

Article Local and Network-Wide Time Scales of Delay Propagation in Air Transport: A Granger Causality Approach

Luisina Pastorino and Massimiliano Zanin *D

Instituto de Física Interdisciplinar y Sistemas Complejos CSIC-UIB, Campus Universitat de les Illes Balears, E-07122 Palma de Mallorca, Spain; luisina@ifisc.uib-csic.es

* Correspondence: massimiliano.zanin@gmail.com

Abstract: Complex network theory, in conjunction with metrics able to detect causality relationships from time series, has recently emerged as an effective and intuitive way of studying delay propagation in air transport. One important step in such analysis is converting the discrete set of landing events into a time series representing the average delay evolution. Most works have hitherto focused on fixed-size windows, whose size is defined based on a priori considerations. Here, we show that an optimal airport-dependent window size, which allows maximising the number of detected causality relationships, can be calculated. We further show how the macro-scale but not the micro-scale structure is modified by such a choice and how airport centrality, and hence its importance in the propagation process, is strongly affected. We finally discuss the implications of these results in terms of detecting the characteristic time scales of delay propagation.

Keywords: air transport; delay propagation; Granger causality; complex networks

1. Introduction

Air transport is a complex system whose dynamics evolve over multiple temporal scales. When focusing on operational aspects, the largest time horizon is given by the daily cycle, with the system resetting every night—as at least most passenger flights stop operating, new crews start their shift, and (except in the case of extreme events) delays are absorbed. At the opposite extreme, decisions can be made by multiple actors on very short time scales; to illustrate, air traffic controllers have to react to potential separation losses that develop on the scale of a few minutes [1] and that require reaction times of between 2 and 3 s [2].

While those time scales are relatively easy to measure, a relevant open problem is the description of the one underpinning the propagation of delays (i.e., secondary or knock-on delays). Delay propagation is the result of processes that exist at different time scales. One may intuitively think that delays are related to the duration of flights, such that, if a flight *a* is delayed at departure and it is to pass the delay to a second flight *b*, the minimum time required to see the effect is the actual duration of *a*. In addition, if delays are measured at landing, the observed time scale would be the duration of *b* plus the turn-around time between *a* and *b*. On the other hand, information about delays can be transmitted much faster; for instance, an airline can delay a flight knowing another one with connecting passengers is delayed well before the latter has landed, and therefore well before its actual delay is recorded [3,4]. The existence of upstream delay propagations, in which the delay of one flight affects the flight prior to, it has also been documented [5]; for instance, if the destination airport is congested, flights may not be allowed to land and may instead be retained on the ground at the airport of origin.

The problem of describing the time scale of delay propagation is made even more complex by the fact that limited options exist for measuring such phenomenon. Two main alternatives have been extensively studied: the analysis of the local dynamics of individual



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Copyright: © 2023 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). flights and airports [6–8] and the use of large-scale synthetic models [5,8–11]. To the best of our knowledge, only one research work has tried to explicitly assess the time scale of network-wide delay propagation from real data [12] by detecting sliding windows for which a stable correlation is observed between the aggregate delays at two airports and then extracting the time lag maximising such correlation; the use of a linear correlation nevertheless introduces some problems, as for instance, it does not discriminate direct (i.e., true causalities) from indirect (spurious correlations) relationships.

In recent years, a complementary approach has been proposed based on the detection of instances of delay propagation through causality metrics, such as, e.g., the celebrated Granger causality test [13,14], and on mapping these instances as links of a complex network—see for instance, Refs. [15–21]. Even if it comes with its own limitations, the Granger test presents the advantage of detecting instances of true "predictive causality" and is thus less affected by the presence of confounding elements—and hence of spurious correlations. A network representation is also easier to describe, as many techniques are available to quantify properties of the emerging structure [22,23].

Intuitively, a study similar to that proposed in Ref. [12] could be performed using the Granger causality test, as this test yields the temporal lag maximising the causal connection for each analysed pair of time series: a lag that can be interpreted as the time required for the information describing delays to propagate between the corresponding airports. This nevertheless comes at a cost: a new time scale has to be defined over which the causality is tested. More specifically, this test requires as input a time series per airport, representing its dynamics. In this case, it represents the evolution of average landing delays; it is thus necessary to define the length of the window in which delays are averaged. Choosing the best time scale for evaluating the presence of a causality in the Granger sense is an open problem, known to be highly complex. Most research works have focused on the case of continuous dynamic processes sampled at a specific resolution-for being the most common problem found in science and engineering. In this case, increasing the temporal sampling rate yields improved causality estimations, both in synthetic models [24] and in empirical studies [25]. This is intuitively to be expected, not only because higher sampling frequencies yield longer time series (which are easier to analyse), but also because important dynamic patterns may otherwise be lost. However, increasing the sampling resolution is not always beneficial, with the detected causality approaching zero almost linearly as the sampling interval tends to zero [26]. On the other hand, is has been shown that using too large a sampling interval can result in statistically significant yet spurious causality relationships [27–31].

The problem becomes even more complex in the analysis of delay propagations, as the underlying process is a fixed point as opposed to a continuous process. In other words, even if the propagation of delays could be visualised as a continuous process, we only observe its result at discrete moments in time, i.e., whenever an aircraft actually lands. This implies that the sampling frequency cannot be made arbitrarily large. Otherwise, most samples would correspond to time windows for which no information (i.e., no landing events) is available [32,33]. On the other hand, safety limitations imply that at best only tens of landing events are available per hour. Ensuring a large number of events in each time window would therefore require impractically large windows.

In this paper, we explore how the Granger causality test can be used to describe the characteristic time scale of delay propagation processes. We show how results can be framed within three complementary viewpoints: a methodological one, an operational one and a systemic or network one. We explore this issue by constructing and analysing a minimal synthetic model of delay events, simulating how delays can propagate between two airports and how such propagation can be detected by the Granger causality test. We also extend the scope to a whole airport network by evaluating such causality on all possible pairs of airports, representing the structure as a complex network. In the latter case, the concept is tested on real data about operations in 50 large European airports during September 2019.

Results indicate that optimising the size of the window used to calculate the Granger causality for each pair of airports results in a substantial increase in the number of detected propagation links and, in turn, in different macro-scale (but notably not micro-scale) propagation structures. We further show how the choice of this temporal resolution strongly affects the ranking of airports in terms of their importance for the propagation of delays. We finally study how the Granger causality can be used to assess the time scale of delay propagation and how the chosen window size affects such estimation.

In the remainder of this paper, we first introduce the data (Section 2.1), the Granger causality test (Section 2.2), and the network reconstruction procedure (Section 2.3). We then present a minimal model, generating synthetic time series of landing events at two airports with custom parameters in Section 3. The results for the real data are analysed in Section 4, organised according to methodological (Section 4.1), operational (Section 4.2), and network (Section 4.3) viewpoints. We finally discuss the validation of the results in terms of time series length (Section 5) and draw some methodological and operational conclusions (Section 6).

