

Article Transient Gel Electrophoresis of a Spherical Colloidal Particle

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Abstract: The general theory is developed for the time-dependent transient electrophoresis of a weakly charged spherical colloidal particle with an electrical double layer of arbitrary thickness in an uncharged or charged polymer gel medium. The Laplace transform of the transient electrophoretic mobility of the particle with respect to time is derived by considering the long-range hydrodynamic interaction between the particle and the polymer gel medium on the basis of the Brinkman–Debye–Bueche model. According to the obtained Laplace transform of the particle's transient electrophoretic mobility, the transient gel electrophoretic mobility approaches the steady gel electrophoretic mobility as time approaches infinity. The present theory of the transient gel electrophoresis also covers the transient free-solution electrophoresis as its limiting case. It is shown that the relaxation time for the transient gel electrophoretic mobility and becomes shorter as the Brinkman screening length decreases. Some limiting or approximate expressions are derived for the Laplace transform of the transient gel electrophoretic mobility.

Keywords: transient gel electrophoresis; transient electrophoresis; gel electrophoresis

1. Introduction

When an external electric field is suddenly applied to a suspension of colloidal particles, the particle starts to move with a time-dependent transient electrophoretic mobility, which reaches steady electrophoretic mobility as time goes to infinity. While there are many theoretical studies on transient free-solution electrokinetics [1–17], including transient electrophoresis of spherical hard particles [1,4,6,7,9,13,14,17], cylindrical hard particles [2,11,16] and soft particles (i.e., polyelectrolyte-coated particles) [12,15], and on steady gel electrophoresis [18–39] including gel electrophoresis of spherical hard particles [18–25,28,30–32,34,35], soft particles [26,27,29,33,36–38] and liquid droplets [39], there are only a few theoretical studies on the transient gel electrophoresis by Saad and Faltas [40], Saad [41,42], and Sherief, et al., [43]. In the present paper, we further develop the theory of Saad and Faltus [40] and present the general theory of transient gel electrophoresis of a weakly charged, spherical solid colloidal particle with an electrical double layer of arbitrary thickness. There are two types of interactions between the particle and the gel medium: (i) the short-range steric interaction due to the particle-gel friction, and (ii) the long-range hydrodynamic interaction. For dilute gels, where the particle size is much smaller than the gel pore size, the long-range hydrodynamic interaction becomes dominant. In this paper, we treat a dilute gel medium and consider the long-range hydrodynamic interaction between the particle and the polymer gel medium on the basis of the Brinkman–Debye– Bueche model [44,45] and derive an expression for the Laplace transform of the transient electrophoretic mobility of a spherical solid colloidal particle. From the obtained Laplace transform of the transient gel electrophoretic mobility, the transient gel electrophoretic mobility can be derived numerically by using the inverse Laplace transformation.



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2. Theory

2.1. Fundamental Electrokinetic Equations

Consider a charged spherical colloidal particle of radius *a* and relative permittivity ε_{p} , carrying zeta potential ζ in a charged polymer gel medium containing an electrolyte solution of viscosity η and relative permittivity ε_{r} . The Brinkman–Debye–Bueche continuum medium [44,45] is employed, in which polymer segments are considered to be resistance centers, exerting frictional forces on the liquid flowing through the gel medium. The gel medium is regarded as a uniform continuum medium, which contains fixed charges of density ρ_{fix} , free mobile electrolyte ions of density $\rho_{el}(r)$ at position r, including added electrolyte ions and gel counterions. Let the electrolyte be composed of N ionic species of valence z_i , bulk concentration (number density) n_i^{∞} and drag coefficient Λ_i (i = 1, 2, ..., N), and the gel counterions be of N + 1-th ionic species of valence z_{N+1} , bulk concentration (number density) n_{N+1}^{∞} and drag coefficient Λ_{N+1} . The electroneutrality condition of the system is given by

$$\sum_{i=1}^{N+1} z_i e n_i^{\infty} + \rho_{\text{fix}} = 0 \tag{1}$$

where *e* is the elementary electric charge.

We suppose that at time t = 0, a step electric field E(t) is suddenly applied to the particle, viz.,

$$E(t) = \begin{cases} 0, & t = 0 \\ E_0, & t > 0 \end{cases}$$
(2)

where E_o is a constant. The particle then starts to migrate with an electrophoretic velocity $U(t) (U(t)\cos\theta, -U(t)\sin\theta, 0)$ in the direction parallel to E_o , U(t) being the magnitude of U(t) (Figure 1).



