpha}_j \bar{\beta}_j) (u_j'(t) - \sum_{k=1}^n e_{jk} u_k'(t - \zeta_{jk}))^2 e^{\lambda t} \\
 &\quad + 2 \sum_{j=1}^n \bar{\alpha}_j [\bar{\alpha}_j (u_j'(t) - \sum_{k=1}^n e_{jk} u_k'(t - \zeta_{jk})) + \bar{\beta}_j (u_j(t) - \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}))] \\
 &\quad \times [-a_j u_j'(t) - b_j u_j(t) + \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) + \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk}))] e^{\lambda t}
 \end{aligned}$$

$$\begin{aligned}
&= \lambda \sum_{j=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) u_j^2(t) e^{\lambda t} - 2\lambda \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} u_j(t) u_k(t - \zeta_{jk}) e^{\lambda t} \\
&\quad + \lambda \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) u_j(t) u_j'(t) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_j(t) u_k'(t - \zeta_{jk}) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) u_j'(t) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n e_{jk} u_k'(t - \zeta_{jk}) e^{\lambda t} \\
&\quad + \sum_{j=1}^n (\lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j) (u_j'(t))^2 e^{\lambda t} - 2 \sum_{j=1}^n \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j) e_{jk} u_j'(t) u_k'(t - \zeta_{jk}) e^{\lambda t} \\
&\quad + \sum_{j=1}^n \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j) e_{jk} u_k'(t - \zeta_{jk}) \sum_{k=1}^n e_{jk} u_k'(t - \zeta_{jk}) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n a_j \bar{\alpha}_j^2 (u_j'(t))^2 e^{\lambda t} - 2 \sum_{j=1}^n b_j \bar{\alpha}_j^2 u_j(t) u_j'(t) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 c_{jk} u_j'(t) \tilde{f}_k(u_k(t)) e^{\lambda t} + 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 d_{jk} u_j(t) \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j^2 e_{jk} u_k'(t - \zeta_{jk}) u_j'(t) e^{\lambda t} + 2 \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j^2 e_{jk} u_k'(t - \zeta_{jk}) u_j(t) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 e_{jk} u_k'(t - \zeta_{jk}) \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 e_{jk} u_k'(t - \zeta_{jk}) \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n a_j \bar{\alpha}_j \bar{\beta}_j u_j(t) u_j'(t) e^{\lambda t} - 2 \sum_{j=1}^n b_j \bar{\alpha}_j \bar{\beta}_j u_j^2(t) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j c_{jk} u_j(t) \tilde{f}_k(u_k(t)) e^{\lambda t} + 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j d_{jk} u_j(t) \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) u_j'(t) e^{\lambda t} + 2 \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) u_j(t) e^{\lambda t} \\
&\quad - 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) e^{\lambda t} \\
&\quad + 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t}. \tag{12}
\end{aligned}$$

Moreover, one can give the following inequalities:

$$\begin{aligned}
 & \lambda \sum_{j=1}^n \left(\sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) \right) \left(\sum_{k=1}^n e_{jk} u_k(t - \zeta_{jk}) \right) e^{\lambda t} \\
 = & \lambda \sum_{j=1}^n \left(\sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) \right) \left(\sum_{l=1}^n e_{jl} u_l(t - \zeta_{jl}) \right) e^{\lambda t} \\
 = & \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} e_{jl} u_k(t - \zeta_{jk}) u_l(t - \zeta_{jl}) e^{\lambda t} \\
 \leq & \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| |e_{jl}| |u_k(t - \zeta_{jk})| |u_l(t - \zeta_{jl})| e^{\lambda t} \\
 \leq & \frac{1}{2} \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| |e_{jl}| u_k^2(t - \zeta_{jk}) e^{\lambda t} \\
 & + \frac{1}{2} \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| |e_{jl}| u_l^2(t - \zeta_{jl}) e^{\lambda t} \\
 = & \frac{1}{2} \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kj}| |e_{kl}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 & + \frac{1}{2} \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kl}| |e_{kj}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 = & \lambda \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kj}| |e_{kl}| u_j^2(t - \zeta_{kj}) e^{\lambda t}. \tag{13}
 \end{aligned}$$

Similarly,

$$\begin{aligned}
 & 2 \sum_{j=1}^n \left(\sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) \right) \left(\sum_{k=1}^n e_{jk} u'_k(t - \zeta_{jk}) \right) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2) |e_{kj}| |e_{kl}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2) |e_{kl}| |e_{kj}| (u'_j(t - \zeta_{kj}))^2 e^{\lambda t}, \tag{14}
 \end{aligned}$$

$$\begin{aligned}
 & \sum_{j=1}^n \left(\sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + 2 \bar{\alpha}_j \bar{\beta}_j) e_{jk} u'_k(t - \zeta_{jk}) \right) \left(\sum_{k=1}^n e_{jk} u'_k(t - \zeta_{jk}) \right) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n (\lambda \bar{\alpha}_k^2 + 2 \bar{\alpha}_k \bar{\beta}_k) |e_{kj}| |e_{kl}| (u'_j(t - \zeta_{kj}))^2 e^{\lambda t}, \tag{15}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \left(\sum_{k=1}^n \bar{\alpha}_j^2 e_{jk} u'_k(t - \zeta_{jk}) \right) \left(\sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) \right) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k^2 |e_{kj}| |c_{kl}| (u'_j(t - \zeta_{kj}))^2 e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l^2 |e_{lk}| |c_{lj}| \tilde{f}_j^2(u_j(t)) e^{\lambda t}, \tag{16}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \left(\sum_{k=1}^n \bar{\alpha}_j^2 e_{jk} u'_k(t - \zeta_{jk}) \right) \left(\sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})) \right) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k^2 |e_{kj}| |d_{kl}| (u'_j(t - \zeta_{kj}))^2 e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k^2 |e_{kl}| |d_{kj}| \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t}, \tag{17}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n c_{jk} \tilde{f}_k(u_k(t)) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k \bar{\beta}_k |e_{kj}| |c_{kl}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l \bar{\beta}_l |e_{lk}| |c_{lj}| \tilde{f}_j^2(u_j(t)) e^{\lambda t}, \tag{18}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \zeta_{jk}) \sum_{k=1}^n d_{jk} \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k \bar{\beta}_k |e_{kj}| |d_{kl}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_k \bar{\beta}_k |e_{kl}| |d_{kj}| \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t}, \tag{19}
 \end{aligned}$$

