



Article

Comparative Numerical Study of Thermal Features Analysis between Oldroyd-B Copper and Molybdenum Disulfide Nanoparticles in Engine-Oil-Based Nanofluids Flow

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Abstract: Apart from the Buongiorno model, no effort was ably accomplished in the literature to investigate the effect of nanomaterials on the Oldroyd-B fluid model caused by an extendable sheet. This article introduces an innovative idea regarding the enforcement of the Tiwari and Das fluid model on the Oldroyd-B fluid (OBF) model by considering engine oil as a conventional base fluid. Tiwari and Das's model takes into account the volume fraction of nanoparticles for heat transport enhancement compared to the Buongiorno model that depends significantly on thermophoresis and Brownian diffusion impacts for heat transport analysis. In this paper, the thermal characteristics of an Oldroyd-B nanofluid are reported. Firstly, the transformation technique is applied on partial differential equations from boundary-layer formulas to produce nonlinear ordinary differential equations. Subsequently, the Keller-box numerical system is utilized to obtain final numerical solutions. Copper engine oil (Cu-EO) and molybdenum disulfide engine oil (MoS₂-EO) nanofluids are considered. From the whole numerical findings and under the same condition, the thermodynamic performance of MoS₂-EO nanofluid is higher than that of Cu-EO nanofluid. The thermal efficiency of Cu-EO over MoS₂-EO is observed between 1.9% and 43%. In addition, the role of the porous media parameter is to reduce the heat transport rate and to enhance the velocity variation. Finally, the impact of the numbers of Reynolds and Brinkman is to increase the entropy.



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Keywords: Oldroyd-B nanofluid; entropy generation; variable thermal conductivity; Keller-box method

1. Introduction

In 1995, Choi [1] first presented the idea of nanofluid. Their main observation was that the thermal conductivity increased when a low rate of copper nanoparticles was immersed in water. Consequently, numerous mixtures of nanoparticles and liquids have been investigated for improving transport phenomena and thermophysical properties, such as thermal conductivity. Characteristic materials utilized for synthesizing nanofluids include metals, inorganic oxides, carbon-based resources, and other porcelains. Meanwhile, a popular selection of cleaners contains aquatic, ionic liquids, glycols, biological liquids, and refrigerants. Other fluids discovered in research works contain oils, biofluids, mixtures, fuels, alcohols, melted salt eutectics, etc. The preferred fluid properties are important for the selected process, to facilitate the optimal combination procedure for a specific nanofluid. Consequently, it is critical to develop a collection of mixture procedures for the nanofluids' choice group, when subjected to objective properties and processes [2–6].

Another significant issue in nanofluids preparation is long-term stability. Therefore, the nanomanufacturing field was established, producing nanoparticles with various scopes, forms, and construction. Nonetheless, protecting nanoparticle suspension homogeneously in the base fluid for a sufficient long time is a challenging task. Therefore, many methods have been developed to grow the suspensions' stability, and they have fundamentally produced short-range stability. However, no specific investigations have been conducted to confirm long-range stability. The strategic reason for keeping nanoparticle suspensions stable for extended periods of time is to avoid nanoparticle agglomeration. For instance, high thermal conductivity is desirable in heat transmission processes. At the same time, non-Newtonian rheological performance and load-carrying capacity are carefully selected in lubrication processes to vanish heat rapidly.

One significant consideration in a nanofluid composition is the cost and practicability of scaling up to a combination of outsized capacities. Unfortunately, such engineering considerations are usually ignored in critical investigations. Still, they are fundamental to the commercial achievement of nanofluids, if this technology were to enter conservative and novel manufacturing processes [7–10].

Accordingly, it is imperative to recognize, model, and maximize the combination environments to allow superior control over the transport instruments, such as similar or dissimilar nucleation of the nanoparticles compared to the originators or the development and monitoring of the accumulation of the nanoparticles generated. Recently, an increased number of studies on non-Newtonian fluids has been introduced by numerous researchers, because of their excellent reputation in many industrial and chemical activities, nuclear production, bioengineering, geophysics, and material processing. Therefore, the importance of non-Newtonian fluids is still puzzling, and thus, many non-Newtonian designs are being investigated to demonstrate their composite rheological perspective. Among these non-Newtonian fluids, the Oldroyd-B fluid (OBF) releases with synchronized relaxation and retardation times. Furthermore, OBF allows clarifying the creep and standard stress changes, which are related to simple shear flow. Nevertheless, the OBF does not define the shear condensing and shear withdrawing structures, unlike other polymeric materials. The OBF contains viscoelastic applications for Maxwell and viscous fluids for example. Based on such remarkable properties, the flow of OBF was thoroughly investigated in the literature [11–18]. Moreover, researchers have explained the effect of slip boundary conditions in nanofluids past the extending slip [19,20].

Entropy computes the amount of chaos in a system and its environment, which describes the impact of heat transfer on the alterations in kinetic energy and potential energy. The analysis of entropy generation can describe the heat losing progression of a fluid wave. Researchers have utilized the entropy generation analysis in fluid flow, aiming at two rotat-

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ing disks moving with different rotation rates. It indicated that because of every thermal progression, the entropy measures the quantity of irreversibility. Therefore, conserving and warming are the most critical issues in numerous industrial fields of engineering investigations, which are utilized primarily on energy and electronic devices [21–28].

Based on the abovementioned literature, none of the published research works independently considered a Tiwari–Das nanofluid scheme [29] over the stretching sheet, together with the impacts of controlling parameters such as penetrable materials, variant thermal conductance, radiation heat flux, and slip conditions. Hence, the current study emphasizes the mentioned controlling parameters and entropy on an OBF using a specific numerical method, namely, the Keller-box method.

2. Mathematical Formulation

This analysis considers a steady, laminar two-dimensional heat transfer flow of the incompressible Oldroyd-B nanofluid through an extending sheet with first-order slip, convective endpoint conditions, and passive control of different nanoparticles. Equation (1) characterizes the moving flat horizontal surface with the nonuniform expanding velocity U_w , where b is a positive constant. (Figure 1).



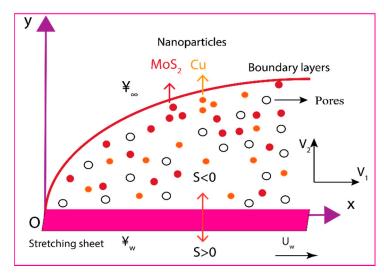


Figure 1. Schematic diagram of the flow model.