Figure 1. Spherical colloidal particle of radius *a* and zeta potential ζ moving with transient electrophoretic velocity U(t) in a polymer gel medium under an applied step electric field E(t). $U(\infty)$ is the magnitude of the static electrophoretic velocity at $t = \infty$.

Our model uses a frame of reference fixed at the center of the particle. The origin of the coordinate system (r, θ , ϕ) is held fixed at the particle center, and the polar axis ($\theta = 0$) is set parallel to E(t). The transient electrophoretic mobility $\mu(t)$ of the particle is defined by $U(t) = \mu(t)E(t) = \mu(t)E_0$. Our model treats the case in which the following conditions are fulfilled: (i) the liquid in the gel medium can be considered to be incompressible; (ii) the applied electric field E(t) is so weak that the particle velocity U(t) is proportional to E(t), and terms involving the square of the liquid velocity in the Navier–Stokes equation can be neglected in our model; (iii) the slipping plane, at which the liquid velocity u(r, t) relative to the particle is zero, is located on the particle surface (at r = a); (iv) electrolyte ions cannot penetrate the particle surface [46]; and (v) in equilibrium (in the absence of E(t)), the ion

distribution is assumed to be given by the Boltzmann distribution and the electric potential follows the Poisson–Boltzmann equation.

Under these conditions (i)–(v), the fundamental electrokinetic equations for the liquid flow velocity $u(\mathbf{r}, t)$ ($u_r(\mathbf{r}, t)$, $u_{\theta}(\mathbf{r}, t)$, 0) at position $\mathbf{r}(\mathbf{r}, \theta, \phi)$ and time t and the velocity $v_i(\mathbf{r}, t)$ of i th ionic species are given by.

$$\rho_{\rm o} \frac{\sigma}{\partial t} \{ \boldsymbol{u}(\boldsymbol{r},t) + \boldsymbol{U}(t) \} + \eta \nabla \times \nabla \times \boldsymbol{u}(\boldsymbol{r},t) + \nabla p(\boldsymbol{r},t) + \rho_{\rm el}(\boldsymbol{r},t) \nabla \psi(\boldsymbol{r},t) + \gamma(\boldsymbol{u}(\boldsymbol{r},t) + \boldsymbol{U}(t)) = \boldsymbol{0}$$
(3)

$$\nabla \cdot \boldsymbol{u}(\boldsymbol{r},t) = 0 \tag{4}$$

$$\boldsymbol{v}_i(\boldsymbol{r},t) = \boldsymbol{u}(\boldsymbol{r},t) - \frac{1}{\Lambda_i} \nabla \mu_i(\boldsymbol{r},t)$$
(5)

$$\frac{\partial n_i(\mathbf{r},t)}{\partial t} + \nabla \cdot \{n_i(\mathbf{r},t)\mathbf{v}_i(\mathbf{r},t)\} = 0$$
(6)

with

$$\rho_{\rm el}(\mathbf{r},t) = \sum_{i=1}^{N+1} z_i n_i(\mathbf{r},t) \tag{7}$$

$$\mu_i(\mathbf{r},t) = \mu_i^{\rm o} + z_i e \psi(\mathbf{r},t) + k T \ln[n_i(\mathbf{r},t)]$$
(8)

$$\Delta \psi(\mathbf{r}, t) = -\frac{\rho_{\rm el}(\mathbf{r}, t)}{\varepsilon_{\rm r} \varepsilon_{\rm o}}$$
⁽⁹⁾

where *k* is the Boltzmann constant, *T* is the absolute temperature, ε_0 is the permittivity of a vacuum, $p(\mathbf{r}, t)$ is the pressure, $\rho_{el}(\mathbf{r}, t)$ is the charge density and $\psi(\mathbf{r}, t)$ is the electric potential. Equation (3) is the Navier–Stokes equation, and Equation (4) is the equation of continuity for an incompressible flow (condition (i)). The term involving \mathbf{U} (*t*) in Equation (3) arises from the fact that the particle has been chosen as the frame of reference for the coordinate system. Equation (5) means that the flow $v_i(\mathbf{r}, t)$ of the *i* th ionic species is caused by $u(\mathbf{r}, t)$, and the gradient of the electrochemical potential $\mu_i(\mathbf{r}, t)$, given by Equation (8), in which μ_i^0 is a constant term. Equation (6) is the continuity equation for the *i* th ionic species. Equation (9) is the Poisson equation. Note that in the absence of the particle, there exists a time-dependent transient electroosmotic flow, which is parallel to E(t). The transient electroosmotic flow velocity $\mathbf{u}_{EOF}(t) = (u_{EOF}(t)\cos\theta, -u_{EOF}(t)\sin\theta, 0)$ obeys

$$\rho_{\rm o}\frac{\partial}{\partial t}\boldsymbol{u}_{\rm EOF}(t) + \rho_{\rm fix}\boldsymbol{E}(t) + \gamma\boldsymbol{u}_{\rm EOF}(t) = \boldsymbol{0}$$
(10)

where $u_{\text{EOF}}(t)$ is the magnitude of $u_{\text{EOF}}(t)$.

