

# Article AquaVision: AI-Powered Marine Species Identification

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**Abstract:** This study addresses the challenge of accurately identifying fish species by using machine learning and image classification techniques. The primary aim is to develop an innovative algorithm that can dynamically identify the most common (within Maltese coastal waters) invasive Mediterranean fish species based on available images. In particular, these include *Fistularia commersonii*, *Lobotes surinamensis, Pomadasys incisus, Siganus luridus,* and *Stephanolepis diaspros,* which have been adopted as this study's target species. Through the use of machine-learning models and transfer learning, the proposed solution seeks to enable precise, on-the-spot species recognition. The methodology involved collecting and organising images as well as training the models with consistent datasets to ensure comparable results. After trying a number of models, ResNet18 was found to be the most accurate and reliable, with YOLO v8 following closely behind. While the performance of YOLO was reasonably good, it exhibited less consistency in its results. These results underline the potential of the developed algorithm to significantly aid marine biology research, including citizen science initiatives, and promote environmental management efforts through accurate fish species identification.

**Keywords:** image classification; machine learning; convolution neural networks; citizen science; Mediterranean basin; invasive alien species

# 1. Introduction

Biodiversity in diverse ecosystems is increasingly under threat due to rapid global changes. Notably, global warming and the introduction of invasive alien species (IAS) and non-indigenous species (NIS) often act in tandem, aggravating their impact on ecosystems [1]. The Mediterranean coastal regions are a prime example of these biodiversity changes. Since the opening and subsequent expansion of the Suez Canal, over 150 non-indigenous fish species from the Red Sea have entered the Mediterranean Sea since 1869 [2]. The significant warming of the Mediterranean surface waters, which has increased by over 1 °C since 1980, has further driven the northward and westward spread of these tropical non-native species, affecting both their distribution and abundance [3].

In recent years, the use of underwater image processing for species identification has gained significant attention, especially in addressing the challenges posed by newly introduced IAS and Alien Invasive Species (AIS). Accurate species classification has become essential in various fields, including fisheries, marine biology, and aquaculture. Identifying fish species serves several purposes in fisheries management. Firstly, it aids in post-catch inspections, particularly in countries with regulations prohibiting the capture of protected species and enforcing quotas on fishing vessels. Additionally, accurate species identification is crucial for effectively monitoring fish harvests and establishing sustainable and profitable fisheries [4].

Alien species are organisms or taxa introduced to regions beyond their natural habitats, often through human activities. These species can survive, reproduce, and spread outside their original range, exceeding their natural propagation [5]. The term includes various synonyms such as non-native, non-indigenous, allochthonous, foreign, exotic, immigrant,



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**Copyright:** © 2024 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). imported, transported, or adventive, as classified within the Colautti and MacIsaac system [6]. In biodiversity conservation, invasive alien species are particularly concerning as they can negatively impact native ecosystems. However, it is important to recognise that not all alien species are harmful; some may benefit society and the economy, especially in sectors like agriculture and aquaculture [5,7].

Invasive species are those that have successfully established themselves in new habitats, are rapidly increasing in population, and pose a threat to native species diversity and abundance [7]. They disrupt the ecological balance and can endanger economic activities and human health. As the International Union for Conservation of Nature (IUCN) notes, their impact is comparable to habitat loss [7]. Biological invasions in marine environments are particularly troubling for conservation and economic interests, prompting awareness campaigns by national governments and international organisations [8]. The Mediterranean Sea has over 500 recorded alien species, leading to significant impacts such as sudden declines in native species abundance and local extinctions. While immediate extinctions may not always occur, the changes induced by invasive species reduce genetic diversity, disrupt ecological functions, and alter habitats, increasing the risk of further declines and ecosystem homogenisation [9].

