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# $(\mathcal{C}, \Psi^*, G)$ Class of Contractions and Fixed Points in a Metric Space Endowed with a Graph

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**Abstract:** In this paper, we introduce the  $(\mathcal{C}, \Psi^*, G)$  class of contraction mappings using  $\mathcal{C}$ -class functions and some improved control functions for a pair of set valued mappings as well as a pair of single-valued mappings, and prove common fixed point theorems for such mappings in a metric space endowed with a graph. Our results unify and generalize many important fixed point results existing in literature. As an application of our main result, we have derived fixed point theorems for a pair of  $\alpha$ -admissible set valued mappings in a metric space.

**Keywords:** fixed point; common fixed point; directed graph; edge preserving; transitivity property

**MSC:** 47H10; 54H25

## 1. Introduction and Preliminaries

In [1], Ran and Reurings proved the existence of fixed points for single-valued mappings in partially ordered metric spaces, and their results were extended by Neito and Lopez [2]. However, it became clear that the concept of a graph gives a better vision of fixed points instead of partial ordering, and the first attempt in this direction was done by Jachymsky [3]. He defined the Banach  $G$ -contraction for single-valued mapping, which was later extended by Beg et al. [4] for the multivalued mappings. After these, there was a lot of work done in the direction of fixed points in metric spaces endowed with graphs, see [5–14].

In 1973, Geraghty [15] defined  $\Theta$  as the class of functions  $\theta : [0, \infty) \rightarrow [0, 1)$  such that

$$\theta(t_n) \rightarrow 1 \Rightarrow t_n \rightarrow 0, \quad (1)$$

and also showed generalizations of the Banach-Neumann contractive mapping principle.

We now recall the following class of functions:

$\Psi$  denotes the class of all continuous and non-decreasing functions  $\psi : [0, \infty) \rightarrow [0, \infty)$ , such that:

- $\psi(t) = 0$  if, and only if  $t = 0$ .

$\Phi$  denotes the class of all lower semi-continuous functions  $\phi : [0, \infty) \rightarrow [0, \infty)$ , such that:

- $\phi(t) = 0$  if, and only if  $t = 0$ .

For more results on contraction principles involving the above said control functions, we refer the reader to [16–18].

In [19], the family of  $\mathcal{C}$ -class functions were introduced as follows:  $F : [0, \infty)^2 \rightarrow \mathbb{R}$  belongs to the  $\mathcal{C}$ -class functions if:

- $F$  is continuous,
- $F(s, t) \leq s$ ,
- $F(s, t) = s$  implies that either  $s = 0$  or  $t = 0$ ; for all  $s, t \in [0, \infty)$ .

In [20], Samet et al. introduced the concept of  $\alpha$ -admissible mappings, and proved fixed point theorems for  $\alpha$ - $\psi$  contractive-type mappings, which paved a way to prove new results and generalise existing results in the fixed point theory. For some recent results on fixed point theorems of  $\alpha$ -admissible mappings, the reader may refer to [21–24].

In this work, we utilised the  $\mathcal{C}$ -class functions to give modified versions of contraction principles involving  $\Psi$  class functions and  $\Phi$  class functions in the sense that we have relaxed the condition  $\alpha(t) = 0$  if, and only if  $t = 0$  in the  $\Psi$  and  $\Phi$  class functions to  $\alpha(t) = 0 \Rightarrow t = 0$ . As an application, we have also deduced some common fixed point theorems for a pair of  $\alpha$ -admissible mappings.

Throughout this work,  $(X_G, d_G)$  will denote the metric space endowed with a directed graph  $G$  with  $V(G) = X_G$  and  $\Delta \subseteq E(G)$ , where  $V(G)$  denotes the set of vertices,  $E(G)$  denotes the set of edges of the graph  $G$  and  $\Delta = \{(x_G, x_G) : x_G \in X\}$ .

**Definition 1.** [3]  $(X_G, d_G)$  is said to have property  $A$  if  $x_n \rightarrow x_G$  and  $(x_n, x_{n+1}) \in E(G)$  implies  $(x_n, x_G) \in E(G)$ , for all sequences  $\{x_n\}_{n \in \mathbb{N}}$  in  $X_G$ .

**Definition 2.** [16] The pair  $(f, g)$  of self mappings of  $X_G$  is  $g$ -edge preserving in  $G$ , if

$$(gx, gy) \in E(G) \Rightarrow (fx, fy) \in E(G). \tag{2}$$

**Definition 3.** [11]  $E(G)$  satisfies transitivity property if, and only if for all  $x, y, z \in X_G$ ,  $(x, z) \in E(G)$  and  $(z, y) \in E(G)$  implies  $(x, y) \in E(G)$ .

Let mappings  $S, T : X_G \rightarrow CL(X_G)$  be given. We will make use of the following notations:

- $COFIX\{S, T\} = \{u \in X_G : u \in Su \cap Tu\}$  is the set of all common fixed points of  $S$  and  $T$
- $FIX\{T\} = \{u \in X_G : u \in Tu\}$  is the set of all fixed points of  $T$ .

## 2. Main Results

Let  $\Theta^*$  be the set of all continuous functions  $\theta : [0, \infty) \rightarrow [0, 1)$ .

$\Psi^*$  be the set of all continuous and non decreasing functions  $\psi : [0, \infty) \rightarrow [0, \infty)$ , such that:

- $\psi(t) = 0 \Rightarrow t = 0$ .

Let  $\Phi^*$  be the set of all lower semi-continuous functions  $\phi : [0, \infty) \rightarrow [0, \infty)$ , such that:

- $\phi(t) = 0 \Rightarrow t = 0$ .

**Definition 4.** Let  $S, T : X_G \rightarrow CB(X_G)$  be two given mappings. We say that the pair  $(S, T)$  belongs to the class of  $(\mathcal{C}, \Psi^*, G)$  contractions if, and only if for all  $x_G, y_G \in X_G$  with  $(x_G, y_G) \in E(G)$ , the following conditions are satisfied:

(4.1) For  $u_G \in Sx_G$ , there exists  $v_G \in Ty_G$  such that  $(u_G, v_G) \in E(G)$

(4.2) For  $u_G \in Tx_G$ , there exists  $v_G \in Sy_G$  such that  $(u_G, v_G) \in E(G)$

(4.3) there exists  $F \in \mathcal{C}$ ,  $\psi \in \Psi^*$ , such that

$$\begin{aligned} \psi(H(Sx_G, Ty_G)) &\leq F(\psi(M(x_G, y_G)), M(x_G, y_G)) \text{ and} \\ \psi(H(Tx_G, Sy_G)) &\leq F(\psi(M(x_G, y_G)), M(x_G, y_G)) \end{aligned}$$

where

$$M(x_G, y_G) = \max \left\{ d_G(x_G, y_G), d_G(Sx_G, x_G), d_G(Ty_G, y_G), \frac{d_G(y_G, Sx_G) + d_G(x_G, Ty_G)}{2} \right\}$$

**Theorem 1.** Let  $(X_G, d_G)$  be complete and  $S, T : X_G \rightarrow CB(X_G)$  satisfy the following:

- (1.1) There exists  $x_{G0}, x_{G1} \in X_G$  such that  $x_{G1} \in Tx_{G0} \cup Sx_{G0}$  and  $(x_{G0}, x_{G1}) \in E(G)$ ,
- (1.2)  $E(G)$  satisfy transitivity property,
- (1.3)  $(S, T) \in (\mathcal{C}, \Psi^*, G)$  for some  $F \in \mathcal{C}^*$  and  $\psi \in \Psi^*$ .

Then  $COFIX\{S, T\} \neq \emptyset$ .

**Proof.** By condition (1.1), suppose  $x_{G0} \in X_G$ , and  $x_{G1} \in S(x_{G0})$ . By condition (4.1), we can find  $x_{G2} \in T(x_{G1})$  with  $(x_{G1}, x_{G2}) \in E(G)$  and

$$\psi(d_G(x_{G1}, x_{G2})) \leq \psi(H(S(x_{G0}), T(x_{G1}))) \leq F(\psi(M(x_{G0}, x_{G1})), \psi(M(x_{G0}, x_{G1})))$$

Now again by condition (4.2), for  $x_{G2} \in T(x_{G1})$ , there exists  $x_{G3} \in S(x_{G2})$  with  $(x_{G2}, x_{G3}) \in E(G)$  and

$$\begin{aligned} \psi(d_G(x_{G2}, x_{G3})) &\leq \psi(H(Tx_{G1}, Sx_{G2})) \\ &\leq F(\psi(M(x_{G1}, x_{G2})), M(x_{G1}, x_{G2})). \end{aligned}$$

Continuing inductively, we construct the sequence  $\{x_{Gn}\}$  recursively as for  $n \geq 0$ , as

$$x_{G2n+1} \in S(x_{G2n}), x_{G2n} \in T(x_{G2n-1}) \tag{3}$$

as well as  $(x_{Gn}, x_{Gn+1}) \in E(G)$ . Our first task is to establish that  $COFIX\{S, T\} \neq \emptyset$ . Note that if  $M(x_{Gm}, x_{Gn}) = 0$  for any  $n, m \in N$  then

$$\begin{aligned} M(x_{Gm}, x_{Gn}) &= \max \left\{ d_G(x_{Gm}, x_{Gn}), d_G(Sx_{Gm}, x_{Gm}), d_G(Tx_{Gn}, x_{Gn}), \right. \\ &\quad \left. \frac{d_G(x_{Gn}, Sx_{Gm}) + d_G(x_{Gm}, Tx_{Gn})}{2} \right\} = 0 \end{aligned}$$

which shows that  $x_{Gm} = x_{Gn} \in COFIX\{S, T\}$ , and our first task will be complete. So let  $M(x_{Gm}, x_{Gn}) \neq 0$  for any  $n, m \in N$ . Then, by definition of  $\psi$ ,  $\psi(M(x_{Gn-1}, x_{Gn})) \neq 0$ .