The following initial condition and boundary conditions at the particle surface (at r = a) and far from the particle ($r \rightarrow \infty$) must be satisfied:

$$u(r,t) = 0$$
 at $t = 0$ (11)

$$\boldsymbol{u}(\boldsymbol{r},t) = \boldsymbol{0} \text{ at } \boldsymbol{r} = \boldsymbol{a} \tag{12}$$

$$\boldsymbol{u}(\boldsymbol{r},t) \to -\boldsymbol{U}(\boldsymbol{t}) + \boldsymbol{u}_{\text{EOF}}(t) \text{ at as } \boldsymbol{r} \to \infty$$
 (13)

$$\boldsymbol{v}_i(\boldsymbol{r}, \boldsymbol{t}) \cdot \hat{\boldsymbol{n}} = 0 \text{ at } \boldsymbol{r} = \boldsymbol{a} \tag{14}$$

$$\psi(\mathbf{r}, \mathbf{t}) \to -\mathbf{E}(t) \cdot \mathbf{r} \text{ as } \mathbf{r} \to \infty$$
 (15)

where \hat{n} is the unit normal outward from the particle surface. Equation (12) is the no-slip boundary condition at the particle surface (condition (iii)). Equation (14) is derived from condition (iv). Equation (15) implies that $\psi(r, t)$ tends to the potential of the applied electric field E(t) as $r \to \infty$.

In addition, the particle velocity U(t) obeys the following equation of motion of the particle:

$$\frac{4\pi a^3}{3}\rho_{\rm p}\frac{d\mathbf{U}(t)}{dt} = \mathbf{F}_{\rm H}(t) + \mathbf{F}_{\rm E}(t)$$
(16)

where $F_{\rm H}(t)$ and $F_{\rm E}(t)$ are, respectively, the hydrodynamic and electric forces acting on the particle and are defined by

$$\mathbf{F}_{\mathrm{H}}(t) = \int_{0}^{\pi} \left[\left(-p + 2\eta \frac{\partial u_{r}}{\partial r} \right) \cos\theta - \eta \left(\frac{1}{r} \frac{\partial u_{r}}{\partial \theta} + \frac{\partial u_{\theta}}{\partial r} - \frac{u_{\theta}}{r} \right) \sin\theta \right]_{r=a} 2\pi a^{2} \sin\theta d\theta \frac{\mathbf{E}(t)}{E_{\mathrm{o}}}$$
(17)

$$F_{\rm E}(t) = \varepsilon_{\rm r}\varepsilon_{\rm o} \int_0^{\pi} \left[\left\{ \frac{\partial\psi}{\partial r} \left(\frac{\partial\psi}{\partial r} \cos\theta - \frac{1}{r} \frac{\partial\psi}{\partial\theta} \sin\theta \right) \right\} - \frac{1}{2} \left\{ \left(\frac{\partial\psi}{\partial r} \right)^2 + \left(\frac{1}{r} \frac{\partial\psi}{\partial\theta} \right)^2 \right\} \cos\theta \right]_{r=a} 2\pi a^2 \sin\theta d\theta \frac{E(t)}{E_{\rm o}}$$
(18)

Equation (16) serves as a boundary condition for u(r, t).

2.2. Weak Electric Field Approximation

For a weak electric field E(t), the deviations of $n_j(\mathbf{r}, t)$, $\psi(\mathbf{r}, t)$ and $\mu_j(\mathbf{r}, t)$ from their equilibrium values due to E(t) are all small so that we may write

$$n_i(\boldsymbol{r}, \boldsymbol{t}) = n_i^{(0)}(\boldsymbol{r}) + \delta n_i(\boldsymbol{r}, \boldsymbol{t})$$
(19)

$$\psi(\mathbf{r}, \mathbf{t}) = \psi^{(0)}(\mathbf{r}) + \delta \psi(\mathbf{r}, t)$$
(20)

$$\mu_i(\mathbf{r}, \mathbf{t}) = \mu_i^{(0)} + \delta \mu_i(\mathbf{r}, t)$$
(21)