2.1. Model Equations

The basic time-independent governing equations of mass, momentum, and thermal energy of a viscous Oldroyd-B nanofluid flow employing customary boundary-layer approximations, subjected to a porous media, and variable thermal conductivity with radiation heat flux are [30]:

$$\frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} = 0, (2)$$

$$v_{1}\frac{\partial v_{1}}{\partial x} + v_{2}\frac{\partial v_{1}}{\partial y} + \lambda_{1}\left[v_{1}^{2}\frac{\partial^{2}v_{1}}{\partial x^{2}} + v_{2}^{2}\frac{\partial^{2}v_{1}}{\partial y^{2}} + 2uv\frac{\partial^{2}v_{1}}{\partial x\partial y}\right]$$

$$= \frac{\mu_{nf}}{\rho_{nf}}\left[\left(\frac{\partial^{2}v_{1}}{\partial y^{2}}\right) - \frac{v_{1}}{k}\right] + \frac{\mu_{nf}}{\rho_{nf}}\left[\lambda_{2}\left(v_{1}\left(\frac{\partial^{3}v_{1}}{\partial x\partial y^{2}}\right) - \frac{\partial v_{1}}{\partial x}\left(\frac{\partial^{2}v_{1}}{\partial y^{2}}\right) + \frac{\partial v_{1}}{\partial y}\left(\frac{\partial^{2}v_{2}}{\partial y^{2}}\right) + v_{2}\left(\frac{\partial^{3}v_{1}}{\partial y^{3}}\right)\right)\right],$$
(3)

$$v_1 \frac{\partial \Psi}{\partial x} + v_2 \frac{\partial \Psi}{\partial y} = \frac{1}{(\rho C_p)_{nf}} \left[\frac{\partial}{\partial y} \left(\kappa_{nf}^*(\Psi) \frac{\partial \Psi}{\partial y} \right) \right] - \frac{1}{(\rho C_p)_{nf}} \frac{\partial q_r}{\partial y}. \tag{4}$$

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The relevant boundary conditions are [31]:

$$v_{1}(x,0) = U_{w} + N\nu\left(\frac{\partial v_{1}}{\partial y}\right), \ v_{2}(x,0) = V_{w}, -k_{0}\left(\frac{\partial \Psi}{\partial y}\right) = h_{f}(\Psi_{w} - \Psi), \text{at } y = 0$$

$$v_{1} \to 0, \ \frac{\partial v_{1}}{\partial y} \to 0, \ \Psi \to \Psi_{\infty} \text{ as } y \to \infty.$$
(5)

where V_w signifies suction (injection) parameter.

2.2. Thermophysical Features of the Oldroyd-B Nanofluid

Thermophysical characteristics are increased by the dispersion of nanoparticles into an aqueous fluid. The material parameters for the Oldroyd-B nanofluid are offered in Table 1 [32,33]:

Table 1. Thermophysical features of the Oldroyd-B nanofluid.

Features	Nanofluid
Viscosity (µ)	$\mu_{nf} = \mu_f (1 - \phi)^{-2.5}$
Density (ρ)	$\rho_{nf} = (1 - \phi)\rho_f + \phi\rho_s$
Heat capacity (ρC_p)	$(\rho C_p)_{nf} = (1 - \phi)(\rho C_p)_f + \phi(\rho C_p)_s$
Thermal conductivity (κ)	$\frac{\kappa_{nf}}{\kappa_f} = \left[\frac{(\kappa_s + 2\kappa_f) - 2\phi(\kappa_f - \kappa_s)}{(\kappa_s + 2\kappa_f) + \phi(\kappa_f - \kappa_s)} \right]$

In Table 1, μ_f , ρ_f , $(C_p)_f$, and κ_f are defined as the nanoparticle volumetric fraction coefficient, dynamic viscosity, intensity, effective heat capacitance, and thermal conductance of the base fluid, respectively. The other properties ρ_s , $(C_p)_s$, and κ_s are denoted as the density, effective heat capacitance, and thermal conductance of the nanoparticles, respectively. The variable thermal conductance is defined as [33,34]:

$$\kappa_{nf}^*(\mathbf{Y}) = k_{nf} \left[1 + \epsilon \frac{\mathbf{Y} - \mathbf{Y}_{\infty}}{\mathbf{Y}_w - \mathbf{Y}_{\infty}} \right] \tag{6}$$

2.3. Nanosolid-Particles and Base Fluid Attributes

The physical characteristics of the base fluid engine oil and various nanosolid particles are tabulated in Table 2 below [35,36].

Table 2. Material characteristics of base fluid and nanosolid particles at 293 K.

Thermophysical	$ ho$ (kg/m 3)	c_p (J/kg·K)	k (W/mK)
Copper (Cu)	8933	385.0	401.00
Engine Oil (EO)	884	1910	0.144
Molybdenum disulfide (MoS ₂)	5060	397.21	904.4

2.4. Rosseland Approximations

Using the Roseland approximation [37], one can write:

$$q_r = -\frac{4\sigma^*}{3k^*} \frac{\partial \mathcal{Y}^4}{\partial y},\tag{7}$$

Here, σ^* is the Stefan–Boltzmann number and k^* is the absorption coefficient.

3. The Solution to the Problem

The boundary value problem in Equations (2)–(5) is in the form of PDEs, which are converted into ODEs with the assistance of the similarity technique. The first step of this

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technique is to introduce stream functions ψ and subsequently, ψ is used to express the velocity components in the x and y axes.

$$v_1 = \frac{\partial \psi}{\partial y}, \ v_2 = -\frac{\partial \psi}{\partial x}.$$
 (8)

Then, similarity variables are formed as:

$$Y(x,y) = \sqrt{\frac{b}{\nu_f}}y, \ \psi(x,y) = \sqrt{\nu_f b} x f(Y), \ \theta(Y) = \frac{\mathbf{Y} - \mathbf{Y}_{\infty}}{\mathbf{Y}_w - \mathbf{Y}_{\infty}}. \tag{9}$$

When Equation (9) is substituted into Equations (2)–(5), then the following ODEs are obtained:

$$f''' + \phi_{a}\phi_{b}\left[ff'' - f'^{2} + \beta_{1}\left(2ff' - f^{2}f'''\right)\right] + \beta_{2}\left(f''^{2} - ff^{iv}\right) - \frac{1}{\phi_{a}}Kf' = 0, \tag{10}$$

$$\theta''\left(1+\epsilon\theta+\frac{1}{\phi_{\rm d}}PrNr\right)+\epsilon\theta'^2+Pr\frac{\phi_{\rm c}}{\phi_{\rm d}}\left(f\theta'-f'\theta\right)=0,\tag{11}$$

with

$$f(0) = S, f'(0) = 1 + \Lambda f''(0), \theta'(0) = -B_{\varsigma}(1 - \theta(0))$$

$$f'(\infty) \to 0, f''(\infty) \to 0, \theta(\infty) \to 0,$$
 (12)

where the $\phi'_i s$ with a $\leq i \leq$ d in Equations (10)–(12) represent the following thermophysical properties for the Oldroyd-B nanofluid

$$\phi_{a} = (1 - \phi)^{2.5}, \ \phi_{b} = \left(1 - \phi + \phi \frac{\rho_{s}}{\rho_{f}}\right), \ \phi_{c} = \left(1 - \phi + \phi \frac{(\rho C_{p})_{s}}{(\rho C_{p})_{f}}\right)$$

$$\phi_{d} = \left(\frac{(k_{s} + 2k_{f}) - 2\phi(k_{f} - k_{s})}{(k_{s} + 2k_{f}) + \phi(k_{f} - k_{s})}\right).$$
(13)

As Equation (2) satisfies identity, the notation (′) is used for representing the derivatives for Y. Here, $\beta_1=b\lambda_1$ (Deborah number-I), $\beta_2=b\lambda_2$ (Deborah number-II) defined along with $K=\frac{v_f}{bk}$ (porous medium) parameter and $Pr=\frac{v_f}{\alpha_f}$ (Prandtl number), $\alpha_f=\frac{\kappa_f}{(\rho C_p)_f}$ (thermal diffusivity), $S=-V_w\sqrt{\frac{1}{v_f}b}$ (mass transfer), $Nr=\frac{16}{3}\frac{\sigma^*Y=\frac{3}{\infty}}{\kappa^*v_f(\rho C_p)_f}$ (thermal radiation), $\Lambda=\sqrt{\frac{b}{v_f}}Nv$ (velocity slip), and $B_{\varsigma}=\frac{h_f}{k_0}\sqrt{\frac{v_f}{b}}$ (Biot number) parameters, respectively.

