



## Article

# On Study of Modified Caputo–Fabrizio Omicron Type COVID-19 Fractional Model

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**Abstract:** In this paper, we analyze the novel type of COVID-19 caused by the Omicron virus under a new operator of fractional order modified by Caputo–Fabrizio. The whole compartment is chosen in the sense of the said operator. For simplicity, the model is distributed into six agents along with the inclusion of the Omicron virus infection agent. The proposed fractional order model is checked for fixed points with the help of fixed point theory. The series solution is carried out by the technique of the Laplace Adomian decomposition technique. The compartments of the proposed problem are simulated for graphical presentation in view of the said technique. The numerical simulation results are established at different fractional orders along with the comparison of integer orders. This consideration will also show the behavior of the Omicron dynamics in human life and will be essential for its control and future prediction at various time durations. The sensitivity of different parameters is also checked graphically.

**Keywords:** modified Caputo–Fabrizio fractional derivative; fractional mathematical model Omicron; qualitative analysis; Laplace Adomian technique



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## 1. Introduction

From the outbreak of infection of COVID-19, different types of it due to several viruses have been discovered, like MERS-COVID, COVID-19, Omicron type COVID-19, etc. The Omicron type virus is a new infection of SARS-CoV-2 caused by the virus known as the Omicron virus. It is produced from the COVID-19 chain of SARS-CoV-2 (COVID-19), discovered in the month of November 2021 in the country of South Africa. After that, the said virus expansion occurs very quickly, and it is transmitted to many continents of the world. The cases of the Omicron disease are growing day by day. The disease of this virus is not more severe than the usual COVID-19 and its other types, but it infects very fast as compared with the other COVID-19 types. According to the reports of World Health Organization (WHO), it can affect the vaccinated population and those who do not have any proper symptoms of infection [1]. However, up to now, few common signs of this infection have been found, like coughing, congestion, watery nose, body aches, etc. Like the bans of COVID-19, this infection also faces bans on overcrowding, unmasking, traffic, and flight suspensions.

COVID-19 has been investigated by many researchers and biologists to control or reduce the infection and its further expansion in the human communities. They tried to find a treatment and a cure in the form of vaccination to vaccinate many people in order to minimize the number of infectious people and their future control. Still, with the duration of time and the emergency of the novel viruses of COVID-19, the world is facing such a type of pandemic in many countries and societies. Mathematical models touched on each and every infection in mathematical terms. Therefore, some mathematical models in natural and non-natural orders are considered to investigate the COVID-19 pandemic. For example, the first infection of COVID-19 in Wuhan, China in the sense of a very

significant mathematical model, was studied in [2]. The optimal control techniques for the eradication or control of the infection in Pakistan, by proposing the real COVID-19 classes have been discussed in [3]. The COVID-19 disease is spread to healthy people very quickly, so the best and most effective framework to minimize the infection, is the self-isolation and quarantining technique, which is analyzed by a mathematical model established by scholars in [4]. The lockdown and its impacts on infection control have been investigated through a mathematical formulation technique in [5]. The researchers constructed an Susceptible-Exposed-Infectious-Recovered (SEIR) model by using the realistic data approach from France and Italy and established the disease control techniques [6]. Various reports related to COVID-19 cases and their formulation in Nigeria, by comparison, have been given in [7]. A global analysis on COVID-19 to study the self-isolation, quarantined, and environmental vital wights has been pointed out in [8]. A comprehensive discussion on COVID-19 in the framework of fractional environment is carried out in [9]. The discussion of the COVID-19 disease modeling the realistic cases in Saudi Arabia has been established in [10].

Mathematical formulations provide a comprehensive tool for the analysis of different dynamics of social, physical, and biological problems. Most linear phenomena are generally idealistic and not realistic, as several real-world phenomena are non-linear. As a result, non-linear mathematical models for real-world problems are superior to linear models. So far, a number of attempts have been made by different scientists to mathematically formulate the dynamics and control of this novel Omicron type virus COVID-19 infection. The Omicron infection of November 2021, which occurred in African and European countries, has been investigated in detail by Altaf et al. [11]. By the application of the controlling theory of optimality, they minimize the said infection [12]. Vaccination and curing have also reduced the transmission of the Omicron virus COVID-19 [13].

In the article of Altaf et al. [14], the six compartmental model subject to the initial conditions along with the inclusion of the Omicron virus agent is considered as follows:

$$\begin{aligned}
 \frac{d}{dt}(\mathbb{S}(\tau)) &= \lambda - \frac{\alpha(\mathbb{I}_\alpha(\tau) + \kappa\mathbb{I}_s(\tau) + u\mathbb{I}_O(\tau)\mathbb{S}(\tau))}{N} - \nu\mathbb{S}(\tau), \\
 \frac{d}{dt}(\mathbb{E}(\tau)) &= \frac{\alpha(\mathbb{I}_\alpha(\tau) + \kappa\mathbb{I}_s(\tau) + u\mathbb{I}_O(\tau)\mathbb{S}(\tau))}{N} - (\tau + \nu)\mathbb{E}(\tau), \\
 \frac{d}{dt}(\mathbb{I}_\beta(\tau)) &= \tau\Psi\mathbb{E}(\tau) - (\Delta_1 + \nu)\mathbb{I}_\beta(\tau), \\
 \frac{d}{dt}(\mathbb{I}_s(\tau)) &= (1 - \Psi - \phi)\tau\mathbb{E}(\tau) - (\Delta_2 + \nu + \delta_1)\mathbb{I}_s(\tau), \\
 \frac{d}{dt}(\mathbb{I}_O(\tau)) &= \phi\tau\mathbb{E}(\tau) - (\Delta_3 + \nu)\mathbb{I}_O(\tau), \\
 \frac{d}{dt}(\mathbb{R}(\tau)) &= \Delta_1\mathbb{I}_\beta(\tau) + \Delta_2\mathbb{I}_s(\tau) + \Delta_3\mathbb{I}_O(\tau) - \nu\mathbb{R}(\tau), \\
 \mathbb{S}(0) = \mathbb{S}_0 \geq 0, \mathbb{E}(0) = \mathbb{E}_0 \geq 0, \mathbb{I}_\beta(0) = \mathbb{I}_{(\beta)0} \geq 0, \mathbb{I}_s(0) = \mathbb{I}_{(s)0} \geq 0, \\
 \mathbb{I}_O(0) = \mathbb{I}_{(O)0} \geq 0, \mathbb{R}(0) = \mathbb{R}_0 \geq 0.
 \end{aligned} \tag{1}$$

The compartments and parameters of the above model are defined in Table 1.