If  $n$  is odd, we have

$$\begin{aligned} \psi(d_G(x_{Gn}, x_{Gn+1})) &\leq \psi(H(Sx_{Gn-1}, Tx_{Gn})) \\ &\leq F(\psi(M(x_{Gn-1}, x_{Gn})), M(x_{Gn-1}, x_{Gn})) \end{aligned} \tag{4}$$

Since  $\psi(M(x_{Gn-1}, x_{Gn})) \neq 0$ , we have

$$F(\psi(M(x_{Gn-1}, x_{Gn})), M(x_{Gn-1}, x_{Gn})) < \psi(M(x_{Gn-1}, x_{Gn}))$$

Then, by (4), we get

$$\psi(d_G(x_{Gn}, x_{Gn+1})) < \psi(M(x_{Gn-1}, x_{Gn})) \tag{5}$$

where

$$\begin{aligned}
 M(x_{G_{n-1}}, x_{G_n}) &= \max \left\{ d_G(x_{G_{n-1}}, x_{G_n}), d_G(Sx_{G_{n-1}}, x_{G_{n-1}}), d_G(Tx_{G_n}, x_{G_n}), \right. \\
 &\quad \left. \frac{d_G(x_{G_n}, Sx_{G_{n-1}}) + d_G(x_{G_{n-1}}, Tx_{G_n})}{2} \right\} \\
 &\leq \max \left\{ d_G(x_{G_{n-1}}, x_{G_n}), d_G(x_{G_n}, x_{G_{n-1}}), d_G(x_{G_{n+1}}, x_{G_n}), \right. \\
 &\quad \left. \frac{d_G(x_{G_n}, x_{G_n}) + d_G(x_{G_{n-1}}, x_{G_{n+1}})}{2} \right\} \\
 &\leq \max \left\{ d_G(x_{G_{n-1}}, x_{G_n}), d_G(x_{G_{n+1}}, x_{G_n}), \frac{d_G(x_{G_{n-1}}, x_{G_{n+1}})}{2} \right\} \\
 &\leq \max \left\{ d_G(x_{G_{n-1}}, x_{G_n}), d_G(x_{G_{n+1}}, x_{G_n}), \right. \\
 &\quad \left. \frac{d_G(x_{G_{n-1}}, x_{G_n}) + d_G(x_{G_n}, x_{G_{n+1}})}{2} \right\} \\
 &\leq \max \{ d_G(x_{G_{n-1}}, x_{G_n}), d_G(x_{G_n}, x_{G_{n+1}}) \}
 \end{aligned}$$

If  $d_G(x_{G_{n+1}}, x_{G_n}) > d_G(x_{G_{n-1}}, x_{G_n})$ , then  $M(x_{G_{n-1}}, x_{G_n}) \leq d_G(x_{G_{n+1}}, x_{G_n})$ . Then (5) gives

$$\psi(d_G(x_{G_n}, x_{G_{n+1}})) < \psi(d_G(x_{G_n}, x_{G_{n+1}}))$$

a contradiction. So, we have

$$d_G(x_{G_n}, x_{G_{n+1}}) \leq d_G(x_{G_{n-1}}, x_{G_n}) \tag{6}$$

For an even number  $n$ , a similar argument leads to inequality (6). Thus,  $\{d_G(x_{n+1}, x_{G_n})\}$  is a monotonically non-increasing sequence which is bounded below, and thereby,

$$\lim_{n \rightarrow \infty} d_G(x_{G_n}, x_{G_{n+1}}) = \lim_{n \rightarrow \infty} M(x_{G_{n-1}}, x_{G_n}) = r \geq 0.$$

Assume that  $r > 0$ , so that  $\psi(r) > 0$ . Taking  $\lim \inf$  on both sides of the inequality (5), we obtain

$$\psi(r) < \psi(r)$$

a contradiction. Hence  $r = 0$ . Consequently, we have

$$\lim_{n \rightarrow \infty} d_G(x_{G_n}, x_{G_{n+1}}) = 0. \tag{7}$$

Next, we prove that  $\{x_{G_n}\}$  is a Cauchy sequence. By (7), it is enough if we show that the subsequence  $\{x_{G_{2n}}\}$  is a Cauchy sequence. Suppose, if possible,  $\{x_{G_{2n}}\}$  is not a Cauchy sequence. Then, there exists  $\epsilon > 0$  and subsequences  $\{x_{G_{2m(k)}}\}$  and  $\{x_{G_{2n(k)}}\}$ , such that  $n(k)$  is the smallest index for which  $n(k) > m(k) > k, d_G(x_{G_{2m(k)}}, x_{G_{2n(k)}}) \geq \epsilon$ . That is,

$$d_G(x_{G_{2m(k)}}, x_{G_{2n(k)-2}}) < \epsilon \tag{8}$$

Now, we have

$$\begin{aligned}
 \epsilon &\leq d_G(x_{G_{2m(k)}}, x_{G_{2n(k)}}) \\
 &\leq d_G(x_{G_{2m(k)}}, x_{G_{2n(k)-2}}) + d_G(x_{G_{2n(k)-2}}, x_{G_{2n(k)-1}}) + d_G(x_{G_{2n(k)-1}}, x_{G_{2n(k)}}) \\
 &< \epsilon + d_G(x_{G_{2n(k)-2}}, x_{G_{2n(k)-1}}) + d_G(x_{G_{2n(k)-1}}, x_{G_{2n(k)}})
 \end{aligned}$$

As  $k \rightarrow \infty$ , we get

$$\lim_{k \rightarrow \infty} d_G(x_{G2m(k)}, x_{G2n(k)}) = \epsilon \tag{9}$$

Also, we have

$$\begin{aligned} &|d_G(x_{G2m(k)}, x_{G2n(k)+1}) - d_G(x_{G2m(k)}, x_{G2n(k)})| \leq d_G(x_{G2n(k)}, x_{G2n(k)+1}) \\ \text{and } &|d_G(x_{G2m(k)-1}, x_{G2n(k)}) - d_G(x_{G2m(k)}, x_{G2n(k)})| \leq d_G(x_{G2m(k)}, x_{G2m(k)-1}). \end{aligned}$$

Letting  $k \rightarrow \infty$  and using (7) and (9), we get

$$\lim_{k \rightarrow \infty} d_G(x_{G2m(k)-1}, x_{G2n(k)}) = \lim_{k \rightarrow \infty} d_G(x_{G2m(k)}, x_{G2n(k)+1}) = \epsilon. \tag{10}$$

From

$$|d_G(x_{G2m(k)-1}, x_{G2n(k)+1}) - d_G(x_{G2m(k)-1}, x_{G2n(k)})| \leq d_G(x_{G2n(k)}, x_{G2n(k)+1})$$

and making use of (7) and (10), we get

$$\lim_{k \rightarrow \infty} d_G(x_{G2m(k)-1}, x_{G2n(k)+1}) = \epsilon \tag{11}$$

Also, from the definition of  $M$  and from (7) and (9)–(11), we have

$$\lim_{k \rightarrow \infty} M(x_{G2m(k)-1}, x_{G2n(k)}) = \epsilon \tag{12}$$

Also by the transitivity property of  $G$ , we have  $(x_{G2m(k)-1}, x_{G2n(k)}) \in E(G)$ . Thus, we have

$$\begin{aligned} \psi(d_G(x_{G2m(k)}, x_{G2n(k)+1})) &= \psi(H(Tx_{G2m(k)-1}, Sx_{G2n(k)})) \\ &\leq F(\psi(M(x_{G2m(k)-1}, x_{G2n(k)})), (M(x_{G2m(k)-1}, x_{G2n(k)}))) \end{aligned}$$

Letting  $k \rightarrow \infty$  and making use of (10) and (11), the above inequality yields

$$\psi(\epsilon) < \psi(\epsilon)$$

a contradiction. Thus,  $\{x_{Gn}\}$  is a Cauchy sequence. By completeness of  $X_G$ , we can find  $u_G \in X_G$ , such that  $x_{Gn} \rightarrow u_G$  as  $n \rightarrow \infty$ .

