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Abstract: The effective length of soil nails is one of the critical parameters ensuring the reinforcing effect, and its accurate estimation is of great significance for the safety of the slope and deep foundation pit supporting projects. Traditional quality insurance methods, such as nail pullout tests, suffer from a series of drawbacks including being destructive, high cost, and time-consuming. In contrast, non-destructive testing (NDT) has been increasingly applied in various engineering fields in the past decades given its advantages of not damaging the material and easy operation. However, the current application of NDT in soil nail length measurement is relatively limited, and its accuracy and reliability are yet to be quantitatively evaluated. This paper introduces three methods for estimating soil nail length based on guided wave theory and collects 116 sets of NDT data for nail length. The accuracy of the NDT in soil nail prediction is statistically analyzed using the model bias method. The results show that those methods can accurately predict the nail length with an average error of less than 3% and a low dispersion of 12%. The accuracy of the NDT methods is not affected by the hammer type or estimation method. Furthermore, this paper proposes a model calibration to the original NDT method, which improves the model's average accuracy by 3% and reduces dispersion by 4% without increasing computational complexity. Finally, the probability distributions of the model biases are characterized. This study can provide practical tools for fast estimation of in situ nail length, which is of high significance to supporting slopes and deep foundation pits.



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Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). **Keywords:** soil nail; non-destructive testing (NDT); accuracy assessment; statistical analysis; model uncertainty

1. Introduction

Soil nails, steel bars encapsulated by cement columns, are widely used to reinforce soil or rocks to enhance the stability and bearing capacity of the mass. The applications include tunnels [1,2], underground mines [3], bridges [4], dams [5], slopes [6], and others. This method uses soil nails as a metal-tensioned system [7]. Consequently, the effective length of a soil nail is a critical parameter that directly affects its tensile strength and shearing capacity, thus the stability and safety of the supported structures. For this reason, the accurate measurement and monitoring of soil nail length are essential for ensuring the design integrity and performance of the soil nail system. Conventional methods of measuring soil nail length, such as pull-out tests, are often destructive, time-consuming, and expensive and may not apply to specific soil or rock formations. The traditional method for quality testing of soil nails is the pull test, which is time-consuming and destructive. More importantly, it is difficult to comprehensively reflect the effective length and compactness of a soil nail.

More sophisticated and complex soil nail systems have been designed and constructed, and as the demand for safety and quality assurance increases, non-destructive testing

(NDT) techniques for soil nail length measurement has become increasingly important in recent years, being considered as a powerful supplement to the pullout tests for the assessment of nail length. Therefore, developing and validating accurate and reliable NDT models for soil nail length measurement is crucial for ensuring the safety and efficiency of geotechnical construction projects. There exist various kinds of non-destructive testing (NDT) techniques applied in real projects, such as ultrasonic testing [8,9], impact echo [10], acoustic emission [11], and electromagnetic wave [8,12] techniques. These methods can also apply to soil nailing inspection. However, their accuracy and reliability can be affected by their inherent drawbacks or external biases, such as material anisotropy, temperature, stress, equipment frequency, noise, or interference, etc. In order to address these challenges and improve the performance of soil nailing length measurement, researchers have been exploring the use of elastic wave NDT techniques, such as guided waves [13–15] and Lamb waves [16,17]. The development of advanced signal processing algorithms [18,19] and modeling techniques [14,20,21] has also facilitated the analysis and interpretation of elastic wave signals to provide information on the length, shape, and condition of soil nails.

Although elastic wave NDT techniques have been widely used, the accuracy of this technique in predicting soil nail length must be evaluated as the site condition is typically highly complicated. The wave reflection and refraction in in situ nails are usually different from those obtained in labs. The wave shape, attenuation, mode, etc., are all influenced by workmanship, soil condition, and construction quality. Engineers who lack of experience may fail to estimate the length of in situ nails, leading to the misjudgment of nail bearing capacity, as well as fulfillment of the design requirements. Therefore, the main work of this study is to first introduce three methods for determining the nail length from NDT elastic wave signals and then conduct a statistical evaluation and calibration of the accuracy of methods. Model accuracy is quantified using model bias, defined as the ratio of the true nail length to the NDT-predicted nail length.