For the analysis of fractional problems, different operators, including fractal derivative, non-integer order derivatives with kernels of singularity and non-singularity, fractional-fractal operator, and some other derivative operators, have been introduced in [15–20]. The inclusion of fractional derivative terms in the form of deterministic equations has more realistic achievements. The analysis of inside properties is found in many infectious disease models, the flow of heat, fluid flow, and many complex advection problems [19,21–23]. Several authors have used different techniques of fractional calculus by applying different operators and studying several types of disease models such as the coronavirus model, co-infection model, typhoid disease model, etc. [24–27]. In fractional calculus, the exponential and Mittag–Leffler mappings are not able to find the inside dynamics. Therefore, to solve such problems, one of the advanced approaches to fractional differentiation and

integration has been introduced by many researchers. They introduced the classical and global derivatives along with some applicable examples [28–31]. We will investigate the said problem for qualitative analysis and numerical analysis in the sense of Modified Caputo–Fabrizio (MCF) fractional derivative. In the sense of a non-singular kernel, (1) can be written in Modified Caputo derivative format as follows:

$$\begin{aligned}
 {}^{CF}D^\varphi(\mathbb{S}(\tau)) &= \lambda - \frac{\alpha(\mathbb{I}_\alpha(\tau) + \kappa\mathbb{I}_s(\tau) + u\mathbb{I}_O(\tau)\mathbb{S}(\tau))}{N} - \nu\mathbb{S}(\tau), \\
 {}^{CF}D^\varphi(\mathbb{E}(\tau)) &= \frac{\alpha(\mathbb{I}_\alpha(\tau) + \kappa\mathbb{I}_s(\tau) + u\mathbb{I}_O(\tau)\mathbb{S}(\tau))}{N} - (\tau + \nu)\mathbb{E}(\tau), \\
 {}^{CF}D^\varphi(\mathbb{I}_\beta(\tau)) &= \tau\Psi\mathbb{E}(\tau) - (\Delta_1 + \nu)\mathbb{I}_\beta(\tau), \\
 {}^{CF}D^\varphi(\mathbb{I}_s(\tau)) &= (1 - \Psi - \phi)\tau\mathbb{E}(\tau) - (\Delta_2 + \nu + \delta_1)\mathbb{I}_s(\tau), \\
 {}^{CF}D^\varphi(\mathbb{I}_O(\tau)) &= \phi\tau\mathbb{E}(\tau) - (\Delta_3 + \nu)\mathbb{I}_O(\tau), \\
 {}^{CF}D^\varphi(\mathbb{R}(\tau)) &= \Delta_1\mathbb{I}_\beta(\tau) + \Delta_2\mathbb{I}_s(\tau) + \Delta_3\mathbb{I}_O(\tau) - \nu\mathbb{R}(\tau), \\
 \mathbb{S}(0) = \mathbb{S}_0 \geq 0, \mathbb{E}(0) = \mathbb{E}_0 \geq 0, \mathbb{I}_\beta(0) = \mathbb{I}_{(\beta)0} \geq 0, \mathbb{I}_s(0) = \mathbb{I}_{(s)0} \geq 0, \\
 \mathbb{I}_O(0) = \mathbb{I}_{(O)0} \geq 0, \mathbb{R}(0) = \mathbb{R}_0 \geq 0.
 \end{aligned}
 \tag{2}$$

**Table 1.** Description of the parameter of (1).

Notation	Description of the Parameter
$\mathbb{S}(t)$	Susceptible or healthy class
$\mathbb{E}(t)$	Exposed class
$\mathbb{I}_\alpha(t)$	Asymptomatic individuals having no symptoms
$\mathbb{I}_s(t)$	Symptomatic individuals having symptoms of COVID-19
$\mathbb{I}_O(t)$	Infection with Omicron virus
$\mathbb{R}(t)$	Recovered class from all type of infections
$\lambda$	Rate of birth to susceptible population
$\alpha$	Rate of infection of susceptible peoples from asymptomatic infection
$\kappa$	Probability of infectiousness of symptomatic class
$u$	Naturally death rate
$\nu$	Probability of infection through omicron variant
$\tau$	Infection incubation period
$\Psi$	Proportion contribution of infection to asymptomatic population
$\phi$	Proportion contribution of infection to Omicron variant population
$\Delta_1$	Rate of recovery of asymptomatic class
$\Delta_2$	Rate of recovery of symptomatic class
$\Delta_3$	Rate of recovery of Omicron variant infection
$d_1$	Rate of death of symptomatic class

As far as the novelty is concerned, we converted the integer order model to a fractional MCF operator. As MCF operators are fractionalized derivative orders, therefore, they have an extra degree of freedom and choices. We have checked the dynamics of different fractional orders lying between 0 and 1, and compared them with the integer order. On small fractional orders, stability is achieved quickly, and vice versa. The fractional model is investigated for the existence and uniqueness of solution in the sense of the MCF operator. The approximate or series solution is obtained by the well-known Laplace Adomian decomposition method under the mentioned operator. All the quantities in the proposed problem are converging to their equilibrium points.

This paper is organized as follows: Section 2 is related to basic definitions taken from the literature of fractional calculus. In Section 3, the existence results and uniqueness of the solution is presented for the considered model. A series solution is obtained for the system with the help of Laplace Adomian decomposition method in Section 4. In Section 5, we

presented the obtained solution graphically and explained the dynamical behavior for each compartment. Finally, we conclude our work in Section 6.

## 2. Preliminaries

Here, we include some definitions regarding this article.