2. Methods

2.1. *Real Operational Data*

Data about air transport operations were extracted from the EUROCONTROL's R&D Data Archive, a public repository of historical flights made available for research purposes, and freely accessible at https://www.eurocontrol.int/dashboard/rnd-data-archive (accessed on 11 February 2022). It includes information about all commercial flights operating in and over Europe, complete with flight plans, radar data and associated airspace structure.

For this study, we considered the information associated with all flights landing in the 50 largest airports in Europe ranked according to their number of landing operations in September 2019. This month was selected for being the one with the largest number of operations in 2019, i.e., the last year not affected by the COVID-19 pandemic. The full list of airports, along with information about number of landings and their delays, can be found in Table A1.

The landing delay of each flight arriving at those 50 airports was estimated as the difference between the actual (from the ATFM-updated flight plan) and the planned (according to the last filed flight plan) landing times. A time series representing the average landing delay at each airport has then be calculated by averaging the delays of all flights landing within non-overlapping windows of a given length *w*. Negative delays, i.e., instances in which the aircraft arrived before the planned times, were not deleted and thus contribute to the final average delay. Note that other alternatives for calculating delays can also be considered, e.g., departure delays. We chose arrival delays, first because they have been the focus of similar studies [15–21] and second, because they directly affect passengers (i.e., a departure delay that is recovered en-route does not negatively impact mobility). In addition, note that delays are calculated according to flight plans; longer than real declared flight times (as commonly used by airlines to reduce the perceived amount of arrival delays) have no impact on the results.

The Granger causality test requires the time series to be stationary in order to avoid spurious results, that is, values in these time series should not explicitly depend on time [34]. This is not fulfilled by raw average delay time series, as the probability for an aircraft arriving late is higher during peak hours. We thus make them stationary by applying a Z-Score detrend procedure defined as:

$$D'(d,h) = \frac{D(d,h) - \langle D(\cdot,h) \rangle}{\sigma[D(\cdot,h)]},$$
(1)

where D'(d, h) is the normalised delay of day d and for the time window h, D(d, h) is the original delay, and $\langle D(\cdot, h) \rangle$ and $\sigma[D(\cdot, h)]$ are the mean and standard deviation for the delays observed in all days of the same week at a window h. Thus, this Z-Score represents how one average delay deviates from that observed in neighbouring days at the same time,

that is, how usual or unusual the delay is for that time window. As a consequence, the resulting time series are stationary, with constant mean and standard deviation. Note that we normalise the average delays considering the same time period of the 7 days after for the first week of the month and the 7 days before for the remaining days of the month.

2.2. Delay Propagation Assessment: The Granger Causality

As mentioned before, we used the Granger causality test to detect causality relationships among the delay time series. This test was developed by the economics Nobel Prize laureate Clive Granger [13], and since then it has been extensively applied to solve problems in different fields, such as economics [35,36], engineering [37] and neuroscience [38–40]. The test is based on two intuitive concepts: the cause precedes the consequence, and the consequence is better predicted using the past information of both the cause and the consequence than of the consequence alone. Mathematically, suppose we have two time series A and B, representing the delays of two airports; also assume they meet some conditions, such as being stationary and regularly sampled. We can then say that B "Granger-causes" A if:

$$\sigma^2(A|U^-) < \sigma^2(A|U^- \backslash B^-), \tag{2}$$

where $\sigma^2(A|U^-)$ is the error in forecasting the time series A using all past information of the universe U, and $\sigma^2(A|U^-\setminus B^-)$ is the corresponding error in forecasting the time series A when the past information of B is dismissed. That means that B "Granger-causes" A if including the past information of B results in a better prediction of A. Note that the universe U represents all available information, or, in this case, the evolution of delays in all other airports. For the sake of simplicity, this can nevertheless be avoided by considering pairwise interactions, i.e., supposing in each test that only airports A and B exist.

The previous definition of the Granger causality test is agnostic with respect to how the forecast is actually performed, and many alternatives have been proposed in the literature [41–43]. Here, we followed the initial proposal of Granger and chose an autoregressive-moving-average (ARMA) model. We fit two models,

$$A_t = C \cdot A_{t-1}^m + \epsilon_t, \tag{3}$$

$$A_t = C' \cdot (A_{t-1}^m \oplus B_{t-1}^m) + \epsilon'_t, \tag{4}$$

where *m* is the model order, \oplus indicates the concatenation of column vectors, *C* and *C'* represent the model coefficients, and ϵ and ϵ' depict the residuals of the models. Here, *m* is also called the lag and indicates the time length used when including past information about the two systems. To illustrate, A_{t-1}^m implies that we use information about A from t - m - 1 to t - 1. Here, we considered $1 \le m \le 12$. For the purpose of determining whether information about *B* has a significant impact, we perform an *F*-test on its coefficients and obtain a *p*-value. In other words, the objective is to conclude if the coefficients *C'* that are related with the information of *B* are significantly different to zero.

It is important to stress that the Granger causality test is very sensitive to missing values. When examining the time series of delays, it can be noted that they have some missing values since most airports stop working around midnight and resume their flights the following morning; therefore, at night, delays are always zero. Note that it is different from having no delays at those times, as more correctly we have no information about what delays there may be; thus, those zero values ought to be represented with missing values. In order to deal with that, we use a weighted variation of the Granger causality test [33], where the weights are set to zero for missing values in the linear models. This means that elements containing missing values are discarded, and only correct ones are considered in the regression and thus in the calculation of the Granger causality test.

2.3. Network Reconstruction and Analysis

As previously introduced, a natural way of representing the structure created by delay propagation is provided by functional complex networks, as extensively performed in neuroscience [44–46] and climate [47–49]. We reconstruct directed and unweighted networks whose nodes represent the 50 considered airports, and directed links between pairs of them are added whenever a statistically significant causality is detected between the corresponding delay time series. Note that the Granger causality test is applied on the data of every possible pair of airports, thus yielding a set of directed relationships that are represented as a complex network. Additionally, and in order to obtain reliable results, such analyses are performed on the series of stationary average delays D'(d,h). It should be noted that the output of the Granger causality test is a *p*-value. In order to compensate for the higher probability of Type I errors as a consequence of the multiple comparisons to be executed, we perform a Bonferroni correction, i.e., we use an effective $\alpha = 0.01/(50 \times 49) \approx 4.08 \times 10^{-6}$.