3.1. Nusselt Number

The local Nusselt number (Nu_x) is the physical parameter that controls the flow and can be expressed as [38,39]:

$$Nu_{x} = \frac{xq_{w}}{k_{f}(Y_{w} - Y_{\infty})} \tag{14}$$

wherein q_w indicates the heat flux, which is presented in Equation (15):

$$q_w = -k_{nf} \left(1 + \frac{16}{3} \frac{\sigma^* \mathcal{Y}_{\infty}^3}{\kappa^* \nu_f(\rho C_p)_f} \right) \left(\frac{\partial \mathcal{Y}}{\partial y} \right)_{y=0}$$
 (15)

Applying the nondimensional transformations (9), one obtains:

$$Nu_x Re_x^{-\frac{1}{2}} = -\frac{k_{nf}}{k_f} (1 + Nr)\theta'(0), \tag{16}$$

where Nu_x and C_f denote the Nusselt number and reduced skin friction, respectively. In addition, $Re_x = \frac{U_w x}{v_f}$ is the local Re which relies on the stretching velocity $U_w(x)$.

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3.2. Entropy Generation Analysis

Researchers in science and technology are always considering the amount of energy used and trying to minimize the wasted energy. Therefore, the reduction of entropy generation is a good decision, since entropy generation is one of the main factors that cause the irreversibility of convenient energy. A nonideal factor that contributes to an increment in the entropy of the system is the presence of penetrable materials. When penetrable materials affect the density of a nanofluid, the following effects arise: First, the medium's permeability decreases, and then the thermal boundary layer and the system entropy increase. Therefore, the real entropy production in the nanofluids can be expressed by [38–41]:

$$E_{G} = \frac{k_{nf}}{\mathbb{Y}_{\infty}^{2}} \left\{ \left(\frac{\partial \mathbb{Y}}{\partial y} \right)^{2} + \frac{16}{3} \frac{\sigma^{*} \mathbb{Y}_{\infty}^{3}}{\kappa^{*} \nu_{f} (\rho C_{p})_{f}} \left(\frac{\partial \mathbb{Y}}{\partial y} \right)^{2} \right\} + \frac{\mu_{nf}}{\mathbb{Y}_{\infty}} \left(\frac{\partial v_{1}}{\partial y} \right)^{2} + \frac{\mu_{nf} v_{1}^{2}}{k \mathbb{Y}_{\infty}}.$$
 (17)

Equation (17) is formed by three terms: the transfer of heat irreversibility, the fluid friction, and the porous media effect. The dimensionless entropy generation N_G [42–46] is expressed as:

$$N_G = \frac{{}^{}_{}_{}^{}$$

By substituting Equation (9) into Equation (18), the final equation of dimensionless entropy generation is:

$$N_{\rm G} = Re \left[\phi_4 (1 + Nr)\theta'^2 + \frac{1}{\phi_1} \frac{Br}{\Omega} \left(f''^2 + Kf'^2 \right) \right]. \tag{19}$$

4. Numerical Implementation

To tackle the nonlinear ordinary differential Equations (10) and (11) concerning the endpoint condition (12), we applied the Keller-box method [47] with the help of algebraic software MATLAB for various values of the involved parameters. The stepwise procedure of the Keller-box method is expressed in the flow chart from Figure 2.

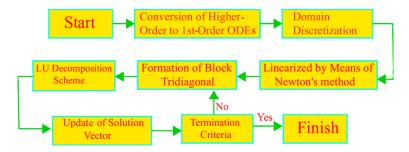


Figure 2. Flow chart illustrating Keller-box method.

Conversion of ODEs

We have introduced the subsequent substitutions for converting the higher-order ODEs to first-order ODEs. We introduce dependent variables Gv_1 , Gv_2 , Gv_3 , Gv_4 , Gv_5 , and Gv_6 such that:

$$Gv_1 = f$$
, $Gv_2 = f'$, $Gv_3 = f''$, $Gv_4 = f'''$, $Gv_5 = \theta$, $Gv_6 = \theta'$. (20)

$$\frac{dGv_1}{dY} = Gv_2, (21)$$

$$\frac{dGv_2}{dY} = Gv_3,\tag{22}$$

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$$\frac{dGv_3}{dY} = Gv_4,\tag{23}$$

$$\frac{dGv_5}{dY} = Gv_6,\tag{24}$$

$$-\beta_{2}Gv_{1}\frac{dGv_{4}}{dY} + \beta_{2}Gv_{3}^{2} + \phi_{a}\phi_{b}Gv_{1}Gv_{3} - \phi_{a}\phi_{b}Gv_{2}^{2} + 2\phi_{a}\phi_{b}\beta_{1}Gv_{1}Gv_{2} - \phi_{a}\phi_{b}\beta_{1}Gv_{1}^{2}Gv_{4} - \frac{1}{\phi_{a}}KGv_{2} + Gv_{4} = 0, \quad (25)$$

$$\frac{dGv_6}{dY} + \epsilon Gv_5 \frac{dGv_6}{dY} + \frac{1}{\phi_d} PrNr \frac{dGv_6}{dY} + \epsilon Gv_6^2 + Pr \frac{\phi_c}{\phi_d} Gv_1 Gv_6 - Pr \frac{\phi_c}{\phi_d} Gv_2 Gv_5 = 0, \quad (26)$$

$$Gv_1(0) = S, Gv_2(0) = 1 + \Lambda Gv_3(0), Gv_6(0) = -B_{\varsigma}(1 - Gv_5(0)), Gv_2(Y) \to 0, Gv_3(Y) \to 0, Gv_5(Y) \to 0, as Y \to \infty.$$
 (27)

The domain [0, 1] has been converted into sub-domains utilizing a regular mesh with the subsequent grid points (Figure 3):

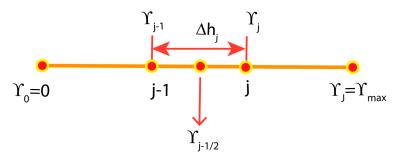


Figure 3. Typical grid structure for difference approximations.

 $Y_0 = 0$, $Y_j = Y_{j-1} + \Delta h_j$, $j = 0, 1, 2, 3 \dots$, J, $Y_J = 1$ where, Δh_j is the step-size (for further details, see Appendix A). For mathematical assessment, a mesh size of $\Delta h_j = 0.01$ was figured out to be appropriate and the results are acquired with an error tolerance of 10^{-6} .

5. Code Validation

In this section, our numerical results are validated by comparing with the findings from the literature [48–51]. The comparison of consistencies is tabulated in Table 3. It is shown that the present study displayed highly accurate outcomes for $-\theta'(0)$ with various values of Pr in the limiting cases.