**Definition 1.** [32] Let a function be  $\Phi \in H^1[0, T]$  and  $0 < T, \varphi \in (0, 1)$ , then the Caputo–Fabrizio fractional derivative (CFFD) is defined as

$${}^{CF}D^\varphi(\Phi(\tau)) = \frac{\mathbf{M}(\varphi)}{(1-\varphi)} \int_0^t \Phi'(\tau) \exp\left[-\varphi \frac{t-\zeta}{1-\varphi}\right] d\zeta,$$

where  $\mathbf{M}(\varphi)$  is  $\mathbf{M}(\varphi) = \frac{2}{2-\varphi}$ ,  $0 < \varphi \leq 1$ . Furthermore,  $\mathbf{M}(0) = 1$ . If  $\Phi \notin H^1(0, T)$ , so the CF operator is

$${}^{CF}D^\varphi(\Phi(\tau)) = \frac{\mathbf{M}(\varphi)}{(1-\varphi)} \int_0^t (\Phi(\tau) - \Phi(\zeta)) \exp\left[-\varphi \frac{t-\zeta}{1-\varphi}\right] d\zeta.$$

**Definition 2.** [33] Let  $\Phi(\tau) : [a, \infty) \rightarrow \mathbb{R}$  be a smooth function with  $a < 0$  and  $t > 0$ , and then the modified CF operator is given as

$${}^{MCF}D^\varphi(\Phi(\tau)) = \frac{1}{1-\varphi} \int_0^t \left( \psi'_0(\zeta) \beta(t-\zeta) + \Phi'(\zeta) \exp\left(-\frac{\varphi}{1-\varphi}(t-\zeta)\right) \right) d\zeta, \quad (3)$$

where

$$\psi'_0(\zeta) = \int_a^0 \Phi'(\zeta) \exp\left(-\frac{\varphi}{1-\varphi}(t-\zeta)\right) d\zeta. \quad (4)$$

**Definition 3.** [32] Suppose  $\varphi \in ]0, 1[$ , then CF integral having order  $\varphi$  of  $\Phi$  is

$${}^{CF}I^\varphi[\Phi(\tau)] = G\Phi(\tau) + \bar{G} \int_0^t \Phi(\zeta) d\zeta, \quad \tau \geq 0,$$

when  $\varphi = 1$ , one can obtain classical integral of  $\Phi$ , where

$$G = \frac{(1-\varphi)}{\mathbf{M}(\varphi)}, \quad \bar{G} = \frac{\varphi}{\mathbf{M}(\varphi)}.$$

**Definition 4.** The Laplace transform of CF operator is

$$\mathcal{L}\left\{ \text{Modified-}{}^{CF}D_x^\varphi \Phi(x, \tau) \right\} = \frac{a(2-\varphi)}{2(s+(1-s)\varphi)} \left[ \zeta^{n+1} \bar{\Phi}(s, \tau) - \sum_{k=0}^n s^{n-k} \left\{ \frac{\partial^k \Phi(0, t)}{\partial x^k} \right\} \right],$$

where,  $n = [\varphi] + 1$

## 3. Qualitative Analysis

This section deals with the existence and uniqueness of solution of the considered model (2). To do this, we need the following theorem from fixed point theory.

*Existence and Uniqueness Solution of Model (2)*

To prove the results, we give the following notions and lemma.

Consider  $\Phi = [0, 1]$  and  $\mathcal{C}(\Phi)$  represents the space containing continuous functions on  $\Phi$ . Consider set  $B = \mathcal{W}(\tau) / \mathcal{W}(\tau) \in \mathcal{C}(\Phi)$  with  $\|\mathcal{W}(\tau)\|_b \leq \max_{t \in \Phi} |\mathcal{W}(\tau)|$  represents

Banach space. For simplicity, consider  $\mathcal{W}(\tau) = \Phi(\tau, \Omega(\tau))$ ,  $v(\tau) = \Phi_1(t, \Omega_1(\tau))$  and  $\mathcal{W}(0) = \Omega(0) = \mathcal{W}_0$  and  $\mathcal{V}(0) = \Omega_1(0) = \mathcal{V}_0$ . The model (2) in integral form is

$$\mathcal{W}(\tau) = \mathcal{W}_0 + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}(\Phi(\tau, \Omega(\tau))) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t \Phi(\zeta, \Omega(\zeta))d\zeta.$$

Let us suppose an operator  $\mathcal{T} : \mathbb{B} \rightarrow \mathbb{B}$  defined as

$$\mathcal{T}\mathcal{W}(\tau) = \mathcal{W}_0 + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}(\Phi(\tau, \Omega(\tau))) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t \Phi(\zeta, \Omega(\zeta))d\zeta,$$

and then operator  $\mathcal{T}$  has same fixed-point (FP) as (2).

**Theorem 1.** Suppose a continuous function to be  $f : \Phi \times \mathcal{R} \rightarrow \mathcal{R}$ . Also, consider in the following at least one is satisfied.

( $\mathcal{H}_1$ ) Let the function  $g(\tau) \in L[0, 1]$  exists which is non-negative, such that

$$|\Phi(\tau, x)| \leq h(\tau) + c_0|x|^\zeta, \text{ here, } c_0 \geq 0, 0 < \zeta < 1.$$

( $\mathcal{H}_2$ ) The function  $\Phi$  satisfies  $|\Phi(\tau, x)| \leq c_0|x|^\zeta$ , where  $c_0 > 0, \zeta > 1$ . Then model (2) has a solution.

