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Global Dynamics of a Diffusive Within-Host HTLV/HIV Co-Infection Model with Latency

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Abstract: In several publications, the dynamical system of HIV and HTLV mono-infections taking into account diffusion, as well as latently infected cells in cellular transmission has been mathematically analyzed. However, no work has been conducted on HTLV/HIV co-infection dynamics taking both factors into consideration. In this paper, a partial differential equations (PDEs) model of HTLV/HIV dual infection was developed and analyzed, considering the cells' and viruses' spatial mobility. CD4⁺T cells are the primary target of both HTLV and HIV. For HIV, there are three routes of transmission: free-to-cell (FTC), latent infected-to-cell (ITC), and active ITC. In contrast, HTLV transmits horizontally through ITC contact and vertically through the mitosis of active HTLV-infected cells. In the beginning, the well-posedness of the model was investigated by proving the existence of global solutions and the boundedness. Eight threshold parameters that determine the existence and stability of the eight equilibria of the model were obtained. Lyapunov functions together with the Lyapunov–LaSalle asymptotic stability theorem were used to investigate the global stability of all equilibria. Finally, the theoretical results were verified utilizing numerical simulations.



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1. Introduction

Mathematical models and their analysis are efficient and important means of comprehending the dynamics of within-host viral infections. This contributes to a deeper understanding of viral disease structures caused by many viruses such as human immunodeficiency virus (HIV) and human T-lymphotropic virus (HTLV), as well as other viruses such as dengue virus (DENV), hepatitis C virus (HCV), hepatitis B virus (HBV), and, most recently, coronavirus (COVID-19). In fact, this may lead to an improvement in therapeutic interferences and control infectious diseases. HTLV and HIV are transmitted in similar ways from one infected person to another. Both viruses share in common the ability to infect specific immune cells, which are the CD4⁺T cells. HTLV does not cause acquired immunodeficiency syndrome (AIDS) as in the case of HIV; however, it causes fatal diseases such as HTLV-associated myelopathy/tropical spastic paraparesis (HAM/TSP) and adult T-cell leukemia (ATL).

In a groundbreaking study, Nowak and Bangham developed a fundamental model of HIV dynamics [1]. Since then, many works have been published that involved expanded

models of this model. Lai and Zou [2] have proposed a mathematical model that describes the dynamics of HIV-1 infection, where direct cell-to-cell transmission and virus-to-cell transmission are considered, as two forms of viral infection. Mojaver and Kheiri [3] developed a model of HIV infection that takes into account cell-to-cell transmission and antiretroviral therapies (HAART) that can be used to treat and control HIV infection. They reported that HAART uses the inhibitors of reverse transcriptase and protease to prevent HIV infection from becoming a fatal disease (AIDS) [3]. A multi-pathway and multi-delay HIV-1 infection model was studied by Adak and Bairagi [4]. It was found that the system exhibited different switching phenomena even without delays. A mathematical model of HIV dynamics was developed by Guo and Qiu [5] to analyze the effect of cytotoxic T lymphocyte (CTL) immune response on the infection dynamics. In this study, the potent therapy, latently infected cells, and cell-to-cell viral transmission were taken into account. Liu and Zhang [6] investigated the dynamics of a two-times delay differential equation model that investigates the dynamics of HIV infection with latency and considering a nonlinear type of HIV infection rate. Chen et al. [7] presented a complete study on the global dynamics of an HIV viral infection model with a saturated incidence rate of infection, as well as a wild-type and a drug-resistant strain of influenza virus.

In the above-mentioned works, all the mathematical models were based on ordinary or delay differential equations without considering the cells' and viruses' spatial mobility. In 2007, Wang and Wang [8] incorporated a spatial dependence into the model presented in [1]. Several considerations have been incorporated into the model presented by [8], and these include time delay, different forms of the incidence rate, and immune responses (see [9–11]).

It is important to note that the model introduced by [8] has neglected two crucial aspects:

- Viral latent reservoirs: A major impediment to eliminating HIV infection by antiretroviral therapy is the presence of latent HIV-infected cells. Cells that are latently infected carry the virions, but do not generate them until they are activated. There are many studies that have dealt with the development of HIV infection models with active and latent infected cells without taking spatial dependence into account, e.g., [12–15].
- Cellular transmission: Wang and Wang [8] considered only one mode of transmission of the infection occurring when the HIV particles infect the healthy $CD4^+T$ cells (FTC), but several studies have indicated that infected-to-cell (ITC) is another method of transmission, carried out through virological synapses between HIV-infected and healthy $CD4^+T$ cells [16]. Wang et al. [17] extended the work of [8] by including ITC transmission. Following that, Sun and Wang [18] incorporated time delay into the model presented in [17] and considered the incidence rate $f(U, H)$ in a general form.

Based on the work presented in [8], Xu et al. [19] included the ITC infection in their model. In this study, ITC infection arises from the contact between active infected cells and healthy cells. Recently, according to [20], latent and active HIV-infected cells are capable of infecting healthy $CD4^+T$ cells through the HIV ITC mechanism. Elaiw and AlShamrani [21] assumed nonlinear general forms of ITC and FTC transmissions in the HIV infection model. It was assumed that virus particles can move according to Fickian diffusion, whereas cells cannot in all of the above-mentioned models.

In several recent studies, the assumption was made that viruses, healthy cells, infected cells, and immune cells were capable of diffusing [22–28]. Gao and Wang [22] investigated a reaction–diffusion HIV-1 dynamics model with time delay and cell-to-cell dissemination. It was assumed in [23] that viruses, uninfected cells, infected cells, and humoral immune cells can diffuse. In [24], the authors examined the global asymptotic stability of a reaction–diffusion virus infection model with homogeneous environments, nonlinear incidence in heterogeneous environments, and humoral immunity. AlAgha and Elaiw [25] presented a study of the global stability of an HIV-1 model with humoral immune response and heterogeneous diffusion. In [26], Elaiw and AlAgha analyzed the dynamics of a system with discrete time delays and three types of infected cells: latently, short-lived productively, and long-lived productively infected cells. The models in [25,26] contain some parameters that

measure the efficiency of highly active antiretroviral therapies (HAARTs). Wang et al. [27] proposed a diffusive viral infection model incorporating cell-to-cell infection mode, nonlinear incidences, incubation period, and spatial heterogeneity. Ren et al. [28] discussed the impact of cell-to-cell transmission and the mobility of viruses and cells on HIV-1 dynamics. The following model that considers the mobility of HIV particles and cells was presented by Wang et al. [27]:

$$\begin{cases} \frac{\partial U(s,t)}{\partial t} = d_U \Delta U(s,t) + \rho - \zeta U(s,t) - U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) + \omega_3 I(s,t)], \\ \frac{\partial L(s,t)}{\partial t} = d_L \Delta L(s,t) + U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) + \omega_3 I(s,t)] - (\beta + \eta)L(s,t), \\ \frac{\partial I(s,t)}{\partial t} = d_I \Delta I(s,t) + \beta L(s,t) - \alpha I(s,t), \\ \frac{\partial H(s,t)}{\partial t} = d_H \Delta H(s,t) + \varpi I(s,t) - \theta H(s,t). \end{cases}$$

In this model, at position $s = (s_1, s_2, \dots, s_k)$ and time t , the densities of healthy CD4⁺T cells, latent infected cells, active infected cells, and free virus particles are represented by $U(s,t)$, $L(s,t)$, $I(s,t)$, and $H(s,t)$, respectively. d_U , d_L , d_I , and d_H are the diffusion coefficients of the corresponding compartments, and Δ is the Laplacian operator. Cells that are healthy are created at a rate ρ . Healthy cells are infected by the viral particles through FTC transmission at a rate $\omega_1 UH$. The terms $\omega_2 UL$ and $\omega_3 UI$ represent the ITC incidence rates that occur when healthy CD4⁺T cells come into contact with latent or active infected cells, respectively. Cells that have been latently infected become active at a rate βL . Viruses are produced by active infected cells at a rate of ϖI . The rates of death for healthy cells, latent infected cells, active infected cells, and viral particles are ζU , ηL , αI , and θH , respectively.

Additionally, in several studies, the dynamics of HTLV mono-infections have been modeled and analyzed [29–36]. Vargas-De-Leon [29] provided a complete classification of the global dynamics for an HTLV mono-infection model taking the latently infected cells into consideration. Lim and Maini [30] formulated a model for HTLV-I dynamics under the consideration of CTL immunity and mitotic division of active HTLV-infected cells. Pan et al. [31] proposed a model to describe the dynamics of HTLV infection with CTL immunity and time delays. Wang et al. [32] developed an HTLV-I infection model with nonlinear lytic and nonlytic CTL immunity, nonlinear incidence rate, distributed delay, and immune impairment. Wang et al. [33] studied a model of HTLV-I infection with two time delays: an intracellular delay and a CTL immune response delay. Refs. [34,35] discussed HTLV infection with the presence of CTL immunity, as well as the mitotic division of the active infected cells. Except for Wang and Ma [36], all of these HTLV dynamics models neglected the diffusion of viruses and cells. In [36], CTL immunity and the mitotic division of active infected cells were included in a diffusive HTLV infection model.

In the past decade, there has been considerable reporting on HTLV and HIV co-infections. Infection by both viruses concurrently affects pathogenic development and associated chronic disease outcomes [37]. There has been documentation of HTLV/HIV co-infection in certain areas where both retroviruses appear endemic [38] and in individuals who are of a certain ethnicity as well. In highly endemic regions such as South America and Sub-Saharan Africa, co-infections with HIV and HTLV are common. Further, the rate of concurrent HTLV and HIV infections is high in areas where people swap needles and participate in unprotected sexual relationships. According to statistics from some parts of Brazil, 16% of HIV patients in some areas have co-infection [39].

According to a recent study, the results showed that HIV-infected individuals are more likely to be co-infected with HTLV 100- to 500-times more often than people who are not infected [40]. Additionally, several studies have shown that HTLV-infected individuals have a higher likelihood of concomitant HIV infection, and vice versa, as compared to the general population who is infection-free [38]. HTLV and HIV affect primarily CD4⁺T cells and cause immune dysfunction, but their etiologies and clinical outcomes are also in conflict [41]. According to many researchers, HIV-infected patients who possibly have concurrent HTLV infection are at risk of developing AIDS. While the progression of HTLV

in co-infected individuals is modified by HIV, resulting in diseases such as HAM\TSP and ATL [38,40].

Although many mathematical models and analyses have been developed for HTLV and HIV mono-infections, very few works have considered the dynamics of co-infection with HTLV and HIV. There are a few exceptions, namely the very recent papers in [42–45].

As a consequence of the above, co-infection of HTLV/HIV; involving both latent and active infected cells sharing ITC infection, as well as the diffusion of viruses and cells; has never been mathematically studied. Therefore, in light of the works of [44,45], this study aims to develop and analyze an HTLV/HIV co-infection model taking into account the following considerations:

- (C1) The hosts of both HIV and HTLV are healthy CD4⁺T cells;
- (C2) The presence of latently infected HIV and HTLV cells;
- (C3) Both HTLV and HIV have a specific bilinear CTL immune response;
- (C4) Several factors can lead to CD4⁺T cells becoming infected with HIV, including free HIV particles, latent HIV-infected cells, and active HIV-infected cells;
- (C5) HTLV has two routes of transmission: (i) horizontally through the straight ITC contact over the virological synapse and (ii) vertically where the active HTLV-infected cells can transmit HTLV via mitotic division;
- (C6) All types of cells and viruses diffuse spatially.

The novelty and advantages of the developed model are generalization and improvement of many mathematical models existing in the literature describing HTLV/HIV co-infection by considering three routes of transmission and other biological factors.

The well-posedness of the model has been verified by proving the non-negativity and the boundedness of the model’s solutions. Our analysis yielded a number of threshold parameters that set the presence of the equilibria and their stability. We formulated Lyapunov functions and used the Lyapunov–LaSalle asymptotic stability theorem (L-LAST) to demonstrate the global stability of all equilibria. To assert our analytical results, we supply numerical simulations of the model. Due to the possibility of an individual having two or more infections at the same time, our model may be useful for studying co-infections such as COVID-19 with influenza and HIV with HCV or HBV. Our proposed model and its mathematical analysis will assist clinicians in estimating when to initiate treatment in patients who have co-infections with more than one virus.

2. Model Formulation

We propose the following partial differential equations model based on the statements (C1)–(C6) mentioned in Section 1:

$$\left\{ \begin{array}{l}
 \frac{\partial U(s,t)}{\partial t} = d_U \Delta U(s,t) + \rho - \zeta U(s,t) - U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) + \omega_3 I(s,t) + \omega_4 E(s,t)], \\
 \frac{\partial L(s,t)}{\partial t} = d_L \Delta L(s,t) + U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) + \omega_3 I(s,t)] - (\beta + \eta)L(s,t), \\
 \frac{\partial I(s,t)}{\partial t} = d_I \Delta I(s,t) + \beta L(s,t) - \alpha I(s,t) - \varkappa_1 Z^I(s,t)I(s,t), \\
 \frac{\partial P(s,t)}{\partial t} = d_P \Delta P(s,t) + \varphi \omega_4 U(s,t)E(s,t) + \varepsilon bE(s,t) - (\theta + b_1)P(s,t), \\
 \frac{\partial E(s,t)}{\partial t} = d_E \Delta E(s,t) + \theta P(s,t) + (1 - \varepsilon)bE(s,t) - b_2 E(s,t) - \varkappa_2 Z^E(s,t)E(s,t), \\
 \frac{\partial H(s,t)}{\partial t} = d_H \Delta H(s,t) + \omega I(s,t) - \vartheta H(s,t), \\
 \frac{\partial Z^I(s,t)}{\partial t} = d_{Z^I} \Delta Z^I(s,t) + v_1 Z^I(s,t)I(s,t) - c_1 Z^I(s,t), \\
 \frac{\partial Z^E(s,t)}{\partial t} = d_{Z^E} \Delta Z^E(s,t) + v_2 Z^E(s,t)E(s,t) - c_2 Z^E(s,t),
 \end{array} \right. \quad (1)$$

where $t \in [0, \infty)$ and $s \in \Omega$, with boundary conditions:

$$\frac{\partial U}{\partial \vec{\rho}} = \frac{\partial L}{\partial \vec{\rho}} = \frac{\partial I}{\partial \vec{\rho}} = \frac{\partial P}{\partial \vec{\rho}} = \frac{\partial E}{\partial \vec{\rho}} = \frac{\partial H}{\partial \vec{\rho}} = \frac{\partial Z^I}{\partial \vec{\rho}} = \frac{\partial Z^E}{\partial \vec{\rho}} = 0, \quad t > 0, \quad s \in \partial\Omega, \quad (2)$$

and initial conditions:

$$\begin{aligned} U(s,0) &= Y_1(s), \quad L(s,0) = Y_2(s), \quad I(s,0) = Y_3(s), \quad P(s,0) = Y_4(s), \quad E(s,0) = Y_5(s), \\ H(s,0) &= Y_6(s), \quad Z^I(s,0) = Y_7(s), \quad Z^E(s,0) = Y_8(s), \quad s \in \bar{\Omega}. \end{aligned} \quad (3)$$

The following is a description of Model (1) with Conditions (2) and (3): At position $s \in \Omega$ and time $t > 0$, the compartments $P(s, t)$ and $E(s, t)$ represent the density of latent and active HTLV-infected cells. $Z^I(s, t)$ and $Z^E(s, t)$ are the CTLs specific for HIV and for HTLV, respectively. Through ITC contact, healthy $CD4^+T$ cells become infected with HTLV at a rate ω_4UE . The ratio $\varphi \in (0, 1)$ identifies the possibility that HTLV infections will be latent. εbE , $\varepsilon \in (0, 1)$ denotes the rate at which active HTLV-infected cells are passed to become latently infected and escape the immune system [35]. The mortality rates of latent and active HTLV-infected cells are b_1P and b_2E , respectively. θP is the rate at which latent HTLV-infected cells are activated. HIV-infected cells and HTLV-infected cells die, respectively, at rates \varkappa_1Z^II , \varkappa_2Z^EE , as a result of their specific immunity. CTLs particular to HIV and HTLV expand at distinct rates v_1Z^II , v_2Z^EE , and they decay at rates c_1Z^I , c_2Z^E , respectively. The diffusion coefficients of the compartments P , E , Z^I , Z^E are d_P , d_E , d_{Z^I} , and d_{Z^E} . As illustrated in Section 1, all remaining parameters have the same name and explanation.

The boundary conditions (2) are the homogeneous Neumann boundary conditions, which can provide a natural spreading limit and ensure that viruses and cells are unable to escape through the isolated boundaries [46]. The open domain $\Omega \subset \mathbb{R}^k$, $k \geq 1$ is connected and bounded with a smooth boundary $\partial\Omega$, and the unit vector $\vec{\rho}$ is the outward normal vector on $\partial\Omega$. The functions $Y_i(s)$, $i = 1, \dots, 8$, are non-negative and continuous.

We will assume that $b < \min\{\zeta, b_1, b_2\}$ [30]. It follows that $(1 - \varepsilon)b < b_2$ and then

$$b_2 - (1 - \varepsilon)b > 0.$$

Let $a = b_2 - (1 - \varepsilon)b$ and $w = \varepsilon b$. Therefore, Model (1) can be written as

$$\left\{ \begin{aligned} \frac{\partial U(s,t)}{\partial t} &= d_U \Delta U(s,t) + \varrho - \zeta U(s,t) - U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) \\ &\quad + \omega_3 I(s,t) + \omega_4 E(s,t)], \\ \frac{\partial L(s,t)}{\partial t} &= d_L \Delta L(s,t) + U(s,t)[\omega_1 H(s,t) + \omega_2 L(s,t) + \omega_3 I(s,t)] \\ &\quad - (\beta + \eta)L(s,t), \\ \frac{\partial I(s,t)}{\partial t} &= d_I \Delta I(s,t) + \beta L(s,t) - \alpha I(s,t) - \varkappa_1 Z^I(s,t)I(s,t), \\ \frac{\partial P(s,t)}{\partial t} &= d_P \Delta P(s,t) + \varphi \omega_4 U(s,t)E(s,t) + wE(s,t) \\ &\quad - (\theta + b_1)P(s,t), \\ \frac{\partial E(s,t)}{\partial t} &= d_E \Delta E(s,t) + \theta P(s,t) - aE(s,t) - \varkappa_2 Z^E(s,t)E(s,t), \\ \frac{\partial H(s,t)}{\partial t} &= d_H \Delta H(s,t) + \omega I(s,t) - \vartheta H(s,t), \\ \frac{\partial Z^I(s,t)}{\partial t} &= d_{Z^I} \Delta Z^I(s,t) + v_1 Z^I(s,t)I(s,t) - c_1 Z^I(s,t), \\ \frac{\partial Z^E(s,t)}{\partial t} &= d_{Z^E} \Delta Z^E(s,t) + v_2 Z^E(s,t)E(s,t) - c_2 Z^E(s,t). \end{aligned} \right. \quad (4)$$

3. Properties of Solutions

Proposition 1. *Suppose that $d_U = d_L = d_I = d_P = d_E = d_H = d_{Z^I} = d_{Z^E} = \vec{d}$. Then, there exists a unique solution $Sol(s, t) = (U(s, t), L(s, t), I(s, t), P(s, t), E(s, t), H(s, t), Z^I(s, t), Z^E(s, t))$ for System (4) with the boundary and initial conditions (2)–(3). Moreover, this solution remains non-negative and bounded on $\bar{\Omega} \times [0, +\infty)$.*

Proof. Define the norm $\|\lambda\|_{\mathcal{Y}} = \sup_{s \in \bar{\Omega}} |\lambda(s)|$, where the set $\mathcal{Y} = BUC(\bar{\Omega}, \mathbb{R}^8)$ comprises all uniformly bounded and continuous functions from $\bar{\Omega}$ to \mathbb{R}^8 . Consider a positive cone $\mathcal{Y}_+ = BUC(\bar{\Omega}, \mathbb{R}_+^8) \subset \mathcal{Y}$ that leads to partial order on \mathcal{Y} . As a result, the space $(\mathcal{Y}, \|\cdot\|_{\mathcal{Y}})$ is a Banach lattice [47,48].

Let $\Phi = (\Phi_1, \Phi_2, \Phi_3, \Phi_4, \Phi_5, \Phi_6, \Phi_7, \Phi_8)^{tr} : \mathcal{Y}_+ \rightarrow \mathcal{Y}$ with any initial data $Y = (Y_1, Y_2, Y_3, Y_4, Y_5, Y_6, Y_7, Y_8)^{tr} \in \mathcal{Y}_+$, given by

$$\begin{aligned} \Phi_1(Y)(s) &= \varrho - \zeta Y_1(s) - Y_1(s)[\omega_1 Y_6(s) + \omega_2 Y_2(s) + \omega_3 Y_3(s) + \omega_4 Y_5(s)], \\ \Phi_2(Y)(s) &= Y_1(s)[\omega_1 Y_6(s) + \omega_2 Y_2(s) + \omega_3 Y_3(s)] - (\beta + \eta) Y_2(s), \\ \Phi_3(Y)(s) &= \beta Y_2(s) - \alpha Y_3(s) - \varkappa_1 Y_7(s) Y_3(s), \\ \Phi_4(Y)(s) &= \varphi \omega_4 Y_1(s) Y_5(s) + w Y_5(s) - (\theta + b_1) Y_4(s), \\ \Phi_5(Y)(s) &= \theta Y_4(s) - a Y_5(s) - \varkappa_2 Y_8(s) Y_5(s), \\ \Phi_6(Y)(s) &= \omega Y_3(s) - \vartheta Y_6(s), \\ \Phi_7(Y)(s) &= v_1 Y_7(s) Y_3(s) - c_1 Y_7(s), \\ \Phi_8(Y)(s) &= v_2 Y_8(s) Y_5(s) - c_2 Y_8(s). \end{aligned}$$

Clearly, Φ is locally Lipschitz on \mathcal{Y}_+ . It is possible to rewrite System (4) with the boundary conditions (2) and initial conditions (3) as the following abstract functional differential equation:

$$\begin{cases} \frac{d\vec{\mathcal{G}}}{dt} = \Theta \vec{\mathcal{G}} + \Phi(\vec{\mathcal{G}}), & t > 0, \\ \vec{\mathcal{G}}(0) = Y \in \mathcal{Y}_+, \end{cases}$$

where $\vec{\mathcal{G}} = (U, L, I, P, E, H, Z^I, Z^E)^{tr}$ and $\Theta \vec{\mathcal{G}} = (d_U \Delta U, d_L \Delta L, d_I \Delta I, d_P \Delta P, d_E \Delta E, d_H \Delta H, d_{Z^I} \Delta Z^I, d_{Z^E} \Delta Z^E)^{tr}$. In this case,

$$\lim_{h \rightarrow 0^+} \frac{1}{h} \text{dist}(Y(0) + h\Phi(Y), \mathcal{Y}_+) = 0, \text{ for all } Y \in \mathcal{Y}_+.$$

According to [47–49], System (4) with (2)–(3) has a unique non-negative mild solution $Sol(s, t)$ defined on $\bar{\Omega} \times [0, \mathcal{L}_k)$ for any $Y \in \mathcal{Y}_+$, where the maximum time interval during which $Sol(s, t)$ exists is $[0, \mathcal{L}_k)$. Additionally, $Sol(s, t)$ is a classical solution.