The introduction of *Siganus luridus* and *S. rivulatus* in the Mediterranean occurred in 1956 and 1927, respectively. *S. luridus* has established significant populations in both eastern and western regions, while *S. rivulatus* has been found as far west as Corsica [10]. These species impact algae through grazing, leading to areas barren of macroalgae, notably affecting species like *Cystoseira* sp. Another invasive species, the blue-spotted cornetfish (*Fistularia commersonii*), originally from the Indian and Pacific Oceans, is one of the most successful invaders in the Mediterranean and European waters and was first recorded along the Mediterranean coasts of Israel in January 2000 [11]. Similarly, the Atlantic tripletail (*Lobotes surinamensis*), a cosmopolitan species, has been found in Maltese coastal waters. The bastard grunt (*Pomadasys incisus*), a subtropical species, has naturally entered the Mediterranean Sea through the Straits of Gibraltar, along with other Haemulidae family members, including the non-native *P. stridens* [6]. Many of the introduced species, such as the reticulated leatherjacket (*Stephanolepis diaspros*), are often discarded by local fishermen [12,13].

Shipping remains the primary introduction pathway for alien species, followed by secondary dispersal within the Mediterranean Sea. There is a clear increasing trend in the reporting of alien species, peaking in the last decade. Additionally, the warming trend in Mediterranean waters is facilitating the spread of thermophilic alien species from the Eastern to the Central Mediterranean and the expansion of tropical and subtropical Eastern Atlantic species towards the east [5].

The study of marine species recognition is a crucial component of efforts to protect the ocean environment. Despite its significance, this area remains under-represented within the field of computer vision. Nevertheless, advancements in deep learning have stimulated a growing interest in this subject [14]. Within recent studies, the precise automation of fish individual detection and identification has been achieved using machine-learning techniques, which include support vector machines, nearest neighbour classifiers, discriminant analysis classifiers, and deep learning. Recent competitions and comparisons indicate that deep-learning methods, specifically CNNs, which integrate automatic image description and classification, consistently demonstrate superior performance [15]. Another study conducted by Catalán et al. [16] investigated advancements in fish identification and classification within underwater imagery using deep learning. They underscored key issues such as the influence of diverse backgrounds, accuracy in labelling small fish, the need for a large training image dataset, and selection methodologies. The researchers introduced an annotated dataset comprising 18,400 records of Mediterranean fish representing 20 species within 1600 images featuring diverse backgrounds. Comparing two leading object-detection models, YOLOv5m and Faster RCNN, they found that YOLOv5m

consistently outperformed Faster RCNN, specifically achieving mAP@0.5 values exceeding 0.8 across various scenarios.

The study by Gauci et al. [17] explored the use of citizen science initiatives for classifying jellyfish species in Maltese waters using CNNs. As citizen science campaigns gain popularity, data collection in marine environments has increased. However, the validation of submitted reports, particularly for the taxonomic identification of jellyfish, remains challenging due to the high volume of reports and the limited number of trained staff. The photos for their dataset were sourced from the "Spot the Jellyfish" campaign to train region-based CNNs to classify the five most commonly reported jellyfish species in Maltese waters: Pelagia noctiluca, Cotylorhiza tuberculata, Carybdea marsupialis, Velella velella, and salps. The reliability of their models was evaluated using precision, recall, f1 score, and  $\kappa$  score metrics. They also investigated the advantages of data augmentation and transfer-learning techniques. The results were very promising, suggesting the potential for embedding automated classification methods, possibly in smartphone apps, to reduce or eliminate the need for human validation of the submitted reports. Confusion matrices were used to assess classification accuracy, and precision, recall, and f1 scores were used as error metrics for each class. The study found that models using the GoogLeNet and ResNet feature extraction network performed the best, with an increase in accuracy observed with more anchors.

The main aim of this research study is to create an algorithm that will identify invasive alien marine species in the Mediterranean region. This algorithm will be integrated within a website where individuals can submit any invasive species caught as by-catch and receive an accurate identification, alongside a species description.