Table 3 Comparison of $-\theta$	'(0) with various values of Pr	when $\phi = 0$ $\epsilon = 0$ $\Lambda = 0$	$Nr = 0$ $S = 0$ and $R_c = 0$
Table 3. Companison of $-v$	(0) Willi various values of 17	when $\omega = 0$, $\epsilon = 0$, $\Lambda = 0$	D_{i}

Pr	Ref. [48]	Ref. [49]	Ref. [50]	Ref. [51]	Present
72×10^{-2}	08086×10^{-4}	08086×10^{-4}	080863135×10^{-8}	080876122×10^{-8}	080876181×10^{-8}
1×10^{0}	1×10^{0}	1×10^{0}	1×10^{0}	1×10^{0}	1×10^{0}
3×10^{0}	19237×10^{-4}	19236×10^{-4}	192368259×10^{-8}	192357431×10^{-8}	192357420×10^{-8}
7×10^0	30723×10^{-4}	30722×10^{-4}	307225021×10^{-8}	307314679×10^{-8}	307314651×10^{-8}
10×10^{0}	37207×10^{-4}	37006×10^{-4}	372067390×10^{-8}	372055436×10^{-8}	372055429×10^{-8}

6. Results and Discussion

This study aimed to analyze the thermal efficacy of OBF flowing over a stretching surface. The Keller-box numerical approach was applied to calculate numerical and graphical results. The impacts of physical parameters on the two-dimensional model of OBF are reported. These parameters are listed as the boundary layer thickness Y, Deborah number β_1 and β_2 , porous media parameter K, nanoparticle volume fraction parameter ϕ , velocity slip parameter Λ , variable thermal conductivity parameter thermal ϵ , radiation parameter Nr, Biot number B_{ζ} , suction parameter S>0, injection parameter S<0, R_{ε} ,

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and B_r . The characteristics of fluid swiftness, temperature, and entropy production are displayed in Figures 4–31. The results are obtained for the Cu–EO– and MoS₂–EO–based non-Newtonian Oldroyd-B nanofluid. This numerical investigation was accomplished by setting up the following values for the related factors: $\beta_1=0.1$, $\beta_2=0.1$, K=0.1, $\phi=0.1$, $\Lambda=0.2$, Pr=6450, $\epsilon=0.2$, Nr=0.3, $B_{\varsigma}=0.1$, S=0.1, S=0.

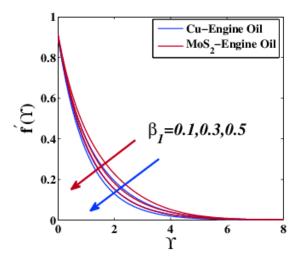


Figure 4. The effect of β_1 on velocity variation f'(Y).

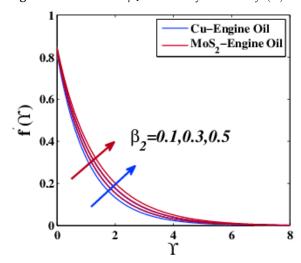


Figure 5. The effect of β_2 on velocity variation f'(Y).

Figures 4–9 describe a dimensionless number, known as Deborah number, on the variations of velocity, temperature, and entropy generation. Deborah number is defined as the relaxation time of non-Newtonian fluid, divided by the scale of time flow. The special effects of the Deborah numbers, which are denoted by β_1 and β_2 on velocity component f'(Y) are presented in Figures 4 and 5, respectively. It is detected that f'(Y) profiles decrease with an increasing value of β_1 , and it shows an opposite pattern when it is controlled by parameter β_2 . Figures 6 and 7 represent the effect of β_1 and β_2 on temperature profile $\theta(Y)$, respectively. From Figure 6, it is observed that the values of $\theta(Y)$ and their associated thermal boundary layer thicknesses are increased when β_1 rises. A rise in the value of β_1 leads to an increase in reduction time. However, the effect of β_2 causes the temperature profile to drop, as shown in Figure 8. The results of entropy generation N_G are presented in Figures 8 and 9 for different values of β_1 and β_2 , respectively. From these figures, the impact of the Deborah number β_1 and β_2 is to reduce the entropy generation profile.

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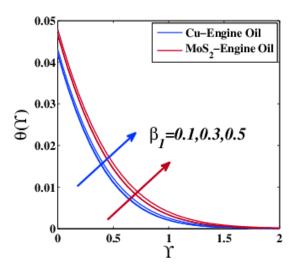


Figure 6. The effect of β_1 on temperature variation $\theta(Y)$.

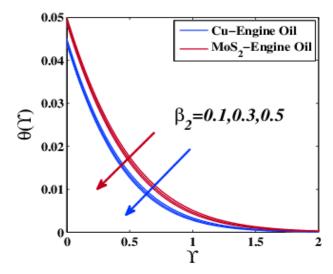


Figure 7. The effect of β_2 on temperature variation $\theta(Y)$.

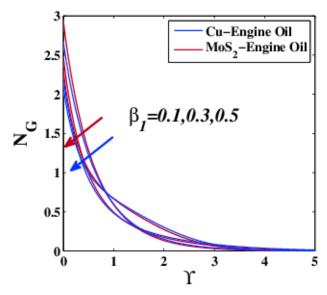


Figure 8. The effect of β_1 on entropy generation variation N_G .

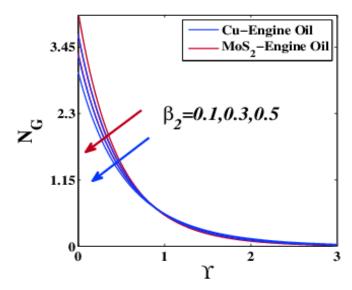


Figure 9. The effect of β_2 on entropy generation variation N_G .

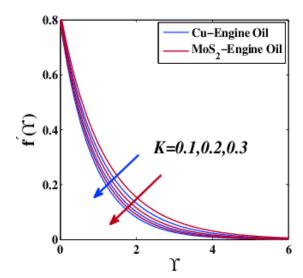


Figure 10. Velocity variation f'(Y) under the influence of K.

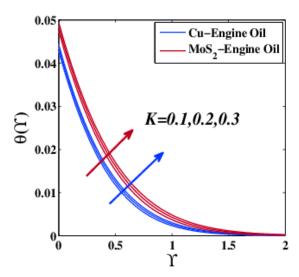


Figure 11. Temperature variation $\theta(Y)$ under the influence of K.

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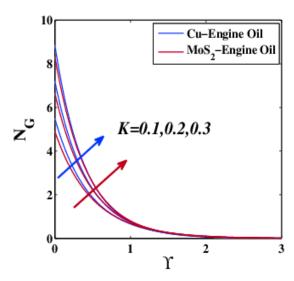


Figure 12. Entropy generation variation N_G under the influence of K.

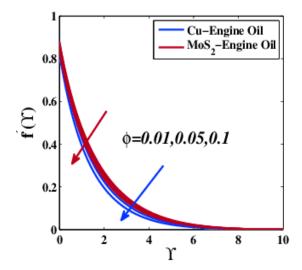


Figure 13. Velocity variation f'(Y) under the influence of ϕ .

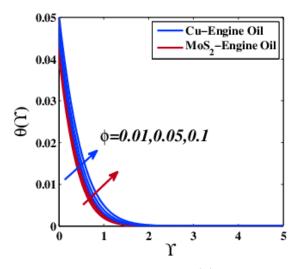


Figure 14. Temperature variation $\theta(Y)$ under the influence of ϕ .

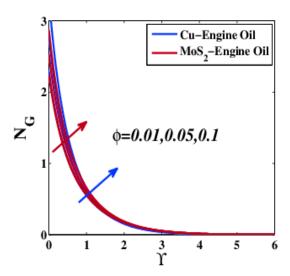


Figure 15. Entropy generation variation N_G under the influence of ϕ .

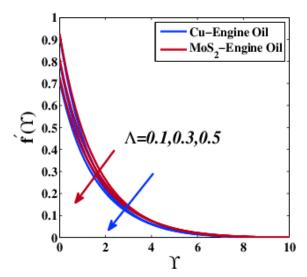


Figure 16. Velocity variation f'(Y) under the influence of Λ .

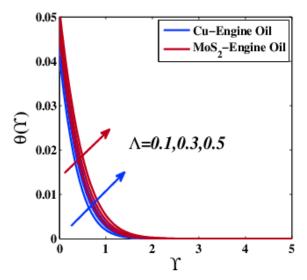


Figure 17. Temperature variation $\theta(Y)$ under the influence of Λ .