**Proof.** By using the Schauder FP theorem to prove the results, consider, ( $\mathcal{H}_1$ ) is holds.

Let us consider  $\mathbb{G} = \{\mathcal{W}(\tau) | \mathcal{W}(\tau) \in \mathbb{B}, \|\mathcal{W}\|_{\mathbb{B}} \leq k, t \in \Phi\}$ , where  $k \geq \max(2Ac_0)^{\frac{1}{1-\zeta}}, 2l$  and  $l = \max_{y \in \Phi} \left( \mathcal{W}_0 + \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}g(\tau) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t |g(\zeta)|d\zeta \right)$ . Obviously,  $\mathbb{G}$  is a ball in  $\mathbb{B}$ . Furthermore, we prove that  $\mathcal{T} : \mathbb{G} \rightarrow \mathbb{G}$ . For all  $u \in \mathbb{G}$ , we have

$$\begin{aligned} |\mathcal{T}\mathcal{W}(\tau)| &= \left| \mathcal{W}_0 + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}(\Phi(\tau, \Omega(\tau))) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t \Phi(\zeta, \Omega(\zeta))d\zeta \right| \\ &\leq \mathcal{W}_0 + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}|\Phi(\tau, \Omega(\tau))| + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t \Phi(\zeta, \Omega(\zeta))d\zeta \\ &\leq \mathcal{W}_0 + \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}(g(\tau) + c_0k^\zeta) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t (g(\zeta) + c_0k^\zeta)d\zeta \\ &\leq \mathcal{W}_0 + \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}(g(\tau) + c_0k^\zeta) + \frac{2\varphi c_0k^\zeta t}{(2-\varphi)\mathbf{M}(\varphi)} + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t (g(\zeta))d\zeta \\ &\leq \mathcal{W}_0 + \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}g(\tau) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t (g(\zeta))d\zeta + \left( \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} + \frac{2\varphi t}{(2-\varphi)\mathbf{M}(\varphi)} \right) c_0k^\zeta \\ &\leq \mathcal{W}_0 + \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)}g(\tau) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^t (g(\zeta))d\zeta + \left( \frac{4(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} + \frac{2c_0k^\zeta}{\mathbf{M}(\varphi)} \right). \end{aligned}$$

Therefore,

$$\begin{aligned} \|\mathcal{T}\mathcal{W}(\tau)\|_{\mathbb{B}} &= \max_{t \in \Phi} |\mathcal{T}\mathcal{W}(\tau)| \\ &\leq l + \frac{2c_0k^\zeta}{\mathbf{M}(\varphi)} = l + Ac_0k^\zeta \leq \frac{k}{2} + \frac{k}{2} = k. \end{aligned}$$

Thus, the operator  $\mathcal{T}\mathcal{W}(\tau)$  is continuous on  $\Phi$ .

Next, suppose that the assumption ( $\mathcal{H}_2$ ) is also satisfied by selecting  $0 \leq k \leq \left(\frac{1}{Ac_0}\right)^{\frac{1}{\zeta-1}}$ . Take into account the same procedure as used above, we obtain

$$\|\mathcal{T}\mathcal{W}\|_{\mathbb{B}} \leq Ac_0k^\zeta \leq k.$$

Finally, we obtain  $\mathcal{T} : \mathbb{G} \rightarrow \mathbb{G}$  that the operator  $\mathcal{T}$  is continuous because of the continuity of  $\Phi$ .

Next, we prove that the operator  $T$  is continuous completely. Let  $R = \max_{t \in \Phi} |\Phi(\tau, \Omega(\tau))|$ , for any  $\Phi \in \mathbb{G}$ . Let  $(\tau_1), (\tau_2) \in \Phi$  such that  $(\tau_1) < (\tau_2)$ .

Also, let  $\Psi_1 = \frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}$  and  $\Psi_2 = \frac{2\varrho}{(2-\varrho)\mathbf{M}(\varrho)}$ , and we get

$$\begin{aligned} &|T\Phi(\tau_2) - T\Phi(\tau_1)| = |\mathscr{W}_0 + \Psi_1[\mathscr{W}(\tau_2, \Phi(\tau_2))] + \Psi_2 \int_0^{(\tau_2)} f(\zeta, u(\zeta))d\zeta \\ &- \mathscr{W}_0 - \Psi_1[\mathscr{W}(\tau_1, \Phi(\tau_1))] + \Psi_2 \int_0^{(\tau_2)} \mathscr{W}(\zeta, u(\zeta))d\zeta| \\ &= |\Psi_1[\mathscr{W}(\tau_2, \Phi(\tau_2)) - \mathscr{W}(\tau_1, \Phi(\tau_1))] + \Psi_2 \int_{(\tau_1)}^{(\tau_2)} \Phi(\zeta, u(\zeta))d\zeta| \\ &\leq \Psi_1 |\mathscr{W}(\tau_2, \Phi(\tau_2))| + \Psi_1 |\mathscr{W}(\tau_1, \Phi(\tau_1))| + \Psi_2 \int_{(\tau_1)}^{(\tau_2)} |\mathscr{W}(\zeta, u(\zeta))| d\zeta \\ &\leq 2R\Psi_1 + R\Psi_2 \int_{(\tau_1)}^{(\tau_2)} d\zeta = R(2\Psi_1 + \Psi_2((\tau_2) - (\tau_1))). \end{aligned}$$

According to uniform continuity of the function  $(\tau_2 - \tau_1)$  on interval  $\Phi$ , we prove that  $\mathcal{T}\mathbb{G}$  is an equicontinuous set. From the above theorems, we observe that this function is uniformly bounded as  $\mathcal{T}\mathbb{G} \subseteq \mathbb{G}$ ; therefore  $\mathcal{T}$  is completely continuous. So by using the Schauder FP theorem,  $\exists$  a solution of Equation (2) in the set  $\mathbb{G}$ .  $\square$

**Corollary 1.** Suppose a bounded continuous function be  $\mathscr{W}$  on  $\Phi \times \mathbb{R}$ , and then Equation (2) has a solution.

**Proof.** As we know that  $\mathscr{W}$  is continuous as well as bounded on  $\Phi \times \mathbb{R}$ ,  $\exists L > 0$ , satisfying  $|\mathscr{W}| < L$ . Consider  $h(\tau) = L, c_0 = 0$  in  $(\mathcal{H}_1)$  of 1, then the model (2) has a solution.

Next we use the Banach contraction principle to establish uniqueness results for solutions to (2).  $\square$

**Theorem 2.** Suppose that  $\mathscr{W} : \text{let } \Phi \times \mathbb{R} \rightarrow \mathbb{R}$  be a continuous function, which also satisfied the following conditions.