In order to establish that solutions are bounded, let

$$G(s, t) = U(s, t) + L(s, t) + I(s, t) + \frac{1}{\varphi} [P(s, t) + E(s, t)] + \frac{\alpha}{2\omega} H(s, t) + \frac{\varkappa_1}{v_1} Z^I(s, t) + \frac{\varkappa_2}{\varphi v_2} Z^E(s, t).$$

Since $d_U = d_L = d_I = d_P = d_E = d_H = d_{Z^I} = d_{Z^E} = \tilde{d}$, then using System (4), we obtain

$$\begin{aligned} \frac{\partial G(s, t)}{\partial t} - \tilde{d} \Delta G(s, t) &= \varrho - \zeta U(s, t) - \eta L(s, t) - \frac{\alpha}{2} I(s, t) - \frac{b_1}{\varphi} P(s, t) \\ &\quad - \frac{a - w}{\varphi} E(s, t) - \frac{\alpha \vartheta}{2\omega} H(s, t) - \frac{\varkappa_1 c_1}{v_1} Z^I(s, t) - \frac{\varkappa_2 c_2}{\varphi v_2} Z^E(s, t). \end{aligned}$$

We have $a - w = b_2 - b > 0$. Hence,

$$\begin{aligned} \frac{\partial G(s,t)}{\partial t} - \tilde{d}\Delta G(s,t) &= \varrho - \zeta U(s,t) - \eta L(s,t) - \frac{\alpha}{2}I(s,t) - \frac{b_1}{\varphi}P(s,t) \\ &\quad - \frac{b_2 - b}{\varphi}E(s,t) - \frac{\alpha\vartheta}{2\omega}H(s,t) - \frac{\varkappa_1 c_1}{v_1}Z^I(s,t) - \frac{\varkappa_2 c_2}{\varphi v_2}Z^E(s,t) \\ &\leq \varrho - \phi \left[U(s,t) + L(s,t) + I(s,t) + \frac{1}{\varphi}\{P(s,t) + E(s,t)\} \right. \\ &\quad \left. + \frac{\alpha}{2\omega}H(s,t) + \frac{\varkappa_1}{v_1}Z^I(s,t) + \frac{\varkappa_2}{\varphi v_2}Z^E(s,t) \right] = \varrho - \phi G(s,t), \end{aligned}$$

where $\phi = \min\{\zeta, \eta, \frac{\alpha}{2}, b_1, b_2 - b, \vartheta, c_1, c_2\}$. Therefore, $G(s, t)$ satisfies the following system:

$$\begin{cases} \frac{\partial G(s,t)}{\partial t} - \tilde{d}\Delta G(s,t) \leq \varrho - \phi G(s,t), \\ G(s,0) = Y_1(s) + Y_2(s) + Y_3(s) + \frac{1}{\varphi}[Y_4(s) + Y_5(s)] + \frac{\alpha}{2\omega}Y_6(s) + \frac{\varkappa_1}{v_1}Y_7(s) + \frac{\varkappa_2}{\varphi v_2}Y_8(s) \geq 0, \\ \frac{\partial G}{\partial \rho} = 0. \end{cases}$$

Assume $\tilde{G}(t)$ is a solution of the ordinary differential equation system given below:

$$\begin{cases} \frac{d\tilde{G}(t)}{dt} = \varrho - \phi\tilde{G}(t), \\ \tilde{G}(0) = \max_{s \in \tilde{\Omega}} G(s,0). \end{cases}$$

Accordingly, this gives $\tilde{G}(t) \leq \max\left\{\frac{\varrho}{\phi}, \max_{s \in \tilde{\Omega}} G(s,0)\right\}$. In accordance with the comparison principle (see [50]), we obtain $G(s, t) \leq \tilde{G}(t)$. Thus,

$$G(s, t) \leq \max\left\{\frac{\varrho}{\phi}, \max_{s \in \tilde{\Omega}} G(s,0)\right\},$$

and this implies that $U(s, t), L(s, t), I(s, t), P(s, t), E(s, t), H(s, t), Z^I(s, t)$, and $Z^E(s, t)$ are bounded on $\tilde{\Omega} \times [0, \mathcal{L}_k)$. Using the standard theory for semi-linear parabolic systems, we concluded that $\mathcal{L}_k = +\infty$ [51]. As a result, the solution $Sol(s, t)$ is defined for all $s \in \Omega, t > 0$, unique, non-negative, and bounded. \square

4. Equilibrium Analysis

This section is devoted to the study of computing the model’s threshold parameters and equilibria. Model (4) satisfies the following equations:

$$\begin{aligned} 0 &= \varrho - \zeta U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE, \\ 0 &= \omega_1 UH + \omega_2 UL + \omega_3 UI - (\beta + \eta)L, \\ 0 &= \beta L - \alpha I - \varkappa_1 Z^I, \\ 0 &= \varphi\omega_4 UE + wE - (\theta + b_1)P, \\ 0 &= \theta P - aE - \varkappa_2 Z^E, \\ 0 &= \omega I - \vartheta H, \\ 0 &= (v_1 I - c_1)Z^I, \\ 0 &= (v_2 E - c_2)Z^E. \end{aligned}$$

The results of the calculations show that there are eight equilibrium points for Model (4):

1. Infection-free equilibrium, $\check{S}_0 = (U_0, 0, 0, 0, 0, 0, 0, 0)$ and $U_0 = \varrho/\zeta$. Both HIV and HTLV are not present in this case.

2. Persistent HIV mono-infection equilibrium accompanied by an inefficient immune response, $\check{S}_1 = (U_1, L_1, I_1, 0, 0, H_1, 0, 0)$, with components given by

$$U_1 = \frac{U_0}{\mathcal{R}_1}, \quad L_1 = \frac{\alpha\zeta\vartheta}{\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)}(\mathcal{R}_1 - 1),$$

$$I_1 = \frac{\zeta\vartheta\beta}{\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)}(\mathcal{R}_1 - 1), \quad H_1 = \frac{\zeta\omega\beta}{\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)}(\mathcal{R}_1 - 1).$$

The parameter \mathcal{R}_1 defines the basic HIV mono-infection reproductive number for Model (4), which is given as

$$\mathcal{R}_1 = \frac{U_0[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]}{\alpha\vartheta(\beta + \eta)} = \frac{U_0\beta\omega\omega_1}{\alpha\vartheta(\beta + \eta)} + \frac{U_0\omega_2}{\beta + \eta} + \frac{U_0\beta\omega_3}{\alpha(\beta + \eta)}.$$

\mathcal{R}_1 is responsible for determining whether or not a persistent HIV mono-infection is possible. In the meantime, the immune system is unable to respond effectively. In addition, \check{S}_1 exists if $\mathcal{R}_1 > 1$.

3. Persistent HTLV mono-infection equilibrium accompanied by an inefficient immune response, $\check{S}_2 = (U_2, 0, 0, P_2, E_2, 0, 0, 0)$, with components given by

$$U_2 = \frac{U_0}{\mathcal{R}_2}, \quad P_2 = \frac{\zeta a}{\omega_4\vartheta}(\mathcal{R}_2 - 1), \quad E_2 = \frac{\zeta}{\omega_4}(\mathcal{R}_2 - 1).$$

The parameter \mathcal{R}_2 specifies the basic HTLV mono-infection reproductive number for Model (4) and is given as

$$\mathcal{R}_2 = \frac{\varphi\omega_4\vartheta U_0}{(a - w)\vartheta + ab_1}.$$

\mathcal{R}_2 is responsible for determining whether or not a persistent HTLV mono-infection is possible. In the meantime, the immune system is unable to work effectively. Further, \check{S}_2 exists if $\mathcal{R}_2 > 1$.

4. Persistent HIV mono-infection equilibrium accompanied only by efficient HIV-specific CTL, $\check{S}_3 = (U_3, L_3, I_3, 0, 0, H_3, Z_3^I, 0)$, with components given by

$$U_3 = \frac{\varrho\vartheta v_1}{\omega c_1\omega_1 + \vartheta(c_1\omega_3 + \zeta v_1 + v_1\omega_2 L_3)}, \quad I_3 = \frac{c_1}{v_1}, \quad H_3 = \frac{\omega}{\vartheta} I_3 = \frac{\omega c_1}{\vartheta v_1}, \quad Z_3^I = \frac{\alpha}{\varkappa_1}(\mathcal{R}_3 - 1),$$

and

$$\mathcal{R}_3 = \frac{\beta v_1 L_3}{\alpha c_1},$$

represents the HIV-specific CTL immunity reproductive number for HIV mono-infection. In the case of HIV mono-infection, \mathcal{R}_3 indicates whether or not HIV-specific CTL immunity is efficient in the case of HIV mono-infection where the HTLV infection is not present. The component L_3 satisfies the quadratic equation:

$$A_1 L_3^2 + B_1 L_3 + C_1 = 0, \tag{5}$$

where

$$A_1 = \vartheta\omega_2 v_1(\beta + \eta),$$

$$B_1 = c_1(\omega\omega_1 + \vartheta\omega_3)(\beta + \eta) + \vartheta v_1[\zeta(\beta + \eta) - \omega_2\varrho],$$

$$C_1 = -c_1\varrho(\omega\omega_1 + \vartheta\omega_3). \tag{6}$$

Since $A_1 > 0$ and $C_1 < 0$, then $B_1^2 - 4A_1C_1 > 0$, and the positive real root of Equation (5) is calculated as follows:

$$L_3 = \frac{-B_1 + \sqrt{B_1^2 - 4A_1C_1}}{2A_1}.$$

\check{S}_3 exists if $\mathcal{R}_3 > 1$.

5. Persistent HTLV mono-infection equilibrium accompanied only by efficient HTLV-specific CTL, $\check{S}_4 = (U_4, 0, 0, P_4, E_4, 0, 0, Z_4^E)$, with components given by

$$U_4 = \frac{v_2\varrho}{c_2\omega_4 + \zeta v_2}, \quad P_4 = \frac{c_2[w(c_2\omega_4 + \zeta v_2) + \omega_4\varrho\varphi v_2]}{v_2(\theta + b_1)(c_2\omega_4 + \zeta v_2)},$$

$$E_4 = \frac{c_2}{v_2}, \quad Z_4^E = \frac{(a - w)\theta + ab_1}{\varkappa_2(\theta + b_1)}(\mathcal{R}_4 - 1).$$

The term \mathcal{R}_4 is introduced as the HTLV-specific CTL immunity reproductive number for HTLV mono-infection and is defined as

$$\mathcal{R}_4 = \frac{v_2\varrho\varphi\omega_4\theta}{(c_2\omega_4 + \zeta v_2)[(a - w)\theta + ab_1]}.$$

In fact, \mathcal{R}_4 indicates whether or not HTLV-specific CTL immunity is efficient in the case HTLV mono-infection where the HIV infection is not present. On the other hand, \check{S}_4 exists if $\mathcal{R}_4 > 1$.

6. Persistent HTLV/HIV co-infection equilibrium accompanied only by efficient HIV-specific CTL, $\check{S}_5 = (U_5, L_5, I_5, P_5, E_5, H_5, Z_5^I, 0)$, with components given by

$$U_5 = \frac{(a - w)\theta + ab_1}{\varphi\omega_4\theta} = U_2, \quad L_5 = \frac{c_1(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1\omega_2(\hat{\mathcal{R}}_5 - 1)},$$

$$I_5 = \frac{c_1}{v_1} = I_3, \quad H_5 = \frac{\omega c_1}{\vartheta v_1} = H_3,$$

$$P_5 = \frac{a[c_1\omega_4\theta\varphi(\omega\omega_1 + \vartheta\omega_3)(\beta + \eta) + \zeta\vartheta v_1\omega_2\{(a - w)\theta + ab_1\}(\hat{\mathcal{R}}_5 - 1)]}{\vartheta v_1\omega_4\theta\omega_2[(a - w)\theta + ab_1]} \left(\frac{\mathcal{R}_5 - 1}{\hat{\mathcal{R}}_5 - 1} \right),$$

$$E_5 = \frac{c_1\varphi\theta\omega_4(\omega\omega_1 + \vartheta\omega_3)(\beta + \eta) + \zeta\vartheta v_1\omega_2[(a - w)\theta + ab_1](\hat{\mathcal{R}}_5 - 1)}{\vartheta v_1\omega_4\omega_2[(a - w)\theta + ab_1]} \left(\frac{\mathcal{R}_5 - 1}{\hat{\mathcal{R}}_5 - 1} \right),$$

$$Z_5^I = \frac{\alpha\omega_4\varphi\theta(\beta + \eta)}{\varkappa_1\omega_2[(a - w)\theta + ab_1](\hat{\mathcal{R}}_5 - 1)}(\mathcal{R}_1/\mathcal{R}_2 - 1).$$

Here, \mathcal{R}_5 is the HTLV infection reproductive number when the HIV infection exists, and

$$\mathcal{R}_5 = \frac{\varrho\varphi\theta\vartheta v_1\omega_4\omega_2(\hat{\mathcal{R}}_5 - 1)}{c_1\varphi\theta\omega_4(\omega\omega_1 + \vartheta\omega_3)(\beta + \eta) + \zeta\vartheta v_1\omega_2[(a - w)\theta + ab_1](\hat{\mathcal{R}}_5 - 1)},$$

where

$$\hat{\mathcal{R}}_5 = \frac{\omega_4\varphi\theta(\beta + \eta)}{\omega_2[(a - w)\theta + ab_1]}.$$

In fact, \mathcal{R}_5 determines whether or not HIV-infected individuals can further be dually infected with HTLV.

7. Persistent HTLV/HIV co-infection equilibrium accompanied only by efficient HTLV-specific CTL, $\check{S}_6 = (U_6, L_6, I_6, P_6, E_6, H_6, 0, Z_6^E)$, with components given by

$$U_6 = \frac{\alpha\vartheta(\beta + \eta)}{\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)} = U_1, \quad L_6 = \frac{\alpha\vartheta(c_2\omega_4 + \zeta v_2)}{v_2[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]}(\mathcal{R}_6 - 1),$$

$$I_6 = \frac{\beta\vartheta(c_2\omega_4 + \zeta v_2)}{v_2[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]}(\mathcal{R}_6 - 1),$$

$$\begin{aligned}
 P_6 &= \frac{c_2[w\{\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)\} + \alpha\vartheta\omega_4\varphi(\beta + \eta)]}{v_2(\theta + b_1)[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]}, \\
 E_6 &= \frac{c_2}{v_2} = E_4, \quad H_6 = \frac{\omega\beta(c_2\omega_4 + \zeta v_2)}{v_2[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]} (\mathcal{R}_6 - 1), \\
 Z_6^E &= \frac{(a - w)\theta + ab_1}{\varkappa_2(\theta + b_1)} (\mathcal{R}_2/\mathcal{R}_1 - 1).
 \end{aligned}$$

\mathcal{R}_6 represents the HIV infection reproductive number when HTLV infection exists, and

$$\mathcal{R}_6 = \frac{\varrho v_2[\alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3)]}{\alpha\vartheta(\beta + \eta)(c_2\omega_4 + \zeta v_2)}.$$

The parameter \mathcal{R}_6 indicates whether or not an HTLV-infected individual can further be dually infected with HIV.

8. Persistent HTLV/HIV co-infection equilibrium accompanied by efficient HIV-specific CTL and HTLV-specific CTL, $\check{S}_7 = (U_7, L_7, I_7, P_7, E_7, H_7, Z_7^I, Z_7^E)$, with components given by

$$\begin{aligned}
 U_7 &= \frac{\vartheta v_1 v_2 \varrho}{c_1 v_2 (\omega\omega_1 + \vartheta\omega_3) + \vartheta v_1 (c_2\omega_4 + \zeta v_2 + \omega_2 v_2 L_7)}, \\
 P_7 &= \frac{c_2 \vartheta \omega_4 \varrho v_1 v_2 \varphi + c_2 w [c_1 v_2 (\omega\omega_1 + \vartheta\omega_3) + \vartheta v_1 (c_2\omega_4 + \zeta v_2 + \omega_2 v_2 L_7)]}{v_2 (\theta + b_1) [c_1 v_2 (\omega\omega_1 + \vartheta\omega_3) + \vartheta v_1 (c_2\omega_4 + \zeta v_2 + \omega_2 v_2 L_7)]}, \\
 I_7 &= \frac{c_1}{v_1} = I_3 = I_5, \quad E_7 = \frac{c_2}{v_2} = E_4 = E_6, \quad H_7 = \frac{\omega c_1}{\vartheta v_1} = H_3 = H_5, \\
 Z_7^I &= \frac{\alpha}{\varkappa_1} (\mathcal{R}_7 - 1), \quad Z_7^E = \frac{(a - w)\theta + ab_1}{\varkappa_2(\theta + b_1)} (\mathcal{R}_8 - 1),
 \end{aligned}$$

and

$$\begin{aligned}
 \mathcal{R}_7 &= \frac{\beta v_1 L_7}{\alpha c_1}, \\
 \mathcal{R}_8 &= \frac{\vartheta \omega_4 \varrho v_1 v_2 \varphi \theta}{((a - w)\theta + ab_1) [c_1 v_2 (\omega\omega_1 + \vartheta\omega_3) + \vartheta v_1 (c_2\omega_4 + \zeta v_2 + \omega_2 v_2 L_7)]}.
 \end{aligned}$$

The parameters \mathcal{R}_7 and \mathcal{R}_8 represent, respectively, the competing HIV-specific CTL and HTLV-specific CTL reproductive numbers in the case of HTLV/HIV co-infection. Here, L_7 satisfies the equation:

$$A_2 L_7^2 + B_2 L_7 + C_2 = 0, \tag{7}$$

where

$$\begin{aligned}
 A_2 &= \vartheta \omega_2 v_1 v_2 (\beta + \eta), \\
 B_2 &= c_2 \vartheta \omega_4 v_1 (\beta + \eta) + c_1 v_2 (\omega\omega_1 + \vartheta\omega_3) (\beta + \eta) + \zeta \vartheta v_1 v_2 (\beta + \eta) - \vartheta \omega_2 \varrho v_1 v_2, \\
 C_2 &= -c_1 \varrho v_2 (\omega\omega_1 + \vartheta\omega_3).
 \end{aligned} \tag{8}$$

Since $A_2 > 0$ and $C_2 < 0$, then $B_2^2 - 4A_2C_2 > 0$, and the positive real root of Equation (7) is calculated as follows:

$$L_7 = \frac{-B_2 + \sqrt{B_2^2 - 4A_2C_2}}{2A_2}.$$

It is obvious that if $\mathcal{R}_7 > 1$ and $\mathcal{R}_8 > 1$, then \check{S}_7 exists.

5. Global Properties

This section is devoted to the implementation of a Lyapunov method to check the global stability of the equilibria of Model (4). To do so, we constructed Lyapunov functions as described in the works [52,53]. We further considered the following concepts:

- According to the arithmetic–geometric mean inequality:

$$\frac{1}{m} \sum_{i=1}^m F_i \geq \sqrt[m]{\prod_{i=1}^m F_i}, \quad F_i \geq 0, \quad i = 1, 2, \dots$$

we have

$$\frac{U_i}{U} + \frac{U I L_i}{U_i I_i L} + \frac{L I_i}{L_i I} \geq 3, \tag{9}$$

$$\frac{U_i}{U} + \frac{H U L_i}{H_i U_i L} + \frac{L I_i}{L_i I} + \frac{I H_i}{I_i H} \geq 4, \tag{10}$$

$$\frac{U_i}{U} + \frac{U E P_i}{U_i E_i P} + \frac{P E_i}{P_i E} \geq 3. \tag{11}$$

- Consider a function $\Psi_j(U, L, I, P, E, H, Z^I, Z^E)$ in which

$$\hat{\Psi}_j(t) = \int_{\Omega} \Psi_j(s, t) \, ds, \quad j = 0, 1, 2, \dots, 7.$$

- Denote

$$\Gamma_j = \left\{ (U, L, I, P, E, H, Z^I, Z^E) : \frac{d\hat{\Psi}_j}{dt} = 0 \right\}, \quad j = 0, 1, 2, \dots, 7,$$

and let Γ'_j represent the largest invariant subset of Γ_j .

- Define a function $F(x) = x - 1 - \ln x$. We have that $F(x) \geq 0$ for all $x > 0$ and $F(x) = 0$ if and only if $x = 1$.
- Based on the condition (2) and the divergence theorem, we derive

$$\begin{aligned} 0 &= \int_{\partial\Omega} \nabla S \cdot \vec{\rho} \, ds = \int_{\Omega} \operatorname{div}(\nabla S) \, ds = \int_{\Omega} \Delta S \, ds, \\ 0 &= \int_{\partial\Omega} \frac{1}{S} \nabla S \cdot \vec{\rho} \, ds = \int_{\Omega} \operatorname{div}\left(\frac{1}{S} \nabla S\right) \, ds = \int_{\Omega} \left(\frac{\Delta S}{S} - \frac{\|\nabla S\|^2}{S^2}\right) \, ds, \end{aligned}$$

for $S \in \{U, L, I, P, E, H, Z^I, Z^E\}$. Thus, we obtain

$$\begin{aligned} \int_{\Omega} \Delta S \, ds &= 0, \\ \int_{\Omega} \frac{\Delta S}{S} \, ds &= \int_{\Omega} \frac{\|\nabla S\|^2}{S^2} \, ds. \end{aligned} \tag{12}$$

In order to simplify the notation, we denote $S(s, t)$ by S . Based on the above concepts, the following subsections will deal with proving the global stability analysis of each equilibrium point.

5.1. Stability of Equilibrium \check{S}_0

Theorem 1. *The equilibrium \check{S}_0 of Model (4) is globally asymptotically stable (GAS) when $\mathcal{R}_1 \leq 1$ and $\mathcal{R}_2 \leq 1$.*

Proof. Define a Lyapunov function $\Psi_0(s, t)$ as

$$\Psi_0(s, t) = U_0 F \left(\frac{U}{U_0} \right) + L + \frac{U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} I + \frac{1}{\varphi} P + \frac{\theta + b_1}{\varphi\theta} E + \frac{\omega_1 U_0}{\vartheta} H + \frac{\varkappa_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2} Z^E.$$

Clearly, $\hat{\Psi}_0(U, L, I, P, E, H, Z^I, Z^E) > 0$ for all $U, L, I, P, E, H, Z^I, Z^E > 0$, and $\hat{\Psi}_0 = 0$ at \check{S}_0 . Calculating $\frac{\partial \Psi_0}{\partial t}$ along the solutions of Model (4) as follows:

$$\begin{aligned} \frac{\partial \Psi_0}{\partial t} &= \left(1 - \frac{U_0}{U}\right) (d_U \Delta U + \varrho - \varsigma U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) + d_L \Delta L + \omega_1 UH \\ &+ \omega_2 UL + \omega_3 UI - (\beta + \eta)L + \frac{U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) \\ &+ \frac{1}{\varphi} [d_P \Delta P + \varphi\omega_4 UE + wE - (\theta + b_1)P] + \frac{\theta + b_1}{\varphi\theta} (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) \\ &+ \frac{\omega_1 U_0}{\vartheta} (d_H \Delta H + \omega I - \vartheta H) + \frac{\varkappa_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) \\ &+ \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2} (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E) \\ &= \left(1 - \frac{U_0}{U}\right) (\varrho - \varsigma U) + \omega_2 U_0 L + \omega_4 U_0 E - (\beta + \eta)L + \frac{\beta U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L \\ &+ \frac{w}{\varphi} E - \frac{a(\theta + b_1)}{\varphi\theta} E - \frac{\varkappa_1 c_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z^E \\ &+ d_U \left(1 - \frac{U_0}{U}\right) \Delta U + d_L \Delta L + \frac{d_I U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \Delta E \\ &+ \frac{\omega_1 d_H U_0}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \Delta Z^E. \end{aligned}$$

Using $U_0 = \varrho/\varsigma$, we obtain

$$\begin{aligned} \frac{\partial \Psi_0}{\partial t} &= -\varsigma \frac{(U - U_0)^2}{U} + (\beta + \eta)(\mathcal{R}_1 - 1)L + \frac{(a - w)\theta + ab_1}{\varphi\theta} (\mathcal{R}_2 - 1)E \\ &- \frac{\varkappa_1 c_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z^E + d_U \left(1 - \frac{U_0}{U}\right) \Delta U \\ &+ d_L \Delta L + \frac{d_I U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \Delta E \\ &+ \frac{\omega_1 d_H U_0}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \Delta Z^E. \end{aligned}$$

Therefore, we calculate $\frac{d\hat{\Psi}_0}{dt}$ as follows:

$$\begin{aligned} \frac{d\hat{\Psi}_0}{dt} &= -\varsigma \int_{\Omega} \frac{(U - U_0)^2}{U} ds + (\beta + \eta)(\mathcal{R}_1 - 1) \int_{\Omega} L ds + \frac{[(a - w)\theta + ab_1](\mathcal{R}_2 - 1)}{\varphi\theta} \int_{\Omega} E ds \\ &- \frac{\varkappa_1 c_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \int_{\Omega} Z^I ds - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} \int_{\Omega} Z^E ds + d_U \int_{\Omega} \left(1 - \frac{U_0}{U}\right) \Delta U ds \\ &+ d_L \int_{\Omega} \Delta L ds + \frac{d_I U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \int_{\Omega} \Delta I ds + \frac{d_P}{\varphi} \int_{\Omega} \Delta P ds + \frac{d_E(\theta + b_1)}{\varphi\theta} \int_{\Omega} \Delta E ds \\ &+ \frac{\omega_1 d_H U_0}{\vartheta} \int_{\Omega} \Delta H ds + \frac{\varkappa_1 d_{Z^I} U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \int_{\Omega} \Delta Z^I ds + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \int_{\Omega} \Delta Z^E ds. \end{aligned} \tag{13}$$

By using Equality (12), Equation (13) is simplified as the following form:

$$\begin{aligned} \frac{d\tilde{\Psi}_0}{dt} = & -\varsigma \int_{\Omega} \frac{(U - U_0)^2}{U} ds + (\beta + \eta)(\mathcal{R}_1 - 1) \int_{\Omega} L ds + \frac{[(a - w)\theta + ab_1](\mathcal{R}_2 - 1)}{\varphi\theta} \int_{\Omega} E ds \\ & - \frac{\varkappa_1 c_1 U_0(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \int_{\Omega} Z^I ds - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\vartheta v_2} \int_{\Omega} Z^E ds - d_U U_0 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds. \end{aligned}$$

Hence, $\frac{d\tilde{\Psi}_0}{dt} \leq 0$ for any $U, L, E, Z^I, Z^E > 0$ and $\frac{d\tilde{\Psi}_0}{dt} = 0$ when $(U, L, E, Z^I, Z^E) = (U_0, 0, 0, 0, 0)$. The solutions of Model (4) are limited to Γ'_0 . It can be seen that the elements of the set Γ'_0 satisfy $(U, L, E, Z^I, Z^E) = (U_0, 0, 0, 0, 0)$. Then, $\frac{\partial E}{\partial t} = \Delta E = 0$, and the fifth equation of Model (4) becomes

$$0 = \frac{\partial E}{\partial t} = \theta P.$$

Thus, $P = 0$. The third and sixth equations of Model (4) yield

$$\begin{cases} \frac{\partial I}{\partial t} = d_I \Delta I - \alpha I, \\ \frac{\partial H}{\partial t} = d_H \Delta H + \omega I - \vartheta H. \end{cases} \tag{14}$$

We can define a Lyapunov function as follows

$$\tilde{\Psi}_0 = \int_{\Omega} I ds + \frac{\alpha}{2\omega} \int_{\Omega} H ds.$$

Then, $\frac{d\tilde{\Psi}_0}{dt}$ can be computed along the solutions of Model (14) as follows

$$\frac{d\tilde{\Psi}_0}{dt} = -\frac{\alpha}{2} \int_{\Omega} \left(I + \frac{\vartheta}{\omega} H \right) ds \leq 0.$$

Clearly, $\frac{d\tilde{\Psi}_0}{dt} = 0$ when $I = H = 0$. Let

$$\Gamma''_0 = \left\{ (U, L, I, P, E, H, Z^I, Z^E) \in \Gamma'_0 : \frac{d\tilde{\Psi}_0}{dt} = 0 \right\}.$$

Thus

$$\Gamma''_0 = \left\{ (U, L, I, P, E, H, Z^I, Z^E) \in \Gamma'_0 : (U, L, I, P, E, H, Z^I, Z^E) = (U_0, 0, 0, 0, 0, 0, 0, 0) \right\} = \{\check{S}_0\}.$$

As a result of applying L-LAST, we concluded that \check{S}_0 is GAS [54–56]. \square

5.2. Stability of Equilibrium \check{S}_1

To prove the global stability of \check{S}_1 , we need the following lemma:

Lemma 1. *If $\mathcal{R}_3 \leq 1$, then $I_1 \leq I_3$.*

Proof. Let $\mathcal{R}_3 \leq 1$; hence, $\frac{\beta v_1 L_3}{\alpha c_1} \leq 1$, and therefore,

$$\begin{aligned} L_3 \leq \frac{\alpha c_1}{\beta v_1} & \implies \frac{-B_1 + \sqrt{B_1^2 - 4A_1 C_1}}{2A_1} \leq \frac{\alpha c_1}{\beta v_1} \\ \implies \sqrt{B_1^2 - 4A_1 C_1} & \leq \frac{2A_1 \alpha c_1 + \beta v_1 B_1}{\beta v_1} \\ \implies \left(\frac{2A_1 \alpha c_1 + \beta v_1 B_1}{\beta v_1} \right)^2 & + 4A_1 C_1 - B_1^2 \geq 0. \end{aligned}$$

Using Equation (6), we obtain

$$\frac{4\alpha c_1 \vartheta \omega_2 v_1 (\beta + \eta)^2 [\alpha \vartheta \omega_2 + \beta (\omega \omega_1 + \vartheta \omega_3)]}{\beta^2} (I_3 - I_1) \geq 0.$$

Hence, $I_1 \leq I_3$. \square

Theorem 2. The equilibrium \check{S}_1 of Model (4) is GAS when $\mathcal{R}_1 > 1$, $\mathcal{R}_2 / \mathcal{R}_1 \leq 1$ and $\mathcal{R}_3 \leq 1$.