The findings will be saved to a database to continuously train the model to new morphological adaptations of the species, thus enhancing its learning and accuracy over time. Initially, the project will begin as a local initiative within the Maltese Islands, engaging the local community. Eventually, it will expand to cover the entire Mediterranean basin, allowing participation from any country in the region to contribute their invasive species data.

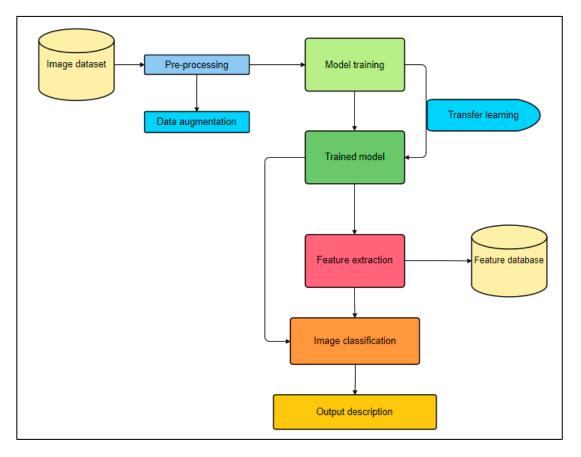
However, technological advancements persist, which can accurately identify fish species despite various factors such as limited datasets, segmentation errors, image distortion, and object overlap, all of which hindered the effectiveness of existing methods [18]. Moreover, the need to distinguish between species with similar characteristics, which is exacerbated by variations in body colouration caused by factors like light absorption at different depths, presents additional obstacles [19]. In addition, the degradation of image quality in underwater settings is consistently identified as a significant factor contributing to inaccuracies and misclassifications in image-based techniques. Addressing image quality concerns is therefore pivotal to improving the accuracy and reliability of underwater image analysis methods [11]. Manual classification methods were previously used for fish species identification, but these are labour-intensive and prone to human errors, necessitating efficient automatic methods [19]. The application of CNNs has shown promise in automating this process, achieving high accuracy scores and reducing reliance on manual intervention [20].

Overall, this project aims to engage citizen scientists and raise awareness about the recurring issue of invasive marine species. It will create a comprehensive database documenting species finding, enabling the tracking of species spread, and facilitating future mitigation efforts. Additionally, it will provide countries with early warnings to prepare for potential extreme invasions, thereby safeguarding local marine flora and fauna.

### 2. Materials and Methods

### 2.1. Framework

The framework adopted in this study is presented in Figure 1. This infrastructure was used to train the image classifiers and the object detector. The only difference was



that during the pre-processing stage there were the inclusion of image annotations and the implementation of bounding boxes.

**Figure 1.** The proposed framework for model training initiates with pre-processing and augmenting an image dataset. This is then used to train the model, whilst employing transfer-learning techniques. Ultimately, the trained model extracts the image features, and stores them in a database, generating an output description.

#### 2.2. Generation of Image Dataset

A comprehensive dataset was created by sourcing images from various platforms, including Google, FishBase, iNaturalist, contributions from divers, and submissions from the 'Spot the Alien' citizen science campaign. These images (Figure 2) varied in resolution, angles, and morphological colours, and depicted both younger and more mature specimens. This diverse range of images ensured thorough training of the algorithm, enabling it to effectively learn and adapt to the nuances of fish species identification.

Table 1 showcases the distribution of images across different classes, showcasing the composition of the final dataset comprising five fish species for this study, totalling 1337 images. These IAS were selected for two reasons; firstly as they are prevalent within Maltese waters, and secondly they have an abundance of images available, which is key for effectively training the models. The dataset was partitioned into train, validation, and test sets with proportions of 70%, 20%, and 10%, respectively, to ensure consistency across model training. All models underwent training on this standardised dataset to facilitate meaningful comparisons. However, it is worth noting that around 15% of the test images were not used as they were not recognised due to format restrictions by YOLO.