2. NDT Methods for Estimating Nail Length

A guided wave is a type of ultrasonic wave, which is an elastic wave formed by the interference of longitudinal or transverse waves traveling simultaneously in an interfacial object, such as a nail, in the reflection or transformation mode [22]. The propagation of guided waves in soil nails depends on the steel bar, the grout column, and the surrounding soil or rock properties. Figure 1 shows the layered structure of a soil nail. The propagation speed and attenuation of waves with different frequencies and modes in the soil nails vary [23,24]. By taking advantage of the propagation characteristics of guided waves in solid media and analyzing the propagation signals, the length of the soil nail can be determined. The basic steps for the guided wave method to estimate the quality of soil nails are as follows. First, select the appropriate sensor and transmitter for generating and receiving guided wave signals. It is then arranged on the soil nail to ensure that the guided wave can propagate along the axial direction of the soil nail. Characteristics include the time to receive and record the pilot signal and its corresponding amplitude and frequency. Finally, the length of the soil nail and the possible defects are estimated according to these characteristics. It is clarified that this paper focuses merely upon the determination of nail length.

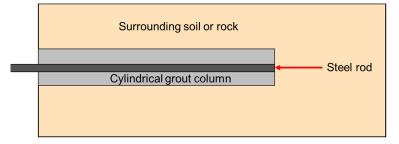


Figure 1. Simplifying a soil nail into a two-layer cylindrical column.

Figure 2 illustrates three methods to process and analyze the signals of guided waves, namely, slope attenuation, end reflection, and frequency change of the end reflection. These methods are used to determine the effective length of a soil nail. Specifically, slope attenuation refers to the decrease in energy of a wave signal as it propagates through the steel rod medium, resulting in a continuous reduction in amplitude. This gradual decrease in amplitude is caused by biases such as distance, scattering, or absorption. Different media, propagation conditions, and waveforms have varying attenuation patterns, which can be categorized into diffraction attenuation, scattering attenuation, and absorption attenuation. In particular, at the bottom of the steel rod, where it meets the boundary with the rock mass, the energy reflected into the steel rod is minimal. As shown in Figure 2a, the crossing point at which the energy is significantly weakened or reaches the end of its attenuation is defined as the bottom signal, and the corresponding distance represents the effective length of the steel rod.

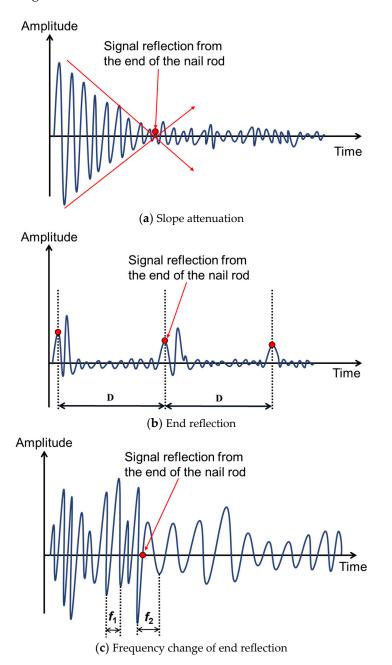


Figure 2. Schematic diagram of NDT methods for determining NDT-predicted nail length.

The second estimation method involves the recurrence of reflection signals at the bottom of the steel rod. Both longitudinal and shear waves propagate within the rod body. Due to the cylindrical shape, there is a small part of energy leaking into the grout column, very little is radiating into the surrounding geomaterials. The wave attenuation is not significant, and thus, when it meets the end of the steel rod, it bounces back 'strongly', forming a clear peak in the wave signals. As shown in Figure 2b, this signal has distinct characteristics that can be differentiated from other signals.

The third estimation method is based on slight frequency changes at the bottom signal position. At the bottom of the steel rod, the mechanical impedance difference between the two media is significant, causing a frequency difference between adjacent peaks. Therefore, when the frequency of a point on the waveform record changes from high to low, i.e., $\lambda_1 < \lambda_2$ (see Figure 2c), it is determined that this point is the bottom signal.

According to the waveform characteristics, different methods are selected, and Equation (1) is used to estimate the effective length of the steel rod.

L

$$=\frac{v\times t}{2}\tag{1}$$

Here, L represents the length of soil nail, v represents the wave propagation speed, and t represents the propagation time.