We then move to studying the obtained networks by calculating and evaluating a set of topological metrics, i.e., metrics describing some properties of the underlying structure. These can be organised in two groups: global topological metrics, describing a property of the overall structure of the network; and centrality metrics, assessing the importance of each node in the network. Therefore, while the former ones yield a single number per network, the latter ones yield one value per node, in other words, a probability distribution per network. For the sake of completeness, a short definition of each metric and its relevance for the process under study are reported below. The full formal definitions are included in Tables A2 and A3. Finally, we invite the interested reader to find additional details in any of the many reviews available on the topic [22,50,51].

- Link density is the fraction of the potential edges in the network that are active, i.e., that have passed the statistical significance test.
- Diameter is the greatest distance between any pair of nodes in the network. Note that such a distance is defined as the number of links in the shortest path connecting the nodes and not the physical distance between them. Thus, it indicates how many intervening airports are needed to disseminate the delays throughout the whole network in the worst possible case.
- Transitivity measures the existence of triangles in the network and represents the propensity of nodes to form clusters. It is defined as the ratio between the number of closed triangles and of connected triplets of nodes. A high density of triplets of airports that are strongly connected (a high transitivity) means that a delay in one of them is easily propagated to the other airports of the group.
- Assortativity is the propensity of links to connect nodes of similar degrees (i.e., with a similar number of connections) [52].
- Efficiency measures how easily the network can move information within it and is defined as the inverse of the harmonic mean of the distances between pairs of nodes [53,54]. The efficiency of a network thus represents how easily information (here, delays) can move between two nodes and is inversely proportional to the number of intervening nodes needed on average to reach the destination of the propagation.
- The information content (IC) metric evaluates the presence of regularities in the adjacency matrix. It is defined as the quantity of information lost when pairs of nodes are iteratively merged [55]. Small values of IC indicate complex topological patterns, while large values correspond to random-like structures.
- Out-degree centrality is the number of edges coming out from a node. It represents how strongly an airport can influence other.
- In-degree centrality is the number of edges arriving to a node. It represents how strongly an airport is influenced by its neighbours.
- Betweenness centrality represents the fraction of times a node is included in the shortest path between two other nodes. Thus, it depicts the amount of influence a node has over the flow of information (delays) in a graph [56].

In some instances, the values of the metric alone are insufficient to compare the topological features of two networks with different characteristics. To illustrate, a network with more links will have a smaller diameter, not due to a different structure, but only because of the overall tighter connectivity. To sort this out, a large ensemble of random networks (1000 unless otherwise specified) is created, each one with the same number of nodes and edges as the considered network. We then compute the Z-Score of the value *m* of the metric as:

$$m_{Z-score} = \frac{m - \mu^M}{\sigma^M},\tag{5}$$

where μ^M y σ^M are, respectively, the average and the standard deviation of the metric under consideration in the random networks. The resulting $m_{Z-score}$ indicates how much the observed metric deviates with respect to what is expected in random equivalent networks [57].

3. Synthetic Model of Delay Propagation

Before delving deeper into the study of real data, we construct and evaluate a synthetic model of delays to understand the relationship between, on one hand, the size w of the window used to estimate the Granger causality and, on the other hand, the efficacy of the causality detection. The approach consists of generating two time series representing the evolution of average delays at two fictitious airports with similar dynamics. By lagging the second one a certain number of time periods and applying the Granger causality test between the original and the lagged series to assess whether a causality is detected, we run several iterations of the simulation for different window sizes and calculate the fraction of times we detect a statistically significant causality.

The first step is the creation of time series representing the global evolution of delays, for which we resort to the well-known Lorenz model [58]:

$$\frac{dx}{dt} = \sigma(y - x),\tag{6}$$

$$\frac{dy}{dt} = x(\rho - z) - y, \tag{7}$$

$$\frac{dz}{dt} = xy - \beta z,\tag{8}$$

With the three parameters fixed to $\sigma = 10$, $\beta = \frac{8}{3}$ and $\rho = 28$. It is well-known that the system exhibits a chaotic behaviour for these three values, and chaotic systems have a long history for being used as models of complex dynamics, e.g., in economics [59] or biology [60]. The *x* variable of the Lorenz system, originally representing the rate of convection in a two-dimensional fluid layer, is here used to model the evolution of the average delay observed at an airport through the day, or in other words, the expected delay of an aircraft landing at time *t*. The time series of *x* is smooth, i.e., no sudden jumps occur. Additionally, it is deterministic but also chaotic; thus, no self-correlations are present. This last point is of relevance, as the Granger test requires stationary time series; if simpler functions are used to create such average delay evolution, e.g., a sinusoidal signal, the resulting time series has been generated, we normalise it in the range [0, 1]. Finally, two time series are generated from it, respectively, referred to as the master (i.e., the cause) and the dependent (i.e., the consequence) time series, by lagging the latter a certain number of time periods representing the time needed for the delay to propagate.

Once the two time series representing the overall evolution of delays have been created, it is necessary to reconstruct a set of landing events, as these are the only data available when analysing the real system. These events, for both the master and the dependent airports, are generated with a time separation between subsequent ones given by random numbers drawn from a uniform distribution $U(0, \eta)$. Thus, η defines the expected separation between consecutive landings and is therefore inversely proportional

to the amount of traffic. The delay assigned to each landing event is drawn from a second uniform distribution U[x(t) - 0.1, x(t) + 0.1], where x(t) is the value of the variable x of the Lorenz model at time t. The result is then two sets of events representing synthetic delays, each one described by a time stamp and an observed landing delay. Finally, for a fixed value of w, we extract the average delay observed in non-overlapping windows of length w, both for the events of the master and the dependent airports. These averages are merged in two time series, which can then be analysed using the Granger causality test. Note that the detrend step is not necessary here, as the use of a chaotic system ensures the stationarity of the time series. An example of the generation of one average delay time series can be seen in Figure 1, top panels. From left to right, the three panels depict the generation of the Lorentz series representing the global evolution of delays, the generation of the landing events and the calculation of the average delays.

This model allows us to evaluate the behaviour of the Granger causality under wellcontrolled conditions. First of all, a causality is present between both time series by construction, as landing events in both airports are generated from time-shifted time series; it is thus possible to evaluate how sensitive the test actually is. Second, it is possible to fully control the parameters of the model and thus test the hypothesis that too small and too large values of *w* can result in an underestimation of the causality.

We proceed with the analysis of the model by varying the two main parameters: the average time between landing events and the window size w. For each combination of parameters, 1000 repetitions are generated, and the fraction of times that the p-value is significant is calculated.