(a)



(**d**)



(e)

**Figure 2.** The five invasive fish species chosen for this research study; (**a**) *Pomadasys incisus*, (**b**) *Stephanolepis diaspros*, (**c**) *Lobotes surinamensis*, (**d**) *Siganus luridus*, (**e**) *Fistularia commersonii*.

Species	Number of Training Images	Number of Validation Images	Number of Testing Images
Fistularia commersonii	277	79	41
Lobotes surinamensis	203	58	30
Pomadasys incisus	123	35	19
Siganus luridus	177	50	26
Stephanolepis diaspros	153	43	23

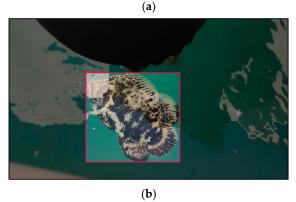
Table 1. Number of images used for training, validation, and testing for each species.

In the pre-processing stage, images were resized to prepare them for training across different models. Unnecessary backgrounds were cropped from certain images, and bounding boxes were created for the YOLO model to ensure the focus remained on relevant objects. Notably, YOLO v8 does not require specific pixel dimensions. However, for ResNet18, images were resized to a standardised size of 224 pixels, while for the TF.Keras Sequential model resizing was set to 180 pixels. This tailoring in image sizes within different model datasets facilitated consistent training and evaluation processes.

## 2.3. Development of the Classification Models

Due to the limited availability of high-resolution images, the existing dataset was utilised until further testing with a larger high-resolution photo dataset can be undertaken. Nonetheless, it is essential to ensure that the training of the algorithm encompasses a wide array of resolutions and augmented images to enhance its robustness [6]. For the YOLO model, Roboflow was used to annotate all images (Figure 3) and to create bounding boxes around objects of interest. This preparation of the dataset facilitates effective training of the model for accurate detection and classification of objects within the images.





**Figure 3.** Bounding boxes applied using Roboflow (https://roboflow.com) to identify two species: (a) *Fistularia commersonii* and (b) *Lobotomes surminensis*. Each bounding box highlights the individual species within the image for clearer recognition and analysis.

In this study, three models were utilised to differentiate between five common invasive fish species, based on research conducted from multiple journal articles and sources. Amongst them, two are image classifiers (ResNet and TF.Keras), whilst the other one, YOLO, serves as an object detector. Despite the widespread use of all these models in species identification studies, image classifiers tend to be the preferred choice in this aspect.

The final models used were built upon the open versions freely available on the internet, which were already optimised and pre-trained on similar pattern recognition tasks via transfer learning. Transfer learning in machine learning involves using a model developed for one task as the foundation for a new model tailored to a different but related task. This technique makes use of the knowledge gained from solving one problem and applies it to another, facilitating more efficient learning, as demonstrated in this study. In computer vision, transfer learning is particularly prevalent, typically involving the use of a pre-trained model from an extensive database as a starting point for a specific task [21]. Such an approach involves the use of a pre-trained CNN that can extract features from thousands of natural images coming from various categories. By utilising a model that has already refined generic features from a similar task, transfer learning significantly reduces the time and computational resources needed in comparison to building and training a new model from the ground up [18].

Subsequently, the models were trained and optimised to extract the features from the fish images. Feature extraction is the process of transforming raw data into interpretable representations modified for a specific classification task. For instance, an image consists of millions of pixels, each containing colour information. Feature extraction reduces the high dimensionality of these images by calculating abstract features, which are quantified representations that preserve relevant information for the classification task (such as shape, texture, or colour) while discarding redundant details [22]. This process enhances the efficiency and accuracy of the classification by focusing on the most pertinent aspects of the data.

These models were trained with different epochs, ensuring sufficient training and achieving reasonable accuracies while avoiding overfitting. Confusion matrices, graphs, and accuracy scores, including metrics like precision, recall, and f1 score, were produced to evaluate the training and learning outcomes. After this thorough evaluation, the best model was chosen based on these scores, and it was then fully optimised and developed for the final implementation.