where the quantities with superscript (0) refer to the equilibrium values and $\mu_i^{(0)}$ is a constant independent of *r*. The equilibrium concentration $n_i^{(0)}(r)$ is assumed to be given by the Boltzmann distribution, and the equilibrium electric potential obeys the Poisson–Boltzmann equation (condition (v)), viz.,

$$n_i^{(0)}(r) = n_i^{\infty} \exp\left(-\frac{z_i e\psi^{(0)}(r)}{kT}\right)$$
(22)

$$\Delta \psi^{(0)}(r) = -\frac{\rho_{\rm el}^{(0)}(r) + \rho_{\rm fix}}{\varepsilon_{\rm r}\varepsilon_{\rm o}}$$
(23)

$$\rho_{\rm el}^{(0)}(r) = \sum_{i=1}^{N+1} z_i e n_i^{(0)}(r) = \sum_{i=1}^{N+1} z_i e n_i^{\infty} \exp\left(-\frac{z_i e \psi^{(0)}(r)}{kT}\right)$$
(24)

The boundary conditions for $\psi^{(0)}(r)$ are given by

$$\psi^{(0)}(a) = \zeta \tag{25}$$

$$\psi^{(0)}(r) \to 0 \text{ as } r \to \infty$$
 (26)

By substituting Equations (19)–(21) into Equation (3) and neglecting the products of the small quantities, we finally obtain

$$\rho_{o}\frac{\partial}{\partial t}\nabla \times \boldsymbol{u}(\boldsymbol{r},t) + \eta\nabla \times \nabla \times \nabla \times \boldsymbol{u}(\boldsymbol{r},t) + \gamma\nabla \times \boldsymbol{u}(\boldsymbol{r},t) + \sum_{i=1}^{N+1}\nabla n_{i}^{(0)}(\boldsymbol{r}) \times \nabla\delta\mu_{i}(\boldsymbol{r}) = \boldsymbol{0}$$
(27)

and form Equation (6)

$$\frac{\partial}{\partial t}\delta n_i(\mathbf{r},t) + \nabla \cdot \left\{ n_i^{(0)}(r)\mathbf{u}(\mathbf{r},t) - \frac{1}{\Lambda_i} n_i^{(0)}(r)\nabla \delta \mu_i(\mathbf{r},t) \right\} = 0$$
(28)

Further, from symmetry, we may write

$$\boldsymbol{u}(\boldsymbol{r},t) = \left(-\frac{2}{r}h(\boldsymbol{r},t)E(t)\cos\theta, \frac{1}{r}\frac{\partial}{\partial r}(rh(\boldsymbol{r},t))E(t)\sin\theta, 0\right)$$
(29)

$$\delta\mu_i(\mathbf{r},t) = -z_i e\phi_i(\mathbf{r},t) E(t) \cos\theta$$
(30)

$$\delta \psi(\mathbf{r}, t) = -Y(\mathbf{r}, t)E(t)\cos\theta \tag{31}$$

where E(t) is the magnitude of E(t), and h(r, t), $\phi_i(r, t)$ and Y(r, t) are functions of r and t. By substituting Equations (29)–(31) into Equations (27) and (28), we obtain the following equations for h(r) and $\phi_i(r)$, and Y(r):

$$L\left[Lh(r,t) - \lambda^2 h(r,t) - \frac{1}{\nu} \frac{\partial h(r,t)}{\partial t}\right] = G(r,t)$$
(32)

$$L\phi_i(r,t) - \frac{\Lambda_i}{kT} \frac{\partial}{\partial t} \{\phi_i(r,t) - Y(r,t)\} = \frac{dy(r)}{dr} \left\{ z_i \frac{\partial \phi_i(r,t)}{\partial r} - \frac{2\lambda_i}{e} \frac{h(r,t)}{r} \right\}$$
(33)

$$LY(r,t) = \frac{e^2}{\varepsilon_r \varepsilon_o kT} \sum_{i=1}^{N+1} z_i^2 n_i^\infty e^{-z_i y(r)} \{Y(r,t) - \phi_i(r,t)\}$$
(34)

with

$$y(r) = \frac{e\psi^{(0)}(r)}{kT}$$
 (35)

$$\lambda = \left(\frac{\gamma}{\eta}\right)^{1/2} \tag{36}$$

where the scaled equilibrium electric potential y(r) is introduced, λ is the reciprocal of the Brinkman screening length $1/\lambda$,

ν

$$L = \frac{\partial}{\partial r} \frac{1}{r^2} \frac{\partial}{\partial r} r^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{2}{r^2}$$
(37)

is a differential operator, and G(r, t) is defined by

$$G(r,t) = -\frac{e}{\eta r} \frac{dy}{dr} \sum_{i=1}^{N} z_i^2 n_i^\infty e^{-z_i y} \phi_i(r,t)$$
(38)

and

$$=\frac{\eta}{\rho_{\rm o}}\tag{39}$$

is the kinematic viscosity.