Proof. Construct a Lyapunov function $\Psi_1(s, t)$ as follows:

$$\begin{aligned} \Psi_1(s, t) = & U_1 F\left(\frac{U}{U_1}\right) + L_1 F\left(\frac{L}{L_1}\right) + \frac{U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} I_1 F\left(\frac{I}{I_1}\right) + \frac{1}{\varphi} P \\ & + \frac{\theta + b_1}{\varphi \theta} E + \frac{\omega_1 U_1}{\vartheta} H_1 F\left(\frac{H}{H_1}\right) + \frac{\varkappa_1 U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I + \frac{\varkappa_2(\theta + b_1)}{\varphi \theta v_2} Z^E. \end{aligned}$$

Calculating $\frac{\partial \Psi_1}{\partial t}$ as

$$\begin{aligned} \frac{\partial \Psi_1}{\partial t} = & \left(1 - \frac{U_1}{U}\right) (d_U \Delta U + \varrho - \varsigma U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) \\ & + \left(1 - \frac{L_1}{L}\right) [d_L \Delta L + \omega_1 UH + \omega_2 UL + \omega_3 UI - (\beta + \eta)L] + \frac{U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \\ & \times \left(1 - \frac{I_1}{I}\right) (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) + \frac{1}{\varphi} [d_P \Delta P + \varphi \omega_4 UE + wE - (\theta + b_1)P] \\ & + \frac{\theta + b_1}{\varphi \theta} (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) + \frac{\omega_1 U_1}{\vartheta} \left(1 - \frac{H_1}{H}\right) (d_H \Delta H + \omega I - \vartheta H) \\ & + \frac{\varkappa_1 U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) + \frac{\varkappa_2(\theta + b_1)}{\varphi \theta v_2} (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E) \\ = & \left(1 - \frac{U_1}{U}\right) (\varrho - \varsigma U) + \omega_2 U_1 L + \omega_4 U_1 E - (\beta + \eta)L - \omega_1 UH \frac{L_1}{L} - \omega_2 UL_1 \\ & - \omega_3 UI \frac{L_1}{L} + (\beta + \eta)L_1 + \frac{\beta U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} L - \frac{\beta U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} L \frac{I_1}{I} \\ & + \frac{U_1(\omega \omega_1 + \vartheta \omega_3)}{\vartheta} I_1 + \frac{\varkappa_1 U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} Z^I I_1 + \frac{w}{\varphi} E - \frac{a(\theta + b_1)}{\varphi \theta} E - \omega_1 U_1 \frac{\omega I}{\vartheta} \frac{H_1}{H} \\ & + \omega_1 U_1 H_1 - \frac{\varkappa_1 c_1 U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_1}{U}\right) \Delta U \\ & + d_L \left(1 - \frac{L_1}{L}\right) \Delta L + \frac{d_I U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \left(1 - \frac{I_1}{I}\right) \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E(\theta + b_1)}{\varphi \theta} \Delta E \\ & + \frac{d_H \omega_1 U_1}{\vartheta} \left(1 - \frac{H_1}{H}\right) \Delta H + \frac{\varkappa_1 d_{Z^I} U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi \theta v_2} \Delta Z^E. \end{aligned}$$

Applying the equilibrium conditions for \check{S}_1 :

$$\begin{aligned} \varrho &= \varsigma U_1 + \omega_1 U_1 H_1 + \omega_2 U_1 L_1 + \omega_3 U_1 I_1, \\ \omega_1 U_1 H_1 + \omega_2 U_1 L_1 + \omega_3 U_1 I_1 &= (\beta + \eta)L_1, \\ \frac{\beta L_1}{\alpha} = I_1, \quad H_1 &= \frac{\omega I_1}{\vartheta}, \end{aligned}$$

we have

$$\omega_1 U_1 H_1 + \omega_3 U_1 I_1 = \frac{U_1(\omega \omega_1 + \vartheta \omega_3)}{\vartheta} I_1 = \frac{\beta U_1(\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} L_1.$$

Further, we obtain

$$\begin{aligned}
 \frac{\partial \Psi_1}{\partial t} &= \left(1 - \frac{U_1}{U}\right) (\zeta U_1 - \zeta U) + (\omega_1 U_1 H_1 + \omega_2 U_1 L_1 + \omega_3 U_1 I_1) \left(1 - \frac{U_1}{U}\right) \\
 &+ \omega_4 U_1 E - \omega_1 U_1 H_1 \frac{UHL_1}{U_1 H_1 L} - \omega_2 U_1 L_1 \frac{U}{U_1} - \omega_3 U_1 I_1 \frac{UILL_1}{U_1 I_1 L} + \omega_1 U_1 H_1 \\
 &+ \omega_2 U_1 L_1 + \omega_3 U_1 I_1 - (\omega_1 U_1 H_1 + \omega_3 U_1 I_1) \frac{LI_1}{L_1 I} + \omega_1 U_1 H_1 + \omega_3 U_1 I_1 \\
 &+ \frac{\varkappa_1 U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} Z^I I_1 + \frac{w}{\varphi} E - \frac{a(\theta + b_1)}{\varphi \theta} E - \omega_1 U_1 H_1 \frac{IH_1}{I_1 H} + \omega_1 U_1 H_1 \\
 &- \frac{\varkappa_1 c_1 U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_1}{U}\right) \Delta U \\
 &+ d_L \left(1 - \frac{L_1}{L}\right) \Delta L + \frac{d_I U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \left(1 - \frac{I_1}{I}\right) \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \Delta E \\
 &+ \frac{d_H \omega_1 U_1}{\vartheta} \left(1 - \frac{H_1}{H}\right) \Delta H + \frac{\varkappa_1 d_{Z^I} U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E \\
 &= -\zeta \frac{(U - U_1)^2}{U} + \omega_1 U_1 H_1 \left(4 - \frac{U_1}{U} - \frac{UHL_1}{U_1 H_1 L} - \frac{IH_1}{I_1 H} - \frac{LI_1}{L_1 I}\right) \\
 &+ \omega_2 U_1 L_1 \left(2 - \frac{U_1}{U} - \frac{U}{U_1}\right) + \omega_3 U_1 I_1 \left(3 - \frac{U_1}{U} - \frac{UILL_1}{U_1 I_1 L} - \frac{LI_1}{L_1 I}\right) \\
 &+ \frac{(a - w)\theta + ab_1}{\varphi \theta} \left(\frac{\varphi \omega_4 \theta U_1}{(a - w)\theta + ab_1} - 1\right) E + \frac{\varkappa_1 U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \left(I_1 - \frac{c_1}{v_1}\right) Z^I \\
 &- \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_1}{U}\right) \Delta U + d_L \left(1 - \frac{L_1}{L}\right) \Delta L + \frac{d_I U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \\
 &\times \left(1 - \frac{I_1}{I}\right) \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \Delta E + \frac{d_H \omega_1 U_1}{\vartheta} \left(1 - \frac{H_1}{H}\right) \Delta H \\
 &+ \frac{\varkappa_1 d_{Z^I} U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E.
 \end{aligned} \tag{15}$$

Therefore, Equation (15) becomes

$$\begin{aligned}
 \frac{\partial \Psi_1}{\partial t} &= -(\zeta + \omega_2 L_1) \frac{(U - U_1)^2}{U} + \omega_1 U_1 H_1 \left(4 - \frac{U_1}{U} - \frac{UHL_1}{U_1 H_1 L} - \frac{IH_1}{I_1 H} - \frac{LI_1}{L_1 I}\right) \\
 &+ \omega_3 U_1 I_1 \left(3 - \frac{U_1}{U} - \frac{UILL_1}{U_1 I_1 L} - \frac{LI_1}{L_1 I}\right) + \frac{(a - w)\theta + ab_1}{\varphi \theta} (\mathcal{R}_2 / \mathcal{R}_1 - 1) E \\
 &+ \frac{\varkappa_1 U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} (I_1 - I_3) Z^I - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_1}{U}\right) \Delta U \\
 &+ d_L \left(1 - \frac{L_1}{L}\right) \Delta L + \frac{d_I U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \left(1 - \frac{I_1}{I}\right) \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \Delta E \\
 &+ \frac{d_H \omega_1 U_1}{\vartheta} \left(1 - \frac{H_1}{H}\right) \Delta H + \frac{\varkappa_1 d_{Z^I} U_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E.
 \end{aligned} \tag{16}$$

Calculating $\frac{d\hat{\Psi}_1}{dt}$ and using Equality (12) to obtain

$$\begin{aligned}
 \frac{d\hat{\Psi}_1}{dt} &= -(\zeta + \omega_2 L_1) \int_{\Omega} \frac{(U - U_1)^2}{U} ds + \omega_1 U_1 H_1 \int_{\Omega} \left(4 - \frac{U_1}{U} - \frac{UHL_1}{U_1 H_1 L} - \frac{IH_1}{I_1 H} - \frac{LI_1}{L_1 I}\right) ds \\
 &+ \omega_3 U_1 I_1 \int_{\Omega} \left(3 - \frac{U_1}{U} - \frac{UILL_1}{U_1 I_1 L} - \frac{LI_1}{L_1 I}\right) ds + \frac{[(a - w)\theta + ab_1](\mathcal{R}_2 / \mathcal{R}_1 - 1)}{\varphi \theta} \int_{\Omega} E ds \\
 &+ \frac{\varkappa_1 U_1 (\omega \omega_1 + \vartheta \omega_3) (I_1 - I_3)}{\alpha \vartheta} \int_{\Omega} Z^I ds - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} \int_{\Omega} Z^E ds - d_U U_1 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds
 \end{aligned}$$

$$-d_L L_1 \int_{\Omega} \frac{\|\nabla L\|^2}{L^2} ds - \frac{d_I U_1 I_1 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \int_{\Omega} \frac{\|\nabla I\|^2}{I^2} ds - \frac{d_H \omega_1 U_1 H_1}{\vartheta} \int_{\Omega} \frac{\|\nabla H\|^2}{H^2} ds.$$

Using Lemma 1, we obtain that $I_1 \leq I_3$ whenever $\mathcal{R}_3 \leq 1$. Moreover, since $\mathcal{R}_2 / \mathcal{R}_1 \leq 1$, then utilizing Inequalities (9)–(10), we obtain $\frac{d\check{\Psi}_1}{dt} \leq 0$ for any $U, L, I, E, H, Z^I, Z^E > 0$. Moreover, $\frac{d\check{\Psi}_1}{dt} = 0$ at $(U, L, I, H, E, Z^I, Z^E) = (U_1, L_1, I_1, H_1, 0, 0, 0)$. The trajectories of Model (4) tend to Γ'_1 , which consists of the element where $E = 0$. Hence, $\frac{\partial E}{\partial t} = \Delta E = 0$, and the fifth equation of Model (4) reduces to

$$0 = \frac{\partial E}{\partial t} = \theta P,$$

and gives $P = 0$. Hence, $\Gamma'_1 = \{\check{S}_1\}$ and \check{S}_1 is GAS by using L-LAST. \square

5.3. Stability of Equilibrium \check{S}_2

Theorem 3. *The equilibrium \check{S}_2 of Model (4) is GAS when $\mathcal{R}_2 > 1$, $\mathcal{R}_1 / \mathcal{R}_2 \leq 1$, and $\mathcal{R}_4 \leq 1$.*

Proof. Assume $\Psi_2(s, t)$ is defined as follows:

$$\begin{aligned} \Psi_2(s, t) = & U_2 F \left(\frac{U}{U_2} \right) + L + \frac{U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} I + \frac{1}{\varphi} P_2 F \left(\frac{P}{P_2} \right) + \frac{\theta + b_1}{\varphi \theta} E_2 F \left(\frac{E}{E_2} \right) \\ & + \frac{\omega_1 U_2}{\vartheta} H + \frac{\varkappa_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta v_2} Z^E. \end{aligned}$$

We calculate $\frac{\partial \Psi_2}{\partial t}$ as

$$\begin{aligned} \frac{\partial \Psi_2}{\partial t} = & \left(1 - \frac{U_2}{U} \right) (d_U \Delta U + \varrho - \varsigma U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) + d_L \Delta L + \omega_1 UH + \omega_2 UL \\ & + \omega_3 UI - (\beta + \eta)L + \frac{U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) + \frac{1}{\varphi} \left(1 - \frac{P_2}{P} \right) \\ & \times [d_P \Delta P + \varphi \omega_4 UE + wE - (\theta + b_1)P] + \frac{\theta + b_1}{\varphi \theta} \left(1 - \frac{E_2}{E} \right) (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) \\ & + \frac{\omega_1 U_2}{\vartheta} (d_H \Delta H + \omega I - \vartheta H) + \frac{\varkappa_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) \\ & + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta v_2} (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E) \\ = & \left(1 - \frac{U_2}{U} \right) (\varrho - \varsigma U) + \omega_2 U_2 L + \omega_4 U_2 E - (\beta + \eta)L + \frac{\beta U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} L + \frac{w}{\varphi} E \\ & - \omega_4 UE \frac{P_2}{P} - \frac{w}{\varphi} E \frac{P_2}{P} + \frac{\theta + b_1}{\varphi} P_2 - \frac{a(\theta + b_1)}{\varphi \theta} E - \frac{\theta + b_1}{\varphi} P \frac{E_2}{E} + \frac{a(\theta + b_1)}{\varphi \theta} E_2 \\ & + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta} Z^E E_2 - \frac{\varkappa_1 c_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_2}{U} \right) \Delta U \\ & + d_L \Delta L + \frac{d_I U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_2}{P} \right) \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_2}{E} \right) \Delta E \\ & + \frac{d_H \omega_1 U_2}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E. \end{aligned}$$

Using the equilibrium conditions for \check{S}_2 :

$$\varrho = \varsigma U_2 + \omega_4 U_2 E_2, \quad \omega_4 U_2 E_2 + \frac{w}{\varphi} E_2 = \frac{\theta + b_1}{\varphi} P_2 = \frac{a(\theta + b_1)}{\varphi \theta} E_2, \tag{17}$$

We obtain

$$\begin{aligned}
 \frac{\partial \Psi_2}{\partial t} &= \left(1 - \frac{U_2}{U}\right) (\zeta U_2 - \zeta U) + \omega_4 U_2 E_2 \left(1 - \frac{U_2}{U}\right) + \omega_2 U_2 L - (\beta + \eta) L \\
 &+ \frac{\beta U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} L - \omega_4 U_2 E_2 \frac{U E P_2}{U_2 E_2 P} - \frac{w}{\varphi} E_2 \frac{E P_2}{E_2 P} + \omega_4 U_2 E_2 + \frac{w}{\varphi} E_2 \\
 &- \omega_4 U_2 E_2 \frac{P E_2}{P_2 E} - \frac{w}{\varphi} E_2 \frac{P E_2}{P_2 E} + \omega_4 U_2 E_2 + \frac{w}{\varphi} E_2 + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta} Z^E E_2 \\
 &- \frac{\varkappa_1 c_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} Z^E + d_U \left(1 - \frac{U_2}{U}\right) \Delta U + d_L \Delta L \\
 &+ \frac{d_I U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_2}{P}\right) \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_2}{E}\right) \Delta E \\
 &+ \frac{d_H \omega_1 U_2}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E \\
 &= -\zeta \frac{(U - U_2)^2}{U} + \omega_4 U_2 E_2 \left(3 - \frac{U_2}{U} - \frac{U E P_2}{U_2 E_2 P} - \frac{P E_2}{P_2 E}\right) \\
 &+ \frac{w}{\varphi} E_2 \left(2 - \frac{E P_2}{E_2 P} - \frac{P E_2}{P_2 E}\right) + (\beta + \eta) \left[\frac{U_2 \{\alpha \vartheta \omega_2 + \beta (\omega \omega_1 + \vartheta \omega_3)\}}{\alpha \vartheta (\beta + \eta)} - 1\right] L \\
 &- \frac{\varkappa_1 c_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta} \left(E_2 - \frac{c_2}{v_2}\right) Z^E + d_U \left(1 - \frac{U_2}{U}\right) \Delta U \\
 &+ d_L \Delta L + \frac{d_I U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_2}{P}\right) \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_2}{E}\right) \Delta E \\
 &+ \frac{d_H \omega_1 U_2}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E \\
 &= -\zeta \frac{(U - U_2)^2}{U} - \frac{w}{\varphi} \frac{(E P_2 - P E_2)^2}{P P_2 E} + \omega_4 U_2 E_2 \left(3 - \frac{U_2}{U} - \frac{U E P_2}{U_2 E_2 P} - \frac{P E_2}{P_2 E}\right) \\
 &+ (\beta + \eta) (\mathcal{R}_1 / \mathcal{R}_2 - 1) L - \frac{\varkappa_1 c_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I + \frac{\varkappa_2 (\theta + b_1) (\zeta v_2 + \omega_4 c_2)}{\varphi \theta \omega_4 v_2} \\
 &\times (\mathcal{R}_4 - 1) Z^E + d_U \left(1 - \frac{U_2}{U}\right) \Delta U + d_L \Delta L + \frac{d_I U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \Delta I \\
 &+ \frac{d_P}{\varphi} \left(1 - \frac{P_2}{P}\right) \Delta P + \frac{d_E (\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_2}{E}\right) \Delta E + \frac{d_H \omega_1 U_2}{\vartheta} \Delta H \\
 &+ \frac{\varkappa_1 d_{Z^I} U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \Delta Z^E. \tag{18}
 \end{aligned}$$

By calculating $\frac{d\hat{\Psi}_2}{dt}$ along the positive solutions of Model (4) and applying Equality (12), we find

$$\begin{aligned}
 \frac{d\hat{\Psi}_2}{dt} &= -\zeta \int_{\Omega} \frac{(U - U_2)^2}{U} ds - \frac{w}{\varphi} \int_{\Omega} \frac{(E P_2 - P E_2)^2}{P P_2 E} ds \\
 &+ \omega_4 U_2 E_2 \int_{\Omega} \left(3 - \frac{U_2}{U} - \frac{U E P_2}{U_2 E_2 P} - \frac{P E_2}{P_2 E}\right) ds + (\beta + \eta) (\mathcal{R}_1 / \mathcal{R}_2 - 1) \int_{\Omega} L ds \\
 &- \frac{\varkappa_1 c_1 U_2 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \int_{\Omega} Z^I ds + \frac{\varkappa_2 (\theta + b_1) (\zeta v_2 + \omega_4 c_2) (\mathcal{R}_4 - 1)}{\varphi \theta \omega_4 v_2} \int_{\Omega} Z^E ds \\
 &- d_U U_2 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds - \frac{d_P P_2}{\varphi} \int_{\Omega} \frac{\|\nabla P\|^2}{P^2} ds - \frac{d_E E_2 (\theta + b_1)}{\varphi \theta} \int_{\Omega} \frac{\|\nabla E\|^2}{E^2} ds.
 \end{aligned}$$

Thus, if $\mathcal{R}_1 / \mathcal{R}_2 \leq 1$ and $\mathcal{R}_4 \leq 1$, then from Inequality (11), we obtain $\frac{d\hat{\Psi}_2}{dt} \leq 0$ for any $U, L, I, P, E, H, Z^I, Z^E > 0$. In addition, $\frac{d\hat{\Psi}_2}{dt} = 0$ at $(U, P, E, L, Z^I, Z^E) = (U_2, P_2, E_2, 0, 0, 0)$.

Similar to the proof of Theorem 1, one can demonstrate that $\Gamma'_2 = \{\check{S}_2\}$, and L-LAST implies that \check{S}_2 is GAS. \square

5.4. Stability of Equilibrium \check{S}_3

Theorem 4. The equilibrium \check{S}_3 of Model (4) is GAS when $\mathcal{R}_3 > 1$ and $\mathcal{R}_5 \leq 1$.

Proof. Define a function $\Psi_3(s, t)$ as

$$\Psi_3 = U_3F\left(\frac{U}{U_3}\right) + L_3F\left(\frac{L}{L_3}\right) + \frac{U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}I_3F\left(\frac{I}{I_3}\right) + \frac{1}{\varphi}P + \frac{\theta + b_1}{\varphi\theta}E$$

$$+ \frac{\omega_1U_3}{\vartheta}H_3F\left(\frac{H}{H_3}\right) + \frac{\varkappa_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1Z_3^I)}Z_3^IF\left(\frac{Z^I}{Z_3^I}\right) + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2}Z^E.$$

We calculate $\frac{\partial\Psi_3}{\partial t}$ as

$$\begin{aligned} \frac{\partial\Psi_3}{\partial t} &= \left(1 - \frac{U_3}{U}\right)(d_U\Delta U + \varrho - \zeta U - \omega_1UH - \omega_2UL - \omega_3UI - \omega_4UE) \\ &+ \left(1 - \frac{L_3}{L}\right)[d_L\Delta L + \omega_1UH + \omega_2UL + \omega_3UI - (\beta + \eta)L] \\ &+ \frac{U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}\left(1 - \frac{I_3}{I}\right)(d_I\Delta I + \beta L - \alpha I - \varkappa_1Z^II) \\ &+ \frac{1}{\varphi}[d_P\Delta P + \varphi\omega_4UE + wE - (\theta + b_1)P] \\ &+ \frac{\theta + b_1}{\varphi\theta}(d_E\Delta E + \theta P - aE - \varkappa_2Z^EE) + \frac{\omega_1U_3}{\vartheta}\left(1 - \frac{H_3}{H}\right)(d_H\Delta H + \omega I - \vartheta H) \\ &+ \frac{\varkappa_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1Z_3^I)}\left(1 - \frac{Z_3^I}{Z^I}\right)(d_{Z^I}\Delta Z^I + v_1Z^II - c_1Z^I) \\ &+ \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2}(d_{Z^E}\Delta Z^E + v_2Z^EE - c_2Z^E). \end{aligned} \tag{19}$$

Equation (19) can be simplified as

$$\begin{aligned} \frac{\partial\Psi_3}{\partial t} &= \left(1 - \frac{U_3}{U}\right)(\varrho - \zeta U) + \omega_2U_3L + \omega_3U_3I + \omega_4U_3E - (\beta + \eta)L - \omega_1UH\frac{L_3}{L} \\ &- \omega_2UL_3 - \omega_3UI\frac{L_3}{L} + (\beta + \eta)L_3 + \frac{\beta U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}L - \frac{\alpha U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}I \\ &- \frac{\beta U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}L\frac{I_3}{I} + \frac{\alpha U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}I_3 + \frac{\varkappa_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}Z^II_3 + \frac{w}{\varphi}E \\ &- \frac{a(\theta + b_1)}{\varphi\theta}E + \frac{\omega_1U_3}{\vartheta}\omega I - \frac{\omega_1U_3}{\vartheta}\omega I\frac{H_3}{H} + \omega_1U_3H_3 - \frac{\varkappa_1c_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1Z_3^I)}Z^I \\ &- \frac{\varkappa_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}Z_3^II + \frac{\varkappa_1c_1U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1Z_3^I)}Z_3^I - \frac{\varkappa_2c_2(\theta + b_1)}{\varphi\theta v_2}Z^E \\ &+ d_U\left(1 - \frac{U_3}{U}\right)\Delta U + d_L\left(1 - \frac{L_3}{L}\right)\Delta L + \frac{d_IU_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1Z_3^I)}\left(1 - \frac{I_3}{I}\right)\Delta I + \frac{d_P}{\varphi}\Delta P \\ &+ \frac{d_E(\theta + b_1)}{\varphi\theta}\Delta E + \frac{d_H\omega_1U_3}{\vartheta}\left(1 - \frac{H_3}{H}\right)\Delta H + \frac{\varkappa_1d_{Z^I}U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1Z_3^I)}\left(1 - \frac{Z_3^I}{Z^I}\right)\Delta Z^I \\ &+ \frac{\varkappa_2d_{Z^E}(\theta + b_1)}{\varphi\theta v_2}\Delta Z^E. \end{aligned}$$