$(\mathcal{H}_3)$  Consider function  $h(\tau) \in L[0, 1]$  exists which is non-negative, such that

$$|\mathscr{W}(\tau)| \leq h |\Phi(\tau, \Omega(\tau))|, \quad t \in [0, 1].$$

In addition, function  $\mathscr{W}$  satisfies  $\mathscr{W}(0) = 0$

$(H_{\mathcal{H}})$  Consider that  $\zeta = \max_{t \in \Phi} |\frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}h(\tau) + \frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t |h(\zeta)|d\zeta| < 1$ , Then model (2) has a unique solution.

**Proof.** We represent the operator  $\mathcal{T}$  as

$$\mathcal{T}\mathscr{W}(\tau) = \mathscr{W}_0 + \frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}\Phi(\tau, \Omega(\tau)) + \frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t |\Phi(\zeta, u(\zeta))|d\zeta.$$

For  $\mathscr{W}(\tau) \in \mathbb{B}$ , we get

$$\begin{aligned} &|\mathcal{T}\mathscr{W}(\tau)| = |\mathscr{W}_0 + \frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}\Phi(\tau, \Omega(\tau)) + \frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t |\Phi(\zeta, u(\zeta))| d\zeta, \\ &\leq |\Phi| + |\frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}\Phi(\tau, \Omega(\tau))| + |\frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t |\Phi(\zeta, u(\zeta))| d\zeta \\ &\leq |\mathscr{W}_0| + \frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}h(\tau) |\mathscr{W}(\tau)| + \frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t h(\zeta) |u(\zeta)|d\zeta \\ &\leq |\mathscr{W}_0| + \left( \frac{2(1-\varrho)}{(2-\varrho)\mathbf{M}(\varrho)}h(\tau) + \frac{(2\varrho)}{(2-\varrho)\mathbf{M}(\varrho)} \int_0^t h(\zeta)d\zeta \right) \|u\|, \end{aligned}$$

and we have

$$\begin{aligned} & \| \mathcal{T}\mathcal{W}(\tau) \|_{B \leq} | \mathcal{W}_0 | + \left( \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} h(\tau) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau h(\zeta) d\zeta \right) \| u \| \\ & \leq | \Phi | + \zeta \| u \| \leq \| u \| . \end{aligned}$$

Let  $\mathcal{W}(\tau), v(\tau) \in \mathbb{B}$ , and then we have

$$\begin{aligned} & | \mathcal{T}\mathcal{W}(\tau) - \mathcal{T}v(\tau) | = | \mathcal{W}_0 + \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \Phi(\tau, \Omega(\tau)) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau | \Phi(\zeta, \Omega(\zeta)) | d\zeta \\ & - \mathcal{W}_0 - \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \Phi_1(\tau, \Omega_1(\tau)) - \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau | \Phi_1(\zeta, \Omega_1(\zeta)) | d\zeta | \\ & \leq \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} | \Phi(\tau, \Omega(\tau)) - \Phi_1(\tau, \Omega_1(\tau)) | + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau | \Phi(\zeta, \Omega(\zeta)) - \Phi_1(\zeta, \Omega_1(\zeta)) | d\zeta | \\ & \leq \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} | \mathcal{W}(\tau) - v(\tau) | + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau | \Omega(\zeta) - \Omega_1(\zeta) | d\zeta \\ & \leq \left( \frac{2(1-\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} h(\tau) + \frac{(2\varphi)}{(2-\varphi)\mathbf{M}(\varphi)} \int_0^\tau | h(\zeta) d\zeta \right) | \Omega(\zeta) - \Omega_1(\zeta) | \\ & \leq \Phi \| \Omega(\zeta) - v(\zeta) \| \leq \| \Omega(\zeta) - \Omega_1(\zeta) \| . \end{aligned}$$

In view of  $\zeta < 1$ ,  $\mathcal{T}$  is contraction. As a result,  $\mathcal{T}$  has only one fixed point according to the Banach contraction principle.  $\square$

#### 4. Analytical Results

Here, we investigate the analytical results. We apply Laplace transformation on both sides of model (2) as

$$\begin{aligned} \mathcal{L}({}^{CF}D_t^\varphi \mathbb{S}(t)) &= \mathcal{L} \left( \lambda - \frac{\alpha(\mathbb{I}_\beta(t) + \kappa \mathbb{I}_s(t) + u \mathbb{I}_O(t)) \mathbb{S}(t)}{N} - \nu \mathbb{S}(t) \right), \\ \mathcal{L}({}^{CF}D_t^\varphi \mathbb{E}(t)) &= \mathcal{L} \left( \frac{\alpha(\mathbb{I}_\beta(t) + \kappa \mathbb{I}_s(t) + u \mathbb{I}_O(t)) \mathbb{S}(t)}{N} - (\tau + \nu) \mathbb{E}(t) \right), \\ \mathcal{L}({}^{CF}D_t^\varphi \mathbb{I}_\beta(t)) &= \mathcal{L}(\tau \Psi \mathbb{E}(t) - (\Delta_1 + \nu) \mathbb{I}_\beta(t)), \\ \mathcal{L}({}^{CF}D_t^\varphi \mathbb{I}_s(t)) &= \mathcal{L}((1 - \Psi - \phi) \tau \mathbb{E}(t) - (\Delta_2 + \nu + \delta_1) \mathbb{I}_s(t)), \\ \mathcal{L}({}^{CF}D_t^\varphi \mathbb{I}_O(t)) &= \mathcal{L}(\phi \tau \mathbb{E}(t) - (\Delta_3 + \nu) \mathbb{I}_O(t)), \\ \mathcal{L}({}^{CF}D_t^\varphi \mathbb{R}(t)) &= \mathcal{L}(\Delta_1 \mathbb{I}_\beta(t) + \Delta_2 \mathbb{I}_s(t) + \Delta_3 \mathbb{I}_O(t) - \nu \mathbb{R}(t)). \end{aligned} \tag{5}$$