The left middle panel of Figure 1 reports the proportion of significant tests for different window lengths w and for different event separation times η . All plots follow a similar trend, where for very low values of the window length (between zero and one), most of the tests are not statistically significant, as not enough landing events are available to obtain meaningful average values. The fraction then increases until it reaches a maximum and finally decreases for large window lengths. This is different than that observed for small w, which is potentially due to the fact that too long a window results in the average of too much information, thus losing the high-frequency dynamics in both airports—or, in other words, that just the global average landing delay is obtained. The right middle panel of Figure 1 additionally reports a scatter plot of the optimal window size as a function of the separation time η . In synthesis, the model confirms that an ideal (optimal) window size exists, for which the maximum number of causality relationships are detected; deviating from such an optimum results in an underestimation of the propagation.

We then change the simulation, specifically the synthesis of the landing events. The time separation between consecutive landings is now given by random numbers drawn from a distribution $[U(0, \eta)]^e$, *e* being an asymmetry exponent that stretches the positive tail of the distribution. In other words, while keeping the average constant, increasing this exponent results in clusters of landing events, with some of them happening after long periods of inactivity. Thus, this exponent is used to break the regularity of landing events and to simulate a more realistic burst distribution. We fix the average time between landing events $\eta = 1.4$ and vary the window size *w* and the asymmetry exponent *e*; similar to before, we execute 1000 iterations for each pair of parameter values and record the proportion of times the *p*-value is significant.

The left bottom panel of Figure 1 depicts how the fraction of significant tests varies when considering different window sizes and asymmetry exponents. In order to compensate for the fluctuations due to the stochastic nature of the analysis, the dotted lines represent second order polynomial fits. The right bottom panel further depicts a scatter plot of the best window size as a function of the exponent *e*. A clear linear relation can be observed, where for larger asymmetry exponents, namely for less uniform separation times, the best window size grows; in other words, a larger window size is needed to detect causality relationships in order to cope with the periods of less activity.



Figure 1. Analysis of the synthetic model—see Section 3 for details. (**Top** panels) Example of the synthesis of one time series, with the calculation of the global delay trend using a Lorenz system (**top left** panel); synthesis of individual landing events (**top central** panel); and reconstruction of the evolution of the average delay (**top right** panel); (**Middle** panels) Analysis of the Granger causality test as a function of the traffic volume: evolution of the fraction of significant tests as a function of the event separation time η ; (**left middle** panel); and size of the best window size, i.e., the one maximising the fraction of significant tests for different values of η (**right middle** panel); (**Bottom** panels) Analysis of the Granger causality test as a function of the traffic regularity: evolution of the fraction of significant tests as a function of the traffic regularity: evolution of the fraction of significant tests as a function of the traffic regularity: evolution of the fraction of significant tests as a function of the traffic regularity: evolution of the fraction of significant tests as a function of *w* and of the asymmetry exponent *e* (**left bottom** panel); and value of *w* maximising that fraction as a function of *e*, as obtained from the quadratic fits (**right bottom** panel). In the middle and bottom panels, coloured points in the right panels correspond to the line of the same colour in the left ones.

In synthesis, results from the model confirm that the ideal window size to detect delay propagation is a function of the number of landing events; in other words, the higher the frequency with which we obtain information from the system, the higher the potential temporal resolution of the results. This optimum is a balance between two forces: the need for analysing large number of events to obtain a reliable average delay estimation, on one hand, and the risk of considering too long time windows, with the consequent smoothing of the fast part of the dynamics, on the other. Still, the estimation of such window length is made more complex by other factors, such as, for instance, the degree of regularity of landing events.

4. Analysis of Real Delay Propagation Patterns

When moving to the analysis of real delay data, the approach proposed here can be applied at three different levels. Firstly, there is a methodological point of view, i.e., one may simply be interested in optimising the analysis of delay propagation patterns and hence derive the best window size for detecting causality relationships. Secondly, such an optimal window size, along with the optimal lag as yielded by the Granger causality test, can be used to derive the time needed for delays to propagate between two airports. Finally, the last step is to move to a network level and see whether and how changing the window size modifies the resulting delay propagation topology. These three aspects will be tackled in this section.

4.1. Methodological Viewpoint: Best Time Scale for Detecting Delay Propagation

The identification of the best time scale for detecting delay propagation in real data is not dissimilar from what is presented in Figure 1; specifically, for a pair of target airports, one needs to reconstruct the corresponding delay time series for different values of *w*; to apply the Granger causality test, thus obtaining a *p*-value as a function of *w* and finally to select the *w* minimising such a *p*-value. Note that a smaller *p*-value implies a more statistically significant relationship, but also that such relationship manifests clearer in the data.

The top left panel of Figure 2 shows the window size w minimising the p-value, for those pairs of airports that display a statistically significant relationship (i.e., p-value < 0.01, with a Bonferroni correction for multiple testing). No clear pattern can be discerned, with the optimal w varying from 30 min to up to two hour (see top right panel for a corresponding histogram). Specifically, no clear relationship seems to exist with the size of the airport (see middle right panel of Figure 2 representing a box plot of all ws for each airport and with airports sorted by decreasing number of operations and Figure A1, reporting a scatter plot of the optimal w as a function of the number of operations of airports).

Then, what are the elements that drive the size of such an optimal window? In order to answer this question, we extracted a set of time series describing the two most important aspects of the operations at an airport, i.e., the separation between landings and their delays—see the first column of Table A4. Each one of these sets of values has been synthesised using metrics such as the average or the standard deviation—second column of Table A4, and these features have further been combined for each pair of airports under analysis, using standard mathematical manipulations (e.g., the product or the maximum)right columns of Table A4. The result is a set of 90 features per link. As a first approach, the linear correlation between each one of these features and the optimal w has been obtained, and the corresponding coefficient of determination R^2 has been calculated—see results in Table A4. Taken individually, none of them seem to substantially explain the best window size; the best result is given by the maximum of the median absolute deviation (MAD) of the landing times although the R^2 is only 0.053. We then exhaustively explored all combinations of four features and evaluated linear models based on them. The best four, yielding an R^2 of 0.133, are: the standard deviation of the landing separation for the receiving airport, the minimum Hurst exponent (HE) of the landing separation, the MAD of the landing times of the source airport, and the maximum of the MAD of the landing times. Scatter plots for these features and the corresponding linear fits are reported in the bottom panels of Figure 2. Finally, when combining all 90 features in a linear model, the resulting R^2 is 0.363.

What conclusions can be obtained from these results? From a general point of view, the landing and delay dynamics of the involved airports are partly responsible for defining the best window length w although a linear model can only explain 36% of the variability. Additionally, it can be seen that such w depends mainly on the landing dynamics, with the delays themselves having a minor role—see Table A4. While selecting a few features is not enough to construct a model able to predict the best w, this latter seems to be related with the variability of the separation between consecutive landings, something that is in agreement with the results of Section 3.