$$\begin{aligned}
 & -2\lambda \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) e_{jk} u_j(t) u_k(t - \zeta_{jk}) e^{\lambda t} \\
 \leq & \lambda \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| u_j^2(t) e^{\lambda t} \\
 & + \lambda \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_k + \bar{\beta}_k^2) |e_{kj}| u_j^2(t - \zeta_{kj}) e^{\lambda t}, \tag{20}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_j(t) u'_k(t - \zeta_{jk}) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| u_j^2(t) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2) |e_{kj}| (u'_j(t - \zeta_{kj}))^2 e^{\lambda t}, \tag{21}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) e_{jk} u_k(t - \zeta_{jk}) u'_j(t) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_k + \lambda \bar{\alpha}_k \bar{\beta}_k + \bar{\beta}_k^2) |e_{kj}| u_j^2(t - \zeta_{kj}) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| (u'_j(t))^2 e^{\lambda t}, \tag{22}
 \end{aligned}$$

$$\begin{aligned}
 & -2 \sum_{j=1}^n \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j) e_{jk} u'_j(t) u'_k(t - \xi_{jk}) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j) |e_{jk}| (u'_j(t))^2 e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n (\lambda \bar{\alpha}_k^2 + 2\bar{\alpha}_k \bar{\beta}_k) |e_{kj}| (u'_j(t - \xi_{kj}))^2 e^{\lambda t}, \tag{23}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 c_{jk} u'_j(t) \tilde{f}_k(u_k(t)) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 |c_{jk}| (u'_j(t))^2 e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_k^2 |c_{kj}| \tilde{f}_j^2(u_j(t)) e^{\lambda t}, \tag{24}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 d_{jk} u'_j(t) \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j^2 |d_{jk}| (u'_j(t))^2 e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_k^2 |d_{kj}| \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t}, \tag{25}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j^2 e_{jk} u'_k(t - \xi_{jk}) u'_j(t) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n a_k \bar{\alpha}_k^2 |e_{kj}| (u'_j(t - \xi_{kj}))^2 e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j^2 |e_{jk}| (u'_j(t))^2 e^{\lambda t}, \tag{26}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j^2 e_{jk} u'_k(t - \xi_{jk}) u_j(t) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n b_k \bar{\alpha}_k^2 |e_{kj}| (u'_j(t - \xi_{kj}))^2 e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j^2 |e_{jk}| u_j^2(t) e^{\lambda t}, \tag{27}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j c_{jk} u_j(t) \tilde{f}_k(u_k(t)) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |c_{jk}| u_j^2(t) e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_k \bar{\beta}_k |c_{kj}| \tilde{f}_j^2(u_j(t)) e^{\lambda t}, \tag{28}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j d_{jk} u_j(t) \tilde{f}_k(u_k(t - \tau_{jk})) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |d_{jk}| u_j^2(t) e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n \bar{\alpha}_k \bar{\beta}_k |d_{kj}| \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t}, \tag{29}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \xi_{jk}) u'_j(t) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n a_k \bar{\alpha}_k \bar{\beta}_k |e_{kj}| u_j^2(t - \xi_{kj}) e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n a_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| (u'_j(t))^2 e^{\lambda t}, \tag{30}
 \end{aligned}$$

$$\begin{aligned}
 & 2 \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j \bar{\beta}_j e_{jk} u_k(t - \xi_{jk}) u_j(t) e^{\lambda t} \\
 \leq & \sum_{j=1}^n \sum_{k=1}^n b_k \bar{\alpha}_k \bar{\beta}_k |e_{kj}| u_j^2(t - \xi_{kj}) e^{\lambda t} + \sum_{j=1}^n \sum_{k=1}^n b_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| u_j^2(t) e^{\lambda t}. \tag{31}
 \end{aligned}$$

Submitting (13)–(31) into (12), we obtain

$$\begin{aligned}
 W'_1(t) \leq & e^{\lambda t} \sum_{j=1}^n \{[\lambda(\bar{\delta}_j + \bar{\beta}_j^2) + \lambda \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2)|e_{jk}| + \sum_{k=1}^n (\bar{\delta}_j + \lambda\bar{\alpha}_j\bar{\beta}_j + \bar{\beta}_j^2)|e_{jk}| \\
 & + \sum_{k=1}^n b_j\bar{\alpha}_j^2|e_{jk}| - 2b_j\bar{\alpha}_j\bar{\beta}_j + \sum_{k=1}^n \bar{\alpha}_j\bar{\beta}_j|c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j\bar{\beta}_j|d_{jk}| + \sum_{k=1}^n b_j\bar{\alpha}_j\bar{\beta}_j|e_{jk}]\}u_j^2(t) \\
 & + [2(\bar{\delta}_j + \lambda\bar{\alpha}_j\bar{\beta}_j + \bar{\beta}_j^2) - 2b_j\bar{\alpha}_j^2 - 2a_j\bar{\alpha}_j\bar{\beta}_j]u_j(t)u'_j(t) \\
 & + [\sum_{k=1}^n (\bar{\delta}_j + \lambda\bar{\alpha}_j\bar{\beta}_j + \bar{\beta}_j^2)|e_{jk}| + (\lambda\bar{\alpha}_j^2 + 2\bar{\alpha}_j\bar{\beta}_j) + \sum_{k=1}^n (\lambda\bar{\alpha}_j^2 + \bar{\alpha}_j\bar{\beta}_j)|e_{jk}| \\
 & - 2a_j\bar{\alpha}_j^2 + \sum_{k=1}^n \bar{\alpha}_j^2|c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j^2|d_{jk}| + \sum_{k=1}^n a_j\bar{\alpha}_j^2|e_{jk}| + \sum_{k=1}^n a_j\bar{\alpha}_j\bar{\beta}_j|e_{jk}|](u'_j(t))^2 \\
 & + [\sum_{k=1}^n \bar{\alpha}_k^2|c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l^2|e_{lk}||c_{lj}| + \sum_{k=1}^n \bar{\alpha}_k\bar{\beta}_k|c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l\bar{\beta}_l|e_{lk}||c_{lj}]]\tilde{f}_j^2(u_j(t)) \\
 & + [\sum_{k=1}^n A_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^2]u_j^2(t - \xi_{kj}) + [\sum_{k=1}^n B_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^2](u'_j(t - \xi_{kj}))^2 \\
 & + [\sum_{k=1}^n C_{kj} + \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl}]\tilde{f}_j^2(u_j(t - \tau_{kj})). \tag{32}
 \end{aligned}$$