3. Database of Measured and Predicted Nail Length

This section presents a broad database of soil nail length, including measured length and NDT-predicted length data. The soil nail data were from various retaining wall projects in Qingdao, a city in Shandong Province, China. Table 1 summarizes the project information, including wall geometry, soil strength properties, and nail arrangement. The soil strength properties were determined by direct shear tests on soil samples in the laboratory. The walls ranged from 6 m to 32 m with very steep facings and flattened back slopes. They were built in a wide range of soils, e.g., silty clay, sand, silt. The soil properties are all within typical ranges. The nails are spaced at a spacing of about 1.2–1.5 m vertically and horizontally. There is a hybrid wall with a height of 32 m; the slope is reinforced with soil nails and prestressed cables. In this wall, i.e., W4, the nail length is over 31 m, which is not very common in practice. Nevertheless, this is a desirable case for testing the ability of the NDT method when applied for long nails.

Wall	Soil Type	Wall Geometry			Soil Strength Properties			Nail			
		<i>H</i> (m)	α (°)	β (°)	φ (°)	<i>c</i> (kPa)	γ (kN/m ³)	<i>S_h</i> (m)	S_v (m)	i (°)	<i>d</i> (mm)
W1	Silty clay	8.1	10	0	22	16	18.2	1.2	1.2	20	22
W2	Silty clay	16	0	5	17	22	17.9	1.2	1.2	15	25
W3	Silty clay with gravel	22	20	20	21	10	19	1.35	1.35	10	30
W4	Clay, medium sand	32	40	6	23-31	10-16	20	1.5	1.5	10	36
W5	Silty clay, sand	6.2	0	0	24	18	19	1.4	1.4	10	22
W6	Silty sand, clay	6-12	15	5	27-31.9	0-17	19.1-20.2	1.4	1.4	10	25
W7	Silty clay, coarse sand	8-10	6	0	12.3	16	20.8	1.2	1.2	15	25
W8	Silty clay	17	10	5	18.9	26	19.2	1.5	1.5	10	25
W9	Sandy silt, fine sand	20.5	11.3-22	0	20-40	0-20	19.2	1.5	1.5	8	30

Table 1. Summary of wall geometry, soil properties, and nail arrangement for soil nail walls.

Note: H = wall height; α = face batter angle; β = back slope angle; ϕ = soil friction angle; c = soil cohesion; γ = soil unit weight; S_h = horizontal nail spacing; S_v = vertical nail spacing; i = nail inclination angle; and d = nail bar diameter.

A total of 116 sets of non-destructive testing (NDT) data for soil nails were collected following the testing procedure: (1) attach the sensor/transducer at a location 2 cm from the nail head through a circular connector that fits the shape of the nail tendon tightly; (2) hit the nail head (tendon) with a small or a large hammer, where small hammer excites waves with low frequencies and large hammer excites waves with high frequencies; (3) record the wave signal received by the sensor through a digital oscilloscope, which is then connected

to a laptop for data storage. Table 2 summarizes the information of the database, including hammer types, estimation methods, measured lengths, and NDT-predicted lengths of these soil nails. By developing this database, the errors of the three NDT methods in predicting nail length can be statistically evaluated and calibrated.