In synthesis, obtaining the best window size w for a pair of airports is not a trivial process. Although it depends on the characteristics of the landing events, and specifically on the time between consecutive operations, the best w strongly changes between different pairs of airports, such that its value cannot be predicted at this stage. While disappointing, this is to be expected, as real operations (and data) are more complex than any synthetic



model. Consequently, the only reliable alternative is testing several values of w and selecting the one yielding the minimal p-value.

Figure 2. Best time scale for detecting real delay propagation patterns. (**Top left**) window length minimising the *p*-value of the Granger causality test for each pair of source–destination airports; note that results are only reported for those pairs for which the test is statistically significant and that airports are sorted in decreasing number of operations (see Table A1); (**Top right**) histogram of the best window lengths *w*; (**Middle right**) box plot depicting the distribution of the best window lengths for each airport, considering the links it causes, with airports sorted by decreasing number of operations; boxes indicate the interquartile range (Q3–Q1) and blue horizontal lines the median of the distribution; (**Bottom**) scatter plots of the four features that best predict the length of the optimal window as a function of the latter for each statistically significant causality link; the black lines represent the best linear fit. *L. sep.*: landing separation; *L. time*: landing time. See main text and Table A4 for details on the metrics.

4.2. Operational Viewpoint: Delay Propagation Time

Next, we tackle the problem of estimating the time it takes for delays to propagate within the network. This is achieved by considering the optimal window size *w* for each pair of airports, as estimated in the previous subsection, for then performing an exhaustive search to find the maximum lag yielding the best (lowest) *p*-value. Finally, the delay propagation time is obtained by multiplying these two values.

The left panel of Figure 3 reports the resulting delay propagation time for each pair of airports. As in the case of Figure 2, only results for those pairs of airports that have a statistically significant propagation are reported. Intuitively, one may hypothesise that such propagation time should be proportional to (or at least, be a function of) the distance between the two involved airports. As is evident in the scatter plot of the right panel of Figure 3, no simple pattern can be observed; a linear correlation analysis yields a coefficient of 0.045, with a *p*-value of 0.411.

We further estimate the time required for a delay to be propagated by an aircraft performing two consecutive flights, respectively, departing from airports *a* and *c*, as a function of the distance between the two airports. The geographical distance is transformed into time by considering a ground speed of 500 knots, plus one hour for departure and arrival procedures and turn-around operations. In other words, the objective is to obtain an estimation of the minimum time required between the two consecutive departures. The result is depicted by the dashed diagonal line in the right panel of Figure 3. It can be seen

that most propagation times are well above the line, suggesting the presence of indirect propagation patterns—e.g., when the propagation between two airports *a* and *c* requires an intermediate airport *b*. This is consistent with the use of the Granger causality test, which is designed to detect these indirect patterns.



Figure 3. Delay propagation time. The left panel reports the delay propagation time in hours between each pair of airports. Only pairs with a statistically significant propagation are reported, and airports are sorted in decreasing number of operations (see Table A1). The right panel represents a scatter plot of the propagation time in hours as a function of the distance between each pair of airports. The diagonal dotted line approximates the flight time as a function of the distance.

At the same time, a few pairs of airports have delays propagating between them in very short times, as low as 50 min—see Table A6. In other words, there are instances in which a delay takes less time to propagate than the duration of the shortest flight connecting the corresponding pair of airports. To illustrate this point, Figure 4 depicts a graphical representation of the five pairs of airports with the largest (red arrows), smallest (green arrows) and most asymmetrical (blue lines) propagation times—numerical data are reported in Tables A5–A7. No clear trend can be identified. While most of the largest propagation times occur between distant airports, this also happens between Brussels and Hamburg and between Hamburg and Stuttgart. If delays between nearby airports are propagated by indirect connections, this does not explain the short time observed from Amsterdam and Hamburg or between Paris Orly and Stuttgart.

Following what was proposed in Ref. [12], the left panel of Figure 5 reports the distribution of the propagation time when airports are classified according to their size, i.e., in large and small ones—see also Figure A2 for full results. The former ones are those with a number of flights larger than the median of all considered airports; the latter ones are those with less flights. Four distributions of propagation times are then calculated corresponding to all possible combinations of airports at each end of a propagation link. As opposed to what was reported in Ref. [12], no significant differences can be observed. Additionally, the right panel of Figure 5 reports two distributions of the propagation times, respectively, corresponding to pairs of airports that are nearer or farther away than the median of all pairwise distances. While the propagation time is slightly larger for airports located farther away, the difference in medians is not statistically significant (Mood's median test, *p*-value = 0.152).



Figure 4. Graphical representation of the most extreme delay propagation times. Red and green arrows indicate the five pairs of airports with, respectively, the largest and smallest propagation times; blue lines indicate those pairs with the most asymmetrical ones. See Tables A5–A7 for numerical values.



Figure 5. Violin plots reporting the distributions of propagation times as a function of the size of the airports at each end of the link (**left** panel) and of the distance between them (**right** panel). *L*: large; *S*: small.

We hypothesise that several factors may contribute to the complex relationship between the propagation time and airports' characteristics. On one hand, it is clear that delays at neighbouring airports are influenced by shared weather patterns or even by interactions between their approach procedures. On the other hand, it is possible for information about delays to be transmitted before the corresponding flights reach their destination, as for instance when managed through ground delay programs. In short, it seems that the delay propagation time is driven by different and intermingling factors, including (but not exclusively) indirect connections and localised weather patterns.

4.3. Network Viewpoint: Propagation Network and Its Structure

The next logical step is to reconstruct the whole functional propagation network by varying the size of the window used to assess the Granger causality on the time series of pairs of airports. In Figure 6, blue lines report the evolution of six topological metrics as defined in Section 2.3 as a function of the window size used in the network reconstruction process. Note that this corresponds to the standard approach of using a single time scale for all possible propagation links. On the other hand, the dotted horizontal lines in the same figure report the network metrics when the optimal time scale is used for each airport pair.

Let us start by analysing the link density in the top left panel of Figure 6. It is apparent that using a fixed time window of 60 min, as common in the literature [15–21], leads to a significant information loss. In other words, and as seen in Figure 1, long windows imply a loss of information about the fast dynamics of delays and hence in an underestimation of the propagation. It is worth noting the magnitude of this effect: almost three-fourths of the causality links are lost for windows of 60 min compared to the use of optimal window lengths. At the same time, using very short time windows seems beneficial, with an increase in the link density. This is nevertheless misleading, as very short windows necessarily include more periods of inactivity—see the aqua line, right Y axis, representing the reliability, i.e., the fraction of airport pairs for which at least 50% of the windows have one or more landing events. As previously discussed, these correspond to missing values, and it has been shown that too large a share of them results in an overestimation of the causality [33].