Using the initial condition, (5) yields

$$\begin{aligned} \mathcal{L}(\mathbb{S}(t)) &= \frac{\mathbb{S}(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L} \left( \lambda - \frac{\alpha(\mathbb{I}_\beta(t) + \kappa \mathbb{I}_s(t) + u \mathbb{I}_O(t)) \mathbb{S}(t)}{N} - \nu \mathbb{S}(t) \right), \\ \mathcal{L}(\mathbb{E}(t)) &= \frac{\mathbb{E}(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L} \left( \frac{\alpha(\mathbb{I}_\beta(t) + \kappa \mathbb{I}_s(t) + u \mathbb{I}_O(t)) \mathbb{S}(t)}{N} - (\tau + \nu) \mathbb{E}(t) \right), \\ \mathcal{L}(\mathbb{I}_\beta(t)) &= \frac{\mathbb{S}(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L}(\tau \Psi \mathbb{E}(t) - (\Delta_1 + \nu) \mathbb{I}_\beta(t)), \\ \mathcal{L}(\mathbb{I}_s(t)) &= \frac{\mathbb{I}_\beta(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L}((1 - \Psi - \phi) \tau \mathbb{E}(t) - (\Delta_2 + \nu + \delta_1) \mathbb{I}_s(t)), \\ \mathcal{L}(\mathbb{I}_O(t)) &= \frac{\mathbb{I}_s(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L}(\phi \tau \mathbb{E}(t) - (\Delta_3 + \nu) \mathbb{I}_O(t)), \\ \mathcal{L}(\mathbb{R}(t)) &= \frac{\mathbb{R}(0)}{s} + \frac{2(s + \varphi(1-s))}{s(2-\varphi)} \mathcal{L}(\Delta_1 \mathbb{I}_\beta(t) + \Delta_2 \mathbb{I}_s(t) + \Delta_3 \mathbb{I}_O(t) - \nu \mathbb{R}(t)). \end{aligned} \tag{6}$$



Now, we suppose the required solution in infinite series form as

$$\begin{aligned}
 \mathbb{S}(t) &= \sum_{n=0}^{\infty} \mathbb{S}_n(t), & \mathbb{E}(t) &= \sum_{n=0}^{\infty} \mathbb{E}_n(t), \\
 \mathbb{I}_{\beta}(t) &= \sum_{n=0}^{\infty} \mathbb{I}_{\beta n}(t), & \mathbb{I}_s(t) &= \sum_{n=0}^{\infty} \mathbb{I}_{sn}(t), \\
 \mathbb{I}_O(t) &= \sum_{n=0}^{\infty} \mathbb{I}_{On}(t), & \mathbb{R}(t) &= \sum_{n=0}^{\infty} \mathbb{R}_n(t).
 \end{aligned}
 \tag{7}$$

We use the Adomian polynomials to express the nonlinear term  $\mathbb{I}_O(t)\mathbb{S}(t)$  as

$$A_n(\mathbb{S}, \mathbb{I}_O) = \frac{1}{n!} \frac{d^n}{d\lambda^n} \left[ \sum_{\kappa=0}^n (\lambda^{\kappa} \mathbb{S}_{\kappa})(\lambda^{\kappa} \mathbb{I}_{O\kappa}) \right]_{\lambda=0}.
 \tag{8}$$

We compute some terms of the Adomian polynomials, which are presented as

$$\begin{aligned}
 n = 0 : & \quad A_0(\mathbb{S}, \mathbb{I}_O) = \mathbb{S}_0 \mathbb{I}_{O0}, \\
 n = 1 : & \quad A_1(\mathbb{S}, \mathbb{I}_O) = \mathbb{S}_0 \mathbb{I}_{O1} + \mathbb{S}_1 \mathbb{I}_{O0}, \\
 n = 2 : & \quad A_2(\mathbb{S}, \mathbb{I}_O) = \mathbb{S}_0 \mathbb{I}_{O2} + \mathbb{S}_1 \mathbb{I}_{O1} + \mathbb{S}_2 \mathbb{I}_{O0},
 \end{aligned}
 \tag{9}$$

and so on. The next part is moved to Appendix A.

The final series solution can be expressed as

$$\begin{aligned}
 \mathbb{S}_n &= \mathbb{S}_0 + \mathbb{S}_1 + \mathbb{S}_2 + \dots, & \mathbb{E}_n &= \mathbb{E}_0 + \mathbb{E}_1 + \mathbb{E}_2 + \dots, \\
 \mathbb{I}_{\beta n} &= \mathbb{I}_{\beta 0} + \mathbb{I}_{\beta 1} + \mathbb{I}_{\beta 2} + \dots, & \mathbb{I}_{sn} &= \mathbb{I}_{s0} + \mathbb{I}_{s1} + \mathbb{I}_{s2} + \dots, \\
 \mathbb{I}_{On} &= \mathbb{I}_{O0} + \mathbb{I}_{O1} + \mathbb{I}_{O2} + \dots, & \mathbb{R}_n &= \mathbb{R}_0 + \mathbb{R}_1 + \mathbb{R}_2 + \dots
 \end{aligned}
 \tag{10}$$