We will now prove that  $u_G \in COFIX\{S, T\}$ . Note that  $(x_{G2n+1}, u_G) \in E(G)$ , and so

$$\begin{aligned} \psi(d_G(x_{G2n+1}, Tu_G)) &\leq \psi(H(Sx_{G2n}, Tu_G)) \\ &\leq F(\psi(M(x_{G2n}, u_G)), M(x_{G2n}, u_G)) \end{aligned} \tag{13}$$

where

$$M(x_{G2n}, u_G) = \max \left\{ d_G(x_{G2n}, u_G), d_G(Sx_{G2n}, x_{G2n}), d_G(Tu_G, u_G), \frac{d_G(x_{G2n}, Tu_G) + d_G(u_G, Sx_{G2n})}{2} \right\}$$

Note that as  $n \rightarrow \infty$ ,  $d_G(Sx_{G2n}, x_{G2n}) \rightarrow 0$ ,  $d_G(u_G, Sx_{G2n}) \rightarrow 0$ , and so  $M(u_G, x_{G2n}) \rightarrow d_G(Tu_G, u_G)$ . Now, if  $d_G(Tu_G, u_G) \neq 0$ , then from (13) as  $n \rightarrow \infty$ , we have

$$\psi(d_G(Tu_G, u_G)) < \psi(d_G(Tu_G, u_G)),$$

again, a contradiction. Thus,  $d_G(Tu_G, u_G) = 0$ , which implies that  $u_G \in \overline{Tu_G}$ , and since  $Tu_G$  is closed, we have  $u_G \in Tu_G$ .

Now again, we have  $M(u_G, u_G) = d_G(u_G, Su_G)$ , and if  $d_G(u_G, Su_G) \neq 0$ , since  $(u_G, u_G) \in \Delta \subset E(G)$ , we get

$$\begin{aligned} \psi(d_G(Su_G, u_G)) &\leq \psi(H(Su_G, Tu_G)) \\ &\leq F(\psi(M(u_G, u_G))M(u_G, u_G)) \\ &< \psi(d_G(u_G, Su_G)) \end{aligned}$$

a contradiction, and thereby,  $d_G(u_G, Su_G) = 0$  or  $u_G \in Su_G$ . Hence,  $COFIX\{S, T\} \neq \phi$ .  $\square$

We will deduce the following important results from Theorem 1:

**Corollary 1.** Let  $(X_G, d_G)$  be complete and  $S, T : X_G \rightarrow CB(X_G)$  satisfy conditions (4.1), condition (4.2), condition (1.1), condition (1.2), and the following:

(1.1) For all  $x_G, y_G \in X_G$  with  $(x_G, y_G) \in E(G)$

$$\begin{aligned} \psi(H(Sx_G, Ty_G)) &\leq \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \text{ and} \\ \psi(H(Tx_G, Sy_G)) &\leq \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \end{aligned}$$

where  $\psi \in \Psi^*$ ,  $\phi \in \Phi^*$  and  $M(x_G, y_G)$  is as in Definition 4. Then,  $COFIX\{S, T\} \neq \phi$ .

**Proof.** Take  $F(r, t) = r - \phi(t)$  in Theorem 1.  $\square$

**Corollary 2.** Let  $(X_G, d_G)$  be complete and  $S, T : X_G \rightarrow CB(X_G)$  satisfy the conditions (4.1), condition (4.2), condition (1.1), condition (1.2), and the following:

(2.1) For all  $x_G, y_G \in X_G$  with  $(x_G, y_G) \in E(G)$

$$\begin{aligned} \psi(H(Sx_G, Ty_G)) &\leq \theta(M(x_G, y_G))\psi(M(x_G, y_G)) \text{ and} \\ \psi(H(Tx_G, Sy_G)) &\leq \theta(M(x_G, y_G))\psi(M(x_G, y_G)) \end{aligned}$$

where  $\psi \in \Psi^*$ ,  $\theta \in \Theta^*$  and  $M(x_G, y_G)$  is as in Definition 4.  $COFIX\{S, T\} \neq \phi$ .

**Proof.** Take  $F(r, t) = \theta(t).r$  in Theorem 1.  $\square$

**Corollary 3.** Let  $(X_G, d_G)$  be complete and  $S, T : X_G \rightarrow CB(X_G)$  satisfy the conditions (4.1), (4.2), (1.1) and (1.2), and the following:

(3.1) For all  $x_G, y_G \in X_G$  with  $(x_G, y_G) \in E(G)$ , there exist  $0 < \lambda < 1$ , such that

$$\begin{aligned} H(Sx_G, Ty_G) &\leq \lambda(M(x_G, y_G)) \text{ and} \\ H(Tx_G, Sy_G) &\leq \lambda(M(x_G, y_G)) \end{aligned}$$

where  $M(x_G, y_G)$  is as in Definition 4. Then  $COFIX\{S, T\} \neq \phi$ .

**Proof.** For some  $k > 0$ , set  $k^* = k(1 - \lambda)$ . Then,

$$\begin{aligned} H(Sx_G, Ty_G) &\leq \lambda(M(x_G, y_G)) \text{ and} \\ H(Tx_G, Sy_G) &\leq \lambda(M(x_G, y_G)) \end{aligned}$$

implies

$$\begin{aligned} H(Sx_G, Ty_G) &\leq \frac{k - k^*}{k}(M(x_G, y_G)) \text{ and} \\ H(Tx_G, Sy_G) &\leq \frac{k - k^*}{k}(M(x_G, y_G)) \end{aligned}$$

or

$$kH(Sx_G, Ty_G) + 1 \leq kM(x_G, y_G) + 1 - k^*M(x_G, y_G) \text{ and } kH(Tx_G, Sy_G) \leq kM(x_G, y_G) - k^*M(x_G, y_G)$$

Now, let  $\psi(t) = kt + 1$  and  $\phi(t) = k^*(t)$ . Then, the above inequality leads to

$$\psi(H(Sx_G, Ty_G)) \leq \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \text{ and } \psi(H(Tx_G, Sy_G)) \leq \psi(M(x_G, y_G)) - \phi(M(x_G, y_G))$$

Thus, all conditions of Corollary 1 are satisfied, and hence,  $COFIX\{S, T\} \neq \phi$ .  $\square$

**Corollary 4.** Let  $(X_G, d_G)$  be complete and  $T : X_G \rightarrow CB(X_G)$  satisfy the following:

- (4.1) There exists  $x_{G0}, x_{G1} \in X_G$ , such that  $x_{G1} \in Tx_{G0}$  and  $(x_{G0}, x_{G1}) \in E(G)$ ;
- (4.2) For any  $u \in Tx_G$ , there exists  $w \in Ty_G$ , such that  $(u, w) \in E(G)$ ;
- (4.3)  $E(G)$  satisfies the transitivity property;
- (4.4)  $\psi(H(Tx_G, Ty_G)) \leq \psi(d_G(x_G, y_G)) - \phi(d_G(x_G, y_G))$

where  $\psi \in \Psi^*$ ,  $\phi \in \Phi^*$ . Then,  $FIX\{T\} \neq \phi$ .

**Proof.** Take  $S = T$  in Corollary 1.  $\square$

**Corollary 5.** Let  $(X_G, d_G)$  be complete and  $T : X_G \rightarrow CB(X_G)$  satisfy conditions (4.1)–(4.3), and the following:

$$(5.1) \quad \psi(H(Tx_G, Ty_G)) \leq \theta(d_G(x_G, y_G))\psi(d_G(x_G, y_G))$$

where  $\psi \in \Psi^*$ ,  $\theta \in \Theta^*$ . Then,  $FIX\{T\} \neq \phi$ .

**Proof.** Take  $F(r, t) = \theta(t).r$  in Corollary 2.  $\square$

**Example 1.** Let  $X_G = \{0, \frac{1}{2^n} : n \in \mathbb{N}\}$ ,  $d_G(x_G, y_G) = |x_G - y_G|$ ,  $G = (V, E)$ , with  $V(G) = X_G$  and  $E(G) = \{(0, 0), (\frac{1}{2^n}, \frac{1}{2^n}), (\frac{1}{2^n}, 0)\}$  and  $S, T : X_G \rightarrow CB(X_G)$  be defined by

$$Sx_G = \begin{cases} \{0\}, & \text{if } x_G = 0 \\ \{\frac{1}{2^{n+1}}, 0\}, & \text{if } x_G = \frac{1}{2^n}. \end{cases}$$

and

$$Tx_G = \begin{cases} \{0\}, & \text{if } x_G = 0 \\ \{\frac{1}{2^{n+2}}, 0\}, & \text{if } x_G = \frac{1}{2^n}. \end{cases}$$

Define  $\psi, \phi : [0, \infty) \rightarrow [0, \infty)$  by  $\psi(t) = 2t + 1$  and  $\phi(t) = \frac{t}{4}$  for all  $t \in [0, \infty)$ . Clearly,  $\psi(t) \in \Psi^*$  (note that  $\psi \notin \Psi$ ) and  $\phi(t) \in \Phi^*$ .