In the following, by (10) and (11), we have

$$\begin{aligned}
 W'_2(t) = & \sum_{j=1}^n \sum_{k=1}^n A_{kj}^2 u_j^2(t) e^{\lambda(t+\xi_{kj})} - \sum_{j=1}^n \sum_{k=1}^n A_{kj}^2 u_j^2(t - \xi_{kj}) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^2 u_j^2(t) e^{\lambda(t+\xi_{kj})} - \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^2 u_j^2(t - \xi_{kj}) e^{\lambda t}, \tag{33}
 \end{aligned}$$

$$\begin{aligned}
 W'_3(t) = & \sum_{j=1}^n \sum_{k=1}^n B_{kj}^2 (u'_j(t))^2 e^{\lambda(t+\xi_{kj})} - \sum_{j=1}^n \sum_{k=1}^n B_{kj}^2 (u'_j(t - \xi_{kj}))^2 e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^2 (u'_j(t))^2 e^{\lambda(t+\xi_{kj})} - \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^2 (u'_j(t - \xi_{kj}))^2 e^{\lambda t}, \tag{34}
 \end{aligned}$$

$$\begin{aligned}
 W'_4(t) = & \sum_{j=1}^n \sum_{k=1}^n C_{kj} \tilde{f}_j^2(u_j(t)) e^{\lambda(t+\tau_{kj})} - \sum_{j=1}^n \sum_{k=1}^n C_{kj} \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t} \\
 & + \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl} \tilde{f}_j^2(u_j(t)) e^{\lambda(t+\tau_{kj})} - \sum_{j=1}^n \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl} \tilde{f}_j^2(u_j(t - \tau_{kj})) e^{\lambda t}. \tag{35}
 \end{aligned}$$

From (32)–(35) and the Assumption 1, one can get

$$\begin{aligned}
 W'(t) &= \sum_{j=1}^4 W'_j(t) \\
 &\leq e^{\lambda t} \sum_{j=1}^n \{ [\lambda(\bar{\delta}_j + \bar{\beta}_j^2) + \lambda \sum_{k=1}^n (\bar{\delta}_j + \bar{\beta}_j^2) |e_{jk}| + \sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| \\
 &\quad + \sum_{k=1}^n b_j \bar{\alpha}_j^2 |e_{jk}| - 2b_j \bar{\alpha}_j \bar{\beta}_j + \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j \bar{\beta}_j |d_{jk}| + \sum_{k=1}^n b_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| \\
 &\quad + (\sum_{k=1}^n \bar{\alpha}_k^2 |c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l^2 |e_{lk}| |c_{lj}| + \sum_{k=1}^n \bar{\alpha}_k \bar{\beta}_k |c_{kj}| + \sum_{k=1}^n \sum_{l=1}^n \bar{\alpha}_l \bar{\beta}_l |e_{lk}| |c_{lj}|) L_j^2 \\
 &\quad + (\sum_{k=1}^n A_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{A}_{kjl}^2) e^{\lambda \xi_{kj}} + (\sum_{k=1}^n C_{kj} + \sum_{k=1}^n \sum_{l=1}^n \tilde{C}_{kjl}) L_j^2 e^{\lambda \tau_{kj}} u_j^2(t) \\
 &\quad + [2(\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) - 2b_j \bar{\alpha}_j^2 - 2a_j \bar{\alpha}_j \bar{\beta}_j] u_j(t) u'_j(t) \\
 &\quad + [\sum_{k=1}^n (\bar{\delta}_j + \lambda \bar{\alpha}_j \bar{\beta}_j + \bar{\beta}_j^2) |e_{jk}| + \lambda \bar{\alpha}_j^2 + 2\bar{\alpha}_j \bar{\beta}_j + \sum_{k=1}^n (\lambda \bar{\alpha}_j^2 + \bar{\alpha}_j \bar{\beta}_j) |e_{jk}| \\
 &\quad - 2a_j \bar{\alpha}_j^2 + \sum_{k=1}^n \bar{\alpha}_j^2 |c_{jk}| + \sum_{k=1}^n \bar{\alpha}_j^2 |d_{jk}| + \sum_{k=1}^n a_j \bar{\alpha}_j^2 |e_{jk}| + \sum_{k=1}^n a_j \bar{\alpha}_j \bar{\beta}_j |e_{jk}| \\
 &\quad + (\sum_{k=1}^n B_{kj}^2 + \sum_{k=1}^n \sum_{l=1}^n \tilde{B}_{kjl}^2) e^{\lambda \xi_{kj}} (u'_j(t))^2 \} \\
 &= e^{\lambda t} \sum_{j=1}^n \left(\mathcal{X}_j^\lambda (u'_j(t))^2 + \mathcal{Z}_j^\lambda u_j(t) u'_j(t) + \mathcal{Y}_j^\lambda u_j^2(t) \right) \\
 &= e^{\lambda t} \sum_{j=1}^n \mathcal{X}_j^\lambda \left(u'_j(t) + \frac{\mathcal{Z}_j^\lambda}{2\mathcal{X}_j^\lambda} u_j(t) \right)^2 + \sum_{j=1}^n \left(\mathcal{Y}_j^\lambda - \frac{(\mathcal{Z}_j^\lambda)^2}{4\mathcal{X}_j^\lambda} \right) u_j^2(t) \\
 &\leq 0.
 \end{aligned} \tag{36}$$

This implies that $W(t) \leq W(0)$ on $[0, +\infty)$, and

$$\sum_{j=1}^n \bar{\delta}_j z_j^2(t) e^{\lambda t} + \sum_{j=1}^n (\bar{\alpha}_j z'_j(t) + \bar{\beta}_j z_j(t))^2 e^{\lambda t} \leq W(0).$$

Note that

$$|z'_j(t)| \leq |z'_j(t) + z_j(t)| + |z_j(t)|,$$

we can easily see that there exists a constant $\Lambda > 0$ obeying

$$|u'_j(t)| \leq \Lambda e^{-\lambda t}, \quad |u_j(t)| \leq \Lambda e^{-\lambda t}, \quad \forall t \in [0, +\infty), j \in \mathfrak{N}.$$

This completes the proof. \square

Remark 1. When $u_j(t)$ is a periodic solution of NTINNs (3), Lemma 2 shows that all solutions of NTINNs (3) and their derivatives are exponentially convergent to $u_j(t)$ and $u'_j(t)$, respectively.