2.3. General Expression for the Laplace Transform of the Transient Gel Electrophoretic Mobility The transient electrophoretic mobility $\mu(t)$ can be obtained from Equation (13), viz.,

$$\mu(t) = \frac{U(t)}{E(t)} = \frac{U(t)}{E_{o}} = 2\lim_{r \to \infty} \frac{h(r, t)}{r} + u(t)$$
(40)

Here h(r, t) is the solution to Equation (32), which can be most easily solved by using the Laplace transformation with respect to time *t*. The Laplace transforms $\hat{h}(r, s)$, $\hat{u}_{\text{EOF}}(s)$, $\hat{G}(r, s)$ and $\hat{\mu}(s)$ of h(r, t), $u_{\text{EOF}}(t)$, G(r, t) and $\mu(t)$, respectively, are defined by

$$\hat{h}(r,s) = \int_0^\infty h(r,t)e^{-st}dt$$
(41)

$$\hat{u}_{\rm EOF}(s) = \int_0^\infty u_{\rm EOF}(t) e^{-st} dt \tag{42}$$

$$\hat{Y}(r,s) = \int_0^\infty Y(r,t)e^{-st}dt$$
(43)

$$\hat{G}(r,s) = \int_0^\infty G(r,t)e^{-st}dt \tag{44}$$

Thus, the Laplace transform of Equation (32) yields

$$L\left[L\hat{h}(r,s) - \lambda^2 \hat{h}(r,s) - \frac{s}{\nu} \hat{h}(r,s)\right] = \hat{G}(r,s)$$
(45)

which is solved to give

$$\hat{h}(r,s) = -\frac{1}{3\beta^2} \int_{\infty}^r \left(r - \frac{x^3}{r^2}\right) \hat{G}(x,s) dx$$
$$-\frac{1}{\beta^3} \int_{\infty}^r \left\{ \left(\frac{x}{\beta r^2} - \frac{1}{\beta r}\right) \cosh[\beta(r-x)] - \left(\frac{x}{r} - \frac{1}{\beta^2 r^2}\right) \sinh[\beta(r-x)] \right\} \hat{G}(x,s) dx$$
$$-\frac{C_1 r}{\beta^2} - \frac{C_2}{\beta^2 r^2} + C_3 \left(\frac{\beta}{r} + \frac{1}{r^2}\right) e^{-\beta(r-a)}$$
(46)

with

$$\beta = \sqrt{\lambda^2 + \frac{s}{\nu}} \tag{47}$$

where C_1 – C_3 are integration constants to be determined.

From the Laplace transform of Equation (10), we obtain

$$\hat{u}_{\rm EOF}(s) = -\frac{\rho_{\rm fix}}{\eta \beta^2 s} E_{\rm o} \tag{48}$$

Equation (40) for the Laplace transform of the transient gel electrophoretic mobility $\mu(t)$ thus becomes

$$\hat{\mu}(s) = 2\lim_{r \to \infty} \frac{\hat{h}(r,s)}{r} - \frac{\rho_{\text{fix}}}{\eta \beta^2 s}$$
(49)

By determining the integration constants C_1 – C_3 in Equation (46) to satisfy the boundary conditions (Equations (11)–(16)) and using Equation (40), we finally obtain the following expression for the Laplace transform $\hat{\mu}(s)$ of the transient gel electrophoretic mobility $\mu(t)$ of a sphere:

$$\hat{\mu}(s) = \frac{2}{3\beta^2 \Omega} \int_a^\infty \left\{ -\left(1 + \beta a + \frac{\beta^2 a^2}{3}\right) + (1 + \beta r)e^{-\beta(r-a)} + \frac{\beta^2 r^3}{3a} \right\} \hat{G}(r,s)dr$$

$$-\frac{\rho_{\text{fix}}}{\eta\beta^2\Omega s}\left\{1+\beta a+\frac{\beta^2 a^2}{3}-\frac{2\beta^2 a s}{9}\hat{Y}(a,s)\right\}$$
(50)

with

$$\Omega = 1 + \beta a + \frac{\beta^2 a^2}{9} + \frac{2\rho_{\rm p}}{9\rho_{\rm o}} \frac{a^2}{\nu} s \tag{51}$$

3. Results and Discussion

Equation (50) is the required general expression for $\hat{\mu}(s)$, which is applicable for arbitrary values of the particle zeta potential ζ and κa . The transient electrophoretic mobility $\mu(t)$ can be obtained numerically from Equation (50) by the inverse transform method.