Applying the equilibrium conditions for \check{S}_3 :

$$\begin{aligned} \varrho &= \zeta U_3 + \omega_1 U_3 H_3 + \omega_2 U_3 L_3 + \omega_3 U_3 I_3, \\ \omega_1 U_3 H_3 + \omega_2 U_3 L_3 + \omega_3 U_3 I_3 &= (\beta + \eta) L_3, \\ \beta L_3 &= (\alpha + \varkappa_1 Z_3^I) I_3, \quad I_3 = \frac{c_1}{v_1}, \quad H_3 = \frac{\omega}{\vartheta} I_3, \end{aligned}$$

we have

$$\omega_1 U_3 H_3 + \omega_3 U_3 I_3 = \frac{U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta} I_3 = \frac{\beta U_3(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_3^I)} L_3.$$

Moreover, we obtain

$$\begin{aligned} \frac{\partial \Psi_3}{\partial t} &= \left(1 - \frac{U_3}{U}\right) (\zeta U_3 - \zeta U) + (\omega_1 U_3 H_3 + \omega_2 U_3 L_3 + \omega_3 U_3 I_3) \left(1 - \frac{U_3}{U}\right) \\ &+ \omega_4 U_3 E - \omega_1 U_3 H_3 \frac{UHL_3}{U_3 H_3 L} - \omega_2 U_3 L_3 \frac{U}{U_3} - \omega_3 U_3 I_3 \frac{UIL_3}{U_3 I_3 L} + \omega_1 U_3 H_3 \\ &+ \omega_2 U_3 L_3 + \omega_3 U_3 I_3 - (\omega_1 U_3 H_3 + \omega_3 U_3 I_3) \frac{LI_3}{L_3 I} + \omega_1 U_3 H_3 + \omega_3 U_3 I_3 \\ &- \frac{(a-w)\theta + ab_1}{\varphi\theta} E - \omega_1 U_3 H_3 \frac{IH_3}{I_3 H} + \omega_1 U_3 H_3 - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi\theta v_2} Z^E \\ &+ d_U \left(1 - \frac{U_3}{U}\right) \Delta U + d_L \left(1 - \frac{L_3}{L}\right) \Delta L + \frac{d_I U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_3^I)} \\ &\times \left(1 - \frac{I_3}{I}\right) \Delta I + \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi\theta} \Delta E + \frac{d_H \omega_1 U_3}{\vartheta} \left(1 - \frac{H_3}{H}\right) \Delta H \\ &+ \frac{\varkappa_1 d_{Z^I} U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_3^I)} \left(1 - \frac{Z_3^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E \\ &= -\zeta \frac{(U - U_3)^2}{U} + \omega_1 U_3 H_3 \left(4 - \frac{U_3}{U} - \frac{UHL_3}{U_3 H_3 L} - \frac{LI_3}{L_3 I} - \frac{IH_3}{I_3 H}\right) \\ &+ \omega_2 U_3 L_3 \left(2 - \frac{U_3}{U} - \frac{U}{U_3}\right) + \omega_3 U_3 I_3 \left(3 - \frac{U_3}{U} - \frac{UIL_3}{U_3 I_3 L} - \frac{LI_3}{L_3 I}\right) \\ &+ \omega_4 \left(U_3 - \frac{(a-w)\theta + ab_1}{\omega_4 \varphi\theta}\right) E - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi\theta v_2} Z^E \\ &+ d_U \left(1 - \frac{U_3}{U}\right) \Delta U + d_L \left(1 - \frac{L_3}{L}\right) \Delta L + \frac{d_I U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_3^I)} \left(1 - \frac{I_3}{I}\right) \Delta I \\ &+ \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi\theta} \Delta E + \frac{d_H \omega_1 U_3}{\vartheta} \left(1 - \frac{H_3}{H}\right) \Delta H \\ &+ \frac{\varkappa_1 d_{Z^I} U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_3^I)} \left(1 - \frac{Z_3^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E \\ &= -(\zeta + \omega_2 L_3) \frac{(U - U_3)^2}{U} + \omega_1 U_3 H_3 \left(4 - \frac{U_3}{U} - \frac{UHL_3}{U_3 H_3 L} - \frac{LI_3}{L_3 I} - \frac{IH_3}{I_3 H}\right) \\ &+ \omega_3 U_3 I_3 \left(3 - \frac{U_3}{U} - \frac{UIL_3}{U_3 I_3 L} - \frac{LI_3}{L_3 I}\right) + \omega_4 (U_3 - U_5) E - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi\theta v_2} Z^E \\ &+ d_U \left(1 - \frac{U_3}{U}\right) \Delta U + d_L \left(1 - \frac{L_3}{L}\right) \Delta L + \frac{d_I U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_3^I)} \left(1 - \frac{I_3}{I}\right) \Delta I \\ &+ \frac{d_P}{\varphi} \Delta P + \frac{d_E (\theta + b_1)}{\varphi\theta} \Delta E + \frac{d_H \omega_1 U_3}{\vartheta} \left(1 - \frac{H_3}{H}\right) \Delta H \\ &+ \frac{\varkappa_1 d_{Z^I} U_3 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_3^I)} \left(1 - \frac{Z_3^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E. \end{aligned} \tag{20}$$

Computing the time derivative of $\Psi_3(t)$ and applying Equality (12), Equation (20) will take the following form:

$$\begin{aligned} \frac{d\Psi_3}{dt} = & -(\zeta + \omega_2 L_3) \int_{\Omega} \frac{(U - U_3)^2}{U} ds + \omega_1 U_3 H_3 \int_{\Omega} \left(4 - \frac{U_3}{U} - \frac{UHL_3}{U_3 H_3 L} - \frac{LI_3}{L_3 I} - \frac{IH_3}{I_3 H} \right) ds \\ & + \omega_3 U_3 I_3 \int_{\Omega} \left(3 - \frac{U_3}{U} - \frac{UILL_3}{U_3 I_3 L} - \frac{LI_3}{L_3 I} \right) ds + \omega_4 (U_3 - U_5) \int_{\Omega} E ds - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi \theta v_2} \int_{\Omega} Z^E ds \\ & - d_U U_3 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds - d_L L_3 \int_{\Omega} \frac{\|\nabla L\|^2}{L^2} ds - \frac{d_I U_3 I_3 (\omega \omega_1 + \vartheta \omega_3)}{\vartheta (\alpha + \varkappa_1 Z_3^I)} \int_{\Omega} \frac{\|\nabla I\|^2}{I^2} ds \\ & - \frac{d_H \omega_1 U_3 H_3}{\vartheta} \int_{\Omega} \frac{\|\nabla H\|^2}{H^2} ds - \frac{\varkappa_1 d_{Z^I} U_3 Z_3^I (\omega \omega_1 + \vartheta \omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_3^I)} \int_{\Omega} \frac{\|\nabla Z^I\|^2}{(Z^I)^2} ds. \end{aligned}$$

Obviously, if $\mathcal{R}_5 \leq 1$, then \check{S}_5 does not exist since $P_5 \leq 0$ and $E_5 \leq 0$. Accordingly, in this case, we have

$$\begin{aligned} \frac{\partial P}{\partial t} &= d_P \Delta P + \varphi \omega_4 U E + w E - (\theta + b_1) P \leq 0, \\ \frac{\partial E}{\partial t} &= d_E \Delta E + \theta P - a E - \varkappa_2 Z^E E \leq 0. \end{aligned}$$

The next step is to find the value \bar{U} with $0 < U(t) \leq \bar{U}$ such that $\frac{\partial P}{\partial t} \leq 0$ and $\frac{\partial E}{\partial t} \leq 0$. Let us consider

$$\begin{aligned} & \frac{d}{dt} \left(P + \frac{\theta + b_1}{\theta} E \right) \\ &= \int_{\Omega} \left[d_P \Delta P + \frac{(\theta + b_1) d_E}{\theta} \Delta E + \varphi \omega_4 U E - \frac{(a - w)\theta + ab_1}{\theta} E - \frac{\varkappa_2 (\theta + b_1)}{\theta} Z^E E \right] ds \\ &= \varphi \omega_4 \int_{\Omega} \left[U - \frac{(a - w)\theta + ab_1}{\omega_4 \varphi \theta} \right] E ds - \frac{\varkappa_2 (\theta + b_1)}{\theta} \int_{\Omega} Z^E E ds \leq 0 \text{ for all } Z^E, E > 0. \end{aligned}$$

This occurs when $U_3 \leq \bar{U} = \frac{(a-w)\theta+ab_1}{\omega_4\varphi\theta} = U_5$. Then, from Inequalities (9)–(10), we have $\frac{d\Psi_3}{dt} \leq 0$ for any $U, L, I, E, H, Z^I, Z^E > 0$. In addition, $\frac{d\Psi_3}{dt} = 0$ at $(U, L, I, H, Z^I, E, Z^E) = (U_3, L_3, I_3, H_3, Z_3^I, 0, 0)$. The solutions of Model (4) are limited to Γ'_3 , which has elements satisfying $E = 0$. Hence, $\frac{\partial E}{\partial t} = \Delta E = 0$, and the fifth equation of Model (4) becomes

$$0 = \frac{\partial P}{\partial t} = \theta P,$$

which yields $P = 0$, and hence, $\Gamma'_3 = \{\check{S}_3\}$. As a result of applying L-LAST, \check{S}_3 is GAS. \square

5.5. Stability of Equilibrium \check{S}_4

Theorem 5. *The equilibrium \check{S}_4 of Model (4) is GAS when $\mathcal{R}_4 > 1$ and $\mathcal{R}_6 \leq 1$.*

Proof. Define $\Psi_4(s, t)$ as follows:

$$\begin{aligned} \Psi_4 = & U_4 F \left(\frac{U}{U_4} \right) + L + \frac{U_4 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} I + \frac{1}{\varphi} P_4 F \left(\frac{P}{P_4} \right) + \frac{\theta + b_1}{\varphi \theta} E_4 F \left(\frac{E}{E_4} \right) \\ & + \frac{\omega_1 U_4}{\vartheta} H + \frac{\varkappa_1 U_4 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} Z^I + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta v_2} Z_4^E F \left(\frac{Z^E}{Z_4^E} \right). \end{aligned}$$

Calculating $\frac{\partial \Psi_4}{\partial t}$ as given below:

$$\begin{aligned} \frac{\partial \Psi_4}{\partial t} &= \left(1 - \frac{U_4}{U}\right) (d_U \Delta U + \varrho - \zeta U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) + d_L \Delta L + \omega_1 UH + \omega_2 UL \\ &+ \omega_3 UI - (\beta + \eta)L + \frac{U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) + \frac{1}{\varphi} \left(1 - \frac{P_4}{P}\right) \\ &\times [d_P \Delta P + \varphi\omega_4 UE + wE - (\theta + b_1)P] + \frac{\theta + b_1}{\varphi\theta} \left(1 - \frac{E_4}{E}\right) (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) \\ &+ \frac{\omega_1 U_4}{\vartheta} (d_H \Delta H + \omega I - \vartheta H) + \frac{\varkappa_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) \\ &+ \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_4^E}{Z^E}\right) (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E) \\ &= \left(1 - \frac{U_4}{U}\right) (\varrho - \zeta U) + \omega_2 U_4 L + \omega_4 U_4 E - (\beta + \eta)L + \frac{\beta U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L \\ &+ \frac{w}{\varphi} E - \omega_4 UE \frac{P_4}{P} - \frac{w}{\varphi} E \frac{P_4}{P} + \frac{\theta + b_1}{\varphi} P_4 - \frac{a(\theta + b_1)}{\varphi\theta} E - \frac{\theta + b_1}{\varphi} P \frac{E_4}{E} \\ &+ \frac{a(\theta + b_1)}{\varphi\theta} E_4 + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z^E E_4 - \frac{\varkappa_1 c_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z^E \\ &- \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z_4^E E + \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z_4^E + d_U \left(1 - \frac{U_4}{U}\right) \Delta U + d_L \Delta L \\ &+ \frac{d_I U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_4}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_4}{E}\right) \Delta E \\ &+ \frac{d_H \omega_1 U_4}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_4^E}{Z^E}\right) \Delta Z^E. \end{aligned}$$

Using the equilibrium conditions for \check{S}_4 :

$$\begin{aligned} \varrho &= \zeta U_4 + \omega_4 U_4 E_4, \quad E_4 = \frac{c_2}{v_2}, \\ \omega_4 U_4 E_4 + \frac{w}{\varphi} E_4 &= \frac{\theta + b_1}{\varphi} P_4 = \frac{a(\theta + b_1)}{\varphi\theta} E_4 + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z_4^E E_4. \end{aligned}$$

Then, we find

$$\begin{aligned} \frac{\partial \Psi_4}{\partial t} &= \left(1 - \frac{U_4}{U}\right) (\zeta U_4 - \zeta U) + \omega_4 U_4 E_4 \left(1 - \frac{U_4}{U}\right) + \omega_2 U_4 L - (\beta + \eta)L + \frac{\beta U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L \\ &- \omega_4 U_4 E_4 \frac{UEP_4}{U_4 E_4 P} - \frac{w}{\varphi} E_4 \frac{EP_4}{E_4 P} + \omega_4 U_4 E_4 + \frac{w}{\varphi} E_4 - \omega_4 U_4 E_4 \frac{PE_4}{P_4 E} - \frac{w}{\varphi} E_4 \frac{PE_4}{P_4 E} + \omega_4 U_4 E_4 \\ &+ \frac{w}{\varphi} E_4 - \frac{\varkappa_1 c_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I + d_U \left(1 - \frac{U_4}{U}\right) \Delta U + d_L \Delta L + \frac{d_I U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \Delta I \\ &+ \frac{d_P}{\varphi} \left(1 - \frac{P_4}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_4}{E}\right) \Delta E + \frac{d_H \omega_1 U_4}{\vartheta} \Delta H \\ &+ \frac{\varkappa_1 d_{Z^I} U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_4^E}{Z^E}\right) \Delta Z^E \\ &= -\zeta \frac{(U - U_4)^2}{U} + \omega_4 U_4 E_4 \left(3 - \frac{U_4}{U} - \frac{UEP_4}{U_4 E_4 P} - \frac{PE_4}{P_4 E}\right) + \frac{w}{\varphi} E_4 \left(2 - \frac{EP_4}{E_4 P} - \frac{PE_4}{P_4 E}\right) \\ &+ (\beta + \eta) \left[\frac{U_4 \{ \alpha\vartheta\omega_2 + \beta(\omega\omega_1 + \vartheta\omega_3) \}}{\alpha\vartheta(\beta + \eta)} - 1 \right] L - \frac{\varkappa_1 c_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I \\ &+ d_U \left(1 - \frac{U_4}{U}\right) \Delta U + d_L \Delta L + \frac{d_I U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_4}{P}\right) \Delta P \\ &+ \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_4}{E}\right) \Delta E + \frac{d_H \omega_1 U_4}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I \end{aligned}$$

$$\begin{aligned}
 & + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi \theta v_2} \left(1 - \frac{Z_4^E}{Z^E}\right) \Delta Z^E \\
 & = -\varsigma \frac{(U - U_4)^2}{U} - \frac{w(EP_4 - PE_4)^2}{\varphi PP_4 E} + \omega_4 U_4 E_4 \left(3 - \frac{U_4}{U} - \frac{UEP_4}{U_4 E_4 P} - \frac{PE_4}{P_4 E}\right) \\
 & + (\beta + \eta)(\mathcal{R}_6 - 1)L - \frac{\varkappa_1 c_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha \vartheta v_1} Z^I + d_U \left(1 - \frac{U_4}{U}\right) \Delta U + d_L \Delta L \\
 & + \frac{d_I U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha \vartheta} \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_4}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_4}{E}\right) \Delta E \\
 & + \frac{d_H \omega_1 U_4}{\vartheta} \Delta H + \frac{\varkappa_1 d_{Z^I} U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi \theta v_2} \left(1 - \frac{Z_4^E}{Z^E}\right) \Delta Z^E.
 \end{aligned}$$

Calculating $\frac{d\hat{\Psi}_4}{dt}$ along the positive solutions of System (4) and using Equality (12), then we obtain

$$\begin{aligned}
 \frac{d\hat{\Psi}_4}{dt} & = -\varsigma \int_{\Omega} \frac{(U - U_4)^2}{U} ds - \frac{w}{\varphi} \int_{\Omega} \frac{(EP_4 - PE_4)^2}{PP_4 E} ds \\
 & + \omega_4 U_4 E_4 \int_{\Omega} \left(3 - \frac{U_4}{U} - \frac{UEP_4}{U_4 E_4 P} - \frac{PE_4}{P_4 E}\right) ds + (\beta + \eta)(\mathcal{R}_6 - 1) \int_{\Omega} L ds \\
 & - \frac{\varkappa_1 c_1 U_4(\omega\omega_1 + \vartheta\omega_3)}{\alpha \vartheta v_1} \int_{\Omega} Z^I ds - d_U U_4 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds - \frac{d_P P_4}{\varphi} \int_{\Omega} \frac{\|\nabla P\|^2}{P^2} ds \\
 & - \frac{d_E E_4(\theta + b_1)}{\varphi \theta} \int_{\Omega} \frac{\|\nabla E\|^2}{E^2} ds - \frac{\varkappa_2 d_{Z^E} Z_4^E(\theta + b_1)}{\varphi \theta v_2} \int_{\Omega} \frac{\|\nabla Z^E\|^2}{(Z^E)^2} ds.
 \end{aligned}$$

Hence, if $\mathcal{R}_6 \leq 1$, then from Inequality (11), we obtain $\frac{d\hat{\Psi}_4}{dt} \leq 0$, for any $U, L, I, P, E, H, Z^I, Z^E > 0$. In addition, $\frac{d\hat{\Psi}_4}{dt} = 0$ at $(U, P, E, Z^E, L, Z^I) = (U_4, P_4, E_4, Z_4^E, 0, 0)$. The solutions of Model (4) are limited to Γ'_4 . Therefore, in the same way that Theorem 1 was proven, one can demonstrate that $\Gamma'_4 = \{\check{S}_4\}$. Applying L-LAST, we obtain that \check{S}_4 is GAS. \square

5.6. Stability of Equilibrium \check{S}_5

Theorem 6. The equilibrium \check{S}_5 of Model (4) is GAS when $\mathcal{R}_5 > 1, \hat{\mathcal{R}}_5 > 1, \mathcal{R}_8 \leq 1$, and $\mathcal{R}_1/\mathcal{R}_2 > 1$.

Proof. Define $\Psi_5(s, t)$ as follows:

$$\begin{aligned}
 \Psi_5 & = U_5 F\left(\frac{U}{U_5}\right) + L_5 F\left(\frac{L}{L_5}\right) + \frac{U_5(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} I_5 F\left(\frac{I}{I_5}\right) + \frac{1}{\varphi} P_5 F\left(\frac{P}{P_5}\right) \\
 & + \frac{\theta + b_1}{\varphi \theta} E_5 F\left(\frac{E}{E_5}\right) + \frac{\omega_1 U_5}{\vartheta} H_5 F\left(\frac{H}{H_5}\right) + \frac{\varkappa_1 U_5(\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_5^I)} Z_5^I F\left(\frac{Z^I}{Z_5^I}\right) + \frac{\varkappa_2(\theta + b_1)}{\varphi \theta v_2} Z^E.
 \end{aligned}$$

Calculating $\frac{\partial \Psi_5}{\partial t}$ as stated below:

$$\begin{aligned}
 \frac{\partial \Psi_5}{\partial t} & = \left(1 - \frac{U_5}{U}\right) (d_U \Delta U + \varrho - \varsigma U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) \\
 & + \left(1 - \frac{L_5}{L}\right) [d_L \Delta L + \omega_1 UH + \omega_2 UL + \omega_3 UI - (\beta + \eta)L] \\
 & + \frac{U_5(\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{I_5}{I}\right) (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) \\
 & + \frac{1}{\varphi} \left(1 - \frac{P_5}{P}\right) [d_P \Delta P + \varphi \omega_4 UE + wE - (\theta + b_1)P]
 \end{aligned}$$

$$\begin{aligned}
 & + \frac{\theta + b_1}{\varphi\theta} \left(1 - \frac{E_5}{E}\right) \left(d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E\right) \\
 & + \frac{\omega_1 U_5}{\vartheta} \left(1 - \frac{H_5}{H}\right) \left(d_H \Delta H + \omega I - \vartheta H\right) \\
 & + \frac{\varkappa_1 U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{Z_5^I}{Z^I}\right) \left(d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I\right) \\
 & + \frac{\varkappa_2 (\theta + b_1)}{\varphi\theta v_2} \left(d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E\right). \tag{21}
 \end{aligned}$$

Equation (21) can be simplified as

$$\begin{aligned}
 \frac{\partial \Psi_5}{\partial t} = & \left(1 - \frac{U_5}{U}\right) (\varrho - \zeta U) + \omega_2 U_5 L + \omega_3 U_5 I + \omega_4 U_5 E - (\beta + \eta)L - \omega_1 U H \frac{L_5}{L} \\
 & - \omega_2 U L_5 - \omega_3 U I \frac{L_5}{L} + (\beta + \eta)L_5 + \frac{\beta U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} L - \frac{\alpha U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} I \\
 & - \frac{\beta U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} L \frac{I_5}{I} + \frac{\alpha U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} I_5 + \frac{\varkappa_1 U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} Z^I I_5 + \frac{w}{\varphi} E \\
 & - \omega_4 U E \frac{P_5}{P} - \frac{w}{\varphi} E \frac{P_5}{P} + \frac{\theta + b_1}{\varphi} P_5 - \frac{a(\theta + b_1)}{\varphi\theta} E - \frac{\theta + b_1}{\varphi} P \frac{E_5}{E} + \frac{a(\theta + b_1)}{\varphi\theta} E_5 \\
 & + \frac{\varkappa_2 (\theta + b_1)}{\varphi\theta} Z^E E_5 + \omega_1 U_5 \frac{\omega I}{\vartheta} - \omega_1 U_5 H_5 \frac{\omega I}{\vartheta H} + \omega_1 U_5 H_5 - \frac{\varkappa_1 c_1 U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} Z^I \\
 & - \frac{\varkappa_1 U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} Z_5^I I + \frac{\varkappa_1 c_1 U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} Z_5^I - \frac{\varkappa_2 c_2 (\theta + b_1)}{\varphi\theta v_2} Z^E \\
 & + d_U \left(1 - \frac{U_5}{U}\right) \Delta U + d_L \left(1 - \frac{L_5}{L}\right) \Delta L + \frac{d_I U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{I_5}{I}\right) \Delta I \\
 & + \frac{d_P}{\varphi} \left(1 - \frac{P_5}{P}\right) \Delta P + \frac{d_E (\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_5}{E}\right) \Delta E + \frac{d_H \omega_1 U_5}{\vartheta} \left(1 - \frac{H_5}{H}\right) \Delta H \\
 & + \frac{\varkappa_1 d_{Z^I} U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{Z_5^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E.
 \end{aligned}$$

Using the equilibrium conditions for \mathfrak{S}_5 :

$$\begin{aligned}
 \varrho & = \zeta U_5 + \omega_1 U_5 H_5 + \omega_2 U_5 L_5 + \omega_3 U_5 I_5 + \omega_4 U_5 E_5, \\
 \omega_1 U_5 H_5 + \omega_2 U_5 L_5 + \omega_3 U_5 I_5 & = (\beta + \eta)L_5, \\
 \beta L_5 & = \left(\alpha + \varkappa_1 Z_5^I\right) I_5, \quad I_5 = \frac{c_1}{v_1}, \quad H_5 = \frac{\omega}{\vartheta} I_5, \\
 \omega_4 U_5 E_5 + \frac{w}{\varphi} E_5 & = \frac{\theta + b_1}{\varphi} P_5 = \frac{a(\theta + b_1)}{\varphi\theta} E_5.
 \end{aligned}$$

We obtain

$$\omega_1 U_5 H_5 + \omega_3 U_5 I_5 = \frac{U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta} I_5 = \frac{\beta U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta (\alpha + \varkappa_1 Z_5^I)} L_5.$$