- If  $x_G = \frac{1}{2^n}$  and  $y_G = 0$  with  $(\frac{1}{2^n}, 0) \in E(G)$ , then  $Sx_G = \{\frac{1}{2^{n+1}}, 0\}$ ,  $Sy = \{0\}$ ,  $Tx_G = \{\frac{1}{2^{n+2}}, 0\}$ ,  $Ty_G = \{0\}$ ,  $d_G(x_G, y_G) = \frac{1}{2^n}$ ,  $H(Sx_G, Ty_G) = \frac{1}{2^{n+1}}$ ,  $\psi(H(Sx_G, Ty_G)) = \frac{1}{2^n} + 1$ ,  $M(x_G, y_G) = \frac{1}{2^n}$ ,  $\psi(M(x_G, y_G)) = \frac{1}{2^{n-1}} + 1$ ,  $\phi(M(x_G, y_G)) = \frac{1}{2^{n+2}}$  and

$$\psi(H(Sx_G, Ty_G)) = \frac{1}{2^n} + 1 < \frac{1}{2^{n-1}} + 1 - \frac{1}{2^{n+2}} = \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \text{ for all } n \in \mathbb{N}.$$

Also, for  $\frac{1}{2^{n+1}} \in Sx_G$ , there exists  $0 \in Ty_G$ , such that  $(\frac{1}{2^{n+1}}, 0) \in E(G)$  and for  $0 \in Sx_G$ , there exists  $0 \in Ty_G$  such that  $(0, 0) \in E(G)$ .

For  $\frac{1}{2^{n+2}} \in Tx_G$ , there exists  $0 \in Sy_G$  such that  $(\frac{1}{2^{n+2}}, 0) \in E(G)$  and for  $0 \in Tx_G$ , there exists  $0 \in Sy_G$  such that  $(0, 0) \in E(G)$ .

- If  $x_G = 0, y_G = 0$  with  $(0, 0) \in E(G)$ , then  $Sx_G = \{0\} = Sy_G = Tx_G = Ty_G, 0 = d_G(x_G, y_G) = H(Sx_G, Ty_G) = M(x_G, y_G), \psi(H(Sx_G, Ty_G)) = \psi(M(x_G, y_G)) = 1, \phi(M(x_G, y_G)) = 0$  and

$$\psi(H(Sx_G, Ty_G)) = 1 = \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)).$$

Also, for  $0 \in Sx_G$ , there exists  $0 \in Ty_G$  such that  $(0, 0) \in E(G)$  and for  $0 \in Sx_G$ , there exists  $0 \in Ty_G$ , such that  $(0, 0) \in E(G)$ .

For  $0 \in Tx_G$ , there exists  $0 \in Sy_G$ , such that  $(0, 0) \in E(G)$  and for  $0 \in Tx_G$ , there exists  $0 \in Sy_G$ , such that  $(0, 0) \in E(G)$

- Also, if  $x_G = \frac{1}{2^n}, y_G = \frac{1}{2^n}$  with  $(\frac{1}{2^n}, \frac{1}{2^n}) \in E(G)$ , then  $Sx_G = \{\frac{1}{2^{n+1}}, 0\} = Sy_G, Tx_G = \{\frac{1}{2^{n+2}}, 0\} = Ty_G, d_G(x_G, y_G) = 0, H(Sx_G, Ty_G) = \frac{1}{2^{n+2}}, \psi(H(Sx_G, Ty_G)) = \frac{1}{2^{n+1}} + 1, M(x_G, y_G) = \frac{1}{2^{n+1}}, \psi(M(x_G, y_G)) = \frac{1}{2^n} + 1, \phi(M(x_G, y_G)) = \frac{1}{2^{n+3}}$  and

$$\psi(H(Sx_G, Ty_G)) = \frac{1}{2^{n+1}} + 1 < \frac{1}{2^n} + 1 - \frac{1}{2^{n+3}} = \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \text{ for all } n \in \mathbb{N}.$$

Also, for  $\frac{1}{2^{n+1}} \in Sx_G$ , there exists  $0 \in Ty_G$ , such that  $(\frac{1}{2^{n+1}}, 0) \in E(G)$  and for  $0 \in Sx_G$ , there exists  $0 \in Ty_G$ , such that  $(0, 0) \in E(G)$ .

For  $\frac{1}{2^{n+2}} \in Tx_G$ , there exists  $0 \in Sy_G$ , such that  $(\frac{1}{2^{n+2}}, 0) \in E(G)$  and for  $0 \in Tx_G$ , there exists  $0 \in Sy_G$ , such that  $(0, 0) \in E(G)$ .

Thus, we see that for all  $x_G, y_G \in X_G$  with  $(x_G, y_G) \in E(G)$

$$\psi(H(Sx_G, Ty_G)) \leq \psi(M(x_G, y_G)) - \phi(M(x_G, y_G)) \text{ for all } x_G, y_G \in X_G.$$

Also, for  $u_G \in Sx_G$ , there exists  $v_G \in Ty$  such that  $(u_G, v_G) \in E(G)$  and for  $u_G \in Tx_G$ , there exists  $v_G \in Sy$ , such that  $(u_G, v_G) \in E(G)$ . Hence, the pair  $(S, T) \in (\mathcal{C}, \Psi^*, G)$  with  $F(r, t) = r - \phi(t)$ . Thus, all conditions of Theorem 1 are satisfied, and  $COFIX\{S, T\} = \{0\}$ .

**Remark 1.** Corollary 3 (and hence, Corollary 1 and Theorem 1) are proper extensions and generalisations of Theorem 3.1 of [4] and Theorem 4.2 of [8].

**Remark 2.** Note that in Example 1, the graph  $G$  is a directed graph and not connected, and so Theorem 3.1 of [4] cannot be applied to neither of the mappings  $S$  or  $T$ . Also note that  $(\frac{1}{2^n}, \frac{1}{2^n}) \in E(G), H(S\frac{1}{2^n}, T\frac{1}{2^n}) = \frac{1}{2^{n+2}} > 0 = d_G(\frac{1}{2^n}, \frac{1}{2^n})$  and hence a simple extension of Theorem 3.1 of [4] and Theorem 4.2 of [8] to two mappings cannot be applied. However, we see that the mappings  $S$  and  $T$  satisfy the conditions of Corollary 3, and so Corollary 3 also ensures the existence of a common fixed point of  $S$  and  $T$ .

**Remark 3.** In Theorem 1, if the directed graph  $G$  is replaced with an undirected graph  $G'$  with  $E(G') = E(G) \cup E(G^{-1})$ , then Condition (4.3) in Definition 4 can be replaced with only one inequality:

$$\psi(H(Sx_G, Ty_G)) \leq F(\psi(M(x_G, y_G)), M(x_G, y_G))$$

Similar arguments follow in Corollaries 1–3 also.



**Definition 5.** Let  $f, g : X_G \rightarrow X_G$ . We say that the pair  $(f, g)$  belongs to the class of Jungck type  $(\mathcal{C}, \Psi^*, G)$  contractions if

(5.1)  $f$  is  $g$  – edge preserving in  $G$ .

(5.2) For all  $x_G, y_G \in X_G$  with  $(gx_G, gy_G) \in E(G)$

$$\psi(d_G(fx_G, fy_G)) \leq F(\psi(M(gx_G, gy_G)), M(gx_G, gy_G)), \text{ for some } \psi \in \Psi^*, F \in \mathcal{C} \tag{14}$$

$$M(gx_G, gy_G) = \max\{d_G(gx_G, gy_G), d_G(gx_G, fx_G), d_G(gy_G, fy_G), \frac{d_G(gx_G, fy_G) + d_G(gy_G, fx_G)}{2}\}.$$

Let mappings  $f, g : X_G \rightarrow X_G$  be given. We will make use of the following notations:

- $X_G(f, g) : \{u \in X_G : (gu, fu) \in E(G)\}$ ,
- $C(f, g) : \{u \in X_G : fu = gu\}$  is the set of all coincidence points of mappings  $f$  and  $g$ ,
- $C_m(f, g) : \{u \in X_G : fu = gu = u\}$  is the set of all common fixed points of mappings  $f$  and  $g$ .
- $CS(X, d) : \text{Collection of all Cauchy sequences in the metric space } (X, d)$ .

**Lemma 1.** Let  $f$  and  $g$  satisfy the following:

(1.1)  $x_G, y_G \in C(f, g)$  implies  $gx_G = gy_G$

(2.1)  $(f, g)$  is compatible

Then,  $C_m(f, g) \neq \phi$ .

**Proof.** Let  $x_G \in C(f, g)$  and  $gx_G = w$ . Then, since  $(f, g)$  is compatible,  $gw = ggx_G = gfx_G = fgx_G = fw$ , or in other words,  $w \in C(f, g)$ . By Lemma (1),  $gw = gx_G = w$ , which, in turn, shows that  $w \in C_m(f, g)$ .  $\square$

**Theorem 2.** Let  $d'_G$  and  $d_G$  be any two metrics defined on  $X_G$ , and  $(X_G, d'_G)$  is complete. Suppose  $f, g : X_G \rightarrow X_G$  satisfy the following:

(2.1)  $(f, g) \in \text{Jungck type } (\mathcal{C}, \Psi^*, G)$  with respect to  $d_G$

(2.2)  $g$  is continuous and  $g(X_G)$  is closed with respect to  $d'_G$

(2.3)  $f(X_G) \subseteq g(X_G)$

(2.4)  $E(G)$  satisfies the transitivity property

(2.5) if  $d_G \geq d'_G$ , then  $f : (X_G, d_G) \rightarrow (X_G, d'_G)$  is  $g$  – Cauchy

(2.6)  $f$  is  $G$  – continuous with respect to  $d'_G$ ,  $f$  and  $g$  are  $d'_G$  – compatible.