In many classification scenarios, the data available are often insufficient to train classifiers that are both accurate and robust. To tackle this challenge, a widely adopted strategy is data augmentation (DA) [23]. This approach involves generating synthetic instances to augment the size of the training dataset, aiding in the prevention of overfitting. In this research study, with only 1337 training images accessible, overfitting was mitigated through augmentation, highlighting the effectiveness of this method in enhancing model robustness despite limited data availability.

In the implementation of the ResNet18 model, data augmentation techniques such as random resize and random horizontal flip were applied, alongside data normalisation, to both the training and validation datasets. Following this, TF.Keras Sequential model utilised data augmentation methods, ensuring that the datasets were enhanced for improved model performance, whilst YOLO v8 incorporated automatic data augmentation techniques. This step ensured that all models benefitted from augmented datasets during training, thereby improving their ability to learn diverse features and prevent overfitting.

### 3. Results

## 3.1. Confusion Matrices

The confusion matrices resulting after testing all three classification models with the same set of images are shown in Table 2. The columns represent the actual species depicted in the test images, while the rows indicate the classifications assigned by the respective model. Confusion matrices were employed as they facilitate in discerning whether a

classifier is exhibiting random behaviour or encountering difficulty in distinguishing between certain classes [24].

**Table 2.** Confusion matrices presenting the classification results for five selected fish species using three different models: TF.Keras, ResNet18, and YOLO v8. Each matrix illustrates the performance and accuracy of the respective model in identifying and distinguishing between the species.

Model		Actual					
		Fistularia commersonii	Lobotes surinamensis	Pomadasys incisus	Siganus luridus	Stephanolepis diaspros	
TF.Keras	Fistularia commersonii	24	2	8	4	3	
	Lobotes surinamensis	4	20	3	1	2	
	Pomadasys incisus	3	2	11	1	2	
	Siganus luridus	4	2	3	12	5	
	Stephanolepis diaspros	3	0	3	5	12	
ResNet18	Fistularia commersonii	40	0	0	1	0	
	Lobotes surinamensis	1	28	0	0	1	
	Pomadasys incisus	0	0	18	1	0	
	Siganus luridus	1	1	1	21	2	
	Stephanolepis diaspros	1	2	0	0	20	
YOLO v8 *	Fistularia commersonii	32	0	0	0	0	
	Lobotes surinamensis	2	17	0	4	1	
	Pomadasys incisus	1	0	9	1	0	
	Siganus luridus	1	0	6	20	0	
	Stephanolepis diaspros	1	1	0	0	15	

\* A select number of images in the test dataset could not be used due to file format restrictions.

# 3.2. Error Metrics

The accuracy, precision, recall, and f1 score are key evaluation metrics that assess the performance of machine-learning models. These were calculated using the following labelled Equations (1)–(4). True positive (TP) is a measure of how much the model correctly predicted the class (fish species). False positive (FP) indicates how much the model incorrectly identifies the positive class but is actually negative. True negative (TN) is a measure of the occurrences that the model identifies the negative class. False negative (FN) corresponds to the number of situations where the model fails to identify the positive class, incorrectly predicting the negative class.

The precision (Equation (1)) measures the proportion of TP predictions among all positive predictions made by the model. Additionally, the recall (Equation (2)) calculates the proportion of true positive predictions among all actual positive instances. The f1 score (Equation (3)) balances precision and recall by calculating their harmonic and is useful for finding a balance between high precision and high recall, as it accounts for extreme values of either metric. Lastly, the accuracy (Equation (4)) takes into consideration the proportion of correct predictions made by the model across the entire dataset.

$$Precision = \frac{TP}{TP + FP} \tag{1}$$

$$Recall = \frac{TP}{TP + FN}$$
(2)

$$f1 \ score = \frac{2(Recall \times Precision)}{Recall \times Precision} \tag{3}$$

# 3.3. Model Performance Metrics

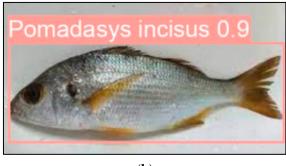
The calculated metrics for all five species and each model can be observed in Table 3. It provides a detailed comparison of how each model performs in identifying each species. In addition, Figures 4 and 5 illustrate the confidence scores on unseen images by YOLO and TF.Keras.