Further, we have

$$\begin{aligned}
 \frac{\partial \Psi_5}{\partial t} = & \left(1 - \frac{U_5}{U}\right) (\zeta U_5 - \zeta U) + (\omega_1 U_5 H_5 + \omega_2 U_5 L_5 + \omega_3 U_5 I_5 + \omega_4 U_5 E_5) \\
 & \times \left(1 - \frac{U_5}{U}\right) - \omega_1 U_5 H_5 \frac{U H L_5}{U_5 H_5 L} - \omega_2 U_5 L_5 \frac{U}{U_5} - \omega_3 U_5 I_5 \frac{U I L_5}{U_5 I_5 L} \\
 & + \omega_1 U_5 H_5 + \omega_2 U_5 L_5 + \omega_3 U_5 I_5 - (\omega_1 U_5 H_5 + \omega_3 U_5 I_5) \frac{L I_5}{L_5 I} + \omega_1 U_5 H_5
 \end{aligned}$$

$$\begin{aligned}
 & + \omega_3 U_5 I_5 - \omega_4 U_5 E_5 \frac{UEP_5}{U_5 E_5 P} - \frac{w}{\varphi} E_5 \frac{EP_5}{E_5 P} + \omega_4 U_5 E_5 + \frac{w}{\varphi} E_5 \\
 & - \omega_4 U_5 E_5 \frac{PE_5}{P_5 E} - \frac{w}{\varphi} E_5 \frac{PE_5}{P_5 E} + \omega_4 U_5 E_5 + \frac{w}{\varphi} E_5 - \omega_1 U_5 H_5 \frac{IH_5}{I_5 H} \\
 & + \omega_1 U_5 H_5 + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} \left(E_5 - \frac{c_2}{v_2} \right) Z^E + d_U \left(1 - \frac{U_5}{U} \right) \Delta U \\
 & + d_L \left(1 - \frac{L_5}{L} \right) \Delta L + \frac{d_I U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{I_5}{I} \right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_5}{P} \right) \\
 & \times \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_5}{E} \right) \Delta E + \frac{d_H \omega_1 U_5}{\vartheta} \left(1 - \frac{H_5}{H} \right) \Delta H \\
 & + \frac{\varkappa_1 d_{Z^I} U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{Z_5^I}{Z^I} \right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E \\
 & = -\zeta \frac{(U - U_5)^2}{U} + \omega_1 U_5 H_5 \left(4 - \frac{U_5}{U} - \frac{UHL_5}{U_5 H_5 L} - \frac{LI_5}{L_5 I} - \frac{IH_5}{I_5 H} \right) \\
 & + \omega_2 U_5 L_5 \left(2 - \frac{U_5}{U} - \frac{U}{U_5} \right) + \omega_3 U_5 I_5 \left(3 - \frac{U_5}{U} - \frac{UIL_5}{U_5 I_5 L} - \frac{LI_5}{L_5 I} \right) \\
 & + \omega_4 U_5 E_5 \left(3 - \frac{U_5}{U} - \frac{UEP_5}{U_5 E_5 P} - \frac{PE_5}{P_5 E} \right) + \frac{w}{\varphi} E_5 \left(2 - \frac{EP_5}{E_5 P} - \frac{PE_5}{P_5 E} \right) \\
 & + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} \left(E_5 - \frac{c_2}{v_2} \right) Z^E + d_U \left(1 - \frac{U_5}{U} \right) \Delta U + d_L \left(1 - \frac{L_5}{L} \right) \Delta L \\
 & + \frac{d_I U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{I_5}{I} \right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_5}{P} \right) \Delta P \\
 & + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_5}{E} \right) \Delta E + \frac{d_H \omega_1 U_5}{\vartheta} \left(1 - \frac{H_5}{H} \right) \Delta H \\
 & + \frac{\varkappa_1 d_{Z^I} U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{Z_5^I}{Z^I} \right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E. \tag{22}
 \end{aligned}$$

Then, Equation (22) will be simplified as follows:

$$\begin{aligned}
 \frac{\partial \Psi_5}{\partial t} & = -(\zeta + \omega_2 L_5) \frac{(U - U_5)^2}{U} - \frac{w}{\varphi} \frac{(EP_5 - PE_5)^2}{PP_5 E} \\
 & + \omega_1 U_5 H_5 \left(4 - \frac{U_5}{U} - \frac{UHL_5}{U_5 H_5 L} - \frac{LI_5}{L_5 I} - \frac{IH_5}{I_5 H} \right) \\
 & + \omega_3 U_5 I_5 \left(3 - \frac{U_5}{U} - \frac{UIL_5}{U_5 I_5 L} - \frac{LI_5}{L_5 I} \right) + \omega_4 U_5 E_5 \left(3 - \frac{U_5}{U} - \frac{UEP_5}{U_5 E_5 P} - \frac{PE_5}{P_5 E} \right) \\
 & + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} (E_5 - E_7) Z^E + d_U \left(1 - \frac{U_5}{U} \right) \Delta U + d_L \left(1 - \frac{L_5}{L} \right) \Delta L \\
 & + \frac{d_I U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{I_5}{I} \right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_5}{P} \right) \Delta P \\
 & + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_5}{E} \right) \Delta E + \frac{d_H \omega_1 U_5}{\vartheta} \left(1 - \frac{H_5}{H} \right) \Delta H \\
 & + \frac{\varkappa_1 d_{Z^I} U_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \left(1 - \frac{Z_5^I}{Z^I} \right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi\theta v_2} \Delta Z^E.
 \end{aligned}$$

Now, along the solution trajectories of Model (4), we calculate $\frac{d\check{\Psi}_5}{dt}$ and utilize Equality (12) to obtain the following result:

$$\begin{aligned} \frac{d\check{\Psi}_5}{dt} = & -(\varsigma + \omega_2 L_5) \int_{\Omega} \frac{(U - U_5)^2}{U} ds - \frac{w}{\varphi} \int_{\Omega} \frac{(EP_5 - PE_5)^2}{PP_5E} ds \\ & + \omega_1 U_5 H_5 \int_{\Omega} \left(4 - \frac{U_5}{U} - \frac{UHL_5}{U_5 H_5 L} - \frac{LI_5}{L_5 I} - \frac{IH_5}{I_5 H} \right) ds \\ & + \omega_3 U_5 I_5 \int_{\Omega} \left(3 - \frac{U_5}{U} - \frac{U I L_5}{U_5 I_5 L} - \frac{L I_5}{L_5 I} \right) ds \\ & + \omega_4 U_5 E_5 \int_{\Omega} \left(3 - \frac{U_5}{U} - \frac{U E P_5}{U_5 E_5 P} - \frac{P E_5}{P_5 E} \right) ds \\ & + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} (E_5 - E_7) \int_{\Omega} Z^E ds - d_U U_5 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds \\ & - d_L L_5 \int_{\Omega} \frac{\|\nabla L\|^2}{L^2} ds - \frac{d_I U_5 I_5 (\omega\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_5^I)} \int_{\Omega} \frac{\|\nabla I\|^2}{I^2} ds \\ & - \frac{d_P P_5}{\varphi} \int_{\Omega} \frac{\|\nabla P\|^2}{P^2} ds - \frac{d_E E_5 (\theta + b_1)}{\varphi\theta} \int_{\Omega} \frac{\|\nabla E\|^2}{E^2} ds \\ & - \frac{d_H \omega_1 U_5 H_5}{\vartheta} \int_{\Omega} \frac{\|\nabla H\|^2}{H^2} ds - \frac{\varkappa_1 d_{Z^I} U_5 Z_5^I (\omega\omega_1 + \vartheta\omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_5^I)} \int_{\Omega} \frac{\|\nabla Z^I\|^2}{(Z^I)^2} ds. \end{aligned}$$

Hence, if $\mathcal{R}_8 \leq 1$, then \check{S}_7 does not exist since $Z_7^E = \frac{(a-w)\theta+ab_1}{\varkappa_2(\theta+b_1)} (\mathcal{R}_8 - 1) \leq 0$. Since the existence of the equilibria does not depend on the diffusion terms, therefore, in the absence of diffusion, we can say $\frac{dZ^E}{dt} = v_2 \left(E - \frac{c_2}{v_2} \right) Z^E \leq 0$ for all $Z^E > 0$. Thus, $E_5 \leq \frac{c_2}{v_2} = E_7$. Hence, from Inequalities (9)–(11), we obtain $\frac{d\check{\Psi}_5}{dt} \leq 0$ for all $U, L, I, P, E, H, Z^I, Z^E > 0$. We also have $\frac{d\check{\Psi}_5}{dt} = 0$ at $(U, L, I, P, E, H, Z^I, Z^E) = (U_5, L_5, I_5, P_5, E_5, H_5, Z_5^I, 0)$. The trajectories of Model (4) are limited to Γ'_5 , and hence, $\Gamma_5 = \{\check{S}_5\}$. Applying L-LAST, we obtain \check{S}_5 is GAS. \square

5.7. Stability of Equilibrium \check{S}_6

To prove the global stability of \check{S}_6 , we need the following lemma:

Lemma 2. *If $\mathcal{R}_7 \leq 1$, then $I_6 \leq I_7$.*

Proof. Let $\mathcal{R}_7 \leq 1$; hence, $\frac{\beta v_1 L_7}{\alpha c_1} \leq 1$, and therefore,

$$\begin{aligned} L_7 \leq \frac{\alpha c_1}{\beta v_1} & \implies \frac{-B_2 + \sqrt{B_2^2 - 4A_2 C_2}}{2A_2} \leq \frac{\alpha c_1}{\beta v_1} \\ \implies \sqrt{B_2^2 - 4A_2 C_2} & \leq \frac{2A_2 \alpha c_1 + \beta v_1 B_2}{\beta v_1} \\ \implies \left(\frac{2A_2 \alpha c_1 + \beta v_1 B_2}{\beta v_1} \right)^2 & + 4A_2 C_2 - B_2^2 \geq 0. \end{aligned}$$

Using Equation (8), we obtain

$$\frac{4\alpha c_1 \vartheta \omega_2 v_1 v_2^2 (\beta + \eta)^2 [\alpha \vartheta \omega_2 + \beta (\omega\omega_1 + \vartheta\omega_3)]}{\beta^2} (I_7 - I_6) \geq 0.$$

Hence, $I_6 \leq I_7$. \square

Theorem 7. The equilibrium \check{S}_6 of Model (4) is GAS when $\mathcal{R}_6 > 1$, $\mathcal{R}_7 \leq 1$, and $\mathcal{R}_2/\mathcal{R}_1 > 1$.

Proof. Define $\Psi_6(s, t)$ as follows:

$$\Psi_6 = U_6 F\left(\frac{U}{U_6}\right) + L_6 F\left(\frac{L}{L_6}\right) + \frac{U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} I_6 F\left(\frac{I}{I_6}\right) + \frac{1}{\varphi} P_6 F\left(\frac{P}{P_6}\right) + \frac{\theta + b_1}{\varphi\theta} E_6 F\left(\frac{E}{E_6}\right) + \frac{\omega_1 U_6}{\vartheta} H_6 F\left(\frac{H}{H_6}\right) + \frac{\varkappa_1 U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I + \frac{\varkappa_2(\theta + b_1)}{\varphi\vartheta v_2} Z_6^E F\left(\frac{Z^E}{Z_6^E}\right).$$

Calculating $\frac{\partial \Psi_6}{\partial t}$ as follows:

$$\begin{aligned} \frac{\partial \Psi_6}{\partial t} &= \left(1 - \frac{U_6}{U}\right) (d_U \Delta U + \varrho - \zeta U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) \\ &+ \left(1 - \frac{L_6}{L}\right) [d_L \Delta L + \omega_1 UH + \omega_2 UL + \omega_3 UI - (\beta + \eta)L] \\ &+ \frac{U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(1 - \frac{I_6}{I}\right) (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) \\ &+ \frac{1}{\varphi} \left(1 - \frac{P_6}{P}\right) [d_P \Delta P + \varphi\omega_4 UE + wE - (\theta + b_1)P] \\ &+ \frac{\theta + b_1}{\varphi\theta} \left(1 - \frac{E_6}{E}\right) (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) \\ &+ \frac{\omega_1 U_6}{\vartheta} \left(1 - \frac{H_6}{H}\right) (d_H \Delta H + \omega I - \vartheta H) \\ &+ \frac{\varkappa_1 U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) \\ &+ \frac{\varkappa_2(\theta + b_1)}{\varphi\vartheta v_2} \left(1 - \frac{Z_6^E}{Z^E}\right) (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E). \end{aligned} \tag{23}$$

Simplifying Equation (23), we derive

$$\begin{aligned} \frac{\partial \Psi_6}{\partial t} &= \left(1 - \frac{U_6}{U}\right) (\varrho - \zeta U) + \omega_2 U_6 L + \omega_3 U_6 I + \omega_4 U_6 E - (\beta + \eta)L - \omega_1 UH \frac{L_6}{L} \\ &- \omega_2 UL_6 - \omega_3 UI \frac{L_6}{L} + (\beta + \eta)L_6 + \frac{\beta U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L - \frac{U_6(\omega\omega_1 + \vartheta\omega_3)}{\vartheta} I \\ &- \frac{\beta U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L \frac{I_6}{I} + \frac{U_6(\omega\omega_1 + \vartheta\omega_3)}{\vartheta} I_6 + \frac{\varkappa_1 U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} Z^I I_6 + \frac{w}{\varphi} E \\ &- \omega_4 UE \frac{P_6}{P} - \frac{w}{\varphi} E \frac{P_6}{P} + \frac{\theta + b_1}{\varphi} P_6 - \frac{a(\theta + b_1)}{\varphi\theta} E - \frac{\theta + b_1}{\varphi} P \frac{E_6}{E} + \frac{a(\theta + b_1)}{\varphi\theta} E_6 \\ &+ \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z^E E_6 + \omega_1 U_6 \frac{\omega I}{\vartheta} - \omega_1 U_6 H_6 \frac{\omega I}{\vartheta H} + \omega_1 U_6 H_6 - \frac{\varkappa_1 c_1 U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} Z^I \\ &- \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\vartheta v_2} Z^E - \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z_6^E E + \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\vartheta v_2} Z_6^E + d_U \left(1 - \frac{U_6}{U}\right) \Delta U \\ &+ d_L \left(1 - \frac{L_6}{L}\right) \Delta L + \frac{d_I U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(1 - \frac{I_6}{I}\right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_6}{P}\right) \Delta P \\ &+ \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_6}{E}\right) \Delta E + \frac{d_H \omega_1 U_6}{\vartheta} \left(1 - \frac{H_6}{H}\right) \Delta H + \frac{\varkappa_1 d_{Z^I} U_6(\omega\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I \\ &+ \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\vartheta v_2} \left(1 - \frac{Z_6^E}{Z^E}\right) \Delta Z^E. \end{aligned}$$

Using the equilibrium conditions for \check{S}_6 :

$$\begin{aligned} \varrho &= \zeta U_6 + \omega_1 U_6 H_6 + \omega_2 U_6 L_6 + \omega_3 U_6 I_6 + \omega_4 U_6 E_6, \\ \omega_1 U_6 H_6 + \omega_2 U_6 L_6 + \omega_3 U_6 I_6 &= (\beta + \eta) L_6, \\ E_6 &= \frac{c_2}{v_2}, \quad H_6 = \frac{\varpi I_6}{\vartheta}, \quad \frac{\beta}{\alpha} L_6 = I_6, \\ \omega_4 U_6 E_6 + \frac{w}{\varphi} E_6 &= \frac{\theta + b_1}{\varphi} P_6 = \frac{a(\theta + b_1)}{\varphi\theta} E_6 + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z_6^E E_6. \end{aligned}$$

It follows that

$$\omega_1 U_6 H_6 + \omega_3 U_6 I_6 = \frac{U_6(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta} I_6 = \frac{\beta U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} L_6.$$

As a result, we obtain

$$\begin{aligned} \frac{\partial \Psi_6}{\partial t} &= \left(1 - \frac{U_6}{U}\right) (\zeta U_6 - \zeta U) + (\omega_1 U_6 H_6 + \omega_2 U_6 L_6 + \omega_3 U_6 I_6 + \omega_4 U_6 E_6) \left(1 - \frac{U_6}{U}\right) \\ &\quad - \omega_1 U_6 H_6 \frac{UHL_6}{U_6 H_6 L} - \omega_2 U_6 L_6 \frac{U}{U_6} - \omega_3 U_6 I_6 \frac{UIL_6}{U_6 I_6 L} + \omega_1 U_6 H_6 + \omega_2 U_6 L_6 + \omega_3 U_6 I_6 \\ &\quad - (\omega_1 U_6 H_6 + \omega_3 U_6 I_6) \frac{LI_6}{L_6 I} + \omega_1 U_6 H_6 + \omega_3 U_6 I_6 - \omega_4 U_6 E_6 \frac{UEP_6}{U_6 E_6 P} - \frac{w}{\varphi} E_6 \frac{EP_6}{E_6 P} \\ &\quad + \omega_4 U_6 E_6 + \frac{w}{\varphi} E_6 - \omega_4 U_6 E_6 \frac{PE_6}{P_6 E} - \frac{w}{\varphi} E_6 \frac{PE_6}{P_6 E} + \omega_4 U_6 E_6 + \frac{w}{\varphi} E_6 \\ &\quad - \omega_1 U_6 H_6 \frac{IH_6}{I_6 H} + \omega_1 U_6 H_6 + \frac{\varkappa_1 U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(I_6 - \frac{c_1}{v_1}\right) Z^I \\ &\quad + d_U \left(1 - \frac{U_6}{U}\right) \Delta U + d_L \left(1 - \frac{L_6}{L}\right) \Delta L + \frac{d_I U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(1 - \frac{I_6}{I}\right) \Delta I \\ &\quad + \frac{d_P}{\varphi} \left(1 - \frac{P_6}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_6}{E}\right) \Delta E + \frac{d_H \omega_1 U_6}{\vartheta} \left(1 - \frac{H_6}{H}\right) \Delta H \\ &\quad + \frac{\varkappa_1 d_{Z^I} U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_6^E}{Z^E}\right) \Delta Z^E \\ &= -\zeta \frac{(U - U_6)^2}{U} + \omega_1 U_6 H_6 \left(4 - \frac{U_6}{U} - \frac{UHL_6}{U_6 H_6 L} - \frac{LI_6}{L_6 I} - \frac{IH_6}{I_6 H}\right) \\ &\quad + \omega_2 U_6 L_6 \left(2 - \frac{U_6}{U} - \frac{U}{U_6}\right) + \omega_3 U_6 I_6 \left(3 - \frac{U_6}{U} - \frac{UIL_6}{U_6 I_6 L} - \frac{LI_6}{L_6 I}\right) \\ &\quad + \omega_4 U_6 E_6 \left(3 - \frac{U_6}{U} - \frac{UEP_6}{U_6 E_6 P} - \frac{PE_6}{P_6 E}\right) + \frac{w}{\varphi} E_6 \left(2 - \frac{EP_6}{E_6 P} - \frac{PE_6}{P_6 E}\right) \\ &\quad + \frac{\varkappa_1 U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(I_6 - \frac{c_1}{v_1}\right) Z^I + d_U \left(1 - \frac{U_6}{U}\right) \Delta U + d_L \left(1 - \frac{L_6}{L}\right) \Delta L \\ &\quad + \frac{d_I U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta} \left(1 - \frac{I_6}{I}\right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_6}{P}\right) \Delta P \\ &\quad + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_6}{E}\right) \Delta E + \frac{d_H \omega_1 U_6}{\vartheta} \left(1 - \frac{H_6}{H}\right) \Delta H \\ &\quad + \frac{\varkappa_1 d_{Z^I} U_6(\varpi\omega_1 + \vartheta\omega_3)}{\alpha\vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_6^E}{Z^E}\right) \Delta Z^E. \end{aligned} \tag{24}$$

Then, Equation (24) will be simplified to

$$\frac{\partial \Psi_6}{\partial t} = -(\zeta + \omega_2 L_6) \frac{(U - U_6)^2}{U} - \frac{w}{\varphi} \frac{(EP_6 - PE_6)^2}{PP_6 E}$$

$$\begin{aligned}
 &+ \omega_1 U_6 H_6 \left(4 - \frac{U_6}{U} - \frac{UHL_6}{U_6 H_6 L} - \frac{LI_6}{L_6 I} - \frac{IH_6}{I_6 H} \right) \\
 &+ \omega_3 U_6 I_6 \left(3 - \frac{U_6}{U} - \frac{UIL_6}{U_6 I_6 L} - \frac{LI_6}{L_6 I} \right) + \omega_4 U_6 E_6 \left(3 - \frac{U_6}{U} - \frac{UEP_6}{U_6 E_6 P} - \frac{PE_6}{P_6 E} \right) \\
 &+ \frac{\varkappa_1 U_6 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} (I_6 - I_7) Z^I + d_U \left(1 - \frac{U_6}{U} \right) \Delta U + d_L \left(1 - \frac{L_6}{L} \right) \Delta L \\
 &+ \frac{d_I U_6 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \left(1 - \frac{I_6}{I} \right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_6}{P} \right) \Delta P \\
 &+ \frac{d_E (\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_6}{E} \right) \Delta E + \frac{d_H \omega_1 U_6}{\vartheta} \left(1 - \frac{H_6}{H} \right) \Delta H \\
 &+ \frac{\varkappa_1 d_{Z^I} U_6 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta v_1} \Delta Z^I + \frac{\varkappa_2 d_{Z^E} (\theta + b_1)}{\varphi \theta v_2} \left(1 - \frac{Z_6^E}{Z^E} \right) \Delta Z^E.
 \end{aligned}$$

Now, along the solution trajectories of Model (4), we calculate $\frac{d\hat{\Psi}_6}{dt}$ and utilize Equality (12) to obtain the following result:

$$\begin{aligned}
 \frac{d\hat{\Psi}_6}{dt} &= -(\zeta + \omega_2 L_6) \int_{\Omega} \frac{(U - U_6)^2}{U} ds - \frac{w}{\varphi} \int_{\Omega} \frac{(EP_6 - PE_6)^2}{PP_6 E} ds \\
 &+ \omega_1 U_6 H_6 \int_{\Omega} \left(4 - \frac{U_6}{U} - \frac{UHL_6}{U_6 H_6 L} - \frac{LI_6}{L_6 I} - \frac{IH_6}{I_6 H} \right) ds \\
 &+ \omega_3 U_6 I_6 \int_{\Omega} \left(3 - \frac{U_6}{U} - \frac{UIL_6}{U_6 I_6 L} - \frac{LI_6}{L_6 I} \right) ds \\
 &+ \omega_4 U_6 E_6 \int_{\Omega} \left(3 - \frac{U_6}{U} - \frac{UEP_6}{U_6 E_6 P} - \frac{PE_6}{P_6 E} \right) ds \\
 &+ \frac{\varkappa_1 U_6 (\omega \omega_1 + \vartheta \omega_3) (I_6 - I_7)}{\alpha \vartheta} \int_{\Omega} Z^I ds - d_U U_6 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds \\
 &- d_L L_6 \int_{\Omega} \frac{\|\nabla L\|^2}{L^2} ds - \frac{d_I U_6 I_6 (\omega \omega_1 + \vartheta \omega_3)}{\alpha \vartheta} \int_{\Omega} \frac{\|\nabla I\|^2}{I^2} ds \\
 &- \frac{d_P P_6}{\varphi} \int_{\Omega} \frac{\|\nabla P\|^2}{P^2} ds - \frac{d_E E_6 (\theta + b_1)}{\varphi \theta} \int_{\Omega} \frac{\|\nabla E\|^2}{E^2} ds \\
 &- \frac{d_H \omega_1 U_6 H_6}{\vartheta} \int_{\Omega} \frac{\|\nabla H\|^2}{H^2} ds - \frac{\varkappa_2 d_{Z^E} Z_6^E (\theta + b_1)}{\varphi \theta v_2} \int_{\Omega} \frac{\|\nabla Z^E\|^2}{(Z^E)^2} ds.
 \end{aligned}$$

Hence, if $\mathcal{R}_7 \leq 1$, then using Lemma 2 to obtain $I_6 \leq I_7$, therefore, using Inequalities (9)–(11), we conclude that $\frac{d\hat{\Psi}_6}{dt} \leq 0$; furthermore, $\frac{d\hat{\Psi}_6}{dt} = 0$ when $(U, L, I, P, E, H, Z^E, Z^I) = (U_6, L_6, I_6, P_6, E_6, H_6, Z_6^E, 0)$. The solutions of Model (4) tend to Γ'_6 , and hence, $\Gamma'_6 = \{\check{S}_6\}$. Applying L-LAST, we obtain that \check{S}_6 is GAS. \square

5.8. Stability of Equilibrium \check{S}_7

Theorem 8. The equilibrium \check{S}_7 of Model (4) is GAS when $\mathcal{R}_7 > 1$ and $\mathcal{R}_8 > 1$.