3. Periodicity of NTINNs

Theorem 1. If the assumptions in Lemma 2 are satisfied, NTINNs (3) possess a globally exponentially stable T -periodic solution.

Proof. Denote $\rho_j(t)$ by setting

$$\begin{aligned} \rho_j''(t) - \sum_{k=1}^n e_{jk} \rho_k''(t - \xi_{jk}) &= -a_j \rho_j'(t) - b_j \rho_j(t) + \sum_{k=1}^n c_{jk} f_k(\rho_k(t)) \\ &\quad + \sum_{k=1}^n d_{jk} f_k(\rho_k(t - \tau_{jk})) + I_j(t), \end{aligned} \tag{37}$$

and

$$\rho_j^0(v) = \varphi_j^0(v), \rho_j^1(v) = \psi_j^0(v), \rho_j^2(v) = \varsigma_j^0(v), \varphi_j^0, \psi_j^0, \varsigma_j^0 \in C([- \sigma_j, 0], \mathbb{R}), j \in \mathfrak{N}. \tag{38}$$

Hence, for any nonnegative integer n ,

$$\begin{aligned} &\rho_j''(t + nT) - \sum_{k=1}^n e_{jk} \rho_k''(t + nT - \xi_{jk}) \\ &= -a_j \rho_j'(t + nT) - b_j \rho_j(t + nT) + \sum_{k=1}^n c_{jk} f_k(\rho_k(t + nT)) \\ &\quad + \sum_{k=1}^n d_{jk} f_k(\rho_k(t + nT - \tau_{jk})) + I_j(t), \forall j \in \mathfrak{N}, t + nT \geq 0, \end{aligned} \tag{39}$$

and $\mu(t) = \rho(t + T)$ is a solution of NTINNs (3), which satisfies

$$\varphi_j^\mu(v) = \rho_j(v + T), \psi_j^\mu(v) = \rho_j'(v + T), \varsigma_j^\mu(v) = \rho_j''(v + T), \forall j \in \mathfrak{N}, v \in [- \sigma_j, 0].$$

By using Lemma 2, one can select a constant $\Lambda = \Lambda(\varphi^0, \psi^0, \varsigma^0, \varphi^\mu, \psi^\mu, \varsigma^\mu) > 0$ satisfying

$$|\rho_j(t) - \mu_j(t)| \leq \Lambda e^{-\lambda t}, \quad |\rho_j'(t) - \mu_j'(t)| \leq \Lambda e^{-\lambda t}, \quad \forall j \in \mathfrak{N}, t \geq 0.$$

Therefore,

$$\begin{aligned} |\rho_j(t + mT) - \rho_j(t + (m + 1)T)| &= |\rho_j(t + mT) - \mu_j(t + mT)| \\ &\leq \Lambda e^{-\lambda(t+mT)}, \forall j \in \mathfrak{N}, t + mT \geq 0 \end{aligned}$$

and

$$\begin{aligned} |\rho_j'(t + mT) - \rho_j'(t + (m + 1)T)| &= |\rho_j'(t + mT) - \mu_j'(t + mT)| \\ &\leq \Lambda e^{-\lambda(t+mT)}, \forall j \in \mathfrak{N}, t + mT \geq 0. \end{aligned}$$

Since

$$\rho_j(t + nT) = \rho_j(t) + \sum_{m=0}^{n-1} [\rho_j(t + (m + 1)T) - \rho_j(t + mT)]$$

and

$$\rho_j'(t + nT) = \rho_j'(t) + \sum_{m=0}^{n-1} [\rho_j'(t + (m + 1)T) - \rho_j'(t + mT)], j \in \mathfrak{N},$$

we can easily reveal that in any compact subset of \mathbb{R} , $\{\rho_j(t + nT)\}_{n \geq 1}$, $\{\rho_j'(t + nT)\}_{n \geq 1}$ and $\{\rho_j'(t + (n + 1)T) - \sum_{k=1}^n e_{jk} \rho_k'(t + (n + 1)T - \xi_{jk})\}_{n \geq 1}$ are uniformly convergent function sequences and there is a differentiable function $x(t)$ obeying

$$\lim_{m \rightarrow +\infty} \rho(t + nT) = x(t), \quad \lim_{m \rightarrow +\infty} \rho'(t + nT) = x'(t).$$

Hence

$$x(t + T) = \lim_{n \rightarrow +\infty} \rho(t + T + nT) = \lim_{(n+1) \rightarrow +\infty} \rho(t + (n + 1)T) = x(t),$$

which indicates that $x(t)$ is T -periodic on \mathbb{R} . In addition, from the Assumption 2 and the continuity of NTINNs (3), one can conclude that on any compact subset of \mathbb{R} , $\{\rho_j''(t + (n + 1)T) - \sum_{k=1}^n e_{jk} \rho_k''(t + (n + 1)T - \xi_{jk})\}_{n \geq 1}$ is uniformly convergent. Setting $n \rightarrow +\infty$, it is easy to acquire that

$$\begin{aligned} x_j''(t) - \sum_{k=1}^n e_{jk} x_k''(t - \xi_{jk}) &= -a_j x_j'(t) - b_j x_j(t) + \sum_{k=1}^n c_{jk} f_k(x_k(t)) \\ &\quad + \sum_{k=1}^n d_{jk} f_k(x_k(t - \tau_{jk})) + I_j(t), \end{aligned}$$

which reveals that $x(t)$ is a T -periodic solution of NTINNs (3). Finally, according to Lemma 2 and Remark 1, we obtain that $x(t)$ possesses global exponential stability. This ends the proof. \square

Remark 2. In recent years, the dynamic behaviors of NTNNs [26,29,39,41] and INNs [3–9,11–15,17–21,30–32]. have been widely studied. However, we note that the global exponential stability of T -periodic solutions on the NTINNs has not been studied, hence our research is novel and further promotes the previous research.