As to be expected, these changes in the link density, and hence in the number of detected links, have an impact on the values of all other topological metrics. Assortativity, transitivity and IC yield qualitatively similar values when comparing the results of using the optimal window size and a fixed 60 minimum one. The same is not true for the other two metrics, with the diameter and the efficiency being, respectively, under- and overestimated by using a fixed time window of 60 min. It is interesting to note that the former group of metrics are mostly local in nature, while the latter (i.e., those not correctly estimated) focuses on the macro-scale structure of the network. In other words, using a fixed (non-optimal) window size does not bias the structure created by pairs and triplets of airports, possibly those more strongly connected, but instead changes the overall structure of the propagation network.

To better understand how the centrality of the airports is modified by the use of different window sizes, Figure 7 reports the evolution of the airport ranking according to three centrality measures: in-degree, out-degree and betweenness centrality. Specifically, in each case, we consider the five airports that have the largest centrality when reconstructing the propagation network with the optimal window size and calculate the position in the ranking of these airports when considering a fixed window size. A simple look at Figure 7 shows that the window size has a profound effect on the centrality of airports, with these top five airports ending, in many cases, in the bottom half of the ranking. The sensitivity of the ranking to the window size is also noticeable, especially in the case of the betweenness. It is worth noting that this centrality metric strongly depends on the macro-scale structure of the network and that this result is therefore aligned with what is observed in Figure 6.



Figure 6. Evolution of the six topological metrics described in Section 2.3 (blue lines, left *Y* axes), as a function of the size of the window used for calculating the Granger causality. Aqua lines (right *Y* axes) depict the reliability of each value, i.e., the fraction of pairs of airports having operations in at least 50% of the windows used to calculate the causality. The horizontal dotted lines indicate the values of the metrics when the optimal window size is used for each link.



Figure 7. Evolution of the centrality ranking as a function of the window size used to calculate the Granger causality. From left to right, the three panels depict the evolution of the ranking according to the out-degree, in-degree and betweenness centrality. In each case, the five reported airports are those with the maximal centrality in the networks reconstructed with optimal window sizes.

5. Resampling Validation

As a last point, we analyse another aspect that can influence the optimal window size for estimating the Granger causality. Several studies indicated that the sensitivity and stability of the test can be improved with higher temporal sampling rates [24,25]; this nevertheless can be due to two factors: the presence of new high-frequency information which is lost for low sampling rates or alternatively, the simple fact that longer time series (i.e., more data) make tests more statistically significant, even if no new information is included. Here, we approach this problem by leveraging the test suggested in Ref. [25] involving artificially resampling the analysed time series and comparing the evolution of the resulting *p*-values.

We start by considering the two original time series for a given pair of airports, reconstructed using the corresponding optimal window length. We then consider a resampling rate $\rho = (2, 3, ..., 5)$, and synthesise a new pair of time series by firstly downsampling the original data by a factor of ρ and secondly upsampling them by the same factor. The result is a new set of time series whose length is preserved but in which high-frequency information is deleted. We finally compare the two *p*-values obtained with the original and resampled time series by calculating $\delta p = \log_{10} p^r - \log_{10} p^o$, where p^r and p^o represent the *p*-values obtained with, respectively, the resampled and original time series. Note that $\delta p < 0$ implies that the causality calculated with the resampled time series is stronger than that seen in the original case.

Figure 8 reports violin plots of the distribution of δp as a function of the resampling rate. In all cases, most δp are greater than zero—see also the aqua line, right *Y* axis, representing the percentage of links for which $\delta p < 0$. In addition, the average of all distributions sits around five, thus indicating that the *p*-values for the original time series are significantly smaller than those for the resampled time series. In synthesis, one can conclude that the length of the optimal window is a function of the information the time series contains, specifically of its high-frequency part, and not directly of the time series length.



Figure 8. Probability distribution of δp , i.e., the difference between the *p*-values obtained with the original and the resampled time series. Each violin plot corresponds to a different resampling, and its values to all pairs of airports with a statistically significant causality (according to the original time series). The water green line (right *Y* axis) shows the percentage of pairs for which the resampled time series yield a smaller *p*-value (that is, a more statistically significant relationship) than the one obtained with the original series.

6. Discussion and Conclusions

In this paper, we have studied the effect of the temporal resolution used in the analysis of delay propagation in air transport, both in a synthetic model and in real operational data. While this is a problem well-known in the literature [24–26], air transport presents several idiosyncrasies, most notably the fact that events generating the time series (i.e., landings and their delays) are discrete. As shown in Section 3, the window size that maximises the sensitivity of a Granger causality test is a balance between several elements; in the simplest and noiseless case, it is between the need for detecting high-frequency dynamics through small windows and the need for windows long enough to contain a significant number of landing operations. Additional elements affecting the optimal window length include the presence of inactivity periods for which no events are available and the shape of the probability distribution of landing separation times, such that more heterogeneously spaced events require longer windows.

When applying these ideas to real data, three main conclusions can be drawn. First of all, due to the high complexity of real operations, the estimation of the best window size for a given airport pair can only be obtained numerically by systematically checking different window sizes and choosing the one minimising the test *p*-value. While these optima are related to some properties of the landing operations (see Figure 2), as previously discussed, such relationships are too weak to support the creation of an analytical solution. Secondly, the same approach can be used to infer the time required by delays to propagate between airports. Once again, results are loosely related to some airport characteristics, such as their distance and size, but no clear pattern can be discerned (see Figure 3). Thirdly, the use of a non-optimal window size has profound effects on the estimated structure of the

delay propagation networks, with global features being more affected than micro-scale ones (see Figure 6).

It is worth noting that research works have hitherto used a fixed window length of one hour [15–21]. This prima facie made sense, as it is a natural way of dividing the day in equal parts; simplifies calculations, as windows of different days always start at the same time and is aligned with the way airport capacity is defined (i.e., operations per hour). We have nevertheless shown that the use of this fixed window substantially underestimates causality relationships and that the reconstructed network topology is thus misrepresented. This should be interpreted as a note of caution by the community, as previously published results may be partly incorrect. The present work is thus not only a theoretical exercise. Rather, it has direct implications on the analysis of real air transport delays.

Regarding the delay propagation times between pairs of airports reported in Figure 3, it is relevant to compare the results obtained here with those of Ref. [12]. Specifically, those authors reported a correlation between the distance between two airports and the corresponding propagation timescale, and the latter was also modified by the role of the airport in the network (e.g., hub vs. peripheral airport), albeit to a lesser degree. Similar trends can be observed in our results, albeit they never are statistically significant (see Figures 3 and 5). Several causes can explain such a discrepancy. First of all, the detection of the delay propagation patterns and the estimation of their time scale is performed in Ref. [12] by using lagged linear correlations as opposed to the Granger causality considered here. Significant differences ought to be expected, especially taking into account that the Granger test is designed to detect indirect propagation patterns, i.e., when delays propagate between two airports through an intervening one. Secondly, Ref. [12] is based on the use of windows of a fixed size of 30 min; even though the analysis is based on a different technique to detect the delay propagation, the use of a fixed window length seems sub-optimal in light of what is presented here. Thirdly, the possibility that differences between the US and European systems, e.g., in the management of delays [61,62], could be the basis of such discrepancies cannot be ruled out.