### 5. Numerical Simulation with Discussion

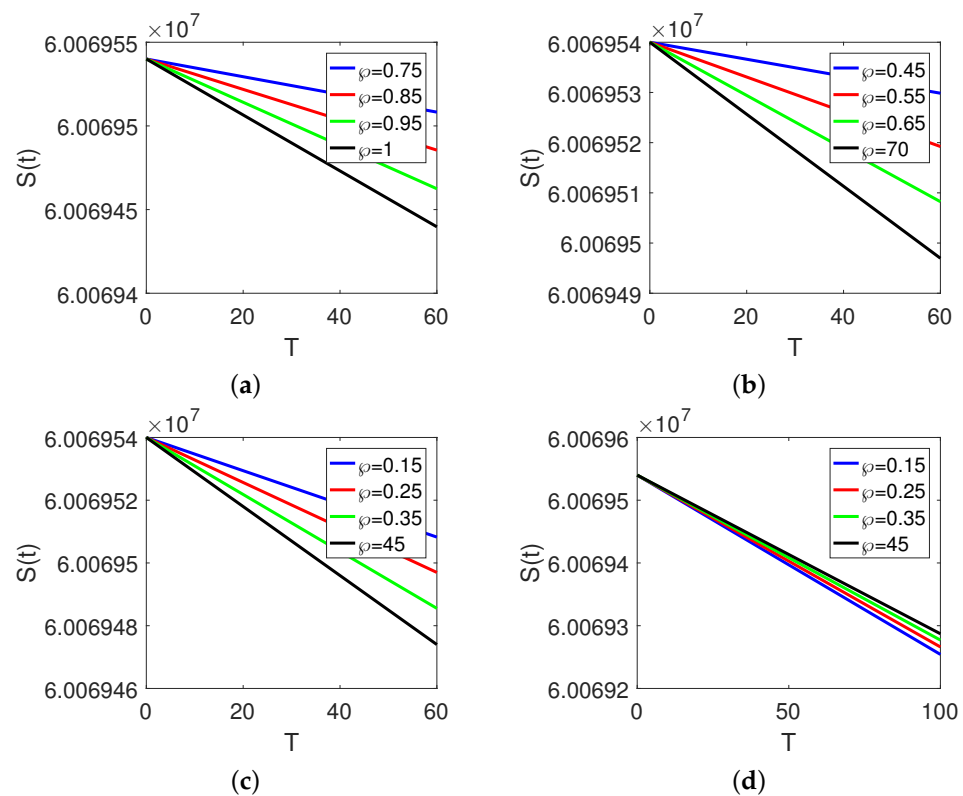
This section is devoted to the Caputo–Fabrizio derivative model numerical simulation representing the new Omicron virus. We simulate our model for three different fractional orders and time intervals. We take data from [14] for different parameters and compartment of the proposed model as given in Table 2.

**Table 2.** Initial and parameters numerical values for Omicron virus model [14].

Parameter	Value	Parameter	Value	Parameter	Value
$\mathbb{S}_0$	60,069,540	$u$	$\frac{1}{64.38 \times 365}$	$N$	60,140,000
$\mathbb{E}_0$	620,000	$\alpha$	0.7999	$\kappa$	0.7800
$\mathbb{I}_{\alpha(0)}$	8000	$\tau$	0.8999	$\Psi$	0.9566
$\mathbb{I}_{s(0)}$	360	$\phi$	0.0101	$\Delta_1$	0.8447
$\mathbb{I}_{O(0)}$	100	$\Delta_2$	0.0200	$\Delta_3$	0.6746
$\mathbb{R}_0$	0	$\delta_1$	0.0015		

In Figure 1a–d, we draw the dynamics of the susceptible population on three different fractional orders and different time durations. We also variate the step size in the first two graphs, showing that the curves are far away from each other in small step size and vice versa. The class showing decay is transferred to other agents of the system for all different fractional orders and time durations. The decay is greater at the low fractional order and lower at high fractional orders.





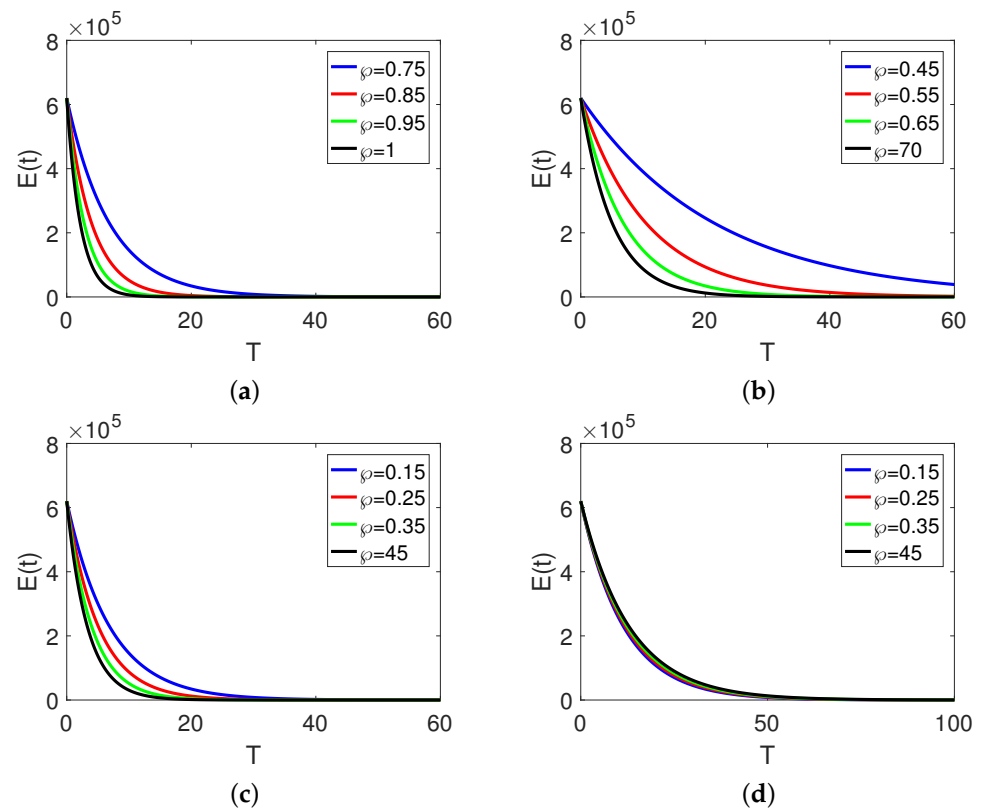
**Figure 1.** Dynamical behavior of susceptible individuals  $\mathbb{S}(t)$  at different arbitrary fractional order  $\varphi$  on  $[0, T]$ , for different times durations.

In Figure 2a–d, we draw the dynamical representation of the exposed population on three different fractional orders and different time durations. We also change the step size in the first two graphs showing that the curves are far away from each other in small step size and vice versa. This class also decreases as it transfers to other compartments of the model for all different fractional orders and time durations. The decrease is greater at low fractional order and lower at high fractional orders.