**Table 3.** The precision, recall, *f1* score, and accuracy metrics for the image classification of five fish species using three models. The metrics provide a detailed assessment of the ability of each model to accurately predict and distinguish between the species.

Model	Species	Precision	Recall	f1 Score	Accuracy
TF.Keras	Fistularia commersonii Lobotes surinamensis Pomadasys incisus Siganus luridus Stephanolepis diaspros	0.63 0.77 0.39 0.52 0.50	0.59 0.67 0.58 0.46 0.52	$\begin{array}{c} 0.61 \\ 0.71 \\ 0.47 \\ 0.49 \\ 0.51 \end{array}$	0.57
ResNet18	Fistularia commersonii Lobotes surinamensis Pomadasys incisus Siganus luridus Stephanolepis diaspros	0.98 0.93 0.95 0.81 0.87	0.93 0.90 0.95 0.91 0.87	0.95 0.92 0.94 0.86 0.87	0.91
YOLO v8	Fistularia commersonii Lobotes surinamensis Pomadasys incisus Siganus luridus Stephanolepis diaspros	$\begin{array}{c} 0.86 \\ 0.94 \\ 0.60 \\ 0.80 \\ 0.94 \end{array}$	$ \begin{array}{r} 1.00\\ 0.71\\ 0.82\\ 0.74\\ 0.88\\ \end{array} $	0.93 0.81 0.69 0.77 0.91	0.84



(a)

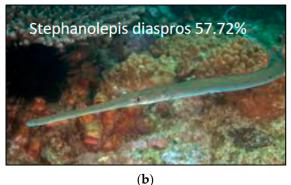


(**b**)

**Figure 4.** Results from the YOLO model, correctly identifying two of the species (**a**,**b**) with a 90% confidence score.



(a)



**Figure 5.** Unseen test images given to the TF.Keras model, where it correctly identified (**a**) *Stephanolepis diaspros*, but misidentified (**b**), which is a *Fistularia commersonii*.

## 3.4. Discussion

It is worth noting that there is a research gap concerning four of the five fish species targeted within this study (i.e., *Fistularia commersonii, Lobotes surinamensis, Pomadasys incisus,* and *Stephanolepis diaspros*) given that the same species have not been previously included in any previous image classification studies. This highlights a clear opportunity for further research and exploration into the application of image classification techniques for these invasive alien species.

A recent study features automated identification protocols for two invasive rabbitfish in the Mediterranean basin, one of which is the *Siganus luridus*. Fleuré et al. compiled a dataset comprising 31,285 images, featuring *Siganus* spp. and six other native Mediterranean fish species, extracted from 40 underwater videos filmed across three reef habitats. Using a deep-learning algorithm based on ResNet50, the researchers trained the model to identify *Siganus* spp. within an image dataset containing these eight species [1].

The results demonstrated that the model achieved a recall of 0.92 for the *Siganus* genus, which increased to 0.98 after confidence-based post-processing, in contrast to the ones used in our study, which achieved slightly lower values (as can be seen in Table 3) as follows: 0.91 (ResNet18), 0.74 (YOLO), and 0.46 (TF.Keras). In terms of precision values, the model of Fleuré et al. obtained a precision of 0.61, whereas our implemented models attained precision values of 0.80 (YOLO) and 0.81 (ResNet18), whilst the TF.Keras model had a significantly lower value of 0.52.

The accuracy values (Table 3) for the ResNet and YOLO (Figure 4) models were notably high, reaching 0.91 and 0.84, respectively, indicating that the resultant automated fish identification from the use of these two models is generally robust and consistent. In contrast, the TF.Keras sequential model (Figure 5) performed the worst, achieving an accuracy of only 0.61.