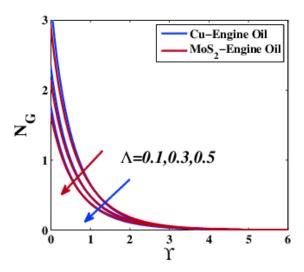


Figure 18. Entropy generation variation N_G under the influence of Λ .

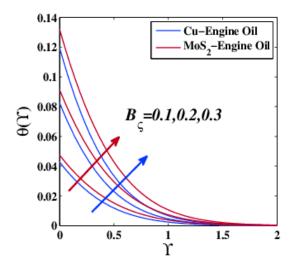


Figure 19. Temperature variation $\theta(Y)$ under the influence of B_{ς} .

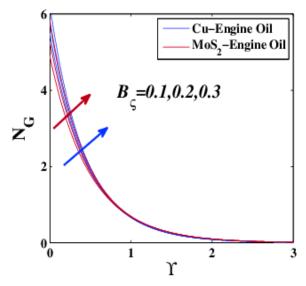


Figure 20. Entropy generation variation N_G under the influence of B_{ς} .

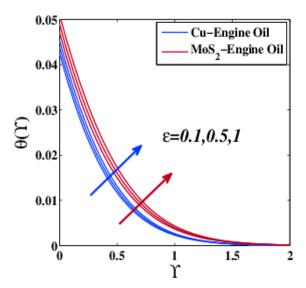


Figure 21. Temperature variation $\theta(Y)$ under the influence of ε .

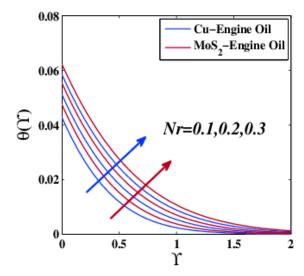


Figure 22. Temperature variation $\theta(Y)$ under the influence of Nr.

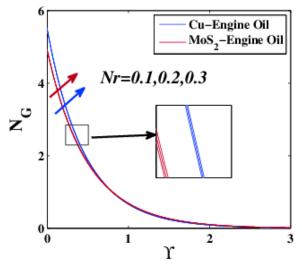


Figure 23. Entropy generation variation N_G under the influence of Nr.

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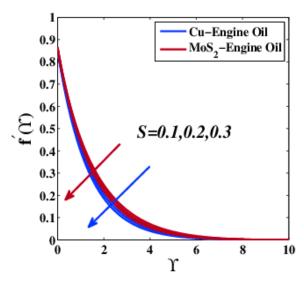


Figure 24. Velocity variation f'(Y) under the influence of S > 0.

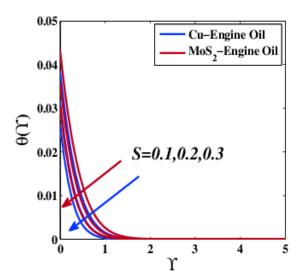


Figure 25. Temperature variation $\theta(Y)$ under the influence of S > 0.

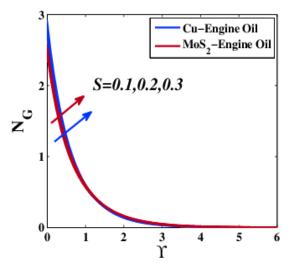


Figure 26. Entropy generation variation N_G under the influence of S > 0.

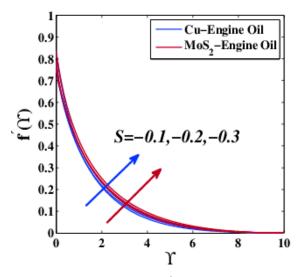


Figure 27. Velocity variation f'(Y) under the influence of S < 0.

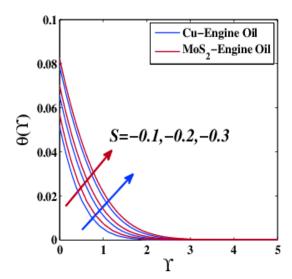


Figure 28. Temperature variation $\theta(Y)$ under the influence of S < 0.

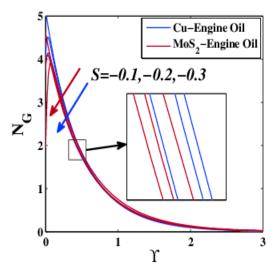


Figure 29. Entropy variation N_G under the influence of S < 0.

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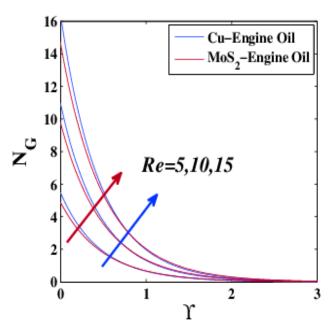


Figure 30. Entropy generation variation N_G under the influence of Re.

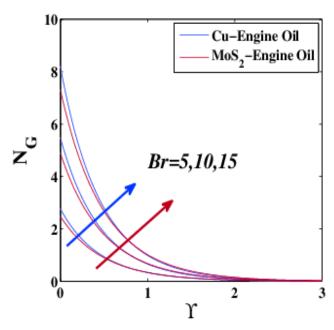


Figure 31. Entropy generation variation N_G under the influence of Br.

Figures 10–12 show the impact of porous media parameter K on the variations of velocity, temperature, and entropy generation. The porous media parameter indicates the absorption rate of the fluid when passing through pores. Since a hybrid nanofluid contains more than one type of nanometer-sized particles, the absorption rate becomes slower, as shown in Figure 10. However, the role of porous media parameter K is to increase the values of temperature (Figure 11) and entropy generation (Figure 12).

The impact of nanosolid particle size factor ϕ on the variations of velocity (Figure 13), temperature (Figure 14), and entropy generation (Figure 15) are depicted against boundary layer thickness Y. The parameter ϕ causes an increase in the variations of temperature $\theta(Y)$ and entropy generation N_G because an increment in ϕ causes the density of the nanofluid to increase. As a result, two effects co-occur: (a) a decreasing simultaneous velocity and (b) an increasing thermal conductivity and simultaneous temperature.

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The graphical representations of velocity slip parameter Λ can be seen in Figures 16–18. These three figures display the variations of velocity, temperature, and entropy generation. The effect of the velocity slip factor is to decrease the values of velocity and entropy generation profiles. However, this parameter causes the temperature profile to increase because an increase in the slip factor produces frictional force, and the fluid velocity is reduced. Nevertheless, this slip parameter causes the temperature to shift upward.

Figures 19 and 20 show that the effect of the Biot number B_{ς} is to increase the variations of temperature $\theta(Y)$ and entropy generation N_G . The Biot number is defined as a dimensionless number related to the convective boundary condition. Therefore, Figure 19 shows that the temperature profile and thermal boundary layer thickness are increased due to the effect of the Biot number. Moreover, the Biot number causes an enhancement in heat transfer rate. Thus, the entropy generation is also increased (Figure 20). The impact of variable thermal conductivity ε on temperature profiles can be seen in Figure 21. When the thermal conductivity increases, the thermal boundary layer thickness increases, and the hybrid nanofluid's temperature rises. Meanwhile, the radiation parameter Nr causes the temperature and entropy generation variations to be improved (Figures 22 and 23, respectively). The radiation parameter is defined as the thermal radiation transfer divided by the conduction heat transfer. A higher amount of heat energy flows into the system is indicated by higher values of Nr. As a result, the temperature profile shifts upward.