Future works will have to be targeted at confirming and extending the results obtained here. Firstly, given the variability observed when changing the temporal scale of the time series reconstruction, it stands to reason to expect even more heterogeneous results when links are obtained with different metrics, e.g., correlation or non-linear causality ones. Specifically, non-linear causality metrics, such as non-linear versions of the Granger causality [42,63,64] or the Transfer Entropy [65], usually require longer time series to obtain reliable results. As a consequence, correctly estimating the optimal time scale may become even more critical. Secondly, similar analyses could be performed when considering alternative ways of reconstructing delay time series, e.g., by analysing each airline independently [15], thus effectively moving from a single- to a multi-layer representation [66], or by estimating the departure (as opposed to arrival) delays. Thirdly, it would be interesting to check whether similar results are also obtained in other large air transport systems, e.g., the US or Chinese ones. It would also simplify future studies to have an explicit a priori estimation of the optimal window length, for instance obtained through a machine learning model trained over a large set of airports and their operations.

As a final note of caution, it is worth recalling that functional networks are a powerful tool to describe delay propagation patterns in air transport, as customarily conducted in other scientific fields [44–49]. At the same time, this kind of analysis provides little information about the factors and reasons behind them. In other words, they allow to describe, but not to explain the dynamics of delay propagation. While it is in principle possible to combine functional network representations with other operational data, and hence understand if and how much the latter affect the former, this has yet to be accomplished and represents an open field of research.

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Appendix A

Table A1. Information on the 50 airports considered in this study, including their 4-letter ICAO code, number of landing flights and percentage of flights delayed more than 10 and 30 min.

Rank	Name	ICAO	# Flights	% Delayed > 10 min. % Delayed > 30 r	
1	Frankfurt Airport	EDDF	23,061	30.65%	5.06%
2	Amsterdam Airport Schiphol	EHAM	22,350	52.77%	11.55%
3	Paris Charles de Gaulle Airport	LFPG	22,275	33.76%	5.39%
4	London Heathrow	EGLL	19,407	68.39%	20.39%
5	Munich Airport	EDDM	18,588	25.22%	2.75%
6	Adolfo Suárez Madrid-Barajas Airport	LEMD	18,345	38.50%	7.44%
7	Josep Tarradellas Barcelona-El Prat	LEBL	15,817	44.39%	10.14%
	Airport				
8	Rome-Fiumicino International Airport	LIRF	13,930	14.45%	2.84%
9	Milan Malpensa Airport	LIMC	13,383	12.67%	2.84%
10	London Gatwick Airport	EGKK	12,985	61.29%	18.78%
11	Palma de Mallorca Airport	LEPA	12,616	32.13%	10.03%
12	Vienna International Airport	LOWW	12,482	42.16%	7.34%
13	Copenhagen Kastrup Airport	EKCH	11,811	18.72%	2.24%
14	Zürich Airport	LSZH	11,426	41.24%	5.56%
15	Oslo Airport	ENGM	11,203	12.79%	1.11%
16	Athens Intl Eleftherios Venizelos	LGAV	10,808	25.54%	3.22%
17	Dublin Airport	EIDW	10,731	26.94%	4.63%
18	Stockholm Arlanda Airport	ESSA	10,585	22.57%	2.51%
19	Brussels Airport	EBBR	10,313	40.79%	6.73%
20	Düsseldorf Âirport	EDDL	10,178	33.52%	4.87%
21	Humberto Delgado Airport	LPPT	9852	45.98%	8.10%
22	Manchester Airport	EGCC	9635	39.81%	6.58%
23	Paris Orly Airport	LFPO	9283	30.09%	4.73%
24	London Stansted Airport	EGSS	8634	41.52%	6.24%
25	Berlin Tegel "Otto Lilienthal" Airport	EDDT	8545	27.55%	3.25%
26	Warsaw Chopin Airport	EPWA	8434	10.91%	1.67%
27	Václav Havel Airport Prague	LKPR	7263	24.03%	3.33%
28	Geneva Airport	LSGG	7108	25.63%	4.47%
29	Nice Côte d'Azur Airport	LFMN	6703	20.50%	3.43%
30	Málaga-Costa del Sol Airport	LEMG	6660	35.47%	4.76%

Rank	Name	ICAO	# Flights	% Delayed > 10 min	. % Delayed > 30 min.
31	Hamburg Airport	EDDH	6531	21.45%	2.56%
32	Cologne Bonn Airport	EDDK	6423	26.48%	3.30%
33	London Luton Airport	EGGW	6103	46.53%	8.65%
34	Stuttgart Airport	EDDS	6066	28.70%	3.07%
35	Edinburgh Airport	EGPH	5843	21.80%	2.57%
36	Boryspil International Airport	UKBB	5620	22.94%	2.74%
37	Budapest Ferenc Liszt International	LHBP	5452	17.59%	2.27%
	Airport				
38	Bucharest Henri Coandă International Airport	LROP	5390	13.36%	1.78%
39	Lvon-Saint Exupéry Airport	LFLL	5127	26.41%	3.49%
40	Alicante-Elche Miguel Hernández	LEAL	4946	34.17%	5.14%
	Airport				
41	Birmingham Airport	EGBB	4891	20.40%	2.25%
42	Venice Marco Polo Airport	LIPZ	4720	27.58%	5.76%
43	Francisco Sá Carneiro Airport	LPPR	4443	38.06%	10.44%
44	Orio al Serio International Airport	LIME	4417	16.32%	2.04%
45	Marseille Provence Airport	LFML	4329	23.56%	2.73%
46	Toulouse-Blagnac Airport	LFBO	4159	17.62%	1.90%
47	Naples International Airport	LIRN	4041	27.86%	3.07%
48	Glasgow Airport	EGPF	3732	28.27%	3.99%
49	Catania-Fontanarossa Airport	LICC	3660	14.64%	1.53%
50	Bologna Guglielmo Marconi Airport	LIPE	3519	25.09%	2.90%

Table A1. Cont.

 Table A2. Formal definition of the network topological metrics considered in this study.