4. A Numerical Example

Example 1. Label $n = 2$, and consider the following NTINNs involving multiple delays:

$$\begin{cases} s_1''(t) - 0.2s_1''(t - 1) + 0.1s_2''(t - 2) \\ = -6.8s_1'(t) - 8s_1(t) - 0.4f_1(s_1(t)) + 0.6f_2(s_2(t)) \\ \quad + 0.2f_1(s_1(t - 0.4)) + 0.3f_2(s_2(t - 0.5)) + 10 \sin t, \\ s_2''(t) - 0.1s_2''(t - 1.2) + 0.15s_2''(t - 1.8) \\ = -10.2s_2'(t) - 11s_2(t) - 0.2f_1(s_1(t)) + 0.4f_2(s_2(t)) \\ \quad + 0.3f_1(s_1(t - 0.2)) + 0.4f_2(s_2(t - 0.3)) + 100 \cos t, \end{cases} \tag{40}$$

where $f_j(u) = \frac{1}{8}(|u + 1| - |u - 1|)$, $j = 1, 2$.

Take $\delta_1 = 34, \delta_2 = 66, \bar{\beta}_1 = 1, \bar{\beta}_2 = 1.2, \bar{\alpha}_1 = 1.8, \bar{\alpha}_2 = 2, L_j = \frac{1}{4}, j = 1, 2$, we get

$$\begin{aligned} \mathcal{X}_1 &= -17.9544, \quad \mathcal{Y}_1 = -3.504, \quad \mathcal{Z}_1 = -6.32, \\ \mathcal{X}_2 &= -37.82, \quad \mathcal{Y}_2 = -15.22, \quad \mathcal{Z}_2 = -2.08. \end{aligned}$$

It is easy to see that

$$\mathcal{X}_j < 0, \quad 4\mathcal{X}_j\mathcal{Y}_j > (\mathcal{Z}_j)^2, \quad j = 1, 2.$$

By utilizing Theorem 1, the NTINNs (40) possess a globally exponentially stable 2π -periodic solution $x(t)$, and all solutions of (40) and their derivatives are exponentially convergent to $x(t)$ and $x'(t)$, respectively. The simulation results of Figures 1 and 2 show that the theoretical analysis is consistent with the numerical observation results.

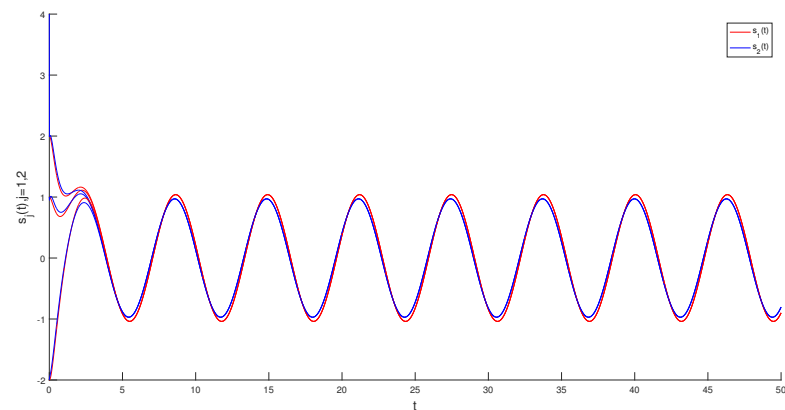


Figure 1. Numerical solutions $s(t)$ on NTINNs (40) incorporating different initial values.

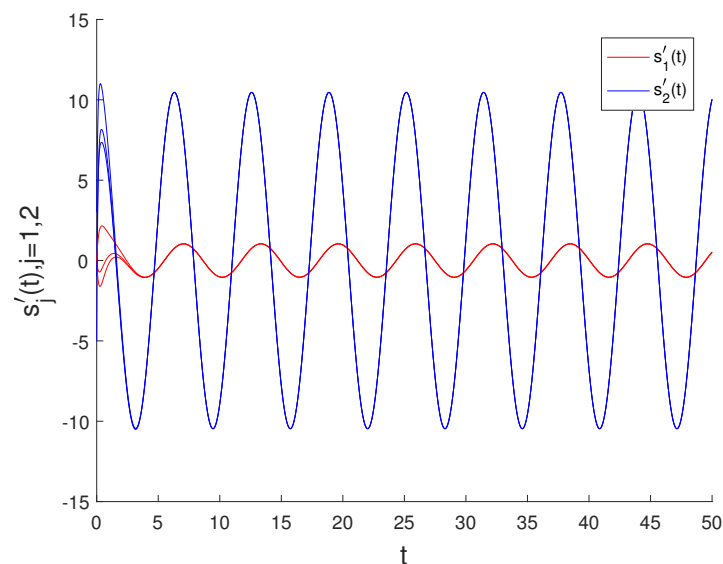


Figure 2. The derivative $s'(t)$ on NTINNs (40) incorporating different initial values.

Remark 3. *Since the global exponential stability of the T -periodic solutions on NTINNs involving multiple delays has never been studied, one can see that all the conclusions in references [42–69] cannot be directly employed to verify the global exponential stability of the 2π -periodic solutions for NTINNs (40).*

5. Conclusions

In this article, we researched the problem of the periodic solutions on NTINNs involving multiple delays. First, by exploring Lyapunov theory and inequality analysis, we establish the exponential attractivity of all solutions. Second, we obtained the existence of periodic solutions and their exponential stability. The effectiveness of the obtained results has been illustrated by an instructive numerical simulation. In addition, the method applied in this article offers a possible way to investigate the dynamic characteristics of other NTINNs, such as NTINNs involving D operators, fuzzy NTINNs, Cohen–Grossberg NTINNs and others.