The representation of the suction parameter and injection parameter is demonstrated in Figures 24–26, and Figures 27–29, respectively. The velocity profile under the influence of the suction parameter is depicted in Figure 24. Meanwhile, the same profile with the effect of the injection parameter is presented in Figure 27. Moreover, the temperature profiles due to the suction and injection parameters are depicted in Figures 25 and 28, respectively. Figures 26 and 29 show the entropy generation profiles against the variations of suction and injection parameters, respectively. The swiftness and temperature outlines are suppressed by the increment of the suction parameter, whereas the same parameter causes the entropy generation parameter to rise. This situation can be explained by the presence of suction causing the heated fluid to flow towards the sheet. Consequently, the buoyancy force slows down the fluid velocity due to the high viscosity. Instantaneously, the temperature is reduced, and the entropy generation increases. However, the opposite pattern has been observed for the same profiles when increasing the injection parameter. The role of the injection parameter is to give an opposite effect on the direction of heated fluid and buoyancy force. Hence, the effect of the injection parameter on all the outlines shows the reverse trend compared to the suction parameter.

The impact of the Reynolds number Re and the Brinkman number Br on entropy production N_G are offered in Figures 30 and 31, respectively. These figures show that N_G increases as Re and Br increase. The Reynolds number is defined as the ratio of inertial forces (frictional forces) to viscous forces. The augmentation of the Reynolds number causes the enhancement of the following: frictional force at the fluid, heat, and mass transfer. Consequently, entropy production is produced. In addition, the increase of Br causes an increase in the rate of viscous dissipation. The Brinkman number Br is defined as the ratio between heat produced by viscous dissipation and heat transported by molecular conduction. This number is also known as a ratio of viscous heat generation to external heating. As a result, entropy generation N_G is enhanced due to the change in viscous dissipation.

The numerical results of the local Nusselt number $=N_uRe_x^{\frac{-1}{2}}$ for various values of B_{ζ} , Λ , S>0, ϕ , Nr, and Pr are observed in Table 4. From this table, it is shown that the effect of B_{ζ} , S>0, Nr, and Pr are to enhance the wall heat flux $N_uRe_x^{\frac{-1}{2}}$ for both Cu–EO and MoS₂–EO nanofluids. In addition, $N_uRe_x^{\frac{-1}{2}}$ for both Cu–EO and MoS₂–EO is reduced due to the increment of Λ . However, the effect of ϕ is to reduce the rate of $N_uRe_x^{\frac{-1}{2}}$ for Cu–EO and to increase the local Nusselt number $N_uRe_x^{\frac{-1}{2}}$ for MoS₂–EO.

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B_{ς}	Λ	S	φ	Nr	Pr	$N_u Re_x^{rac{-1}{2}}$ Cu–EO	$N_u Re_x^{rac{-1}{2}} \ extbf{MoS}_2 ext{-EO}$	$\frac{\text{Relative\%}}{\frac{Nu_{(Cu)} - Nu_{(MoS_2)}}{Nu_{(Cu)}}} \times 100$
0.1	0.2	0.1	0.1	0.3	0.2	0.0907	0.1209	25%
0.2						0.1735	0.2302	26%
0.3						0.2492	0.3291	27%
	0.1					0.0909	0.1212	24%
	0.2					0.0907	0.1209	23%
	0.3					0.0905	0.1207	22%
		0.1				0.0911	0.6010	29%
		0.2				0.0915	0.1219	28%
		0.3				0.0920	0.1225	27%
			0.01			0.1100	0.1079	1.9%
			0.05			0.0980	0.1209	20%
			0.1			0.0852	0.1388	40%
				0.1		0.0857	0.1400	38%
				0.2		0.0920	0.1513	39%
				0.3		0.0982	0.1625	39%
					10	0.0857	0.1513	41%
					15	0.0859	0.1519	42%
					20	0.0860	0.1523	43%

Table 4. Calculations of the Nusselt number = $N_u Re_x^{\frac{-1}{2}}$ for Pr = 6450.

7. Final Outcomes

The numerical solutions are controlled by the following parameters: the first component of Deborah number β_1 , second component of Deborah number β_2 , porous media parameter K, volume friction parameter ϕ , velocity slip parameter Λ , Biot number B_{ς} , variable thermal conductivity ε , radiation parameter Nr, suction parameter S>0, injection parameter S<0, Reynolds number Re, and Brinkman number Br. The previous section showed that the effect of the related parameters on the variations of velocity, temperature, and entropy generation was valid for both Cu–EO and MoS₂–EO. As a result, the main findings of this paper are summarized below:

- (a) An increase in velocity distribution was observed, under the influence of β_2 and S > 0. Otherwise, this profile decreased due to the increase of β_1 , K, ϕ , Λ and S > 0.
- (b) The velocity of molybdenum disulfide engine oil (MoS₂–EO) nanofluid was found to be higher than copper engine oil (Cu–EO) nanofluid. This comparison was depicted under the impact of the Deborah number, porous media parameter, nanoparticle volume fraction parameter, velocity slip parameter, suction, and injection.
- (c) The fluid temperature increased due to increasing values of β_1 , K, ϕ , Λ , B_{ς} , ε , Nr, and S < 0. However, the same profile decreased due to β_2 and S > 0.
- (d) Temperature profiles showed that the graphs for MoS₂–EO were above those for the Cu–EO nanofluid. These two lines can be observed when varying controlling parameters such as the Deborah number, porous media parameter, velocity slip parameter, Biot number, variable thermal conductivity, radiation parameter, suction, and injection. However, the temperature measured for the Cu–EO nanofluid was greater than for MoS₂–EO, for various values of the nanoparticle volume fraction parameter.
- (e) The roles of Deborah number (β_1 and β_2), velocity slip parameter, and injection parameter were to lessen the values of entropy generation. At the same time, this profile was enhanced when the following parameters increased: porous media parameter, volume friction parameter, Biot number, radiation parameter, suction parameter, Reynolds number, and Brinkman number.
- (f) At the small thickness boundary layer, the entropy generation of MoS₂–EO was higher than that of Cu–EO when this profile was affected by Deborah number. Moreover, Cu–EO entropy generation was greatest for increasing series of porous media parameter, nanoparticle volume fraction parameter, velocity slip parameter, Biot number, radiation parameter, suction, injection, Reynolds number, and Brinkman number.

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(g) The local Nusselt number was an ascending function of B_{ς} , S>0, Nr, and Pr. Moreover, the local Nusselt number was a decreasing function of Λ . The effects of B_{ς} , S>0, Nr, Pr, and Λ are valid for both Cu–EO and MoS₂–EO. However, the effect of ϕ on the local Nusselt number was described as follows: (i) decrease for Cu–EO; (ii) increase for MoS₂–EO.

8. Future Direction

In this work, we have employed the concept of entropy generation analysis and the effects of slip conditions on fluid flow. One can replace Equation (21) with another formula of entropy. For example, we suggest considering a fractional entropy such as the Tsallis entropy.