Metric	Definition	Range
Link density	$l_d = \frac{L}{N^2}$, <i>L</i> being the total number of active links in the network and <i>N</i> the number of nodes.	$0 \le l_d \le 1$
Diameter	$D = \max_{i,j} d_{i,j}$, $d_{i,j}$ being the distance between nodes <i>i</i> and <i>j</i>	$0 \le D \le N$
Transitivity	$T = \frac{3N_{\triangle}}{N_3},$ $N_{\triangle} \text{being the number of closed triangles}$ $3N_{\triangle} = \sum_{k>i>j} a_{i,j}a_{i,k}a_{j,k}, \text{ and } N_3 \text{ the number of connected}$ triplets $N_3 = \sum_{k>i>j} (a_{i,j}a_{i,k} + a_{j,i}a_{j,k} + a_{k,i}a_{k,j}).$	$0 \le T \le 1$
Assortativity	$r = \frac{1}{\sigma_q^2} \sum_{jk} jk(e_{jk} - q_j q_k),$ <i>j</i> and <i>k</i> being the degrees of nodes at each end of a link; <i>q_k</i> the distribution of the remaining degree, i.e., of the degree without the link under study; σ_q^2 the variance of the distribution <i>q_k</i> ; and <i>e_{jk}</i> the joint probability distribution of the remaining degrees of the two vertices at either end of a randomly chosen link.	$-1 \le r \le 1$

Metric	Definition	Range
Efficiency	$E = \frac{1}{N(N-1)} \sum_{i \neq j} \frac{1}{d_{ij}},$ <i>d_{ij}</i> being the distance between the nodes <i>i</i> and <i>j</i> .	$0 \le E \le 1$
Information Content	See [55]	$0 \leq IC$

Table A3. Formal definition of the centrality metrics considered in this study. Note that these metrics are calculated for a single node (here denoted as w), as opposed to the whole network; nodes can then be ranked in importance accordingly.

Centrality Metric	Definition
Out-degree centrality	$c_O(w) \propto \sum_j a_{w,j}$, where $a_{w,j}$ is equal to one if a link exists between nodes w and j , and zero otherwise.
In-degree centrality	$c_I(w) \propto \sum_j a_{j,w}$, where $a_{j,w}$ is equal to one if a link exists between nodes j and w , and zero otherwise.
Betweenness centrality	$c_B(w) \propto \sum_{s,t \in V} \frac{P_w(s,t)}{P(s,t)}$, where <i>V</i> is the set of nodes, $P(s,t)$ the number of shortest paths between <i>s</i> and <i>t</i> , and $P_w(s,t)$ the number of shortest paths between <i>s</i> and <i>t</i> that includes <i>w</i> .



Figure A1. Scatter plot of the length of the optimal window for each pair of airports as a function of the number of operations recorded in the data set for the source (*X* axis) and destination (*Y* axis) airports.

Input Time	Motric						
Series	wiethe	a	b	$a \cdot b$	$\log_2 a/b$	Max	Min
Landing times	MAD	0.00	0.01	0.00	0.01	0.05	0.02
Landing times	Hurst exponent	0.00	0.01	0.01	0.00	0.02	0.00
	Mean	0.01	0.01	0.03	0.00	0.02	0.02
Landing	Standard deviation	0.00	0.04	0.03	0.01	0.02	0.04
separation	Linear correlation	0.00	0.00	0.00	0.00	0.01	0.00
	MAD	0.01	0.00	0.01	0.00	0.01	0.01
	Mean	0.01	0.02	0.01	0.00	0.02	0.01
	Standard deviation	0.01	0.02	0.02	0.00	0.02	0.01
Delays	Linear correlation	0.01	0.00	0.01	0.00	0.01	0.00
·	MAD	0.00	0.00	0.00	0.00	0.01	0.00
	Hurst exponent	0.02	0.01	0.03	0.00	0.02	0.02
	Mean	0.00	0.01	0.00	0.00	0.01	0.01
Δ consecutive	Standard deviation	0.00	0.01	0.01	0.00	0.01	0.01
delays	Linear correlation	0.00	0.00	0.00	0.00	0.00	0.00
-	MAD	0.00	0.00	0.00	0.00	0.00	0.00

Table A4. Coefficients of determination R^2 obtained by fitting linear models to recover the best window size for each pair of airports, using the corresponding features listed in the left columns; *a*: source airport of the causality (i.e., the cause); *b*: destination airport of the causality (i.e., the consequence).

Table A5. List of the ten pairs of airports with the longest propagation time (in hours); *a*: source airport of the causality (i.e., the cause); *b*: destination airport of the causality (i.e., the consequence).

Airport a	Airport b	Distance (NM)	Prop. Time $a \rightarrow b$
EBBR	EDDH	482	8.0
LIME	LEMG	1549	8.0
EDDH	EDDS	552	7.5
EDDT	LPPR	2077	7.3
LEBL	LHBP	1523	7.1
EBBR	EGBB	463	7.1
LIMC	LOWW	657	7.1
LIMC	LKPR	646	7.1
LIME	LOWW	588	7.1
EGBB	EBBR	463	7.1

Table A6. List of the ten pairs of airports with the shortest propagation time (in hours); *a*: source airport of the causality (i.e., the cause); *b*: destination airport of the causality (i.e., the consequence).

Airport <i>a</i>	Airport b	Distance (NM)	Prop. Time $a \rightarrow b$
LFPO	EDDS	502	0.8
UKBB	LGAV	1485	1.0
EDDS	LFPO	502	1.2
EHAM	EDDH	379	1.2
LIML	ENGM	1645	1.4
LGAV	UKBB	1485	1.8
EDDS	EDDH	552	1.8
LFML	ENGM	1906	2.0
ENGM	EDDS	1286	2.0
LSZH	EPWA	1031	2.2

Table A7. List of the ten pairs of airports with the most asymmetrical propagation time, defined as the difference between the forward (reported in the fourth column) and backward time (fifth column); *a*: source airport of the causality (i.e., the cause); *b*: destination airport of the causality (i.e., the consequence). Propagation times in hours.

Airport a	Airport b	Distance (NM)	Prop. Time $a \rightarrow b$	Prop. Time $b \rightarrow a$
EDDH	EDDS	552	7.5	1.8
LIME	LEMG	1549	8.0	3.7
EBBR	EDDH	482	8.0	4.0
LICC	LSGG	1223	6.5	4.2
EKCH	ESSA	546	7.0	5.2
LIMC	EDDS	342	6.8	5.0
LGAV	LPPR	2803	7.0	5.7
LIMC	EHAM	795	7.0	5.8
LIMC	LOWW	657	7.1	6.0
LIME	LOWW	588	7.1	6.0



Figure A2. Probability distributions of delay propagation times. Violin plots report the distribution of the delay propagation times in hours for all 50 considered airports for outgoing (i.e., delays propagated by an airport, top panels) and incoming (i.e., delays received by an airport, bottom panels) links.

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