Proof. Define $\Psi_7(s, t)$ as follows:

$$\begin{aligned}
 \Psi_7 &= U_7 F\left(\frac{U}{U_7}\right) + L_7 F\left(\frac{L}{L_7}\right) + \frac{U_7 (\omega \omega_1 + \vartheta \omega_3)}{\vartheta (\alpha + \varkappa_1 Z_7^I)} I_7 F\left(\frac{I}{I_7}\right) + \frac{1}{\varphi} P_7 F\left(\frac{P}{P_7}\right) + \frac{\theta + b_1}{\varphi \theta} E_7 F\left(\frac{E}{E_7}\right) \\
 &+ \frac{\omega_1 U_7}{\vartheta} H_7 F\left(\frac{H}{H_7}\right) + \frac{\varkappa_1 U_7 (\omega \omega_1 + \vartheta \omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_7^I)} Z_7^I F\left(\frac{Z^I}{Z_7^I}\right) + \frac{\varkappa_2 (\theta + b_1)}{\varphi \theta v_2} Z_7^E F\left(\frac{Z^E}{Z_7^E}\right).
 \end{aligned}$$

Calculating $\frac{\partial \Psi_7}{\partial t}$ as follows:

$$\begin{aligned} \frac{\partial \Psi_7}{\partial t} = & \left(1 - \frac{U_7}{U}\right) (d_U \Delta U + \varrho - \zeta U - \omega_1 UH - \omega_2 UL - \omega_3 UI - \omega_4 UE) \\ & + \left(1 - \frac{L_7}{L}\right) [d_L \Delta L + \omega_1 UH + \omega_2 UL + \omega_3 UI - (\beta + \eta)L] \\ & + \frac{U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{I_7}{I}\right) (d_I \Delta I + \beta L - \alpha I - \varkappa_1 Z^I I) \\ & + \frac{1}{\varphi} \left(1 - \frac{P_7}{P}\right) [d_P \Delta P + \varphi\omega_4 UE + wE - (\theta + b_1)P] \\ & + \frac{\theta + b_1}{\varphi\theta} \left(1 - \frac{E_7}{E}\right) (d_E \Delta E + \theta P - aE - \varkappa_2 Z^E E) \\ & + \frac{\omega_1 U_7}{\vartheta} \left(1 - \frac{H_7}{H}\right) (d_H \Delta H + \varpi I - \vartheta H) \\ & + \frac{\varkappa_1 U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{Z_7^I}{Z^I}\right) (d_{Z^I} \Delta Z^I + v_1 Z^I I - c_1 Z^I) \\ & + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_7^E}{Z^E}\right) (d_{Z^E} \Delta Z^E + v_2 Z^E E - c_2 Z^E). \end{aligned} \tag{25}$$

Simplifying Equation (25), we derive

$$\begin{aligned} \frac{\partial \Psi_7}{\partial t} = & \left(1 - \frac{U_7}{U}\right) (\varrho - \zeta U) + \omega_2 U_7 L + \omega_3 U_7 I + \omega_4 U_7 E - (\beta + \eta)L - \omega_1 UH \frac{L_7}{L} \\ & - \omega_2 UL_7 - \omega_3 UI \frac{L_7}{L} + (\beta + \eta)L_7 + \frac{\beta U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} L - \frac{\alpha U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} I \\ & - \frac{\beta U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} L \frac{I_7}{I} + \frac{\alpha U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} I_7 + \frac{\varkappa_1 U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} Z^I I_7 \\ & + \frac{w}{\varphi} E - \omega_4 UE \frac{P_7}{P} - \frac{w}{\varphi} E \frac{P_7}{P} + \frac{\theta + b_1}{\varphi} P_7 - \frac{a(\theta + b_1)}{\varphi\theta} E - \frac{\theta + b_1}{\varphi} P \frac{E_7}{E} \\ & + \frac{a(\theta + b_1)}{\varphi\theta} E_7 + \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z^E E_7 + \omega_1 U_7 \frac{\varpi I}{\vartheta} - \omega_1 U_7 H_7 \frac{\varpi I}{\vartheta H} + \omega_1 U_7 H_7 \\ & - \frac{\varkappa_1 c_1 U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} Z^I - \frac{\varkappa_1 U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} Z_7^I I + \frac{\varkappa_1 c_1 U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} Z_7^I \\ & - \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z^E - \frac{\varkappa_2(\theta + b_1)}{\varphi\theta} Z_7^E E + \frac{\varkappa_2 c_2(\theta + b_1)}{\varphi\theta v_2} Z_7^E + d_U \left(1 - \frac{U_7}{U}\right) \Delta U \\ & + d_L \left(1 - \frac{L_7}{L}\right) \Delta L + \frac{d_I U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{I_7}{I}\right) \Delta I + \frac{d_P}{\varphi} \left(1 - \frac{P_7}{P}\right) \Delta P \\ & + \frac{d_E(\theta + b_1)}{\varphi\theta} \left(1 - \frac{E_7}{E}\right) \Delta E + \frac{d_H \omega_1 U_7}{\vartheta} \left(1 - \frac{H_7}{H}\right) \Delta H \\ & + \frac{\varkappa_1 d_{Z^I} U_7(\varpi\omega_1 + \vartheta\omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{Z_7^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi\theta v_2} \left(1 - \frac{Z_7^E}{Z^E}\right) \Delta Z^E. \end{aligned}$$

The equilibrium conditions for \check{S}_7 give

$$\begin{aligned} \varrho &= \zeta U_7 + \omega_1 U_7 H_7 + \omega_2 U_7 L_7 + \omega_3 U_7 I_7 + \omega_4 U_7 E_7, \\ \omega_1 U_7 H_7 + \omega_2 U_7 L_7 + \omega_3 U_7 I_7 &= (\beta + \eta)L_7, \\ \beta L_7 &= (\alpha + \varkappa_1 Z_7^I) I_7, \quad I_7 = \frac{c_1}{v_1}, \quad E_7 = \frac{c_2}{v_2}, \quad H_7 = \frac{\varpi I_7}{\vartheta} \end{aligned}$$

$$\omega_4 U_7 E_7 + \frac{w}{\varphi} E_7 = \frac{\theta + b_1}{\varphi} P_7 = \frac{a(\theta + b_1)}{\varphi \theta} E_7 + \frac{\varkappa_2(\theta + b_1)}{\varphi \theta} Z_7^E E_7.$$

This implies that

$$\omega_1 U_7 H_7 + \omega_3 U_7 I_7 = \frac{U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta} I_7 = \frac{\beta U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} L_7.$$

In addition, we obtain

$$\begin{aligned} \frac{\partial \Psi_7}{\partial t} &= \left(1 - \frac{U_7}{U}\right) (\zeta U_7 - \zeta U) + (\omega_1 U_7 H_7 + \omega_2 U_7 L_7 + \omega_3 U_7 I_7 + \omega_4 U_7 E_7) \left(1 - \frac{U_7}{U}\right) \\ &\quad - \omega_1 U_7 H_7 \frac{UHL_7}{U_7 H_7 L} - \omega_2 U_7 L_7 \frac{U}{U_7} - \omega_3 U_7 I_7 \frac{UIL_7}{U_7 I_7 L} + \omega_1 U_7 H_7 + \omega_2 U_7 L_7 + \omega_3 U_7 I_7 \\ &\quad - (\omega_1 U_7 H_7 + \omega_3 U_7 I_7) \frac{LI_7}{L_7 I} + \omega_1 U_7 H_7 + \omega_3 U_7 I_7 - \omega_4 U_7 E_7 \frac{UEP_7}{U_7 E_7 P} - \frac{w}{\varphi} E_7 \frac{EP_7}{E_7 P} \\ &\quad + \omega_4 U_7 E_7 + \frac{w}{\varphi} E_7 - \omega_4 U_7 E_7 \frac{PE_7}{P_7 E} - \frac{w}{\varphi} E_7 \frac{PE_7}{P_7 E} + \omega_4 U_7 E_7 + \frac{w}{\varphi} E_7 - \omega_1 U_7 H_7 \frac{IH_7}{I_7 H} \\ &\quad + \omega_1 U_7 H_7 + d_U \left(1 - \frac{U_7}{U}\right) \Delta U + d_L \left(1 - \frac{L_7}{L}\right) \Delta L + \frac{d_I U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{I_7}{I}\right) \Delta I \\ &\quad + \frac{d_P}{\varphi} \left(1 - \frac{P_7}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_7}{E}\right) \Delta E + \frac{d_H \omega_1 U_7}{\vartheta} \left(1 - \frac{H_7}{H}\right) \Delta H \\ &\quad + \frac{\varkappa_1 d_{Z^I} U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{Z_7^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi \theta v_2} \left(1 - \frac{Z_7^E}{Z^E}\right) \Delta Z^E \\ &= -(\zeta + \omega_2 L_7) \frac{(U - U_7)^2}{U} - \frac{w}{\varphi} \frac{(EP_7 - PE_7)^2}{PP_7 E} \\ &\quad + \omega_1 U_7 H_7 \left(4 - \frac{U_7}{U} - \frac{UHL_7}{U_7 H_7 L} - \frac{LI_7}{L_7 I} - \frac{IH_7}{I_7 H}\right) \\ &\quad + \omega_3 U_7 I_7 \left(3 - \frac{U_7}{U} - \frac{UIL_7}{U_7 I_7 L} - \frac{LI_7}{L_7 I}\right) + \omega_4 U_7 E_7 \left(3 - \frac{U_7}{U} - \frac{UEP_7}{U_7 E_7 P} - \frac{PE_7}{P_7 E}\right) \\ &\quad + d_U \left(1 - \frac{U_7}{U}\right) \Delta U + d_L \left(1 - \frac{L_7}{L}\right) \Delta L + \frac{d_I U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{I_7}{I}\right) \Delta I \\ &\quad + \frac{d_P}{\varphi} \left(1 - \frac{P_7}{P}\right) \Delta P + \frac{d_E(\theta + b_1)}{\varphi \theta} \left(1 - \frac{E_7}{E}\right) \Delta E + \frac{d_H \omega_1 U_7}{\vartheta} \left(1 - \frac{H_7}{H}\right) \Delta H \\ &\quad + \frac{\varkappa_1 d_{Z^I} U_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta v_1(\alpha + \varkappa_1 Z_7^I)} \left(1 - \frac{Z_7^I}{Z^I}\right) \Delta Z^I + \frac{\varkappa_2 d_{Z^E}(\theta + b_1)}{\varphi \theta v_2} \left(1 - \frac{Z_7^E}{Z^E}\right) \Delta Z^E. \end{aligned}$$

Calculating $\frac{d\hat{\Psi}_7}{dt}$ and using Equality (12), we find

$$\begin{aligned} \frac{d\hat{\Psi}_7}{dt} &= -(\zeta + \omega_2 L_7) \int_{\Omega} \frac{(U - U_7)^2}{U} ds - \frac{w}{\varphi} \int_{\Omega} \frac{(EP_7 - PE_7)^2}{PP_7 E} ds \\ &\quad + \omega_1 U_7 H_7 \int_{\Omega} \left(4 - \frac{U_7}{U} - \frac{UHL_7}{U_7 H_7 L} - \frac{LI_7}{L_7 I} - \frac{IH_7}{I_7 H}\right) ds \\ &\quad + \omega_3 U_7 I_7 \int_{\Omega} \left(3 - \frac{U_7}{U} - \frac{UIL_7}{U_7 I_7 L} - \frac{LI_7}{L_7 I}\right) ds + \omega_4 U_7 E_7 \int_{\Omega} \left(3 - \frac{U_7}{U} - \frac{UEP_7}{U_7 E_7 P} - \frac{PE_7}{P_7 E}\right) ds \\ &\quad - d_U U_7 \int_{\Omega} \frac{\|\nabla U\|^2}{U^2} ds - d_L L_7 \int_{\Omega} \frac{\|\nabla L\|^2}{L^2} ds - \frac{d_I U_7 I_7(\omega \omega_1 + \vartheta \omega_3)}{\vartheta(\alpha + \varkappa_1 Z_7^I)} \int_{\Omega} \frac{\|\nabla I\|^2}{I^2} ds \\ &\quad - \frac{d_P P_7}{\varphi} \int_{\Omega} \frac{\|\nabla P\|^2}{P^2} ds - \frac{d_E E_7(\theta + b_1)}{\varphi \theta} \int_{\Omega} \frac{\|\nabla E\|^2}{E^2} ds - \frac{d_H \omega_1 U_7 H_7}{\vartheta} \int_{\Omega} \frac{\|\nabla H\|^2}{H^2} ds \end{aligned}$$

$$-\frac{\varkappa_1 d_{Z^I} U_7 Z_7^I (\omega \omega_1 + \vartheta \omega_3)}{\vartheta v_1 (\alpha + \varkappa_1 Z_7^I)} \int_{\Omega} \frac{\|\nabla Z^I\|^2}{(Z^I)^2} ds - \frac{\varkappa_2 d_{Z^E} Z_7^E (\theta + b_1)}{\varphi \theta v_2} \int_{\Omega} \frac{\|\nabla Z^E\|^2}{(Z^E)^2} ds.$$

Inequalities (9)–(11) imply that $\frac{d\check{\Psi}_7}{dt} \leq 0$ where $\frac{d\check{\Psi}_7}{dt} = 0$ occurs at \check{S}_7 . The solutions of Model (4) are limited to $\Gamma'_7 = \{\check{S}_7\}$. Applying L-LAST, we obtain that \check{S}_7 is GAS. \square

Let $X = (U, L, I, P, E, H, Z^I, Z^E) \in \mathbb{R}^8$ with the norm $\|X\| = |U| + |L| + |I| + |P| + |E| + |H| + |Z^I| + |Z^E|$. By a simple computation, we have $\Psi_i(X) \rightarrow \infty$ as $\|X\| \rightarrow \infty$. Hence, the Lyapunov functions $\Psi_i, i = 0, 1, \dots, 7$ considered in the proofs of Theorems 1–8 are unbounded. In addition, Table 1 summarizes the results obtained in these theorems.

Table 1. Global stability conditions for the equilibria of Model (4).

Equilibrium	Global Stability Conditions
\check{S}_0	$\mathcal{R}_1 \leq 1$ and $\mathcal{R}_2 \leq 1$
\check{S}_1	$\mathcal{R}_1 > 1, \mathcal{R}_2/\mathcal{R}_1 \leq 1$ and $\mathcal{R}_3 \leq 1$
\check{S}_2	$\mathcal{R}_2 > 1, \mathcal{R}_1/\mathcal{R}_2 \leq 1$ and $\mathcal{R}_4 \leq 1$
\check{S}_3	$\mathcal{R}_3 > 1$ and $\mathcal{R}_5 \leq 1$
\check{S}_4	$\mathcal{R}_4 > 1$ and $\mathcal{R}_6 \leq 1$
\check{S}_5	$\hat{\mathcal{R}}_5, \mathcal{R}_5 > 1, \mathcal{R}_8 \leq 1$ and $\mathcal{R}_1/\mathcal{R}_2 > 1$
\check{S}_6	$\mathcal{R}_6 > 1, \mathcal{R}_7 \leq 1$ and $\mathcal{R}_2/\mathcal{R}_1 > 1$
\check{S}_7	$\mathcal{R}_7 > 1$ and $\mathcal{R}_8 > 1$

6. Numerical Simulations

This part illustrates the global stability of equilibria using numerical simulations based on the parameters listed in Table 2; some values of these parameters for HIV were obtained from [57]. To numerically solve the system of PDEs, we used the solver PDEPE in MATLAB (see the code given in the link given in [58]: <https://www.mdpi.com/article/10.3390/math10224390/s1> (accessed on 15 January 2023)). Additionally, a comparison study between mono-infection and co-infection dynamics will be demonstrated. We selected a step size of 0.1 for time $t > 0$ and a domain Ω as $\Omega = [0, 2]$ with a step size of 0.02. In addition, we considered Model (1) under the initial conditions:

$$\begin{aligned} U(s, 0) &= 500 [1 + 0.2 \cos^2(\pi s)], & L(s, 0) &= 10 [1 + 0.5 \cos^2(\pi s)], \\ I(s, 0) &= 2 [1 + 0.5 \cos^2(\pi s)], & P(s, 0) &= 20 [1 + 0.5 \cos^2(\pi s)], \\ E(s, 0) &= 0.2 [1 + 0.5 \cos^2(\pi s)], & H(s, 0) &= 4 [1 + 0.5 \cos^2(\pi s)], \\ Z^I(s, 0) &= 4 [1 + 0.5 \cos^2(\pi s)], & Z^E(s, 0) &= 1.5 [1 + 0.5 \cos^2(\pi s)], \end{aligned} \quad s \in [0, 2], \quad (26)$$

and the homogeneous Neumann boundary conditions:

$$\frac{\partial U}{\partial \bar{\rho}} = \frac{\partial L}{\partial \bar{\rho}} = \frac{\partial I}{\partial \bar{\rho}} = \frac{\partial P}{\partial \bar{\rho}} = \frac{\partial E}{\partial \bar{\rho}} = \frac{\partial H}{\partial \bar{\rho}} = \frac{\partial Z^I}{\partial \bar{\rho}} = \frac{\partial Z^E}{\partial \bar{\rho}} = 0, \quad t > 0, \quad s = 0, 2. \quad (27)$$

Table 2. List of parameters of Model (1).

Parameter	Value	Parameter	Value	Parameter	Value	Parameter	Value
ϱ	10	ε	0.9	ϑ	2	d_L	0.1
ς	0.01	b	0.008	η	0.02	d_I	0.01
ω_1	Varied	b_2	0.2	v_1	Varied	d_P	0.01
ω_2	Varied	ω	5	v_2	Varied	d_E	0.2
ω_3	Varied	c_1	0.1	β	0.2	d_H	0.01
ω_4	Varied	c_2	0.1	b_1	0.01	d_{Z^I}	0.2
α	0.5	\varkappa_1	0.2	θ	0.003	d_{Z^E}	0.2
φ	0.2	\varkappa_2	0.2	d_U	0.1		

6.1. Stability of the Equilibria

Under the above initial and boundary conditions, we chose various values of the parameters $\omega_1, \omega_2, \omega_3, \omega_4, v_1,$ and $v_2,$ which yielded the following cases:

- (1) We picked $\omega_1 = 0.00006, \omega_2 = 0.00005, \omega_3 = 0.00007, \omega_4 = 0.001, v_1 = 0.3,$ and $v_2 = 0.5.$ For this set of parameters, we have $\mathcal{R}_1 = 0.63 < 1$ and $\mathcal{R}_2 = 0.23 < 1.$ As shown in Figure 1, the solution of Model (1) reaches the equilibrium $\check{S}_0 = (1000, 0, 0, 0, 0, 0, 0, 0).$ This shows that \check{S}_0 is GAS in accordance with Theorem 1. Both HTLV and HIV will be removed in this case.
- (2) We selected $\omega_1 = 0.0001, \omega_2 = 0.0002, \omega_3 = 0.0003, \omega_4 = 0.0005, v_1 = 0.003,$ and $v_2 = 0.2.$ With such a choice, we obtained $\mathcal{R}_2 = 0.12 < 1 < 1.91 = \mathcal{R}_1,$ $\mathcal{R}_3 = 0.39 < 1,$ and hence, $\mathcal{R}_2/\mathcal{R}_1 = 0.06 < 1.$ Theorem 2 implies that $\check{S}_1 = (523.81, 21.65, 8.66, 0, 0, 21.65, 0, 0)$ is GAS, which is displayed in Figure 2. As a result, HIV mono-infection will persist, but with an inefficient CTL immune response.
- (3) We set $\omega_1 = 0.0001, \omega_2 = 0.00005, \omega_3 = 0.00007, \omega_4 = 0.006, v_1 = 0.001,$ and $v_2 = 0.05.$ Then, we calculated $\mathcal{R}_1 = 0.81 < 1 < 1.4 = \mathcal{R}_2, \mathcal{R}_4 = 0.64 < 1,$ and then, $\mathcal{R}_1/\mathcal{R}_2 = 0.58 < 1.$ The numerical results showed that $\check{S}_2 = (713.33, 0, 0, 44.47, 0.67, 0, 0, 0)$ exists. Figure 3 illustrates that \check{S}_2 is GAS. It is evident from this that the numerical outcomes and the theoretical finding of Theorem 3 are consistent. Therefore, a persistent HTLV mono-infection with an inefficient CTL immunity is present.
- (4) We took $\omega_1 = 0.001, \omega_2 = 0.0001, \omega_3 = 0.0003, \omega_4 = 0.001, v_1 = 0.05,$ and $v_2 = 0.005$ to yield $\mathcal{R}_3 = 3.91 > 1$ and $\mathcal{R}_5 = 0.22 < 1.$ Figure 4 shows that $\check{S}_3 = (569.59, 19.56, 2, 0, 0, 5, 7.28, 0)$ is GAS based on Theorem 4. Therefore, a persistent HIV mono-infection with an efficient HIV-specific CTL immune response is reached.
- (5) We set $\omega_1 = \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.035, v_1 = 0.05,$ and $v_2 = 0.4.$ Then, we calculated $\mathcal{R}_4 = 4.35 > 1$ and $\mathcal{R}_6 = 0.68 < 1.$ According to these data, \check{S}_4 exists and is given by $\check{S}_4 = (533.33, 0, 0, 71.93, 0.25, 0, 0, 3.32).$ In Figure 5, we show that \check{S}_4 is GAS, which is consistent with Theorem 5. There is a persistent HTLV mono-infection in this case, with efficient HTLV-specific CTL immunity.
- (6) We chose $\omega_1 = 0.001, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.011, v_1 = 0.1,$ and $v_2 = 0.01.$ Hence, we have $\hat{\mathcal{R}}_5 = 5.64 > 1, \mathcal{R}_5 = 1.93 > 1, \mathcal{R}_8 = 0.21 < 1,$ and $\mathcal{R}_1/\mathcal{R}_2 = 2.09 > 1.$ The numerical outcomes displayed in Figure 6 confirmed the existence and global stability of $\check{S}_5 = (389.09, 5.80, 1, 74.98, 1.13, 2.5, 3.30, 0).$ Theorem 6 is, therefore, affirmed by this result. In this case, there is a persistent co-infection with HTLV and HIV together with an efficient HIV-specific CTL immunity, whereas the HTLV-specific CTL immunity is an inefficient.
- (7) We picked $\omega_1 = 0.0006, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.04, v_1 = 0.001,$ and $v_2 = 0.7.$ This gives $\mathcal{R}_6 = 2.26 > 1, \mathcal{R}_7 = 0.17 < 1,$ and $\mathcal{R}_2/\mathcal{R}_1 = 2.63 > 1.$ As can be seen from Figure 7, the equilibrium $\check{S}_6 = (282.05, 25.31, 10.12, 24.87, 0.143, 25.31, 0, 1.62)$ is GAS, and this is a confirmation of Theorem 7. In such a case, a persistent co-infection with HTLV and HIV occurs together with the effective HTLV-specific CTL immunity; however, the HIV-specific CTL immunity is not working.
- (8) We chose $\omega_1 = 0.0006, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.03, v_1 = 0.04,$ and $v_2 = 0.5.$ These data give $\mathcal{R}_7 = 1.83 > 1$ and $\mathcal{R}_8 = 3.27 > 1.$ Figure 8 illustrates that $\check{S}_7 = (467.37, 11.46, 2.5, 43.25, 0.2, 6.25, 2.09, 2.25)$ is GAS. Theorem 8 is, therefore, confirmed. Consequently, a persistent co-infection with HTLV and HIV occurs where the immune system is functioning well.

6.2. Comparison Study

We compare mono- and co-infection dynamics in this part, through studying the effect of one of the infections (HIV infection or HTLV infection) on the dynamical behavior of the other mono-infection as in the following points:

- (i) The impact of HTLV infection on the dynamical behavior of HIV mono-infection:

The following HIV mono-infection model was compared with Model (1) in order to determine the impact of HTLV infections on HIV mono-infection dynamics:

$$\begin{cases} \frac{\partial U(s,t)}{\partial t} = d_U \Delta U(s,t) + \rho - \zeta U(s,t) - \omega_1 U(s,t)H(s,t) \\ \quad - \omega_2 U(s,t)L(s,t) - \omega_3 U(s,t)I(s,t), \\ \frac{\partial L(s,t)}{\partial t} = d_L \Delta L(s,t) + \omega_1 U(s,t)H(s,t) + \omega_2 U(s,t)L(s,t) \\ \quad + \omega_3 U(s,t)I(s,t) - (\beta + \eta)L(s,t), \\ \frac{\partial I(s,t)}{\partial t} = d_I \Delta I(s,t) + \beta L(s,t) - \alpha I(s,t) - \varkappa_1 Z^I(s,t)I(s,t), \\ \frac{\partial H(s,t)}{\partial t} = d_H \Delta H(s,t) + \omega I(s,t) - \theta H(s,t), \\ \frac{\partial Z^I(s,t)}{\partial t} = d_{Z^I} \Delta Z^I(s,t) + v_1 Z^I(s,t)I(s,t) - c_1 Z^I(s,t). \end{cases} \tag{28}$$

The comparison was made through the following considerations:

- The parameters $\omega_1 = 0.0006$, $\omega_2 = 0.0002$, $\omega_3 = 0.0004$, $v_1 = 0.05$, and $v_2 = 0.5$ are fixed.
- Both the initial conditions (26) and boundary conditions (27) were taken into consideration.
- We chose $\omega_4 = 0.07$ (in the case of HTLV/HIV co-infection dynamics).

As shown in Figure 9, patients with only HIV who are co-infected with HTLV have lower levels of CD4⁺T cells (both latent and healthy), as well as HIV-specific CTLs. On the other hand, the concentration of free HIV particles reaches the same level in both HIV mono-infection and HTLV/HIV co-infection. Actually, this finding is compatible with the results of a recently published paper [59], where the study indicated that there are no discernible contrasts between HIV mono-infected and HTLV/HIV co-infected in terms of the number of HIV particles.

- (ii) The impact of HIV infection on the dynamical behavior of HTLV mono-infection: In order to know how HIV infection influences the HTLV mono-infection dynamics, we compared Model (1) with an HTLV mono-infection model as given below:

$$\begin{cases} \frac{\partial U(s,t)}{\partial t} = d_U \Delta U(s,t) + \rho - \zeta U(s,t) - \omega_4 U(s,t)E(s,t), \\ \frac{\partial P(s,t)}{\partial t} = d_P \Delta P(s,t) + \varphi \omega_4 U(s,t)E(s,t) + \varepsilon b E(s,t) \\ \quad - (\theta + b_1)P(s,t), \\ \frac{\partial E(s,t)}{\partial t} = d_E \Delta E(s,t) + \theta P(s,t) + (1 - \varepsilon)b E(s,t) \\ \quad - b_2 E(s,t) - \varkappa_2 Z^E(s,t)E(s,t), \\ \frac{\partial Z^E(s,t)}{\partial t} = d_{Z^E} \Delta Z^E(s,t) + v_2 Z^E(s,t)E(s,t) - c_2 Z^E(s,t). \end{cases} \tag{29}$$

To make the comparison, we took into account the following factors:

- The parameters $\omega_4 = 0.01$, $v_1 = 0.05$, and $v_2 = 0.5$ are fixed.
- The initial conditions (26) and boundary conditions (27) were considered.
- We picked $\omega_1 = 0.0005$, $\omega_2 = 0.0002$, and $\omega_3 = 0.0003$ (in the case of HTLV/HIV co-infection dynamics).

The solutions of Models (1) and (29) are shown by Figure 10. We noticed that, in the case of co-infection, the densities of CD4⁺T cells (both latent and healthy) and HTLV-specific CTLs are less than those in the case of HTLV mono-infection. However, both HTLV mono-infection and HTLV/HIV co-infection have the same level of density of active HTLV-infected cells.