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Nomenclatures

b	initial stretching rate	Greek Symb	pols
B_{ς}	Biot number	¥	fluid temperature (K)
B_r	Brinkman number	Ψ_w	fluid temperature of the surface (K)
C_f	skin friction coefficient	Ψ_{∞}	ambient temperature (K)
C_p	specific heat $\left(J \text{ kg}^{-1} \text{ K}^{-1} \right)$	ϕ	volume fraction of the nanoparticles
E_G	$dimensional\ entropy\ (J/K)$	ρ	density $\left(\text{kg m}^{-3} \right)$
h	Heat transfer coefficient	σ^*	Stefan-Boltzmann constant
κ	thermal conductivity $\left(W \text{ m}^{-1} \text{ K}^{-1}\right)$	ψ	stream function
K	porous medium	γ	independent similarity variable
k^*	absorption coefficient	θ	dimensionless temperature
ϵ	variable thermal conductivity	Λ	velocity slip
N_r	radiation parameter	μ	dynamic viscosity (kg $m^{-1}s^{-1}$)
N_G	dimensionless entropy generation	ν	kinematic viscosity (m^2s^{-1})
Nu_x	local Nusselt number	α	thermal diffusivity $(m^2 s^{-1})$
P_r	Prandtl number (ν/α)	eta_1	Deborah number-I
q_r	radiative heat flux	eta_2	Deborah number-II
q_w	wall heat flux	Ω	dimensionless temperature gradient
R_e	Reynolds number	Subscripts	
S	suction/injection parameter	f	base fluid
v_1, v_2	velocity component $(m s^{-1})$	s	particles
U_w	stretching velocity $(m s^{-1})$	nf	nanofluid
V_w	vertical velocity $({ m m~s^{-1}})$		
x, y	dimensional space coordinates (m)		

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Appendix A. In This Part, We Give the Details of the Numerical Procedure for the Keller-Box Method

Appendix A.1. Difference Equations

The domain [0,1] has been converted into subdomains utilizing a regular mesh with the subsequent grid points:

 $Y_0 = 0$, $Y_j = Y_{j-1} + \Delta h_j$, $j = 0, 1, 2, 3 \dots, J$, $Y_J = 1$, where Δh_j is the step-size. First-order ODES (21)–(26) have been estimated with the aid of central differences at the midpoint $Y_{j-1/2}$, as follows:

$$(Gv_1)_j - (Gv_1)_{j-1} = 0.5\Delta h_j((Gv_2)_j + (Gv_2)_{j-1}), \tag{A1}$$

$$(Gv_2)_i - (Gv_2)_{i-1} = 0.5\Delta h_i((Gv_3)_i + (Gv_3)_{i-1}), \tag{A2}$$

$$(Gv_3)_j - (Gv_3)_{j-1} = 0.5\Delta h_j((Gv_4)_j + (Gv_4)_{j-1}), \tag{A3}$$

$$(Gv_5)_j - (Gv_5)_{j-1} = 0.5\Delta h_j((Gv_6)_j + (Gv_6)_{j-1}), \tag{A4}$$

$$-\beta_{2} \frac{((Gv_{1})_{j} + (Gv_{1})_{j-1})}{2} ((Gv_{4})_{j} - (Gv_{4})_{j-1}) + \Delta h_{j} \beta_{2} \frac{((Gv_{3})_{j} + (Gv_{3})_{j-1})^{2}}{4} + \Delta h_{j} \phi_{a} \phi_{b} \frac{((Gv_{1})_{j} + (Gv_{1})_{j-1})}{2} \frac{((Gv_{3})_{j} + (Gv_{3})_{j-1})}{2} - \phi_{a} \phi_{b} \frac{((Gv_{2})_{j} + (Gv_{2})_{j-1})^{2}}{4} + 2\Delta h_{j} \phi_{a} \phi_{b} \beta_{1} \frac{((Gv_{1})_{j} + (Gv_{1})_{j-1})}{2} \frac{((Gv_{2})_{j} + (Gv_{2})_{j-1})}{2} - \Delta h_{j} \phi_{a} \phi_{b} \beta_{1} \frac{((Gv_{1})_{j} + (Gv_{1})_{j-1})^{2}}{4} + \Delta h_{j} \frac{((Gv_{2})_{j} + (Gv_{2})_{j-1})}{2} + \Delta h_{j} \frac{((Gv_{2})_{j} + (Gv_{2})_{j-1})}{2} = 0,$$

$$(A5)$$

$$\left\{ ((Gv_{6})_{j} - (Gv_{6})_{j-1}) + \varepsilon \frac{((Gv_{5})_{j} + (Gv_{5})_{j-1})}{2} ((Gv_{6})_{j} - (Gv_{6})_{j-1}) \right.$$

$$\left. + \frac{1}{\phi_{d}} PrNr((Gv_{6})_{j} - (Gv_{6})_{j-1}) + \Delta h_{j} \varepsilon \frac{((Gv_{6})_{j} + (Gv_{6})_{j-1})^{2}}{4} \right.$$

$$\left. + \Delta h_{j} Pr \frac{\phi_{c}}{\phi_{d}} \frac{((Gv_{1})_{j} + (Gv_{1})_{j-1})}{2} \frac{((Gv_{6})_{j} + (Gv_{6})_{j-1})}{2} \right.$$

$$\left. - \Delta h_{j} Pr \frac{\phi_{c}}{\phi_{d}} \frac{((Gv_{2})_{j} + (Gv_{2})_{j-1})}{2} \frac{((Gv_{5})_{j} + (Gv_{5})_{j-1})}{2} = 0, \right.$$

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Appendix A.2. Newton Linearization

The above system of Equations (A1)–(A6) is linearized by Newton's linearization method using the following substitution:

$$(Gv_{1})_{j}^{n+1} = (Gv_{1})_{j}^{n} + (\delta G_{1})_{j}^{n}, (Gv_{2})_{j}^{n+1} = (Gv_{2})_{j}^{n} + (\delta G_{2})_{j}^{n},
(Gv_{3})_{j}^{n+1} = (Gv_{3})_{j}^{n} + (\delta Gv_{3})_{j}^{n}, (Gv_{4})_{j}^{n+1} = (Gv_{4})_{j}^{n} + (\delta Gv_{4})_{j}^{n},
(Gv_{5})_{j}^{n+1} = (Gv_{5})_{j}^{n} + (\delta Gv_{5})_{j}^{n}, (Gv_{6})_{j}^{n+1} = (Gv_{6})_{j}^{n} + (\delta Gv_{6})_{j}^{n}.$$
(A7)

Substituting the expressions obtained in (A1)–(A6) and dropping the square and higher powers of δ , the following set of equations is achieved:

$$((\delta G_1)_i - (\delta G_1)_{j-1}) - 0.5\Delta h_i((\delta G_2)_i + (\delta G_2)_{j-1}) = (r_1)_i, \tag{A8}$$

$$((\delta G_2)_j - (\delta G_2)_{j-1}) - 0.5\Delta h_j((\delta G v_3)_j + (\delta G v_3)_{j-1}) = (r_2)_j, \tag{A9}$$

$$((\delta G v_3)_j - (\delta G v_3)_{j-1}) - 0.5\Delta h_j((\delta G v_4)_j + (\delta G v_4)_{j-1}) = (r_3)_j, \tag{A10}$$

$$((\delta G v_5)_j - (\delta G v_5)_{j-1}) - 0.5\Delta h_j ((\delta G v_6)_j + (\delta G v_6)_{j-1}) = (r_4)_j, \tag{A11}$$

$$(\pi_1)_i(\delta G_1)_i + (\pi_2)_i(\delta G_1)_{i-1} + (\pi_3)_i(\delta G_2)_i + (\pi_4)_i(\delta G_2)_{i-1} + (\pi_5)_i(\delta G v_3)_i + (\pi_6)_i(\delta G v_3)_{i-1} + (\pi_7)_i(\delta G v_4)_i + (\pi_8)_i(\delta G v_4)_{i-1} = (r_5)_i, \quad \text{(A12)}$$

$$(m_1)_i(\delta G_1)_i + (m_2)_i(\delta G_1)_{i-1} + (m_3)_i(\delta G_2)_i + (m_4)_i(\delta G_2)_{i-1} + (m_5)_i(\delta G v_5)_i + (m_6)_i(\delta G v_5)_{i-1} + (m_7)_i(\delta G v_6)_i + (m_8)_i(\delta G v_6)_{i-1} = (r_6)_i, \quad (A13)_i(\delta G_1)_i + (m_7)_i(\delta G_2)_i + (m_8)_i(\delta G_2)$$