No.	True Length (m)	Hammer Type	Estimation Method ^a	NDT Nail Length (m)	No.	True Length (m)	Hammer Type	Estimation Method ^a	NDT Nail Length (m)
1	9.0	Small	SA	9.11	59	4.5	Large	FC	4.33
2	9.0	Small	SA	9.09	60	4.5	Large	FC	4.33
3	9.0	Large	FC	9.08	61	4.5	Small	SA	4.13
4	9.0	Large	FC	9.08	62	4.5	Small	FC	4.10
5	9.0	Small	FC	9.04	63	4.5	Large	FC	4.13
6	9.0	Small	SA	9.05	64	4.5	Large	FC	4.09
7	9.0	Large	SA	8.99	65	4.5	Small	SA	4.36
8	9.0	Large	FC	8.87	66	4.5	Small	FC	4.33
9	15.2	Small	SA	16.71	67	4.5	Large	SA	4.14
10	15.2	Small	SA	15.94	68	4.5	Large	SA	4.10
10	15.2	Large	ER	16.52	69	4.5	Small	SA	3.48
12	15.2	Large	ER	16.59	70	4.5	Small	SA	3.50
12	15.6	Small	SA	16.40	70 71	4.5	Large	SA	3.47
13	15.6	Small	FC	15.89	72	4.5	Large	SA	3.50
14	15.6		FC	15.47	73	4.5	Small	FC	3.71
15	15.6	Large	FC	15.47	73	4.5	Small	FC	3.69
10	15.6	Large	SA	16.37	74 75	4.5		FC	3.69
17 18		Small Small	SA	16.37	75		Large	FC	
	15.6					4.5	Large		3.66
19	15.6	Large	FC	15.09	77	4.5	Small	SA	3.56
20	15.6	Large	FC	16.00	78 70	4.5	Small	SA	3.50
21	15.6	Small	SA	15.98	79	4.5	Large	SA	3.54
22	15.6	Small	SA	16.07	80	4.5	Large	SA	3.51
23	15.6	Large	FC	15.90	81	5.0	Small	SA	4.79
24	15.6	Large	SA	16.39	82	5.0	Small	FC	4.72
25	15.6	Small	ER	15.52	83	5.0	Large	FC	4.77
26	15.6	Small	FC	15.45	84	5.0	Large	FC	4.75
27	15.6	Large	ER	16.17	85	12.0	Small	SA	12.01
28	15.6	Large	FC	16.16	86	12.0	Small	SA	11.80
29	31.6	Small	FC	32.40	87	12.0	Large	SA	11.93
30	31.6	Small	FC	32.5	88	12.0	Large	SA	11.90
31	31.2	Small	SA	32.2	89	12.0	Small	ER	11.63
32	31.2	Small	ER	30.42	90	12.0	Small	FC	11.62
33	31.2	Large	SA	32.13	91	12.0	Large	FC	12.16
34	31.2	Large	FC	32.08	92	12.0	Large	FC	11.90
35	31.6	Small	SA	29.98	93	21.0	Small	ER	21.17
36	31.6	Small	FC	29.04	94	20.5	Small	FC	17.65
37	31.6	Large	SA	31.84	95	20.6	Large	FC	19.80
38	31.6	Large	SA	32.21	96	20.8	Large	FC	25.20
39	31.6	Small	FC	31.66	97	21.0	Small	ER	20.35
40	31.6	Small	FC	29.37	98	21.0	Small	FC	25.00
41	31.6	Large	FC	32.74	99	24.5	Large	FC	28.00
42	31.6	Large	FC	33.08	100	28.2	Large	FC	29.50
43	31.6	Large	FC	31.74	101	3.5	Small	ER	3.20
44	31.6	Large	SA	32.07	102	3.5	Small	FC	3.07
45	4.5	Small	SA	4.28	103	6.2	Large	FC	6.00
46	4.5	Small	SA	4.42	104	9.0	Large	FC	9.74
47	4.5	Large	SA	4.09	105	9.0	Small	ER	9.80
48	4.5	Large	SA	4.15	106	9.0	Small	FC	10.40
49	4.5	Small	SA	3.95	107	26.1	Large	FC	27.50
50	4.5	Small	SA	3.94	108	26.1	Large	FC	27.25
51	4.5	Large	SA	4.10	109	23.1	Small	ER	22.50
52	4.5	Large	SA	4.16	110	3.5	Small	FC	6.45
53	4.5	Small	SA	4.35	110	3.5	Large	FC	4.25
55 54	4.5	Small	SA	4.31	111	15.56	Large	FC	15.50
55	4.5	Large	SA	4.40	112	3.0	Small	ER	3.08
56	4.5	Large	SA	4.24	113	3.0	Small	FC	2.00
57	4.5	Small	FC	4.24	114	3.0	Large	FC	4.00
58	4.5	Small	SA	4.23	115	3.0	Large	FC	3.12
50	1.0	Jilian N. L. a		4.54	110	0.0			0.12

Table 2. Summary of soil nail parameter of NDT method.

Note: ^a SA = Slope attenuation; FC = Frequency change of end reflection; ER = End reflection.

Hammers that are used to strike the head of soil nails to generate acoustic signals are specified into two types, i.e., large and small. Both types of hammers are in a cylindrical shape. The large hammer has a diameter of 40 mm, while the small hammer has a diameter of 10 mm. The waves excited from small diameter hammers have higher frequencies and are theoretically more suitable for shorter nails; meanwhile, large hammers excite waves with lower frequencies and are more suitable for longer nails.