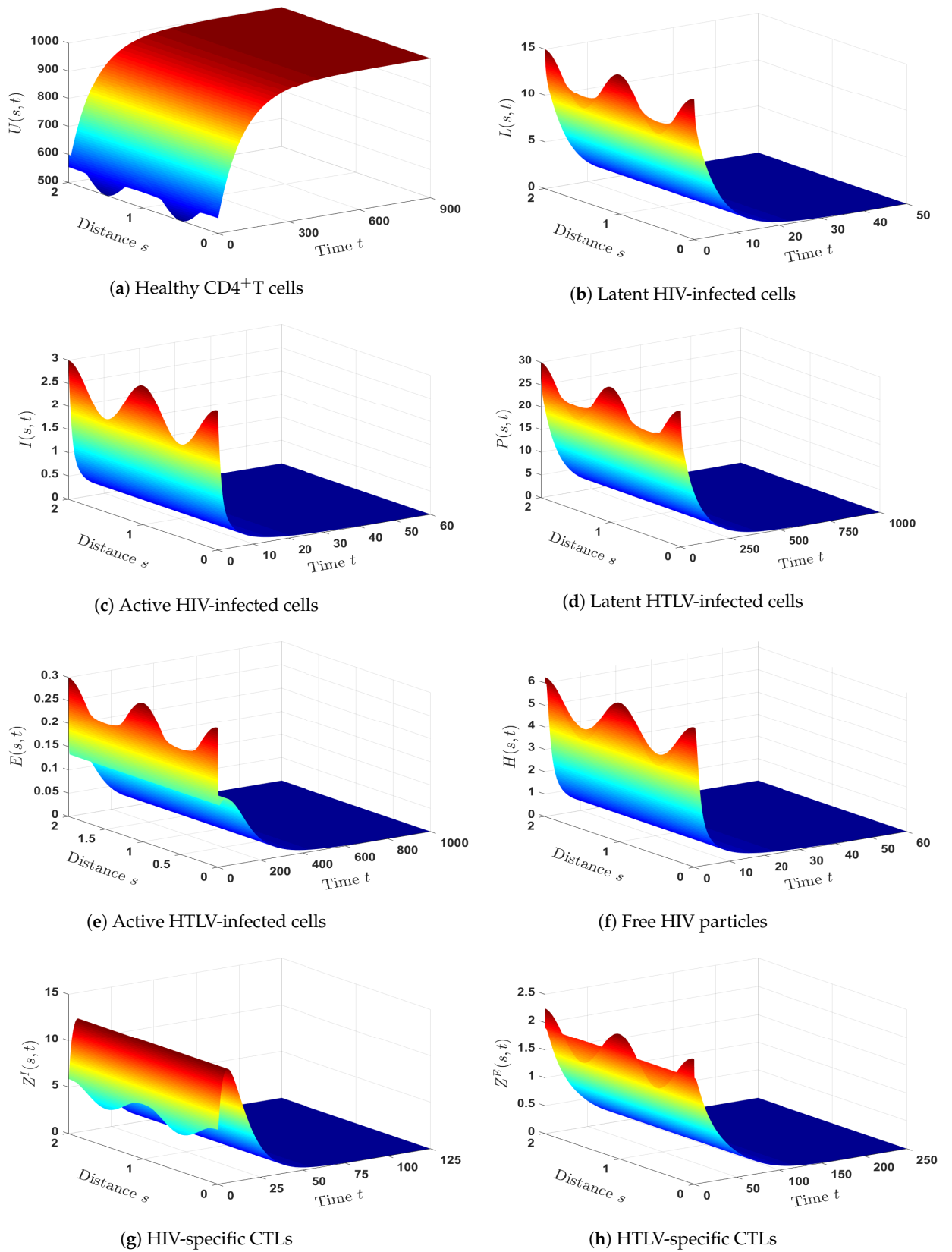


Figure 1. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.00006, \omega_2 = 0.00005, \omega_3 = 0.00007, \omega_4 = 0.001, v_1 = 0.3, v_2 = 0.5$, we have $\mathcal{R}_1 = 0.63 < 1, \mathcal{R}_2 = 0.23 < 1$, and the equilibrium $\check{S}_0 = (1000, 0, 0, 0, 0, 0, 0)$ is asymptotically stable.

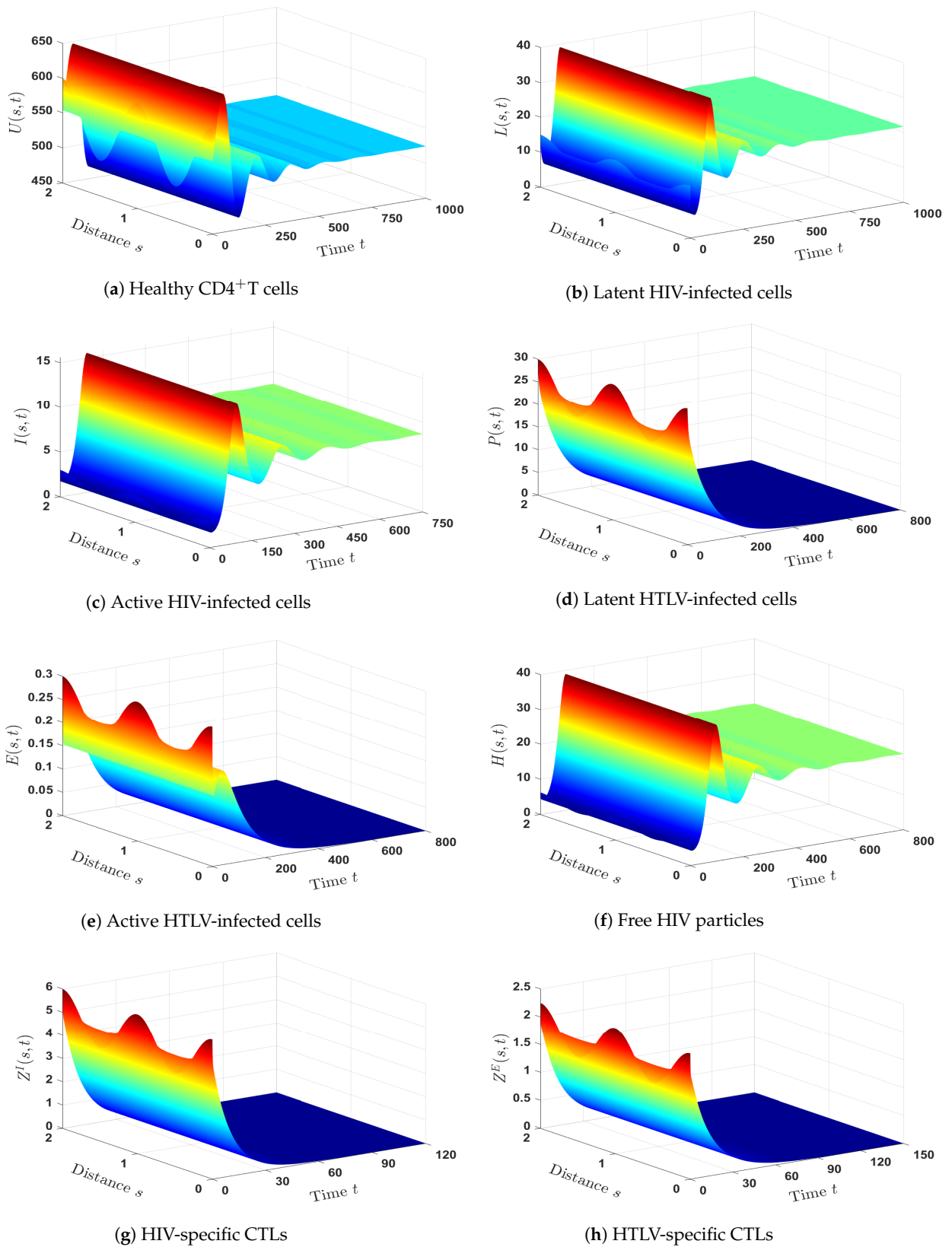


Figure 2. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.0001, \omega_2 = 0.0002, \omega_3 = 0.0003, \omega_4 = 0.0005, v_1 = 0.003, v_2 = 0.2$, we have $\mathcal{R}_1 = 1.91 > 1, \mathcal{R}_2/\mathcal{R}_1 = 0.063 < 1, \mathcal{R}_3 = 0.39 < 1$, and the equilibrium $\check{S}_1 = (523.81, 21.65, 8.66, 0, 0, 21.65, 0, 0)$ is asymptotically stable.

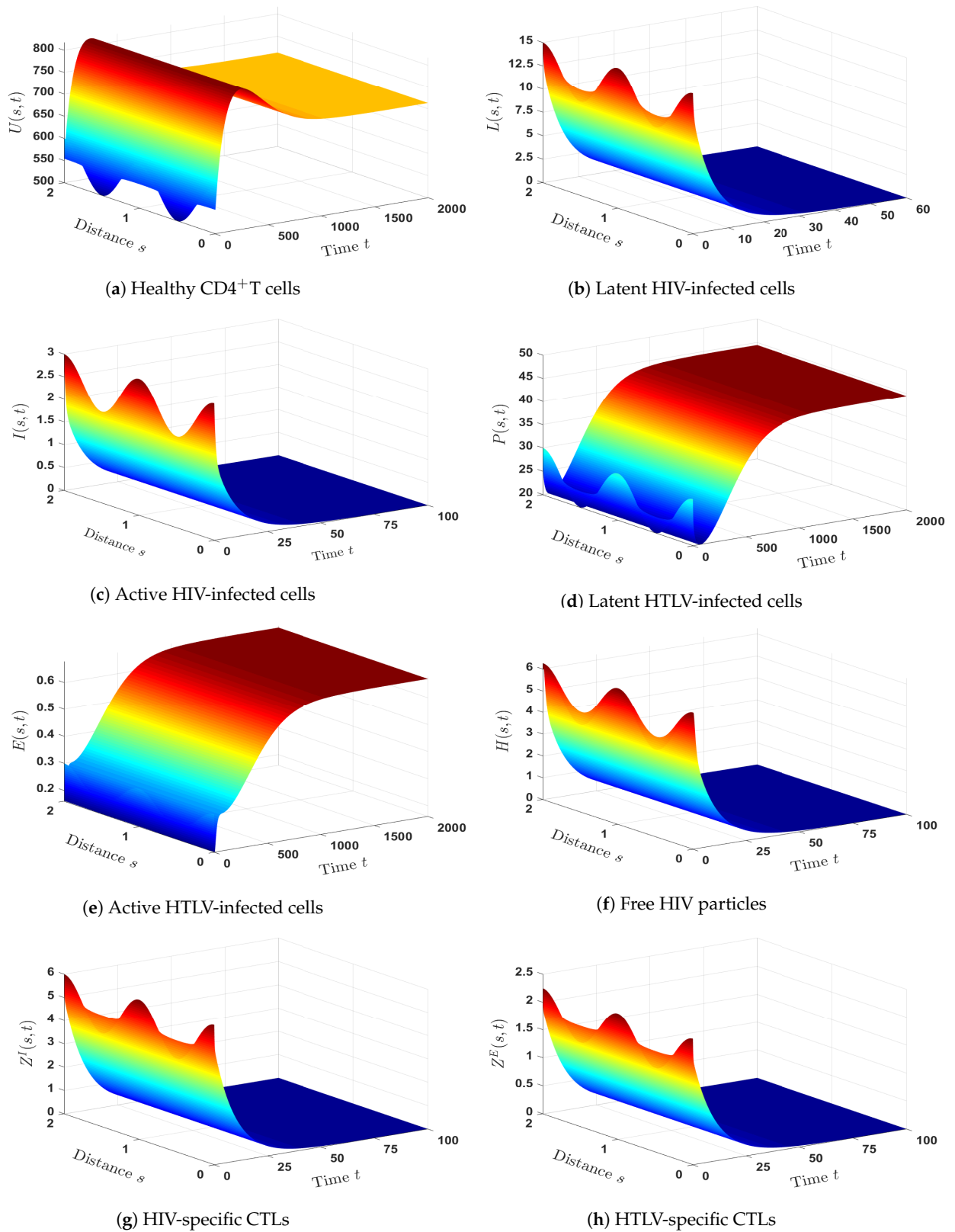


Figure 3. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.0001, \omega_2 = 0.00005, \omega_3 = 0.00007, \omega_4 = 0.006, v_1 = 0.001, v_2 = 0.05$, we have $\mathcal{R}_2 = 1.4 > 1, \mathcal{R}_1/\mathcal{R}_2 = 0.58 < 1, \mathcal{R}_4 = 0.64 < 1$, and the equilibrium $\check{S}_2 = (713.33, 0, 0, 44.47, 0.67, 0, 0, 0)$ is asymptotically stable.

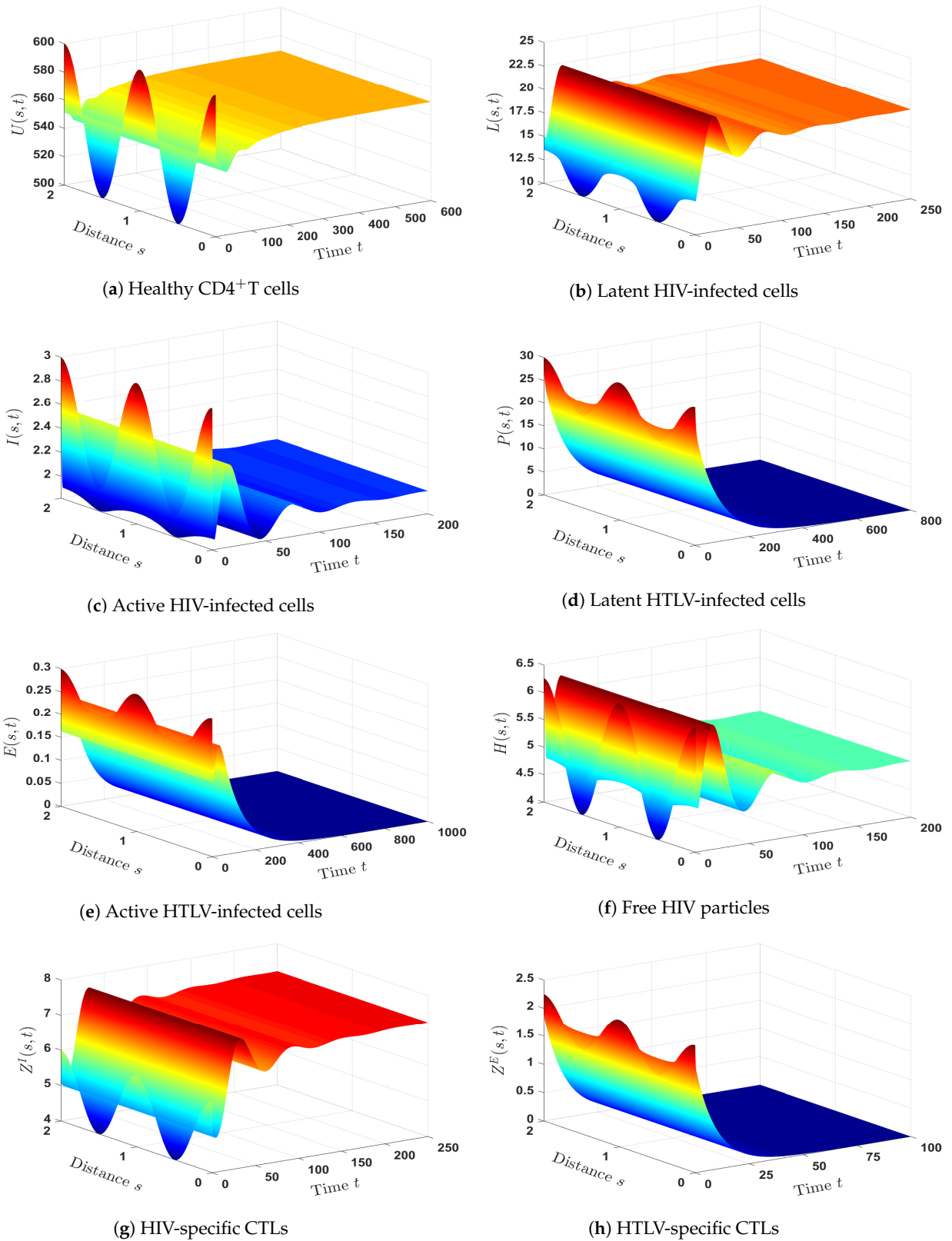


Figure 4. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.001, \omega_2 = 0.0001, \omega_3 = 0.0003, \omega_4 = 0.001, v_1 = 0.05, v_2 = 0.005$, we have $\mathcal{R}_3 = 3.91 > 1$, $\mathcal{R}_5 = 0.22 < 1$, and the equilibrium $\check{\xi}_3 = (569.59, 19.56, 2, 0, 0, 5, 7.28, 0)$ is asymptotically stable.

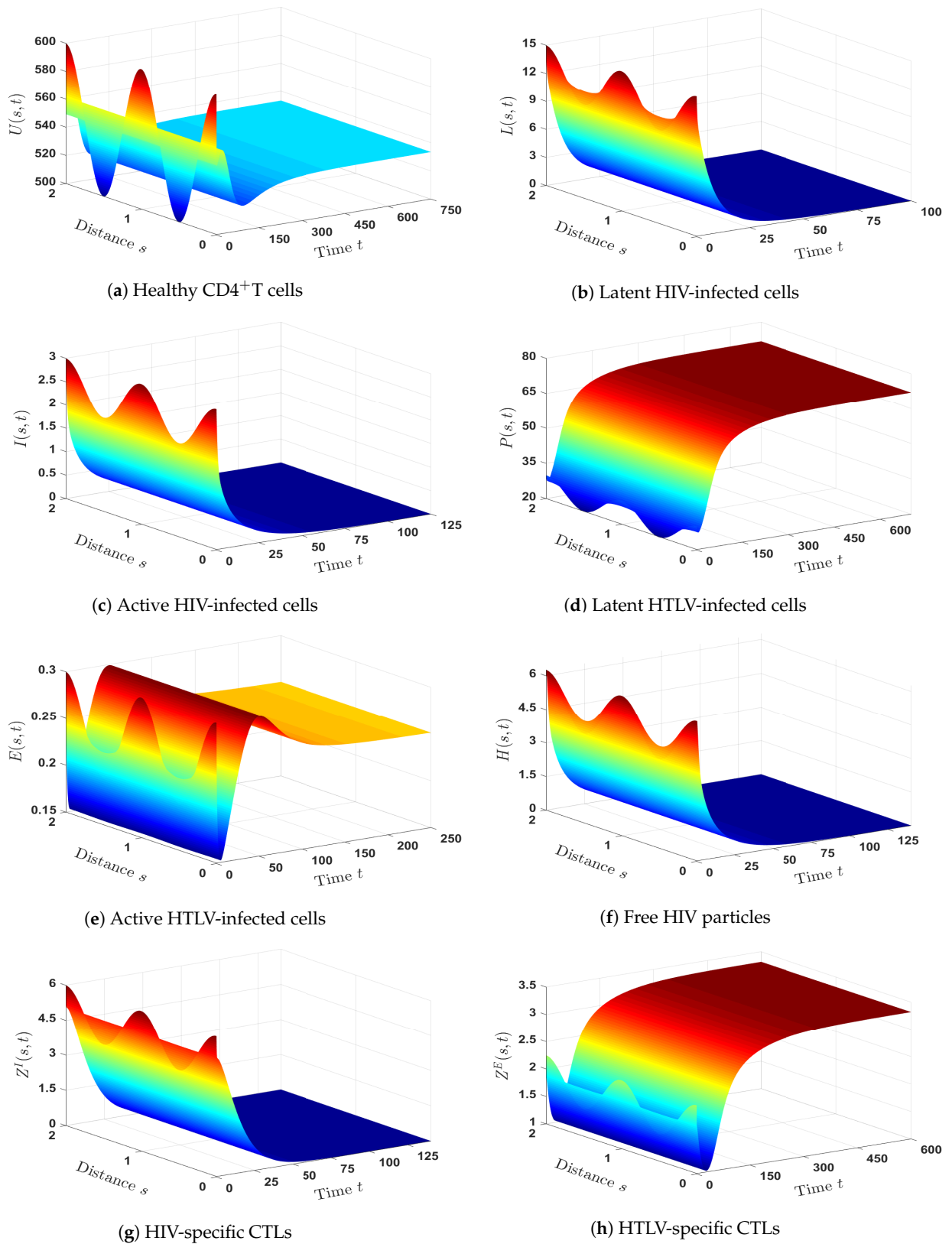


Figure 5. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.035, v_1 = 0.05, v_2 = 0.4$, we have $\mathcal{R}_4 = 4.35 > 1, \mathcal{R}_6 = 0.68 < 1$, and the equilibrium $\check{S}_4 = (533.33, 0, 0, 71.93, 0.25, 0, 0, 3.32)$ is asymptotically stable.

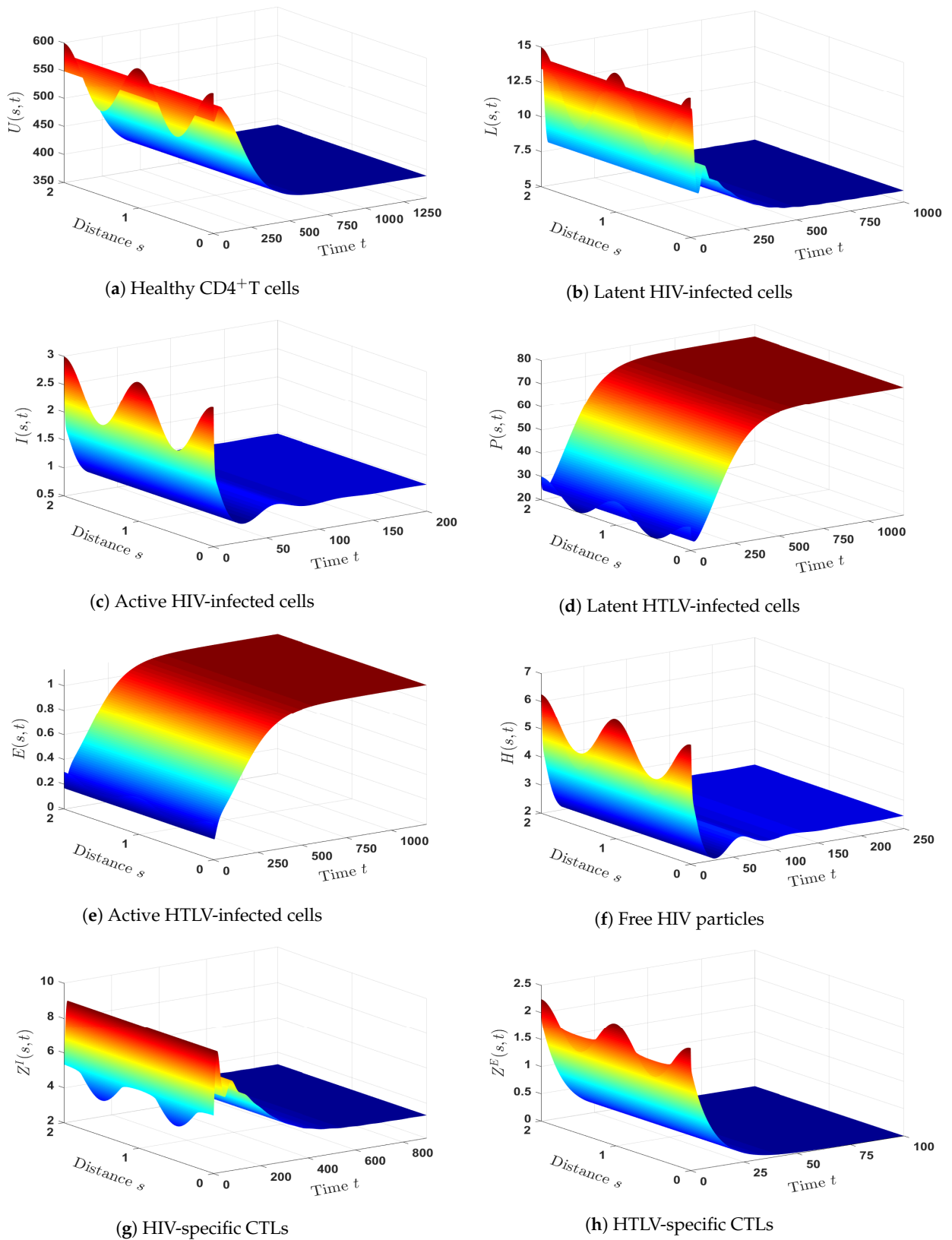


Figure 6. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.001, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.011, v_1 = 0.1, v_2 = 0.01$, we have $\hat{\mathcal{R}}_5 = 5.64 > 1, \mathcal{R}_5 = 1.93 > 1, \mathcal{R}_8 = 0.21 < 1, \mathcal{R}_1/\mathcal{R}_2 = 2.09 > 1$, and the equilibrium $\check{S}_5 = (389.09, 5.80, 1, 74.98, 1.13, 2.5, 3.30, 0)$ is asymptotically stable.