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where:

$$(\pi_1)_j = -\Delta h_j \phi_a \phi_b \beta_1 \frac{((Gv_1)_j + (Gv_1)_{j-1})((Gv_4)_j + (Gv_4)_{j-1})}{4} = (\pi_2)_j, \\ (\pi_3)_j = -\frac{\kappa \Delta h_j}{2\phi_a} + 2\Delta h_j \phi_a \phi_b \beta_1 \frac{((Gv_1)_j + (Gv_1)_{j-1})}{4} + \Delta h_j \phi_a \phi_b \frac{((Gv_2)_j + (Gv_2)_{j-1})}{2} = (\pi_4)_j, \\ (\pi_5)_j = \Delta h_j \phi_a \phi_b \frac{((Gv_1)_j + (Gv_1)_{j-1})}{4} + \Delta h_j \beta_2 \frac{((Gv_3)_j + (Gv_3)_{j-1})}{2} = (\pi_6)_j, \\ (\pi_7)_j = \frac{\Delta h_j}{2} - \beta_2 \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} - 8\Delta h_j \phi_a \phi_b \beta_1 ((Gv_1)_j + (Gv_1)_{j-1})^2 = (\pi_8)_j, \\ (r_5)_j = \beta_2 \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} (((Gv_4)_j - (Gv_4)_{j-1}) - \Delta h_j \beta_2 \frac{((Gv_3)_j + (Gv_3)_{j-1})^2}{4} \\ -\Delta h_j \phi_a \phi_b \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} \frac{((Gv_3)_j + (Gv_3)_{j-1})}{2} - \phi_a \phi_b \frac{((Gv_2)_j + (Gv_2)_{j-1})^2}{4} \\ -2\Delta h_j \phi_a \phi_b \beta_1 \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} \frac{((Gv_2)_j + (Gv_2)_{j-1})}{2} - \Delta h_j \phi_a \phi_b \beta_1 \frac{((Gv_1)_j + (Gv_1)_{j-1})^2}{4} \\ \frac{((Gv_4)_j + (Gv_4)_{j-1})}{2} + \frac{\lambda h_j}{\phi_a} K \frac{((Gv_2)_j + (Gv_2)_{j-1})}{2} - \Delta h_j \frac{((Gv_4)_j + (Gv_4)_{j-1})}{2},$$

$$(m_1)_j = \Delta h_j \frac{pr\phi_c}{\phi_d} \frac{((Gv_6)_j + (Gv_6)_{j-1})}{4} = (m_2)_j,$$

$$(m_3)_j = -\Delta h_j \frac{pr\phi_c}{\phi_d} \frac{((Gv_2)_j + (Gv_6)_{j-1})}{4} = (m_4)_j,$$

$$(m_5)_j = \Delta h_j \frac{pr\phi_c}{\phi_d} \frac{((Gv_2)_j + (Gv_2)_{j-1})}{4} + \epsilon \frac{((Gv_6)_j - (Gv_6)_{j-1})}{2} = (m_6)_j,$$

$$(m_7)_j = 1 + \frac{N_r Pr}{\phi_d} + \Delta h_j \frac{pr\phi_c}{\phi_d} \frac{((Gv_1)_j + (Gv_1)_{j-1})}{4} + \epsilon \frac{((Gv_5)_j - (Gv_5)_{j-1})}{2} + \Delta h_j \epsilon \frac{((Gv_6)_j - (Gv_6)_{j-1})}{2},$$

$$(m_8)_j = -1 - \frac{N_r Pr}{\phi_d} + \Delta h_j \frac{pr\phi_c}{\phi_d} \frac{((Gv_1)_j + (Gv_1)_{j-1})}{4} + \epsilon \frac{((Gv_5)_j - (Gv_5)_{j-1})}{2} + \Delta h_j \epsilon \frac{((Gv_6)_j - (Gv_6)_{j-1})}{2},$$

$$(r_6)_j = -((Gv_6)_j - (Gv_6)_{j-1}) - \epsilon \frac{((Gv_5)_j + (Gv_5)_{j-1})}{2} (((Gv_6)_j + (Gv_6)_{j-1})^2 + \Delta h_j \epsilon \frac{((Gv_6)_j + (Gv_6)_{j-1})^2}{4} + \Delta h_j Pr \frac{\phi_c}{\phi_d} \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} \frac{((Gv_6)_j + (Gv_6)_{j-1})}{2} + \Delta h_j Pr \frac{\phi_c}{\phi_d} \frac{((Gv_1)_j + (Gv_1)_{j-1})}{2} \frac{((Gv_5)_j + (Gv_5)_{j-1})}{2} + \Delta h_j Pr \frac{\phi_c}{\phi_d} \frac{((Gv_2)_j + (Gv_2)_{j-1})}{2} \frac{((Gv_5)_j + (Gv_5)_{j-1})}{2},$$

Appendix A.3. Block Tridiagonal Structure

Next, the linearized system has the following block-tridiagonal structure:

$$A\Delta = S, (A16)$$

where the elements defined in Equation (A17) are:

$$[\ L_1 \] = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ -0.5\Delta h_1 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & -0.5\Delta h_1 & 0 & -0.5\Delta h_1 & 0 \\ 0 & -1 & 0 & 0 & 0 & -0.5\Delta h_1 & 0 \\ (\pi_6)_1 & 0 & (\pi_8)_1 & (\pi_1)_1 & (\pi_7)_1 & 0 \\ 0 & (m_6)_1 & 0 & (m_1)_1 & 0 & (m_7)_1 \end{bmatrix},$$

$$[\ L_j \] = \begin{bmatrix} -0.5\Delta h_j & 0 & 0 & 1 & 0 & 0 \\ -1 & -0.5\Delta h_j & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & -0.5\Delta h_j & 0 \\ 0 & -1 & 0 & 0 & -0.5\Delta h_j & 0 \\ (\pi_4)_j & (\pi_6)_j & 0 & (\pi_1)_j & (\pi_7)_j & 0 \\ (m_4)_j & 0 & (m_6)_j & (m_1)_j & 0 & (m_7)_j \end{bmatrix}, 2 \leq j \leq J$$

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Now we factorize A as:

$$A = LU, (A18)$$

where:

$$L = \left[\begin{array}{ccccc} \left[\Gamma_1 \right] & & & & \\ & \left[\Gamma_2 \right] & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & \ddots & \left[\Gamma_{J-1} \right] & \\ \left[O_I \right] & \left[\Gamma_I \right] \end{array} \right], U = \left[\begin{array}{ccccc} \left[I \right] & \left[\alpha_1 \right] & & & & \\ & \left[I \right] & \left[\alpha_2 \right] & & & \\ & & \ddots & \ddots & \\ & & & & \left[I \right] & \left[\alpha_{J-1} \right] & \\ & & & & \left[I \right] & \left[I \right] \end{array} \right]$$

where the total size of the block-tridiagonal matrix A is $J \times J$ with each block size of super vectors is 6×6 and [I], $[\Gamma_i]$ and $[\alpha_i]$ are the matrices of order 6. Implementing an LU decomposition algorithm for the solution of Δ .

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