Author Contributions: Conceptualization, J.Z. and A.C.; methodology, J.Z.; software, J.Z. and G.Y.; validation, J.Z., A.C. and G.Y.; writing—original draft preparation, J.Z.; writing—review and editing, J.Z., A.C. and G.Y. All authors have read and agreed to the published version of the manuscript.

Funding: This work was supported by the National Natural Science Foundation of China (No. 11971076), the Scientific Research Fund of Hunan Provincial Education Department (No. 19A347), the Natural Science Foundation of Hunan Province (No. 2019JJ40142), Postgraduate Scientific Research Innovation Project of Hunan Province (No. CX20210820).

Institutional Review Board Statement: Not applicable.

Informed Consent Statement: Not applicable.

Data Availability Statement: Not applicable.

Acknowledgments: The authors would like to thank the referees and the editor for very helpful suggestions and comments which led to improvements of our original paper.

Conflicts of Interest: We confirm that we have no conflict of interest.

Abbreviations

The following abbreviations are used in this manuscript:

NTINNs	Neutral-type inertial neural networks
NTNNs	Neutral-type neural networks
INNs	Inertial neural networks
NNs	Neural networks

References

- Babcock, K.; Westervelt, R. Stability and dynamics of simple electronic neural networks with added inertia. *Physica D* **1986**, *23*, 142–149. [[CrossRef](#)]
- Babcock, K.; Westervelt, R. Dynamics of simple electronic neural networks. *Physica D* **1987**, *28*, 305–316. [[CrossRef](#)]
- Shi, M.; Guo, J.; Fang, X.; Huang, C. Global exponential stability of delayed inertial competitive neural networks. *Adv. Differ. Equ.* **2020**, *87*. [[CrossRef](#)]
- Li, H.; Li, C.; Ouyang, D.; Nguang, S.K. Impulsive synchronization of unbounded delayed inertial neural networks with actuator saturation and sampled-data control and its application to image encryption. *IEEE Trans. Neural Netw. Learn. Syst.* **2021**, *32*, 1460–1473. [[CrossRef](#)] [[PubMed](#)]
- Zhang, Z.; Chen, M.; Li, A. Further study on finite-time synchronization for delayed inertial neural networks via inequality skills. *Neurocomputing* **2020**, *375*, 15–23. [[CrossRef](#)]
- Wang, L.; Huang, T.; Xiao, Q. Lagrange stability of delayed switched inertial neural networks. *Neurocomputing* **2020**, *381*, 52–60. [[CrossRef](#)]
- Kong, F.; Zhu, Q.; Sakthivel, R.; Mohammadzadeh, A. Fixed-time synchronization analysis for discontinuous fuzzy inertial neural networks with parameter uncertainties. *Neurocomputing* **2021**, *422*, 295–313. [[CrossRef](#)]
- Kong, F.; Zhu, Q.; Huang, T. New fixed-time stability lemmas and applications to the discontinuous fuzzy inertial neural networks. *IEEE Trans. Fuzzy Syst.* **2020**. [[CrossRef](#)]
- Wang, J.; Wang, Z.; Chen, X.; Qiu, J. Synchronization criteria of delayed inertial neural networks with generally Markovian jumping. *Neural Netw.* **2021**, *139*, 64–76. [[CrossRef](#)]
- Liu, Y.; Wu, J.; Wang, X. Collective periodic motions in a multiparticle model involving processing delay. *Math. Methods Appl. Sci.* **2020**, *44*, 3280–3302. [[CrossRef](#)]
- Wei, X.; Zhang, Z.; Lin, C.; Chen, J. Synchronization and anti-synchronization for complex-valued inertial neural networks with time-varying delays. *Appl. Math. Comput.* **2021**, *403*, 126194. [[CrossRef](#)]
- Li, X.; Li, X.; Hu, C. Some new results on stability and synchronization for delayed inertial neural networks based on non-reduced order method. *Neural Netw.* **2017**, *96*, 91–100. [[CrossRef](#)] [[PubMed](#)]
- Huang, C.; Liu, B. New studies on dynamic analysis of inertial neural networks involving non-reduced order method. *Neurocomputing* **2019**, *325*, 283–287. [[CrossRef](#)]
- Zhang, J.; Huang, C. Dynamics analysis on a class of delayed neural networks involving inertial terms. *Adv. Differ. Equ.* **2020**, *120*. [[CrossRef](#)]
- Cao, Q.; Long, X. New convergence on inertial neural networks with time-varying delays and continuously distributed delays. *AIMS Math.* **2020**, *5*, 5955–5968. [[CrossRef](#)]
- Cai, Z.; Huang, J.; Yang, L.; Huang, L. Periodicity and stabilization control of the delayed filippov system with perturbation. *D Contin. Dyn. Syst.-Ser. B* **2020**, *25*, 1439–1467. [[CrossRef](#)]