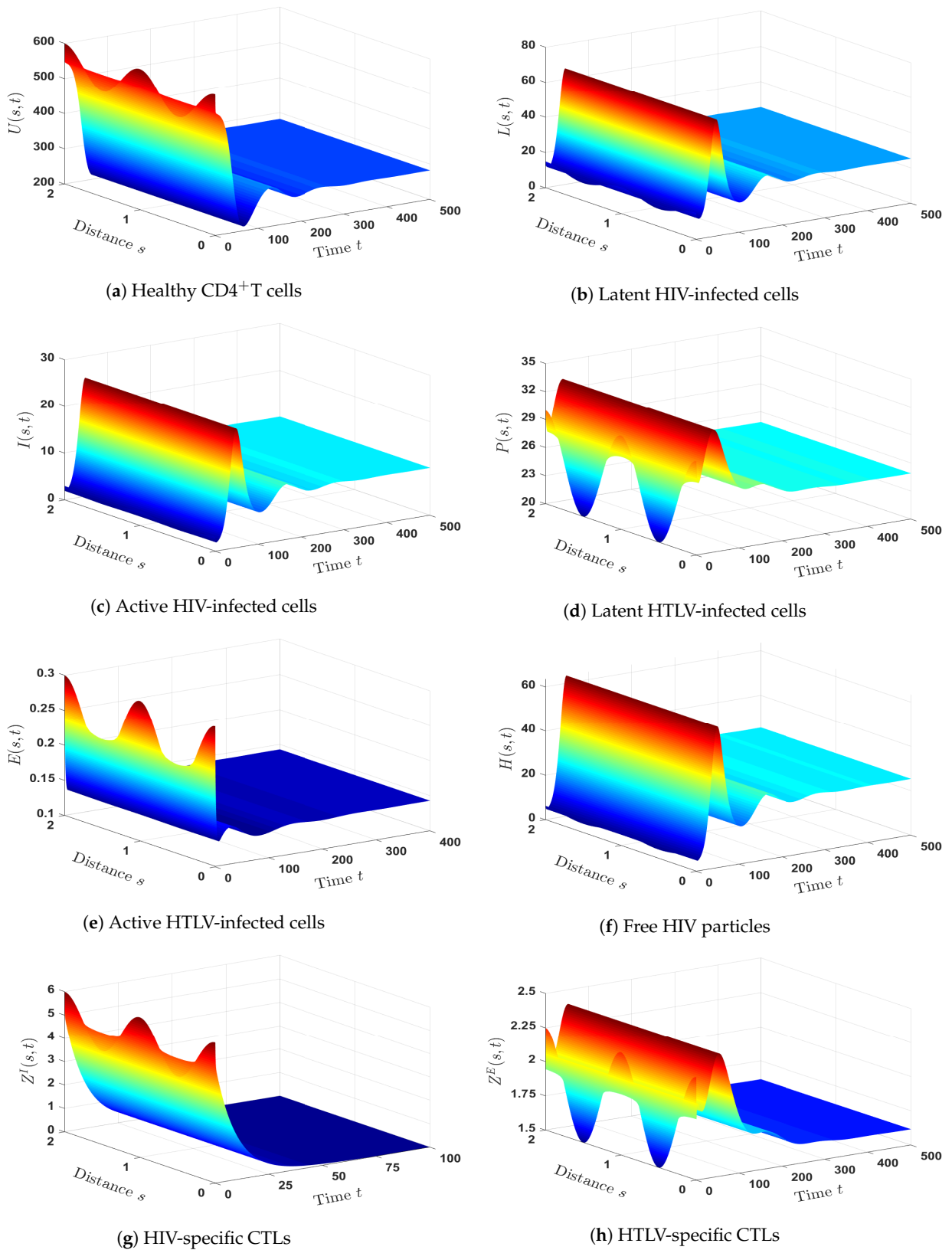
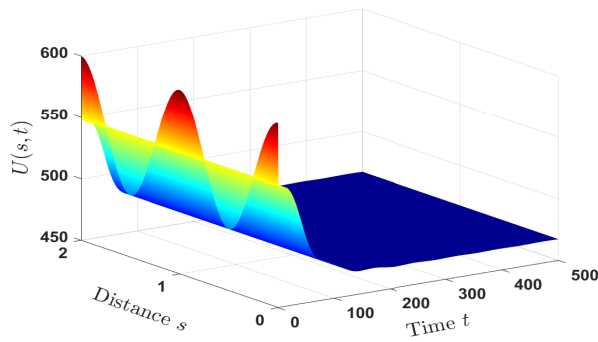
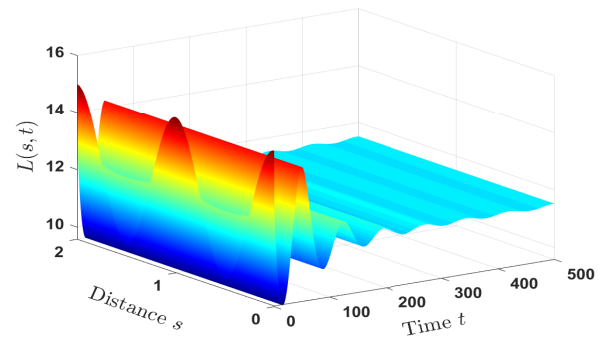


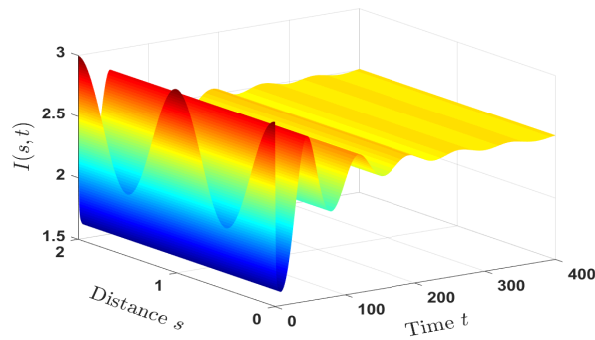
Figure 7. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.0006, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.04, v_1 = 0.001, v_2 = 0.7$, we have $\mathcal{R}_6 = 2.26 > 1, \mathcal{R}_7 = 0.17 < 1, \mathcal{R}_2/\mathcal{R}_1 = 2.63 > 1$, and the equilibrium $\check{S}_6 = (282.05, 25.31, 10.12, 24.87, 0.143, 25.31, 0, 1.62)$ is asymptotically stable.



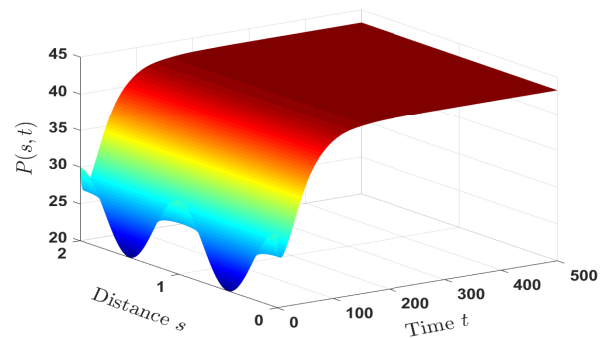
(a) Healthy CD4⁺T cells



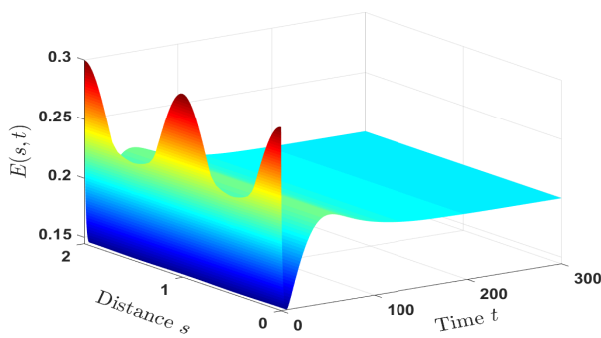
(b) Latent HIV-infected cells



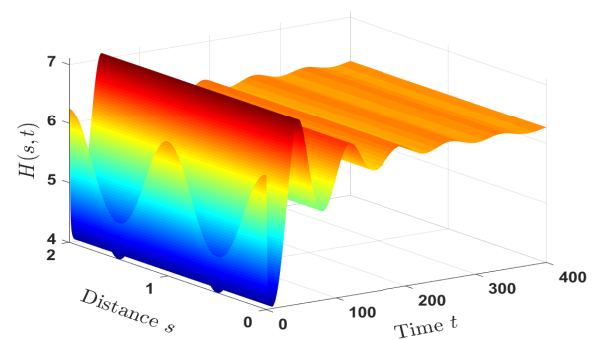
(c) Active HIV-infected cells



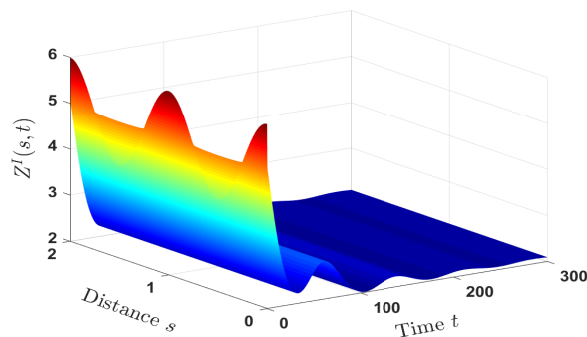
(d) Latent HTLV-infected cells



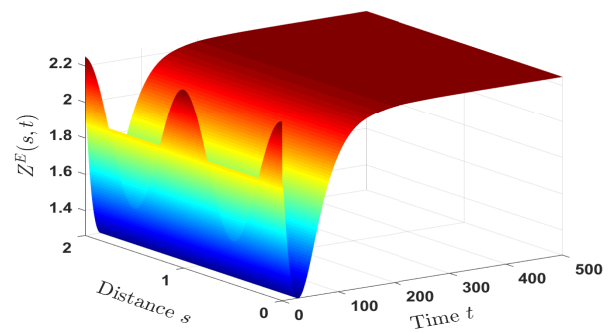
(e) Active HTLV-infected cells



(f) Free HIV particles

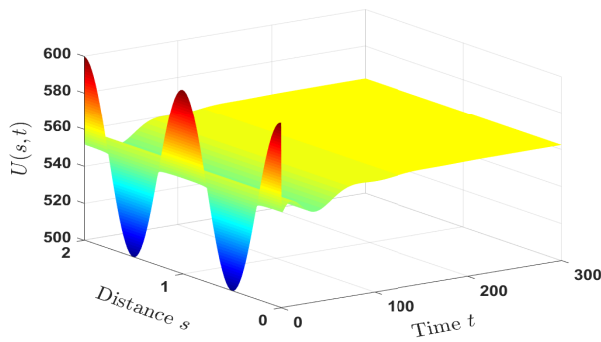


(g) HIV-specific CTLs

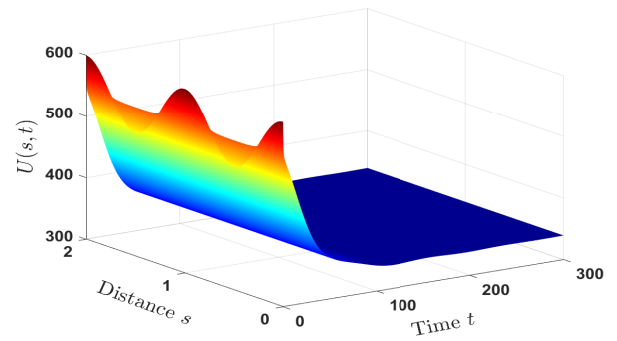


(h) HTLV-specific CTLs

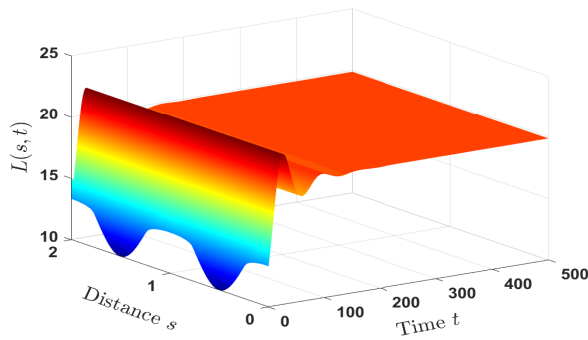
Figure 8. The solution behavior of Model (1) with the initial conditions (26) and boundary conditions (27). Taking $\omega_1 = 0.0006, \omega_2 = 0.0001, \omega_3 = 0.0002, \omega_4 = 0.03, v_1 = 0.04, v_2 = 0.5$, we have $\mathcal{R}_7 = 1.83 > 1, \mathcal{R}_8 = 3.27 > 1$, and the equilibrium $\check{S}_7 = (467.37, 11.46, 2.5, 43.25, 0.2, 6.25, 2.09, 2.25)$ is asymptotically stable.



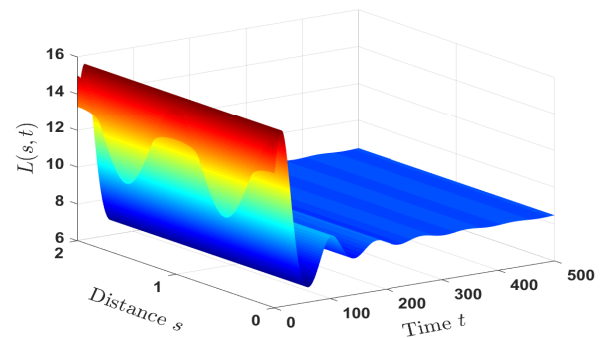
(a) Healthy CD4⁺T cells for Model (28)



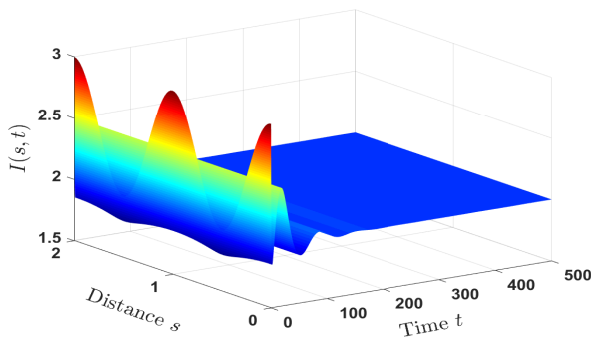
(b) Healthy CD4⁺T cells for Model (1)



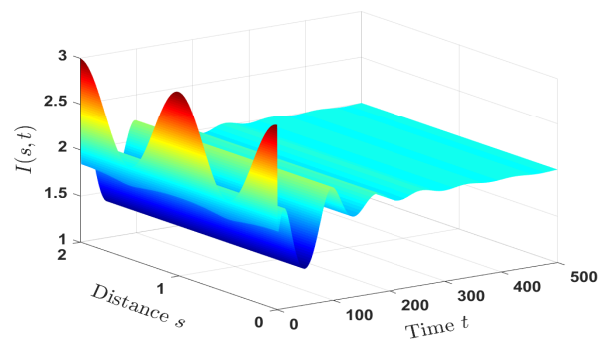
(c) Latent HIV-infected cells for Model (28)



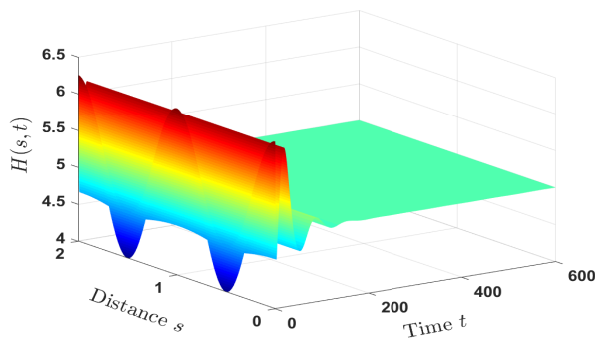
(d) Latent HIV-infected cells for Model (1)



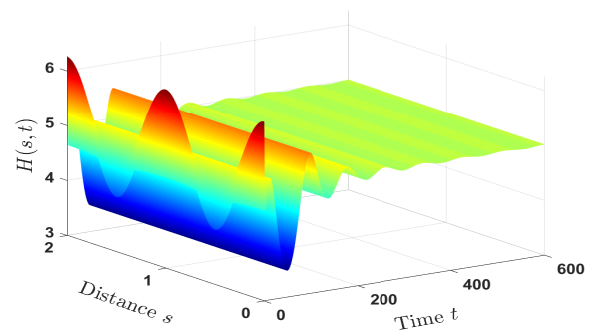
(e) Active HIV-infected cells for Model (28)



(f) Active HIV-infected cells for Model (1)

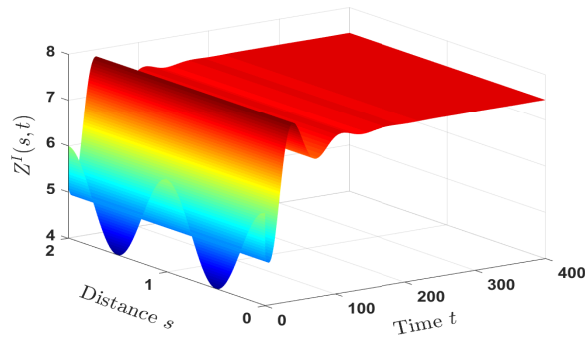


(g) Free HIV particles for Model (28)

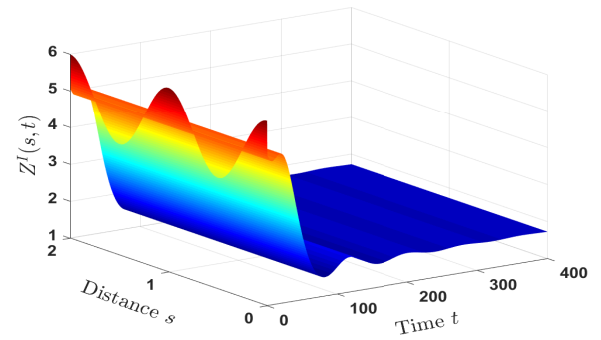


(h) Free HIV particles for Model (1)

Figure 9. Cont.

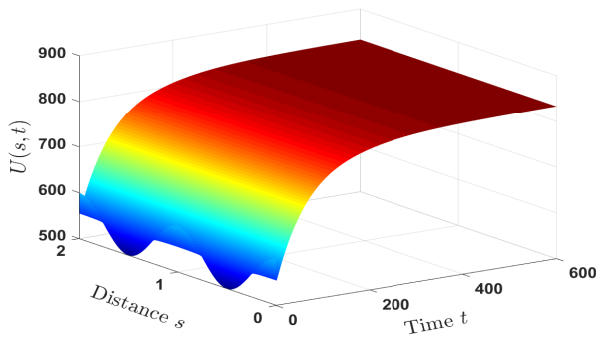


(i) HIV-specific CTLs for Model (28)

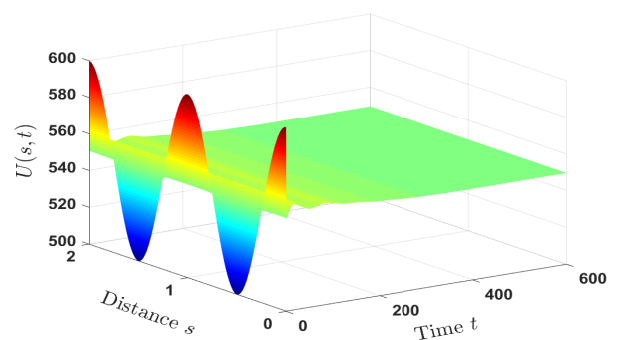


(j) HIV-specific CTLs for Model (1)

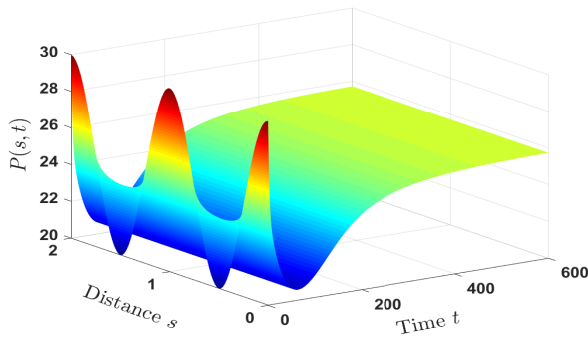
Figure 9. Comparison between the solutions of two models: HIV mono-infection Model (28) and HTLV/HIV co-infection Model (1), under the initial conditions (26) and boundary conditions (27), taking $\omega_1 = 0.0006, \omega_2 = 0.0002, \omega_3 = 0.0004, \omega_4 = 0.07, v_1 = 0.05, v_2 = 0.5$.



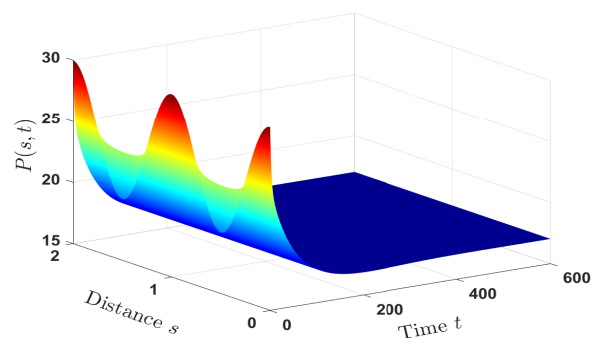
(a) Healthy CD4⁺T cells for Model (29)



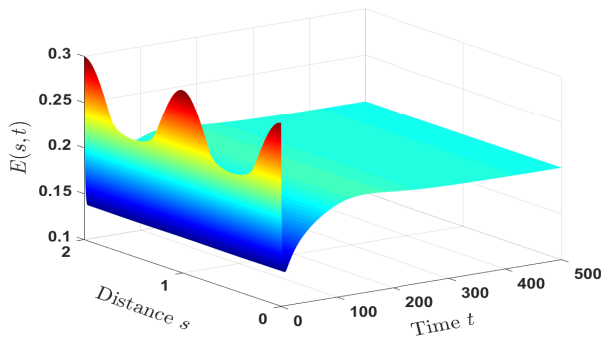
(b) Healthy CD4⁺T cells for Model (1)



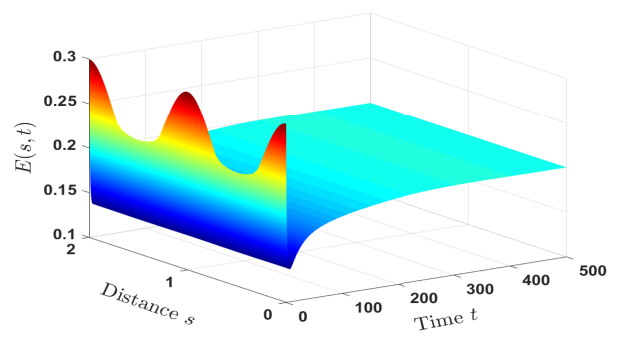
(c) Latent HTLV-infected cells for Model (29)



(d) Latent HTLV-infected cells for Model (1)



(e) Active HTLV-infected cells for Model (29)



(f) Active HTLV-infected cells for Model (1)

Figure 10. Cont.

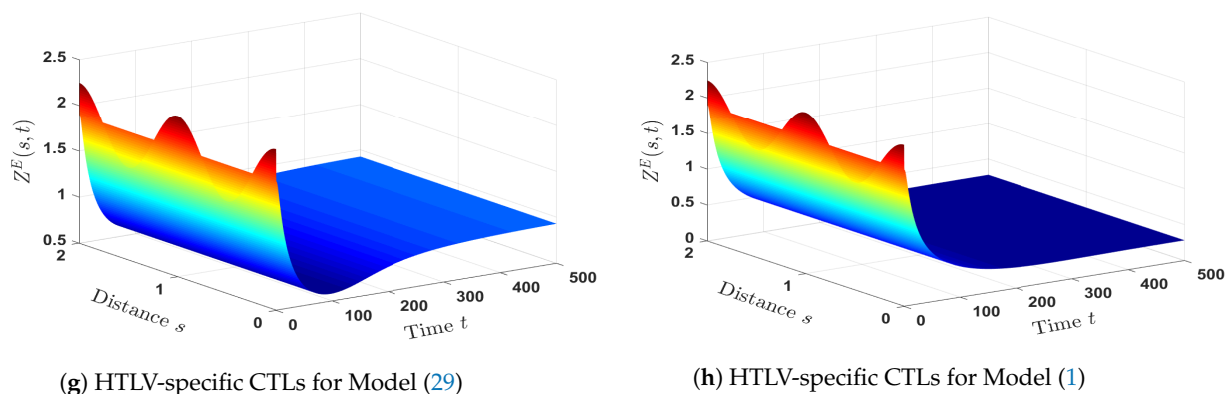


Figure 10. Comparison between the solutions of two models: HTLV mono-infection Model (29) and HTLV/HIV co-infection Model (1), under the initial conditions (26) and boundary conditions (27), taking $\omega_1 = 0.0005, \omega_2 = 0.0002, \omega_3 = 0.0003, \omega_4 = 0.01, v_1 = 0.05, v_2 = 0.5$.

7. Conclusions

In this work, we developed and analyzed the spatiotemporal dynamics of a mathematical PDE model for HTLV/HIV co-infection in the presence of three routes of transmission, which are FTC, latent ITC, and active ITC. The developed PDE model also incorporated latent infected cells, which represent reservoirs for both HTLV and HIV, as well as the cellular immunity mediated by CTL cells in order to control the HTLV/HIV co-infection. We first studied the properties of the solutions including the existence, uniqueness, non-negativity, and boundedness to guarantee that our developed model is biologically and mathematically well-posed. Furthermore, we proved that the dynamics of the model is fully determined by eight threshold parameters: $\mathcal{R}_i, i = 1, 2, \dots, 8$. More precisely, the infection-free equilibrium is globally asymptotically stable when $\mathcal{R}_1 \leq 1$ and $\mathcal{R}_2 \leq 1$, which biologically means that both HIV and HTLV are cleared and the co-infection dies out. However, when $\mathcal{R}_1 > 1$ or $\mathcal{R}_2 > 1$, one or both viruses persist in the host and seven steady states appear; their global stability conditions are summarized in Table 1.

The reaction in the present model was modeled by the classical temporal derivative, and the diffusion was described by the Laplacian operator. Further, the model considered only one arm of adaptive immunity. Therefore, the study of the impact of immunological memory on the dynamics of the PDEs model by means of the new generalized Hattaf fractional (GHF) derivative introduced in [60,61] and the modeling the role of the second arm of adaptive immunity exercised antibodies as in [62] will be the main aims of our future works.

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