The data show that using large and small hammers each account for 50% of the collected soil nail NDT projects. The NDT estimation methods of frequency change of end reflection, slope attenuation, and end reflection take up 48.3%, 41.4%, and 10.3%, respectively. Figure 3 displays the histogram and cumulative percentage of the true (measured) lengths of soil nails. The x-axis is the measured nail length L_m ; the y-axis on the left is the relative frequency, defined as the ratio of the value of L_m in a certain interval to the total number of data; the y-axis on the right is the cumulative distribution, defined as the percentage of L_m data below a certain value. According to the data, the minimum true nail length is 3.00 m, the maximum is 31.60 m, and the average is 12.86 m; 50% of lengths are less than 9.0 m, and over 80% of the lengths are within 21.00 m. Figure 4 illustrates the tests carried out on site. Following the testing procedure described above, the wave signals are acquired on site and then analyzed according to the three methods introduced in Section 2 to determine the nail length. Overall, the database contains good information for the evaluation of model accuracy of the NDT methods on the length of soil nails.

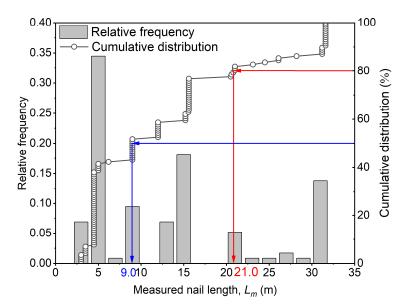


Figure 3. Histograms and cumulative distributions of measured nail length.



Figure 4. Illustration of the non-destructive tests on soil nails on site.

4. Results of Accuracy Assessment

In this section, the model bias λ is used to quantify the accuracy of the NDT methods for nail length. The model bias λ is defined as the ratio of the true nail length to the NDT-predicted nail length. The model bias λ is treated as a random variable, with its mean representing the average accuracy of the model and its coefficient of variation (COV) characterizing the deviation between predicted and actual values. This section firstly evaluates the NDT methods using all collected data as one group; then, the data are further divided into several subsets according to hammer type and estimation method in order to discuss the impact of these factors on the estimation accuracy. In addition, this section also characterizes the probability density functions for the model biases.

Figure 5 shows the comparison between the true (measured) nail length and the NDTpredicted nail length. Visually, the measured and predicted nail lengths from all ranges are in good agreement with each other, following around the 1:1 corresponding line. By computing the bias data, it is found that the mean and COV of the bias are 1.03 and 0.12, respectively. This means that, on average, the NDT-predicted nail length is nearly accurate, i.e., just 3% shorter than the true length, and the dispersion in prediction accuracy is very low, i.e., just 12%. According to the ranking scheme proposed by Phoon and Tang [25], the accuracy of the proposed NDT methods can be considered as high. Therefore, the three NDT methods can satisfactorily predict the nail length.

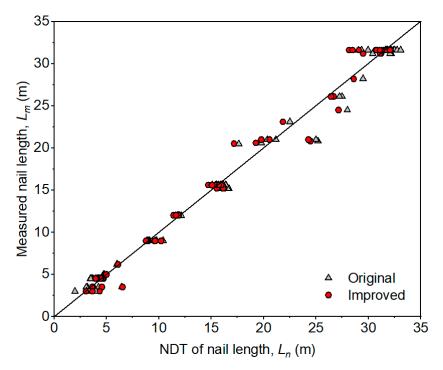


Figure 5. Plots of measured versus NDT-predicted nail length.

Figure 6 plots the model biases, λ , against the NDT predicted nail length. The model bias λ appears to decrease from about 1.5 to 1.0 as the predicted length L_n increases from about 2 m to 5 m. After that, there appears to be no apparent trend between λ and L_n . A Spearman rank correlation test was conducted on the dataset, and the results showed that the Spearman correlation coefficient ρ between L_n and λ is -0.65 and the *p*-value is 0 (less than 0.05), suggesting a statistically significant negative correlation between λ and L_n at a significance level of 0.05. This is undesirable, as the model accuracy statistically depends upon the predicted value.

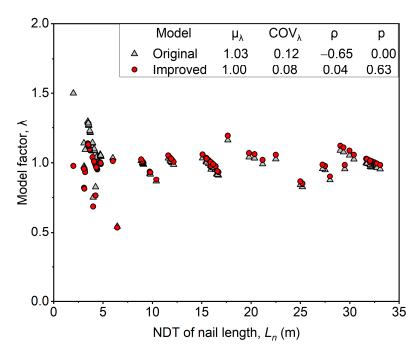


Figure 6. Plots of original and improved values λ for the NDT model against its predicted values.