Then,

$$X_G(f, g) \neq \phi \text{ iff } C(f, g) \neq \phi$$

**Proof.** Suppose that  $C(f, g) \neq \phi$ . Let  $u \in C(f, g)$ . Then,  $(gu, fu) = (gu, gu) \in \Delta \subset E(G)$  and so  $u \in X_G(f, g)$ ; that is,  $X_G(f, g) \neq \phi$ .

Suppose now,  $X_G(f, g) \neq \phi$ . Let  $x_{G0} \in X_G$ , such that  $(gx_{G0}, fx_{G0}) \in E(G)$ . Now, since  $F(X_G) \subseteq g(X_G)$ , using condition (5.1) we can construct sequence  $\{x_{Gn}\}$  in  $X_G$ , such that

$$gx_{Gn} = fx_{Gn-1}, (gx_{Gn-1}, gx_{Gn}) \in E(G)$$

for all  $n \in \mathbb{N}$ . It is easy to see that if  $M(x_{G_m}, x_{G_n}) = 0$  for any  $m, n \in \mathbb{N}$ , then  $x_{G_m}, x_{G_n} \in C(f, g)$  and the proof is done. So we assume that for all  $m, n \in \mathbb{N}$ ,  $M(x_{G_m}, x_{G_n}) \neq 0$ . Then,

$$\begin{aligned} \psi(d_G(gx_{G_{n+1}}, gx_{n+2})) &= \psi(d_G(fx_{G_n}, fx_{G_{n+1}})) \\ &\leq F(\psi(M(gx_{G_n}, gx_{G_{n+1}})), M(gx_{G_n}, gx_{G_{n+1}})) \\ &< \psi(M(gx_{G_n}, gx_{G_{n+1}})) \end{aligned} \tag{15}$$

We also have

$$\begin{aligned} M(gx_{G_n}, gx_{G_{n+1}}) &= \max \left\{ d_G(gx_{G_n}, gx_{G_{n+1}}), d_G(gx_{G_n}, fx_{G_n}), d_G(gx_{G_{n+1}}, fx_{G_{n+1}}), \right. \\ &\quad \left. \frac{d_G(gx_{G_n}, fx_{G_{n+1}}) + d_G(gx_{G_{n+1}}, fx_{G_n})}{2} \right\} \\ &= \max \left\{ d_G(gx_{G_n}, gx_{G_{n+1}}), d_G(gx_{G_{n+1}}, gx_{n+2}), \frac{d_G(gx_{G_n}, gx_{n+2})}{2} \right\} \\ &\leq \max \{ d_G(gx_{G_n}, gx_{G_{n+1}}), d_G(gx_{G_n}, gx_{n+2}) \} \end{aligned}$$

If  $M(gx_{G_n}, gx_{G_{n+1}}) = d_G(gx_{G_{n+1}}, gx_{n+2})$ , then by (15), we obtain that

$$\psi(d_G(gx_{G_{n+1}}, gx_{n+2})) < \psi(d_G(gx_{G_{n+1}}, gx_{n+2}))$$

a contradiction. Hence,

$$M(gx_{G_n}, gx_{G_{n+1}}) = d_G(gx_{G_n}, gx_{G_{n+1}})$$

Substituting in (15), we get  $\psi(d_G(gx_{G_{n+1}}, gx_{n+2})) < \psi(d_G(gx_{G_n}, gx_{G_{n+1}}))$ . So by the definition of  $\psi$ , we have

$$d_G(gx_{G_{n+1}}, gx_{n+2}) \leq d_G(gx_{G_n}, gx_{G_{n+1}}), \quad \forall n \in \mathbb{N}$$

Hence, the sequence  $\{d_G(gx_{G_n}, gx_{G_{n+1}})\}$  is non-negative and non-increasing, and thereby we can find  $r \geq 0$ , such that  $\lim_{n \rightarrow \infty} d_G(gx_{G_n}, gx_{G_{n+1}}) = r$ . We claim that  $r = 0$ . Suppose, on the contrary, that  $r > 0$ . Letting  $n \rightarrow \infty$  in (15), we obtain

$$\psi(r) \leq F(\psi(r), r) < \psi(r)$$

a contradiction. Thus,

$$\lim_{n \rightarrow \infty} d_G(gx_{G_n}, gx_{G_{n+1}}) = 0. \tag{16}$$

We will show that  $\{gx_{G_n}\} \in CS(X_G, d_G)$ . Suppose  $\{gx_{G_n}\} \notin CS(X_G, d_G)$  and for  $\epsilon > 0, k \in \mathbb{N}$ , let  $n(k) \in \mathbb{N}$  be the smallest integer with  $n(k) > m(k) \geq k$  and

$$\begin{aligned} d_G(gx_{G_{n(k)}}, gx_{G_{m(k)}}) &\geq \epsilon \\ d_G(gx_{G_{n(k)-1}}, gx_{G_{m(k)}}) &< \epsilon. \end{aligned}$$

Then, we have

$$\begin{aligned} \epsilon &\leq d_G(gx_{G_{m(k)}}, gx_{G_{n(k)}}) \\ &\leq d_G(gx_{G_{m(k)}}, gx_{G_{n(k)-1}}) + d_G(gx_{G_{n(k)-1}}, gx_{G_{n(k)}}) \\ &< \epsilon + d_G(gx_{G_{n(k)-1}}, gx_{G_{n(k)}}) \end{aligned}$$

Using (16) in the above inequality, we get

$$\lim_{k \rightarrow \infty} d_G(gx_{Gm(k)}, gx_{Gn(k)}) = \epsilon > 0.$$

By condition (2.4) we get  $(gx_{Gm(k)}, gx_{Gn(k)}) \in E(G)$ . Thus, we have

$$\begin{aligned} \psi(d_G(gx_{Gm(k)+1}, gx_{Gn(k)+1})) &= \psi(d_G(fx_{Gm(k)}, fx_{Gn(k)})) \\ &\leq F(\psi(M(gx_{Gm(k)}, gx_{Gn(k)})), M(gx_{Gm(k)}, gx_{Gn(k)})) \end{aligned} \tag{17}$$

where

$$\begin{aligned} M(gx_{Gm(k)}, gx_{Gn(k)}) &= \max \left\{ d_G(gx_{Gm(k)}, gx_{Gn(k)}), d_G(gx_{Gm(k)}, fx_{Gm(k)}), d_G(gx_{Gn(k)}, fx_{Gn(k)}), \right. \\ &\quad \left. \frac{d_G(gx_{Gm(k)}, fx_{Gn(k)}) + d_G(gx_{Gn(k)}, fx_{Gm(k)})}{2} \right\} \\ &= \max \left\{ d_G(gx_{Gm(k)}, gx_{Gn(k)}), d_G(gx_{Gm(k)}, gx_{m(k)+1}), d_G(gx_{Gn(k)}, gx_{n(k)+1}), \right. \\ &\quad \left. \frac{d_G(gx_{Gm(k)}, gx_{Gn(k)+1}) + d_G(gx_{Gn(k)}, gx_{m(k)+1})}{2} \right\} \end{aligned}$$

Letting  $k \rightarrow \infty$ , we obtain

$$\lim_{k \rightarrow \infty} M(gx_{Gm(k)}, gx_{Gn(k)}) = \epsilon$$

By inequality (17), we get

$$\psi(\epsilon) < \psi(\epsilon)$$

a contradiction. So  $\{gx_{Gn}\} \in CS(X_G, d_G)$ .

We will show that  $\{gx_{Gn}\} \in CS(X_G, d'_G)$ . If  $d_G \geq d'_G$ , it is trivial. Thus, suppose  $d_G < d'_G$ . Let  $\epsilon > 0$ . Since  $\{gx_{Gn} \in CS(X_G, d_G)\}$ , by condition (2.5) we see that  $\{fx_{Gn}\} \in CS(X_G, d'_G)$ . Then, there exists  $N_0 \in \mathbb{N}$  with

$$d'_G(gx_{Gn+1}, gx_{m+1}) = d'_G(fx_{Gn}, fx_m) < \epsilon$$

whenever  $n, m \geq N_0$ . So  $\{gx_{Gn}\} \in CS(X_G, d'_G)$ .