Consider the following two limiting cases. In the limit of $t \to \infty$, $\mu(t)$ tends to the steady gel electrophoretic mobility $\mu(\infty) = \mu_s$, which can be obtained from $\hat{\mu}(s)$ by using the following formula:

$$\mu_{s} = \mu(\infty) = \lim_{s \to 0} [s\hat{\mu}(s)] \tag{52}$$

The result is

$$\mu_{\rm s} = \frac{2}{3\lambda^2\Omega_{\rm s}} \int_a^\infty \left\{ -\left(1 + \lambda a + \frac{\lambda^2 a^2}{3}\right) + (1 + \lambda r)e^{-\lambda(r-a)} + \frac{\lambda^2 r^3}{3a} \right\} G(r)dr - \frac{\rho_{\rm fix}}{\eta\lambda^2} \left[1 - \frac{2\lambda^2 a^2}{9\Omega_{\rm s}} \left\{\frac{Y(a)}{a} - 1\right\}\right] \tag{53}$$

with

$$\Omega_{\rm s} = 1 + \lambda a + \frac{\lambda^2 a^2}{9} \tag{54}$$

Equation (53) agrees with the general expression for the steady electrophoretic mobility m(t) of a sphere in a polymer gel medium [35]. Next, in the limit of $\rho_{\text{fix}} = 0$ and $\lambda = 0$, i.e., $\beta = \sqrt{s/\nu}$, Equation (50) reduces to

$$\hat{\mu}(s) = \frac{2\nu}{3s\Omega_{\rm f}} \int_a^\infty \left\{ -\left(1 + a\sqrt{\frac{s}{\nu}} + \frac{a^2s}{3\nu}\right) + \left(1 + \sqrt{\frac{s}{\nu}}r\right) \exp\left[-\sqrt{\frac{s}{\nu}}(r-a)\right] + \frac{r^3s}{3a\nu}\right\} \hat{G}(r,s)dr \tag{55}$$

with

$$\Omega_{\rm f} = 1 + a \sqrt{\frac{s}{\nu}} + \frac{a^2 s}{9\nu} + \frac{2\rho_{\rm p}}{9\rho_{\rm o}} \frac{a^2 s}{\nu}$$
(56)

which agrees with the general expression for the Laplace transform $\hat{\mu}(s)$ of the transient electrophoretic mobility $\mu(t)$ of a sphere in a free solution [14]. It is thus found that in the above two limiting cases, Equation (50) reduces to the correct limiting forms.

Now consider the case where the particle ζ potential is low, and the relative permittivity of ε_p of the particle is much smaller than that of the electrolyte solution ε_r ($\varepsilon_p \ll \varepsilon_r$) so that ε_p is practically equal to zero. In this case, Equations (33) and (34) give

$$\phi_i(r,t) = Y(r,t) = r + \frac{a^3}{2r^2}$$
(57)

and Equation (38) becomes

$$G(r,t) = -\frac{\varepsilon_{\rm r}\varepsilon_{\rm o}\kappa^2}{\eta} \left(1 + \frac{a^3}{2r^3}\right) \frac{d\psi^{(0)}(r)}{dr}$$
(58)

with

$$\kappa = \sqrt{\frac{e^2}{\varepsilon_{\rm r}\varepsilon_{\rm o}kT}} \sum_{i=1}^{N+1} z_i^2 n_i^{\infty}$$
(59)

where κ is the Debye–Hückel parameter (1/ κ is the Debye length). The Laplace transform $\hat{G}(r, s)$ of G(r, t) is thus given by

$$\hat{G}(r,s) = \frac{G(r,t)}{s} = -\frac{\varepsilon_{\rm r}\varepsilon_{\rm o}\kappa^2}{\eta s} \left(1 + \frac{a^3}{2r^3}\right) \frac{d\psi^{(0)}(r)}{dr}$$
(60)

where the equilibrium electric potential $\psi^{(0)}(r)$ for low ζ potential is given by

$$\psi^{(0)}(r) = \zeta \frac{a}{r} e^{-\kappa(r-a)}$$
(61)

which is obtained from the linearized Poisson–Boltzmann equation $\Delta \psi^{(0)}(r) = \kappa^2 \psi^{(0)}(r)$ (see Equation (23)). By substituting Equation (58) into Equation (55), we obtain

$$\hat{\mu}(s) = \frac{2\varepsilon_{\rm r}\varepsilon_{\rm o}\kappa^2}{3\beta^2\Omega\eta s} \int_a^\infty \left\{ \left(1 + \beta a + \frac{\beta^2 a^2}{3}\right) - (1 + \beta r)e^{-\beta(r-a)} - \frac{\beta^2 r^3}{3a} \right\} \left(1 + \frac{a^3}{2r^3}\right) \frac{d\psi^{(0)}(r)}{dr} dr - \frac{\rho_{\rm fix}}{\eta\beta^2\Omega s} (1 + \beta a)$$
(62)