17. Cao, Q.; Guo, X. Anti-periodic dynamics on high-order inertial Hopfield neural networks involving time-varying delays. *AIMS Math.* **2020**, *5*, 5402–5421. [[CrossRef](#)]
18. Yao, L.; Cao, Q. Anti-periodicity on high-order inertial Hopfield neural networks involving mixed delays. *J. Inequal. Appl.* **2020**, 182. [[CrossRef](#)]
19. Shi, J.; Zeng, Z. Global exponential stabilization and lag synchronization control of inertial neural networks with time delays. *Neural Netw.* **2020**, *126*, 11–20. [[CrossRef](#)]
20. Yu, J.; Hu, C.; Jiang, H.; Wang, L. Exponential and adaptive synchronization of inertial complex-valued neural networks: A non-reduced order and non-separation approach. *Neural Netw.* **2020**, *124*, 20–59. [[CrossRef](#)]
21. Wu, K.; Jian, J. Non-reduced order strategies for global dissipativity of memristive neutral-type inertial neural networks with mixed time-varying delays. *Neurocomputing* **2021**, *436*, 174–183. [[CrossRef](#)]
22. Yu, F.; Qian, S.; Chen, X.; Huang, Y.; Liu, L.; Shi, C.; Cai, S.; Song, Y.; Wang, C. A new 4D four-wing memristive hyperchaotic system: Dynamical analysis, electronic circuit design, shape synchronization and secure communication. *Int. J. Bifurc. Chaos* **2020**, *30*, 2050147. [[CrossRef](#)]
23. Gao, Z.; Wang, Y.; Xiong, J.; Pan, Y.; Huang, Y. Structural balance control of complex dynamical networks based on state observer for dynamic connection relationships. *Complexity* **2020**, *2020*, 5075487. [[CrossRef](#)]
24. Li, W.; Huang, L.; Ji, J. Globally exponentially stable periodic solution in a general delayed predator-prey model under discontinuous prey control strategy. *Discret. Contin. Dyn. Syst.-Ser. B* **2020**, *25*, 2639–2664. [[CrossRef](#)]
25. Zhu, Q.; Li, X. Exponential and almost sure exponential stability of stochastic fuzzy delayed Cohen-Grossberg neural networks. *Fuzzy Sets Syst.* **2012**, *203*, 74–94. [[CrossRef](#)]
26. Zhang, X.; Hu, H. Convergence in a system of critical neutral functional differential equations. *Appl. Math. Lett.* **2020**, *107*, 106385. [[CrossRef](#)]
27. Tan, T. Dynamics analysis of Mackey-glass model with two variable delays. *Math. Biosci. Eng.* **2020**, *17*, 4513–4526. [[CrossRef](#)]
28. Hale, J.K. *Theory of Functional Differential Equations*; Springer: New York, NY, USA, 1977.
29. Zhang, X.; Han, Q. A new stability criterion for a partial element equivalent circuit model of neutral type. *IEEE Trans. Circuits Syst. II Express Briefs* **2009**, *56*, 798–802. [[CrossRef](#)]
30. Jian, J.; Duan, L. Finite-time synchronization for fuzzy neutral-type inertial neural networks with time-varying coefficients and proportional delays. *Fuzzy Sets Syst.* **2020**, *381*, 51–67. [[CrossRef](#)]
31. Lakshmanana, S.; Lima, C.P.; Prakashb, M.; Nahavandia, S.; Balasubramaniam, P. Neutral-type of delayed inertial neural networks and their stability analysis using the LMI Approach. *Neurocomputing* **2017**, *230*, 243–250. [[CrossRef](#)]
32. Xu, M.; Du, B. Periodic solution for neutral-type inertial neural networks with time-varying delays. *Adv. Differ. Equ.* **2020**, 607. [[CrossRef](#)]
33. Guo, X.; Huang, C.; Cao, J. Nonnegative periodicity on high-order proportional delayed cellular neural networks involving D operator. *AIMS Math.* **2021**, *6*, 2228–2243. [[CrossRef](#)]
34. Huang, C.; Yang, H.; Cao, J. Weighted pseudo almost periodicity of multi-proportional delayed shunting inhibitory cellular neural networks with D operator. *Discret. Contin. Dyn. Syst. Ser. S* **2021**, *14*, 1259–1272. [[CrossRef](#)]
35. Chen, D.; Zhang, W.; Cao, J.; Huang, C. Fixed time synchronization of delayed quaternion-valued memristor-based neural networks. *Adv. Differ. Equ.* **2020**, *2020*, 92. [[CrossRef](#)]
36. Cai, Z.; Huang, L.; Wang, Z. Mono/multi-periodicity generated by impulses control in time-delayed memristor-based neural networks. *Nonlinear Anal.-Hybrid Syst.* **2020**, *36*, 100861. [[CrossRef](#)]
37. Huang, C.; Long, X.; Cao, J. Stability of anti-periodic recurrent neural networks with multiproportional delays. *Math. Methods Appl. Sci.* **2020**, *43*, 6093–6102. [[CrossRef](#)]
38. Xu, C.; Liao, M.; Li, P.; Guo, Y.; Xiao, Q.; Yuan, S. Influence of multiple time delays on bifurcation of fractional-order neural networks. *Appl. Math. Comput.* **2019**, *361*, 565–582. [[CrossRef](#)]
39. Faydasicok, O. New criteria for global stability of neutral-type Cohen-Grossberg neural networks with multiple delays. *Neural Netw.* **2020**, *125*, 330–337. [[CrossRef](#)]
40. Iswarya, M.; Raja, R.; Rajchakit, G.; Cao, J.; Alzabut, J.; Huang, C. Existence, uniqueness and exponential stability of periodic solution for discrete-time delayed BAM neural networks based on coincidence degree theory and graph theoretic method. *Mathematics* **2019**, *7*, 1055. [[CrossRef](#)]
41. Yang, H. Weighted pseudo almost periodicity on neutral type CNNs involving multi-proportional delays and D operator. *AIMS Math.* **2021**, *6*, 1865–1879. [[CrossRef](#)]
42. Huang, C.; Long, X.; Huang, L.; Fu, S. Stability of almost periodic Nicholson’s blowflies model involving patch structure and mortality terms. *Canad. Math. Bull.* **2020**, *63*, 405–422. [[CrossRef](#)]
43. Huang, C.; Tan, Y. Global behavior of a reaction-diffusion model with time delay and Dirichlet condition. *J. Differ. Equ.* **2021**, *271*, 186–215. [[CrossRef](#)]
44. Huang, C.; Zhang, H.; Cao, J.; Hu, H. Stability and Hopf bifurcation of a delayed prey-predator model with disease in the predator. *Internat. J. Bifur. Chaos Appl. Sci. Engrg.* **2019**, *29*, 1950091. [[CrossRef](#)]
45. Huang, C.; Zhang, H.; Huang, L. Almost periodicity analysis for a delayed Nicholson’s blowflies model with nonlinear density-dependent mortality term. *Commun. Pure Appl. Anal.* **2019**, *18*, 3337–3349. [[CrossRef](#)]