Since  $g(X_G)$  is  $d'_G$ -closed and  $(X_G, d'_G)$  is complete, there exists  $u_G = gx_G \in g(X_G)$ , such that

$$\lim_{n \rightarrow \infty} gx_{Gn} = \lim_{n \rightarrow \infty} fx_{Gn} = u_G.$$

By  $d'_G$ -compatibility of  $f$  and  $g$ , we have

$$\lim_{n \rightarrow \infty} d'_G(gfx_{Gn}, fgx_{Gn}) = 0 \tag{18}$$

Then,

$$d'_G(gu_G, fu_G) \leq d'_G(gu_G, gfx_{Gn}) + d'_G(gfx_{Gn}, fgx_{Gn}) + d'_G(fgx_{Gn}, fu_G)$$

Letting  $n \rightarrow \infty$  and using (18), the continuity of  $g$ , and the  $G$ -continuity of  $f$ , it follows that  $d'_G(gu_G, fu_G) = 0$ , which implies that  $gu_G = fu_G$ . So  $u_G \in C(f, g)$  and the proof is complete.  $\square$

If  $d_G = d'_G$ , we have the following

**Theorem 3.** Let  $(X_G, d_G)$  be complete and  $f, g : X_G \rightarrow X_G$  satisfy the following:

- (3.1)  $(f, g) \in \text{Jungck type } (C, \Psi^*, G)$
- (3.2)  $g$  is continuous and  $g(X_G)$  is closed
- (3.3)  $F(X_G) \subset g(X_G)$
- (3.4)  $E(G)$  satisfies the transitivity property
- (3.5) (a)  $f$  is  $G$ -continuous and  $f$  and  $g$  are  $d_G$ -compatible or  
 (b)  $(X_G, d_G, G)$  has property A.

Then,

$$X_G(f, g) \neq \phi \text{ iff } C(f, g) \neq \phi.$$

**Proof.** Proceeding as in the proof of Theorem 2, we see that if  $C(f, g) \neq \phi$  then  $X_G(f, g) \neq \phi$  and if  $X_G(f, g) \neq \phi$  then  $\{gx_{Gn}\} \in CS(X_G, d_G)$ . Now since  $g(X_G)$  is closed in  $X_G$ , there exists  $u_G \in X_G$ , such that

$$\lim_{n \rightarrow \infty} gx_{Gn} = gu_G = \lim_{n \rightarrow \infty} fx_{Gn}. \tag{19}$$

We will show that  $u_G \in C(f, g)$ . Suppose  $u_G \notin C(f, g)$ . Then  $d_G(fu_G, gu_G) > 0$ . Note that if  $M(x_{Gm}, u_G) = 0$  for any  $m \in \mathbb{N}$ , then  $x_{Gm}, u_G \in C(f, g)$  and the proof is done. So we assume that for all  $m \in \mathbb{N}$ ,  $M(x_{Gm}, u_G) \neq 0$ . If condition (3.5a) is satisfied, then proof follows from a similar argument as in Theorem 2. If condition (3.5b) is satisfied, then  $(gx_{Gn}, gu) \in E(G)$  for each  $n \in \mathbb{N}$ . Thus, we have

$$d_G(gu_G fu_G) \leq d_G(gu_G, fx_{Gn(k)}) + d_G(fx_{Gn(k)}, fu_G)$$

which implies that

$$d_G(gu_G, fu_G) - d_G(gu_G, fx_{Gn(k)}) \leq d_G(fx_{Gn(k)}, fu_G)$$

Since  $\psi$  is non-decreasing, we get

$$\begin{aligned} \psi(d_G(gu_G, fu_G) - d_G(gu_G, fx_{Gn(k)})) &\leq \psi(d_G(fx_{Gn(k)}, fu_G)) \\ &\leq F(\psi(M(gx_{Gn(k)}, gu_G)), M(gx_{Gn(k)}, gu_G)) \end{aligned} \tag{20}$$

where

$$M(gx_{Gn(k)}, gu_G) = \max \left\{ d_G(gx_{Gn(k)}, gu_G), d_G(gx_{Gn(k)}, fx_{Gn(k)}), d_G(gu_G, fu_G), \frac{d_G(gx_{Gn(k)}, fu_G) + d_G(gu_G, fx_{Gn(k)})}{2} \right\}$$

Using (19), we obtain

$$\lim_{k \rightarrow \infty} M(gx_{Gn(k)}, gu_G) = d_G(gu_G, fu_G) > 0.$$

Thus, taking  $k \rightarrow \infty$  in (20), we get  $\psi(d_G(gu_G, fu_G)) < \psi(d_G(gu_G, fu_G))$ , a contradiction. Therefore,  $fu_G = gu_G$  and so  $C(f, g) \neq \phi$ .  $\square$

**Theorem 4.** Suppose  $f$  and  $g$  satisfy condition (2.1)–(2.6), condition (2.6) and the following:

- (4.1) If  $x_G, y_G \in C(f, g)$  and  $gx_G \neq gy_G$ , then  $(gx_G, gy_G) \in E(G)$ .  
 If  $X_G(f, g) \neq \phi$ , then  $C_m(f, g) \neq \phi$ .

**Proof.** By Theorem 2  $C(f, g) \neq \phi$ . Let  $x_G, y_G \in C(f, g)$  and suppose  $gx_G \neq gy_G$  so that  $M(gx_G, gy_G) \neq 0$ . By assumption (K),  $(gx_G, gy_G) \in E(G)$ , and we have

$$\begin{aligned} \psi(d_G(fx_G, fy_G)) &\leq F(\psi(M(gx_G, gy_G)), M(gx_G, gy_G)) \\ &< \psi(M(gx_G, gy_G)) \\ &= \psi(d_G(fx_G, fy_G)) \end{aligned} \tag{21}$$

which is a contradiction. Therefore,  $gx_G = gy_G$ . Now by Lemma 1,  $C_m(f, g) \neq \phi$ .  $\square$

**Corollary 6.** Let  $d'_G$  and  $d_G$  be any two metrics defined on  $X_G$ , and  $(X_G, d'_G)$  is complete. Suppose  $f, g : X_G \rightarrow X_G$  satisfy conditions (5.1) and Theorem (2.1) to Theorem (2.5), and the following: for some  $\psi \in \Psi^*$ ,  $\phi \in \Phi^*$  and all  $x_G, y_G \in X_G$  with  $(gx_G, gy_G) \in E(G)$

$$\psi(d_G(fx_G, fy_G)) \leq \psi(M(gx_G, gy_G)) - \phi(M(gx_G, gy_G)) \tag{22}$$

Then,

$$X_G(f, g) \neq \phi \text{ iff } C(f, g) \neq \phi$$

**Corollary 7.** Let  $d'_G$  and  $d_G$  be any two metrics defined on  $X_G$  and  $(X_G, d'_G)$  is complete. Suppose  $f, g : X_G \rightarrow X_G$  satisfy conditions (5.1) and condition (2.1) to condition (2.5) and the following: for some  $\psi \in \Psi^*$ ,  $\theta \in \Theta^*$  and all  $x_G, y_G \in X_G$  with  $(gx_G, gy_G) \in E(G)$

$$\psi(d_G(fx_G, fy_G)) \leq \theta(M(gx_G, gy_G))\psi(M(gx_G, gy_G)) \tag{23}$$

Then,

$$X_G(f, g) \neq \phi \text{ iff } C(f, g) \neq \phi$$

Let  $X_G = [0, \infty)$  and  $d_G, d'_G : X_G \times X_G \rightarrow [0, \infty)$  be defined by

$$d_G(x_G, y_G) = \begin{cases} 0 & \text{if } x_G = y_G \\ \max \{x_G, y_G\} & \text{otherwise} \end{cases} \quad d'_G(x_G, y_G) = |x_G - y_G| \tag{24}$$

Then clearly,  $d_G \geq d'_G$ . We define

$$E(G) = \{(x_G, y_G) : x_G = y_G \text{ or } x_G, y_G \in [0, \frac{1}{2}] \text{ with } x_G \leq y_G\}$$

Consider the mappings  $f : X_G \rightarrow X_G$  and  $g : X_G \rightarrow X_G$ , defined by

$$fx_G = \begin{cases} 4x_G^4, & \text{if } 0 \leq x_G \leq \frac{1}{2} \\ 2x_G^2, & \text{if } x_G > \frac{1}{2} \end{cases} \quad gx_G = \begin{cases} 2x_G^2, & \text{if } 0 \leq x_G \leq \frac{1}{2} \\ 8x_G^4, & \text{if } x_G > \frac{1}{2} \end{cases} \tag{25}$$

for all  $x_G \in X_G$ .

Let  $\psi : [0, \infty) \rightarrow [0, \infty)$  be defined by

$$\psi(t) = 2t$$

and  $\theta : [0, \infty) \rightarrow [0, 1)$  be defined by

$$\theta(t) = \begin{cases} t, & \text{if } 0 \leq t \leq \frac{1}{2} \\ \frac{1}{2t+1}, & t > \frac{1}{2} \end{cases}$$

and  $F \in \mathcal{C}$  be given by

$$F(r, t) = \theta(t).r$$

We will show that the pair  $(f, g)$  is a  $(F, \psi, G)$  contraction.