In terms of precision values, the fish species included in the study which were classified most correctly were *Lobotes surinamensis* (with two out of three models reporting a precision higher than 0.93) and *Fistularia commersonii* (with two out of three models reporting a precision higher than 0.86, including an impressive 0.98 precision from the ResNet18 model).

Interestingly, the ResNet18 model had the highest precision value of 0.95 for *Pomadasys incisus*, while the other models achieved precision values of 0.60 and 0.39, making *Pomadasys incisus* the least identified species for those models. Both the YOLO and ResNet models registered precision values above 0.80 for *Stephanolepis diaspros*, with YOLO achieving an impressive 0.94 precision for *S. diaspros*.

Similarly, high recall and f1 score metrics were recorded for two of the three classification models, further substantiating their robust performance in correctly identifying fish species from the images provided. The f1 scores obtained in this study ranged from 0.47 to 0.95, with the lowest values for all species coming from the TF. Keras model, while the other two models had scores ranging from 0.69 to 0.95. Notably, the lowest f1 score for the ResNet model was 0.86 for *S. luridus*, followed by 0.87 for *S. diaspros*, which is still relatively high compared to values from the other models.

Upon reviewing the outcomes of this study, it is crucial to acknowledge its limitations. As discussed by Villon et al. [25], there are multiple drawbacks when it comes to underwater image classification. For instance, one drawback of the deep-learning algorithm classifier is that its ability to identify a fish species is limited only to images featuring a single individual at the centre. Consequently, raw underwater videos or images must be cropped to isolate fish individuals from noise (e.g., surrounding habitat features or other fish species). Moreover, underwater images might be affected by noise arising from poor lighting conditions or the image compression process. The training and testing sets used in this study were not significantly affected to the extent that it would hinder the detection process. To maintain the sharpness of the images, it was decided not to incorporate any filtering in the processing pipeline. Future work could explore the impact of impulse noise and potential filtering techniques to enhance classification performance further.

Another constraint involves the classifiers' reliance on an adequate number of training dataset photos for each of the targeted species. This necessitates the acquisition of thousands of images per species, often resulting in reduced recall and precision values.

## 4. Conclusions

This study has identified the ResNet18 model as the most effective tool for the automated identification of fish species from images, achieving the highest accuracy score of 0.91. The performance of this model in classifying various fish species, such as *Lobotes surinamensis* and *Fistularia commersonii*, was particularly robust, with precision values reaching as high as 0.98. Given these promising results, it is planned to further develop the ResNet18 model and to focus on improving the overall database to ensure even higher accuracy and reliability values.

Currently, a website is being developed to integrate online the ResNet18 model for use by any citizen scientist. This platform will feature an interactive map and will allow users to submit new sightings of marine species. Eventually, the long-term goal is to expand this database and to include multiple marine invasive species, covering various taxa such as crabs, sea hares, and algae. This initiative will not only help in monitoring marine biodiversity changes through the monitoring of invasive alien species populations but also raise awareness about the same species' introductions through citizen science.

The website will enable citizen scientists to submit their findings, where the algorithm will identify the species and provide a brief description alongside the submitted photo. Each submission will record the location, and, after a review, the image will be added to the database to continually train and improve the algorithm.

An interactive map will eventually display these sightings, initially focusing on the Maltese Islands, so as to engage local citizens through 'Spot the Alien Fish' citizen science campaign. By starting with Malta, we aim to build a strong foundation of local participation

and data collection, which will be instrumental, at a second stage, in scaling up the project so as to cover the entire Mediterranean region.

Through this approach, we aspire to create a comprehensive and dynamic tool that not only aids in species identification but also contributes to the broader effort of marine conservation and invasive species management. The integration of citizen science will play a vital role in this process, empowering individuals to contribute to scientific research.

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