Equation (62) can be rewritten in terms of exponential integrals as

$$\hat{\mu}(s) = \frac{2\epsilon_{\rm r}\epsilon_{\rm o}\zeta}{3\eta\Omega s} \left[1 + \frac{\kappa\beta a}{\kappa+\beta} + \frac{3\kappa^2}{2\beta^2} \left(1 + \beta a + \frac{\beta^2 a^2}{3} \right) e^{\kappa a} E_5(\kappa a) - \frac{3\kappa^2}{2\beta^2} e^{(\kappa+\beta)a} \left\{ E_5((\kappa+\beta)a) + \beta a E_4((\kappa+\beta)a) + \frac{\beta^2 a^2}{3} E_3((\kappa+\beta)a) \right\} \right] - \frac{\rho_{\rm fix}}{\eta\beta^2\Omega s} (1+\beta a)$$

$$(63)$$

where $E_n(\kappa a)$ is the exponential integral of order *n* and is defined by

$$E_n(\kappa a) = (\kappa a)^{n-1} \int_{\kappa a}^{\infty} \frac{e^{-t}}{t^n} dt$$
(64)

Equations (62) and (63) are the generalization of the result of Saad and Faltas [40] and are applicable for low zeta potentials and arbitrary values of κa .

Equations (62) and (63) involve integration or exponential integrals, so they are not very convenient for practical use. To avoid this inconvenience, we approximately replace r in the factor $(1 + a^3/2r^3)$ by $r = a + \delta/$, viz.,

$$1 + \frac{a^3}{2r^3} \approx 1 + \frac{1}{2\left(1 + \frac{\delta}{\kappa a}\right)^3} \tag{65}$$

In the steady gel electrophoresis [35], we have found that the best approximation can be achieved if δ is chosen to be $\delta = (2.33\kappa + 1.52\lambda)/(\kappa + \lambda)$, and the maximum relative error becomes less than 1.6%. We use this choice of δ in the transient gel electrophoresis problem. By using this approximation, the integration in Equation (62) can be carried out analytically to give

$$\hat{\mu}(s) = \frac{2\varepsilon_{\rm r}\varepsilon_{\rm o}\zeta}{3\eta\Omega s} \left(1 + \frac{\kappa\beta a}{\kappa + \beta}\right) \left[1 + \frac{1}{2\left\{1 + \frac{(2.33\kappa + 1.52\beta)}{(\kappa + \beta)\kappa a}\right\}^3}\right] - \frac{\rho_{\rm fix}}{\eta\lambda^2\Omega s} (1 + \beta a) \tag{66}$$

We next consider the following two limiting cases.

(i) In the limit of $\kappa a \rightarrow \infty$ (Smoluchowski limit), Equation (66) becomes

$$\hat{\mu}(s) = \frac{\varepsilon_{\rm r}\varepsilon_{\rm o}\zeta(1+\beta a)}{\eta\Omega s} - \frac{\rho_{\rm fix}}{\eta\beta^2\Omega s}(1+\beta a) \tag{67}$$

(ii) In the limit of $\kappa a \rightarrow 0$ (Hückel limit), Equation (66) becomes

$$\hat{\mu}(s) = \frac{2\varepsilon_{\rm r}\varepsilon_{\rm o}\zeta}{3\eta\Omega s} - \frac{\rho_{\rm fix}}{\eta\beta^2\Omega s}(1+\beta a)$$
(68)

Figure 2 shows some results of the calculation of the transient gel electrophoretic mobility $\mu(t)$ of a sphere of radius a, zeta potential ζ and mass density ρ_p in an uncharged gel medium ($\rho_{\text{fix}}=0$) of the Debye length $1/\kappa$, mass density ρ_o and viscosity η . The ratio of $\mu(t)$ at time t to its value $\mu(\infty)$ at $t = \infty$, which is the steady gel electrophoretic mobility μ_s ($\mu(\infty) = \mu_s$), is plotted as a function of the scaled time vt/a^2 , v being the kinematic viscosity ($v = \eta/\rho_o$) for $\kappa a = 10$ and $\rho_p/\rho_o = 2$. The transient gel electrophoretic mobility can be obtained numerically from $\hat{\mu}(s)$ (Equation (63) or Equation (66) with negligible errors) via the inverse Laplace transformation method.