Let  $(gx_G, gy_G) \in E(G)$ . If  $gx_G = gy_G$  (which is possible only if  $x_G = y_G = 0$ ), then  $fx_G = gy_G = 0$  and so  $(fx_G, fy_G) \in E(G)$ . If  $(gx_G, gy_G) \in E(G)$  with  $gx_G, gy_G \in [0, \frac{1}{2}]$  and  $gx_G \leq gy_G$ , then we obtain  $x_G, y_G \in [0, \frac{1}{2}]$ ,  $x_G \leq y_G$  and then  $x_G^4, y_G^4 \in [0, \frac{1}{2}]$ ,  $fx_G = 4x_G^4 \leq 4y_G^4 = fy_G$ , and thus  $(fx_G, fy_G) \in E(G)$ . Thus, the pair  $(f, g)$  is  $g$ -edge preserving in  $G$ . Now, let  $x_G, y_G \in X_G$  and  $(gx_G, gy_G) \in E(G)$ . From the argument given above, if  $gx_G = gy_G$ , then  $\psi(d_G(fx_G, fy_G)) = 0$  and  $(f, g)$  satisfy the condition condition (5.2). If  $(gx_G, gy_G) \in E(G)$  with  $gx_G, gy_G \in [0, \frac{1}{2}]$  and  $gx_G \leq gy_G$ , then

$$\begin{aligned} \psi(d_G(fx_G, fy_G)) &= 8y_G^4 \\ &\leq 2y_G^2 \\ &\leq y_G \cdot 2y_G \\ &\leq \max\{x_G, y_G\} \cdot 2 \max\{x_G, y_G\} \\ &= \theta(d_G(x_G, y_G)) \psi(d_G(x_G, y_G)) \\ &\leq \theta(M(gx_G, gy_G)) \psi(M(gx_G, gy_G)) \end{aligned}$$

and so  $(f, g)$  satisfy the condition condition (5.1).

We will show that  $g$  and  $f$  are  $d'$ -compatible. Let  $\{x_{Gn}\}$  be a sequence in  $X_G$ , such that

$$\lim_{n \rightarrow \infty} gx_{Gn} = \lim_{n \rightarrow \infty} fx_{Gn} = u$$

Note that

$$d'(gfx_{Gn}, fgx_{Gn}) = 32x_{GN}^8 \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Clearly,  $f : (X_G, d) \rightarrow (X_G, d')$  is  $G$ -continuous, and consequently, all the conditions of Theorem 2 are satisfied. Also note that  $0, \frac{1}{2} \in C(f, g)$ ,  $g0 \neq g(\frac{1}{2})$ , and  $(g0, g(\frac{1}{2})) \in E(G)$ , and thus condition Theorem (4.1) of Theorem 4 is satisfied. Consequently,  $\{0, \frac{1}{2}\} \subset X_G(f, g) \cap C(f, g) \cap C_m(f, g)$ .

### 3. Applications

In this section, as an application of our results, we will give some fixed point results for a pair of set valued  $\alpha$ -admissible contraction mappings in a metric space. Throughout this section,  $(X, d)$  is any metric space,  $S, T : X \rightarrow CB(X)$  two given mappings, and  $\alpha : X \times X \rightarrow [0, \infty)$ .

**Definition 6.** We say that the pair  $(S, T)$  is  $\alpha$ -admissible if, and only if for all  $x, y \in X$  with  $\alpha(x, y) \geq 1$ , the following conditions hold:

- (6.1) For  $u \in Sx$ , there exists  $v \in Ty$ , such that  $\alpha(u, v) \geq 1$ .
- (6.2) For  $u \in Tx$ , there exists  $v \in Sy$ , such that  $\alpha(u, v) \geq 1$ .

**Theorem 5.** Suppose the following conditions hold:

- (5.1) There exists  $x_0, x_1 \in X$  such that  $x_1 \in Tx_0 \cup Sx_0$  and  $\alpha(x_0, x_1) \geq 1$ ,
- (5.2)  $\alpha$  is a triangular function,
- (5.3) The pair  $(S, T)$  is  $\alpha$ -admissible,
- (5.4) there exists  $F \in \mathcal{C}$ ,  $\psi \in \Psi^*$ , such that for all  $x, y \in X$  with  $\alpha(x, y) \geq 1$

$$\begin{aligned} \psi(H(Sx, Ty)) &\leq F(\psi(M(x, y)), M(x, y)) \text{ and} \\ \psi(H(Tx, Sy)) &\leq F(\psi(M(x, y)), M(x, y)) \end{aligned}$$

where

$$M(x, y) = \max \left\{ d(x, y), d(Sx, x), d_G(Ty, y), \frac{d(y, Sx) + d(x, Ty)}{2} \right\}$$

Then  $\text{COFIX}\{S, T\}$  is a singleton set.

**Proof.** Consider the graph  $G$  on  $(X, d)$ , defined by  $V(G) = X$  and  $E(G) = (x, y) \in X \times X : \alpha(x, y) \geq 1$ . It is easy to see that the functions  $S$  and  $T$  satisfy all conditions of Theorem 1, and hence,  $\text{COFIX}\{S, T\}$  is a singleton set.  $\square$

Similarly, we have the following results:

**Theorem 6.** Suppose conditions Theorem (5.1), Theorem (6.1), Theorem (6.3), and the following hold:

- (6.1) for all  $x, y \in X$  with  $\alpha(x, y) \geq 1$
- $$\begin{aligned} \psi(H(Sx, Ty)) &\leq \psi(M(x, y)) - \phi(M(x, y)) \text{ and} \\ \psi(H(Tx, Sy)) &\leq \psi(M(x, y)) - \phi(M(x, y)) \end{aligned}$$

where  $\psi \in \Psi^*$ ,  $\phi \in \Phi^*$  and  $M(x, y)$  is as in Theorem 5. Then  $\text{COFIX}\{S, T\} \neq \emptyset$ .

**Theorem 7.** Suppose conditions Theorem (5.1), Theorem (6.1), Theorem (5.3), and the following hold:

- (7.1) for all  $x, y \in X$  with  $\alpha(x, y) \geq 1$
- $$\begin{aligned} \psi(H(Sx, Ty)) &\leq \theta(M(x, y))\psi(M(x, y)) \text{ and} \\ \psi(H(Tx, Sy)) &\leq \theta(M(x, y))\psi(M(x, y)) \end{aligned}$$

where  $\psi \in \Psi^*$ ,  $\phi \in \Phi^*$  and  $M(x, y)$  is as in Theorem 5. Then,  $\text{COFIX}\{S, T\} \neq \emptyset$ .

**Example 2.** Let  $X_G = [0, \infty) \subseteq \mathbb{R}$ , and let the metrics  $d_G, d'_G : X_G \times X_G \rightarrow [0, \infty)$  be defined by

$$\begin{aligned} d_G(x_G, y_G) &= \max \{x_G, y_G\} \\ d'_G(x_G, y_G) &= L|x_G - y_G| \end{aligned} \tag{26}$$

for all  $x_G, y_G \in X_G$ , respectively, where  $L$  is a constant real number, such that  $L \in (1, \infty)$ . It is easy to see that  $d < d'$ . Now,  $E(G)$  is given by

$$E(G) = \{(x_G, y_G) : x_G = y_G \text{ or } x_G, y_G \in [0, 1] \text{ with } x_G \leq y_G\} \tag{27}$$

Consider the mappings  $f : X_G \rightarrow X_G$  and  $g : X_G \rightarrow X_G$  defined by

$$fx = \ln \left( 1 + \frac{x_G^2}{2} \right), \quad gx = x_G^2 \tag{28}$$

for all  $x_G \in X_G$ , respectively.

Let  $\psi, \phi : [0, \infty) \rightarrow [0, \infty)$  be defined by

$$\psi(t) = \begin{cases} t, & \text{if } 0 \leq t \leq 1 \\ t^2, & \text{if } t > 1 \end{cases} \tag{29}$$

$$\phi(t) = \begin{cases} \frac{t^2}{2}, & \text{if } 0 \leq t \leq 2 \\ \frac{1}{2}, & \text{otherwise } t > 1 \end{cases} \tag{30}$$

Next, let  $(gx, gy) \in E(G)$  if  $x_G = y_G$ . Then,  $(fx, fy) \in E(G)$ , and if  $(gx, gy) \in E(G)$  with  $gx \leq gy$ , then we obtain  $gx = x_G^2, gy = y_G^2 \in [0, 1]$  and  $x_G^2 = gx \leq gy = y_G^2$ , and we have  $fx = \ln(1 + \frac{x_G^2}{2}) \leq \ln(1 + \frac{y_G^2}{2}) = fy$  and  $fx_G, fy \in [0, 1]$ . This implies that  $(fx_G, fy) \in E(G)$ .