46. Long, X. Novel stability criteria on a patch structure Nicholson's blowflies model with multiple pairs of time-varying delays. *AIMS Math.* **2020**, *5*, 7387–7401. [[CrossRef](#)]
47. Huang, C.; Zhao, X.; Cao, J.; Alsaadi, F.E. Global dynamics of neoclassical growth model with multiple pairs of variable delays. *Nonlinearity* **2020**, *33*, 6819–6834. [[CrossRef](#)]
48. Huang, C.; Wang, J.; Huang, L. Asymptotically almost periodicity of delayed Nicholson-type system involving patch structure. *Electron. J. Differ. Equ.* **2020**, 102. [[CrossRef](#)]
49. Huang, C.; Zhang, J.; Cao, J. Delay-dependent attractivity on a tick population dynamics model incorporating two distinctive time-varying delays. *Proc. R. Soc. A-Math. Phys. Eng. Sci.* **2021**, *447*, 20210302. [[CrossRef](#)]
50. Long, X.; Gong, S. New results on stability of Nicholson's blowflies equation with multiple pairs of time-varying delays. *Appl. Math. Lett.* **2020**, *2020*, 106027. [[CrossRef](#)]
51. Qian, C.; Hu, Y. Novel stability criteria on nonlinear density-dependent mortality Nicholson's blowflies systems in asymptotically almost periodic environments. *J. Inequal. Appl.* **2020**, *13*. [[CrossRef](#)]
52. Xu, C.; Li, P.; Xiao, Q.; Yuan, S. New results on competition and cooperation model of two enterprises with multiple delays and feedback controls. *Bound. Value Probl.* **2019**, *36*. [[CrossRef](#)]
53. Hu, H.; Yuan, X.; Huang, L.; Huang, C. Global dynamics of an sirs model with demographics and transfer from infectious to susceptible on heterogeneous networks. *Math. Biosci. Eng.* **2019**, *16*, 5729–5749. [[CrossRef](#)] [[PubMed](#)]
54. Duan, L.; Huang, L.; Guo, Z.; Fang, X. Periodic attractor for reaction-diffusion high-order Hopfield neural networks with time-varying delays. *Comput. Math. Appl.* **2017**, *73*, 233–245. [[CrossRef](#)]
55. Cai, Z.; Huang, J.; Huang, L. Generalized Lyapunov-Razumikhin method for retarded differential inclusions: Applications to discontinuous neural networks. *Discret. Contin. Dyn. Syst.-Ser. B* **2017**, *22*, 3591–3614. [[CrossRef](#)]
56. Zhang, H.; Qian, C. Convergence analysis on inertial proportional delayed neural networks. *Adv. Differ. Equ.* **2020**, 277. [[CrossRef](#)]
57. Pratap, A.; Raja, R.; Cao, J.; Huang, C.; Niezabitowski, M.; Bagdasar, O. Stability of discrete-time fractional-order time-delayed neural networks in complex field. *Math. Meth. Appl. Sci.* **2020**, *44*, 419–440. [[CrossRef](#)]
58. Wei, R.; Cao, J.; Huang, C. Lagrange exponential stability of quaternion-valued memristive neural networks with time delays. *Math. Meth. Appl. Sci.* **2020**, *43*, 7269–7291. [[CrossRef](#)]
59. Pratap, A.; Raja, R.; Cao, J.; Alzabut, J.; Huang, C. Finite-time synchronization criterion of graph theory perspective fractional-order coupled discontinuous neural networks. *Adv. Differ. Equ.* **2020**, 97. [[CrossRef](#)]
60. Wang, P.; Hu, H.; Jun, Z.; Tan, Y.; Liu, L. Delay-Dependent Dynamics of Switched Cohen-Grossberg Neural Networks with Mixed Delays. *Abstr. Appl. Anal.* **2013**, *2013*, 826426. [[CrossRef](#)]
61. Pratap, A.; Raja, R.; Alzabut, J.; Cao, J.; Rajchakit, G.; Huang, C. Mittag-leffler stability and adaptive impulsive synchronization of fractional order neural networks in quaternion field. *Math. Meth. Appl. Sci.* **2020**, *43*, 6223–6253. [[CrossRef](#)]
62. Rajchakit, G.; Pratap, A.; Raja, R.; Cao, J.; Alzabut, J.; Huang, C. Hybrid Control Scheme for Projective Lag Synchronization of Riemann–Liouville Sense Fractional Order Memristive BAM Neural Networks with Mixed Delays. *Mathematics* **2019**, *7*, 759. [[CrossRef](#)]
63. Iswarya, M.; Raja, R.; Rajchakit, G.; Cao, J.; Alzabut, J.; Huang, C. A perspective on graph theory-based stability analysis of impulsive stochastic recurrent neural networks with time-varying delays. *Adv. Differ. Equ.* **2019**, 502. [[CrossRef](#)]
64. Kuang, H.; Liu, J.; Chen, X.; Mao, J.; He, L. Asymptotic Behavior of Switched Stochastic Delayed Cellular Neural Networks via Average Dwell Time Method. *Abstr. Appl. Anal.* **2013**, *2013*, 270791. [[CrossRef](#)]
65. Zhu, Q.; Huang, C.; Yang, X. Exponential stability for stochastic jumping BAM neural networks with time-varying and distributed delays. *Nonlinear Anal.-Hybrid Syst.* **2011**, *5*, 52–77. [[CrossRef](#)]
66. Li, L.; Wang, W.; Huang, L.; Wu, J. Some weak flocking models and its application to target tracking. *J. Math Anal. Appl.* **2019**, *480*, 123404. [[CrossRef](#)]
67. Manickam, I.; Ramachandran, R.; Rajchakit, G.; Cao, J.; Huang, C. Novel lagrange sense exponential stability criteria for time-delayed stochastic cohen-grossberg neural networks with markovian jump parameters: A graph-theoretic approach. *Nonlinear Anal.-Model Control* **2020**, *25*, 726–744. [[CrossRef](#)]
68. Huang, C.; Liu, B.; Qian, C.; Cao, J. Stability on positive pseudo almost periodic solutions of HPDCNNs incorporating D operator. *Math. Comput. Simul.* **2021**, *190*, 1150–1163. [[CrossRef](#)]
69. Xu, C.; Li, P.; Liao, M.; Liu, Z.; Xiao, Q. Antiperiodic solutions to delayed inertial quaternion-valued neural networks. *Math. Methods Appl. Sci.* **2020**, *43*, 7326–7344. [[CrossRef](#)]