To further investigate the influence of hammer type and NDT estimation method on prediction accuracy, the bias data were divided into subsets, for example, λ based on small or large hammers and λ based on the frequency change of the end reflection method, the end reflection method, and the slope attenuation method. The cumulative distributions of these bias data subsets are plotted in Figure 7a,b. Visually, the distributions appears to have similar trends, suggesting no significant differences among the subsets. The bias means are 1.02 and 1.04 for the data subsets from the large and small hammers, respectively, and the bias COVs are 0.104 and 0.126, respectively. The differences between the means and the COVs are actually small. This suggests that these two subsets could be from the same population. Similar observations can be made for the method-based subset cases.

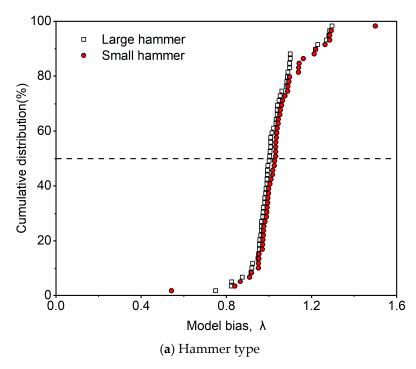
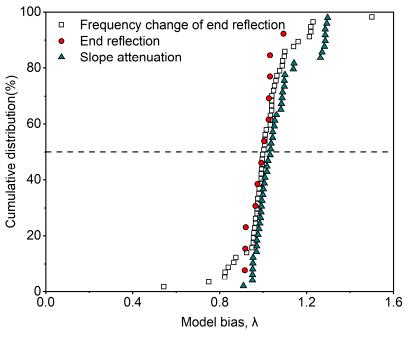


Figure 7. Cont.



(b) Estimation method

Figure 7. Probability cumulative distribution of model bias for the hammer type and estimation method.

The Mann–Whitney test was applied to the two subsets based on hammer type, and the Kruskal–Wallis test was applied to those based on NDT methods. The test results were summarized in Table 3. The *p*-value from the Mann–Whitney test was 0.219, which is greater than 0.05, quantitatively confirming that the two bias data subsets can be considered from the same population at the 0.05 significance level. In other words, selecting either a small or big hammer has no significant effect on the accuracy of the NDT method in predicting the effective length of soil nails. The Kruskal–Wallis test results showed that the *p*-values were 1.000, 0.162, and 0.125; all again exceeded 0.05. Therefore, it can be concluded that the selection of hammer type and estimation method has no significant impact on the accuracy of the NDT method for soil nail length.

Data Crown	Model	Bias, λ	Mann–Whitney or Kruskal–Wallis	
Data Group	Mean	COV	<i>p</i> -Value	
All data, <i>n</i> = 116	1.03	0.116	Not applicable	
Large hammer, $n = 58$	1.02	0.104	0.219	
Small hammer, $n = 58$	1.04	0.126	>0.05	
Frequency change of end reflection, $n = 56$	1.01	0.129	1.000	
End reflection, $n = 12$	0.99	0.053	>0.05	
End reflection, $n = 12$	0.99	0.053	0.162	
Slope attenuation, $n = 48$	1.06	0.103	>0.05	
Slope attenuation, $n = 48$	1.06	0.103	0.125	
Frequency change of end reflection, $n = 56$	1.01	0.129	>0.05	

Table 3. Summary of statistics of model biases and Mann–Whitney or Kruskal–Wallis test results for different data cases.

5. Model Calibration

While the prediction accuracy of the NDT methods is small, i.e., the average error is between 1% and 6%, as shown in Table 2, it is still desirable to make improvements given that no computational complexity is added. This section attempts to complete this improvement task. Figure 6 shows that the model bias of the original method decreases as the predicted value increases; the Spearman's correlation coefficient is $\rho = -0.65$, and the *p*-value is 0.00, showing statistical correlation at the 0.05 significance level. Therefore, an empirical correction term can be introduced to the predicted value to improve accuracy. To be practical, the expression of the correction term should be kept simple. As a result, this section uses the simple linear function, logarithmic function, exponential function, and power function to fit the model bias against the predicted value, i.e., λ vs. L_n . The power function outperformed other fittings, and the deterministic coefficient reaches R² = 0.44; the fitting expression *M* is as follows:

$$M = \alpha L_n^\beta + \eta \tag{2}$$

where α , β , and η are empirical constants to be optimally determined based on the database. With the introduction of M, the new NDT-predicted nail length L_{new} can be calculated as:

$$L_{new} = ML_n = \left(\alpha L_n^\beta + \eta\right) L_n \tag{3}$$

Accordingly, the new model bias can be calculated as $= L_m/L_{new}$. The empirical constants α , β , and η are optimally obtained by solving for the minimum value of the coefficient of variation (COV) of the new model bias while keeping the mean value of the new model bias at 1. The optimal values of α , β , and η are $\alpha = 2.56$, $\beta = -2.18$, and $\eta = 0.97$ (see Table 4). The corrected model, i.e., Equation (3), has a bias mean of 1.00 and a bias COV of 0.08. This represents a 3% enhancement in the average model accuracy and a 4% decrease in the accuracy dispersion after a simple calibration. The Spearman's rank correlation test showed no statistical correlation between the new model biases and the new NDT-predicted values.

Table 4. Summary of statistics of model biases for the original and improved NDT methods for nail length.

Model	C	orrection Bi	as		Model Bias, λ			
widdei	α	β	η	μ	COV	Correlation with L_n	Distribution	
Original	1	1	0	1.03	0.12	Negative	Second-order Gaussian	
Improved	2.56	-2.18	0.97	1.00	0.08	Uncorrelated	Cubic Polynomial	

6. Probability Distribution of λ

This section characterizes the probability distributions of the model biases for both the original and improved NDT methods. Figure 8 shows the cumulative distribution of all original and improved model biases. The (modified) Kolmogorov–Smirnov (K-S) tests were applied to the data and the results showed that the biases do not follow Normal, Lognormal, Gamma, or Weibull distributions. For cases where bias does not follow common distributions, multi-order Gaussian functions can be used to track the trend of the bias data. The effectiveness of this method in approximating highly non-linear distributions has been proven by, e.g., Yuan and Lin [26] and Lin et al. [27]. Table 5 summarizes the mathematical expressions and parameters of the second-order Gaussian model and cubic polynomial model, corresponding to the biases for the original and improved models. The coefficients of determination for both cases are all close to 1.00; thus, the fittings appear satisfactory in capturing data trends.

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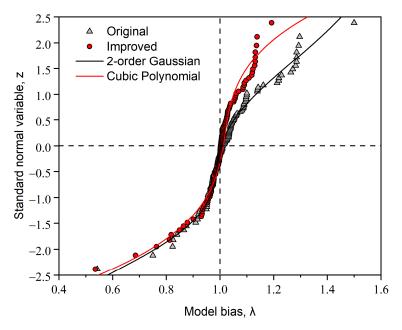


Figure 8. Second-order Gaussian and Cubic polynomial fittings to the cumulative distribution of model biases.

Table 5. Formulations and parameters for the multi-order Gaussian and polynomial fittings.

Model	Fitting Model	Expression	Parameter	Value	R^2
Original	Second-order Gaussian	$\lambda = \sum_{k=1}^{k=2} a_k exp\left[-\left(\frac{z-b_k}{c_k}\right)^2\right]$	$ \begin{array}{c} a_1\\ b_1\\ c_1\\ a_2\\ b_2\\ c_2 \end{array} $	$\begin{array}{c} 1.593 \\ 3.962 \\ 4.777 \\ 0.460 \\ -1.510 \\ 1.681 \end{array}$	0.975
Improved	Cubic Polynomial	$\lambda = p_1 z^3 + p_2 z^2 + p_3 z + p_4$	p ₁ p ₂ p ₃ p ₄	0.020 - 0.012 0.031 1.012	0.965

7. Conclusions

This study first collected 116 sets of nail length data from real soil nail wall projects and then conducted a quantitative evaluation of the accuracy of non-destructive testing (NDT) methods for predicting nail length based on statistical theory. The main conclusions are as follows:

- (1) Three NDT methods for estimating soil nail length are developed. They are slope attenuation, end reflection, and the frequency change of the end reflection. On average, these NDT methods can accurately predict soil length with an error of 3%. The dispersion of prediction accuracy is low, i.e., only about 12%.
- (2) The three NDT methods have good stability in predicting soil nail length; their accuracies do not depend upon the hammer types and the method types at a level of significance of 0.05.
- (3) By introducing a simple power function to the prediction of the original NDT methods, the on-average accuracy increases by 3% and the dispersion decreases by 4%, without additional computational complexity.
- (4) The probability distributions of the biases for the original and improved NDT methods can be approximated using second-order Gaussian and cubic polynomial functions, respectively.

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