Since  $d < d'$ , we need to prove that the function  $f : (X_G, d) \rightarrow (X_G, d')$  is a  $g$ -Cauchy sequence in  $X_G$ . Let  $\epsilon > 0$ , and let  $\{x_{G_n}\}$  be a sequence in  $X_G$  such that  $\{gx_{G_n}\}$  is a Cauchy sequence in  $(X_G, d)$ . Then, there exists  $k \in \mathbb{N}$ , such that for all  $n, m \geq k, d_G(gx_{G_n}, gx_m) < \frac{\epsilon}{L}$ . Then, we have

$$\begin{aligned} d'(fx_{G_n}, fx_m) &= L|fx_{G_n} - fx_m| \\ &= L \left| \ln \left( 1 + \frac{(x_{G_n})^2}{2} \right) - \ln \left( 1 + \frac{(x_m)^2}{2} \right) \right| \\ &= L \left| \ln \frac{1 + \frac{(x_m)^2}{2}}{1 + \frac{(x_{G_n})^2}{2}} \right| \\ &= L \left| \ln \left( 1 + \frac{\frac{(x_m)^2}{2} - \frac{(x_{G_n})^2}{2}}{1 + \frac{(x_{G_n})^2}{2}} \right) \right| \\ &\leq L \left[ \ln \left( 1 + \left| \frac{(x_{G_n})^2}{2} - \frac{(x_m)^2}{2} \right| \right) \right] \\ &\leq L \left[ \frac{2 \ln(1 + \frac{1}{2} |(x_{G_n})^2 - (x_m)^2|)}{|(x_{G_n})^2 - (x_m)^2|} |(x_{G_n})^2 - (x_m)^2| \right] \\ &< L|(x_{G_n})^2 - (x_m)^2| \\ &= Ld_G(gx_{G_n}, gx_m) \\ &< L \cdot \frac{\epsilon}{L} = \epsilon. \end{aligned}$$

This implies that  $f : (X_G, d) \rightarrow (X_G, d')$  is a  $g$ -Cauchy on  $X_G$ . It can easily be shown that  $f : (X_G, d) \rightarrow (X_G, d')$  is  $G$ -continuous. As a result, we will only need to prove that  $g$  and  $f$  are  $d'$ -compatible. Let  $\{x_{G_n}\}$  be a sequence in  $X_G$ , such that

$$\lim_{n \rightarrow \infty} gx_{G_n} = \lim_{n \rightarrow \infty} fx_{G_n} = u \tag{31}$$

Then, we have  $\ln(1 + u/2) = a$  and so it follows that  $u = 0$ . Now, we have

$$d'(gfx_{G_n}, fgx_{G_n}) = L \left| \ln \left( 1 + \frac{(x_{G_n})^2}{2} \right)^2 - \ln \left( 1 + \frac{(x_{G_n})^4}{2} \right) \right| \rightarrow 0 \tag{32}$$



as  $n \rightarrow \infty$ . It is easy to see that there exists a point  $u \in X_G$ , such that  $(gu, fu) \in E(G)$ , and thus  $X_G(f, g) \neq \phi$ . Consequently, all the conditions of Theorem 2 are satisfied.

**Example 3.** Let  $X_G = [0, \infty) \subseteq \mathbb{R}$  and let the metrics  $d_G, d'_G : X_G \times X_G \rightarrow [0, \infty)$  be defined by

$$\begin{aligned} d_G(x_G, y_G) &= \max \{x_G, y_G\} \\ d'_G(x_G, y_G) &= L \cdot \max \{x_G, y_G\} \end{aligned} \tag{33}$$

for all  $x_G, y_G \in X_G$  and some  $L \in (1, \infty)$ . Then clearly,  $d_G < d'_G$ . We define

$$E(G) = \{(x_G, y_G) : x_G = y_G \text{ or } x_G, y_G \in [0, 1] \text{ with } x_G \leq y_G\}$$

Consider the mappings  $f : X_G \rightarrow X_G$  and  $g : X_G \rightarrow X_G$  defined by

$$fx_G = \begin{cases} x_G^4, & \text{if } 0 \leq x_G \leq 1 \\ x_G^2, & \text{if } x_G > 1 \end{cases} \quad gx_G = \begin{cases} 2x_G^2, & \text{if } 0 \leq x_G \leq 1 \\ 2x_G^4, & \text{if } x_G > 1 \end{cases} \tag{34}$$

for all  $x_G \in X_G$ .

Let  $\psi : [0, \infty) \rightarrow [0, \infty)$  be defined by

$$\psi(t) = 2t$$

and,  $\theta : [0, \infty) \rightarrow [0, 1)$  be defined by

$$\theta(t) = \begin{cases} t, & \text{if } 0 \leq t < 1 \\ \frac{1}{t+1}, & \text{if } t \geq 1 \end{cases}$$

Next, if  $(gx_G, gy_G) \in E(G)$  and  $x_G = y_G$  then  $(fx_G, fy_G) \in E(G)$  and if  $(gx_G, gy_G) \in E(G)$  with  $gx_G \leq gy_G$ , then we obtain  $x_G, y_G \in [0, \frac{1}{\sqrt{2}}]$ ,  $x_G \leq y_G$  and then  $x_G^4, y_G^4 \in [0, \frac{1}{4}]$ ,  $fx_G = x_G^4 \leq y_G^4 = fy_G$ , and thus  $(fx_G, fy) \in E(G)$ .

Since  $d_G < d'_G$ , we need to prove that the function  $f : (X_G, d) \rightarrow (X_G, d')$  is a  $g$ -Cauchy sequence in  $X_G$ . Let  $\epsilon > 0$ , and let  $\{x_{G_n}\}$  be a sequence in  $X_G$  such that  $\{gx_{G_n}\}$  is a Cauchy sequence in  $(X_G, d)$ . Then, there exists  $k \in \mathbb{N}$  such that, for all  $n, m \geq k$ ,  $d_G(gx_{G_n}, gx_{G_m}) < \frac{\epsilon}{L}$ . Then, we have

$$d'_G(fx_{G_n}, fx_{G_m}) = L \max \{fx_{G_n}, fx_{G_m}\}$$

We will consider the following cases:

Case 1 :  $x_{G_n}, x_{G_m} \in [0, 1]$ . Then, we have

$$\begin{aligned} d'_G(fx_{G_n}, fx_m) &= L \max \{x_{G_n}^4, x_{G_m}^4\} \leq L \max \{2x_{G_n}^2, 2x_{G_m}^2\} \\ &= L \max \{gx_{G_n}, gx_{G_m}\} = L \cdot d_G(gx_{G_n}, gx_{G_m}) < L \cdot \frac{\epsilon}{L} = \epsilon \end{aligned}$$

Case 2 :  $x_{G_n}, x_{G_m} \in (0, \infty)$ . Then, we have

$$\begin{aligned} d'_G(fx_{G_n}, fx_m) &= L \max \{x_{G_n}^2, x_{G_m}^2\} \leq L \max \{2x_{G_n}^4, 2x_{G_m}^4\} \\ &= L \max \{gx_{G_n}, gx_{G_m}\} = L \cdot d_G(gx_{G_n}, gx_{G_m}) < L \cdot \frac{\epsilon}{L} = \epsilon \end{aligned}$$

Case 3 :  $x_{G_n} \in [0, 1], x_{G_m} \in (1, \infty)$ . Then, we have

$$\begin{aligned} d'_G(fx_{G_n}, fx_m) &= L \max \{x_{G_n}^4, x_{G_m}^2\} \leq L \max \{2x_{G_n}^2, 2x_{G_m}^4\} \\ &= L \max \{gx_{G_n}, gx_{G_m}\} = L.d_G(gx_{G_n}, gx_{G_m}) < L \cdot \frac{\epsilon}{L} = \epsilon \end{aligned}$$

Case 1 :  $x_{G_n} \in (0, \infty), x_{G_m} \in [0, 1]$ . Then, we have

$$\begin{aligned} d'_G(fx_{G_n}, fx_m) &= L \max \{x_{G_n}^2, x_{G_m}^4\} \leq L \max \{2x_{G_n}^4, 2x_{G_m}^2\} \\ &= L \max \{gx_{G_n}, gx_{G_m}\} = L.d_G(gx_{G_n}, gx_{G_m}) < L \cdot \frac{\epsilon}{L} = \epsilon \end{aligned}$$

Thus,  $f : (X_G, d) \rightarrow (X_G, d')$  is a  $g$ -Cauchy on  $X_G$ .

It can be easily shown that  $f : (X_G, d) \rightarrow (X_G, d')$  is  $G$ -continuous. We will show that  $g$  and  $f$  are  $d'$  compatible. Let  $\{x_{G_n}\}$  be a sequence in  $X_G$ , such that

$$\lim_{n \rightarrow \infty} gx_{G_n} = \lim_{n \rightarrow \infty} fx_{G_n} = u$$

Then, we have  $\ln(1 + u/2) = a$ , and so it follows that  $u = 0$ . Now, we have

$$d'(gfx_{G_n}, fgx_{G_n}) = L \left| \ln \left( 1 + \frac{(x_{G_n})^2}{2} \right)^2 - \ln \left( 1 + \frac{(x_{G_n})^4}{2} \right)^2 \right| \rightarrow 0 \tag{35}$$

as  $n \rightarrow \infty$ . It is easy to see that there exists a point  $u \in X_G$  such that  $(gu, fu) \in E(G)$ , and thus  $X_G(f, g) \neq \phi$ . Consequently, all the conditions of Theorem 2 are satisfied.

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