Figure 2. Transient gel electrophoretic mobility $\mu(t)$ of a sphere of radius *a* and mass density ρ_p , carrying zeta potential ζ in an uncharged gel medium ($\rho_{\text{fix}} = 0$) of the Debye length $1/\kappa$, mass density ρ_o and viscosity η . The ratio of $\mu(t)$ at time *t* to its value $\mu(\infty)$ at $t = \infty$, which is equal to the steady gel electrophoretic mobility μ_s ($\mu(\infty) = \mu_s$), is plotted as a function of the scaled time $\nu t/a^2$, ν being the kinematic viscosity ($\nu = \eta/\rho_o$) for the case where $\kappa a = 10$ and $\rho_p/\rho_o = 2$). The dotted curves ($\lambda a = 10$, and 100) are the result calculated in Equation (72) for the large λa approximate gel electrophoretic mobility.

Figure 2 shows that the relaxation time required for $\mu(t)$ to reach its steady value μ_s becomes shorter as λa increases. An approximate expression for the relaxation time *T* for large λa can be derived as follows. For large λa , β in Equation (60) can be approximately replaced with λ and Equation (61) reduces to

$$\hat{\mu}(s) = \frac{2\varepsilon_{\rm r}\varepsilon_{\rm o}\kappa^2}{3\lambda^2\Omega\eta s} \int_a^\infty \left\{ \left(1 + \lambda a + \frac{\lambda^2 a^2}{3}\right) - (1 + \lambda r)e^{-\beta(r-a)} - \frac{\lambda^2 r^3}{3a} \right\} \left(1 + \frac{a^3}{2r^3}\right) \frac{d\psi^{(0)}(r)}{dr} dr - \frac{\rho_{\rm fix}}{\eta\lambda^2\Omega s} (1 + \lambda a) \tag{69}$$

and we obtain

$$\frac{\hat{\mu}(s)}{\mu_{\rm s}} = \frac{\Omega_{\rm s}}{s\Omega} = \frac{\Omega_{\rm s}}{s\left(\Omega_{\rm s} + \frac{2\rho_{\rm p}}{9\rho_{\rm o}}\frac{a^2}{\nu}s\right)}$$
(70)

From Equation (70), the transient gel electrophoretic mobility $\mu(t)$ can be derived, viz.,

$$\frac{\mu(t)}{\mu_{\rm s}} = 1 - \exp\left(-\frac{9\rho_{\rm o}\Omega_{\rm s}}{2\rho_{\rm p}}\frac{\nu t}{a^2}\right) \tag{71}$$

which can be rewritten as

$$\frac{\mu(t)}{\mu_{\rm s}} = 1 - {\rm e}^{-t/T}$$
(72)

with

$$T = \frac{2\rho_{\rm p}a^2}{9\rho_{\rm o}\Omega_{\rm s}\nu}\tag{73}$$

Here *T* can be regarded as the relaxation time. The relaxation time T_f for the transient free-solution electrophoresis is given by

$$T_{\rm f} = \frac{2\rho_{\rm p}a^2}{9\rho_{\rm o}\nu} \tag{74}$$

so that

$$\frac{T}{T_{\rm f}} = \frac{1}{\Omega_{\rm s}} = \frac{1}{1 + \lambda a + \lambda^2 a^2/9}$$
 (75)

which shows that the relaxation time *T* for the transient gel electrophoresis is shorter than the relaxation time T_f for the transient free-solution electrophoresis by a factor Ω_s and becomes shorter as λa decreases. This is because the steady gel electrophoretic mobility μ_s itself becomes smaller as λa increases [36], and the time required to reach the steady value becomes smaller as λa increases. The dotted curves ($\lambda a = 10$, and 100) are the results calculated via Equation (72) for the large λa approximate gel electrophoretic mobility.

4. Conclusions

We have derived an approximate expression (Equation (63)) and its approximate form with negligible errors (Equation (66)) for the Laplace transform $\hat{\mu}(s)$ of the transient gel electrophoretic mobility $\mu(t)$ of a sphere in a polymer gel medium. Equations (63) and (66) are the generalization of the result of Saad and Faltas [40] and are applicable for low zeta potentials and arbitrary values of κa . Equation (66), in particular, which does not involve exponential integrals, is convenient for practical use. It is shown that the relaxation time *T* for the transient gel electrophoretic mobility $\mu(t)$ to reach its steady value μ_s is shorter than that for the transient free-solution electrophoretic mobility, and *T* becomes shorter as λa increases.

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