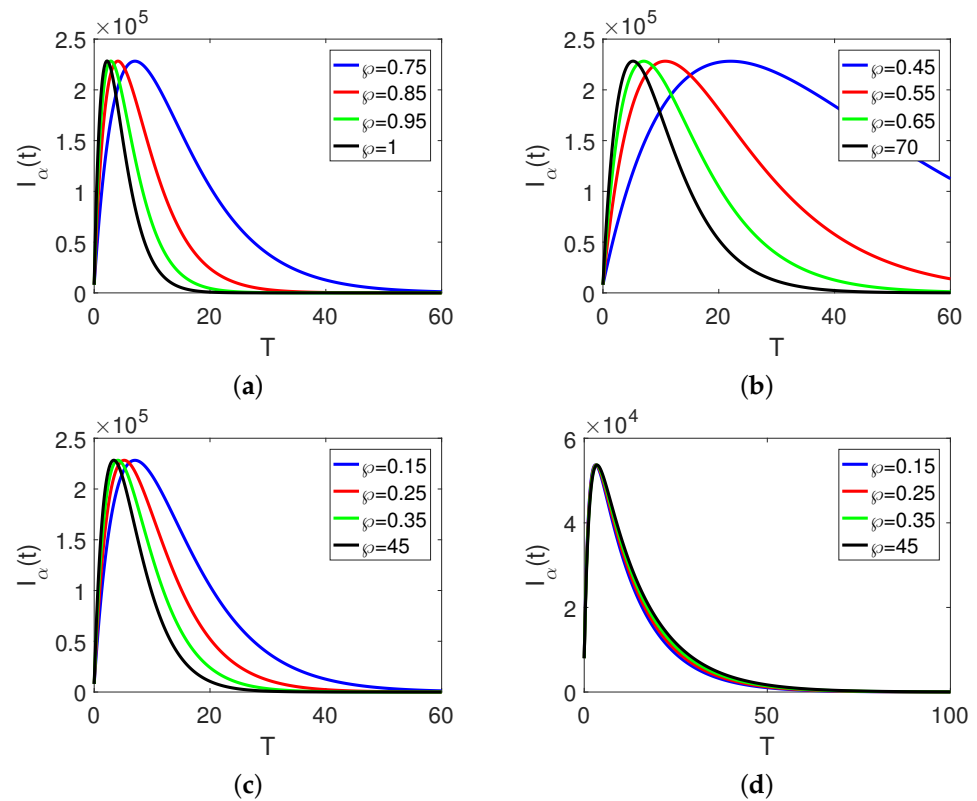
Figure 3a–d shows the dynamics of asymptomatic individuals on three different arbitrary orders and time durations. We also change the step size in the first two figures showing that the curves are far away from each other in small step size and vice versa. The population of the said class grows, and after reaching the peak value it declines along with bending at middle. The said class increases by transferring the population from first two classes to it. The increase is greater at high fractional order and lower at low fractional orders while the decrease is the reverse.

Figure 4a–d shows the dynamical behavior of symptomatic individuals on three different arbitrary orders and time durations for two subintervals showing bending behavior. We change the step size in the first two figures to know about the sensitivity of the model for step size. The population of the said class grows, and after reaching the maximum value it declines and turns at middle. The said class increases by transferring the population from first two classes to it. The increase is greater at high fractional order and lower at low fractional orders while the decrease is the reverse.

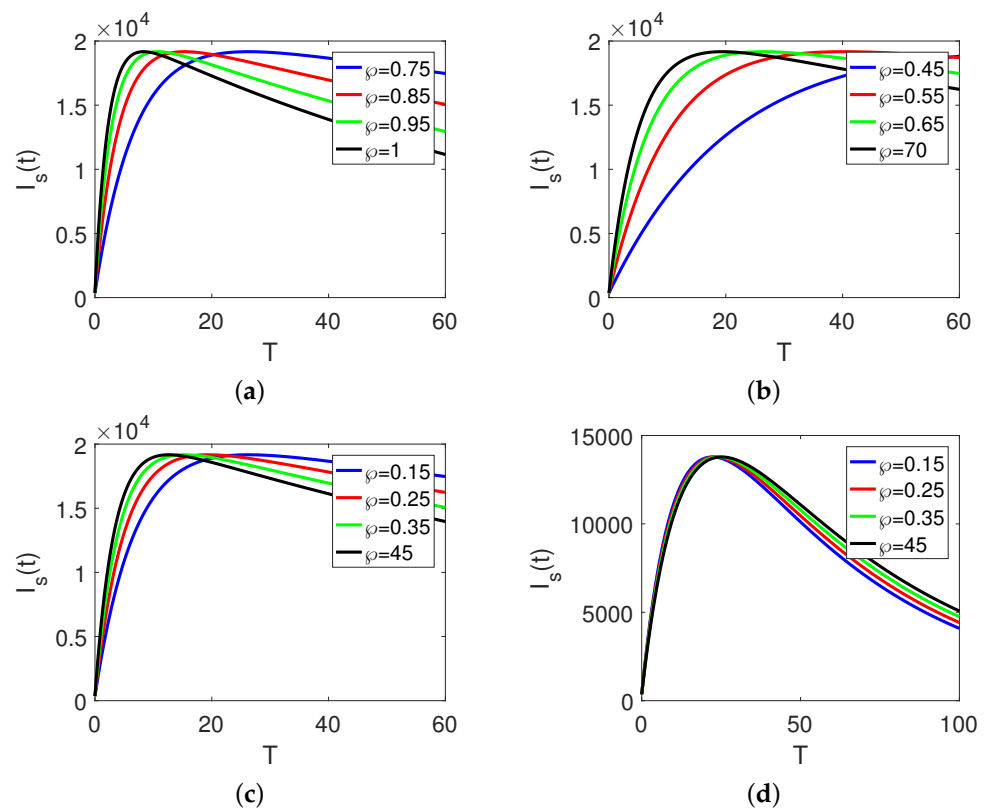
Figure 5a–d shows the dynamics of Omicron virus infected individuals on four different arbitrary orders and time durations. We change the step size in the first two figures to know about the sensitivity of it. The population of the said class grows and after reaching the maximum value it declines along decay properties at the middle and then stabilizes. The said class increased by transferring the population from first two classes to it in the form of infection caused by Omicron novel infection. The increase is greater at high fractional order and lower at low fractional orders while the decrease is the reverse. With passage of time, the class vanishes or is reduced to minimum or the controlled level.



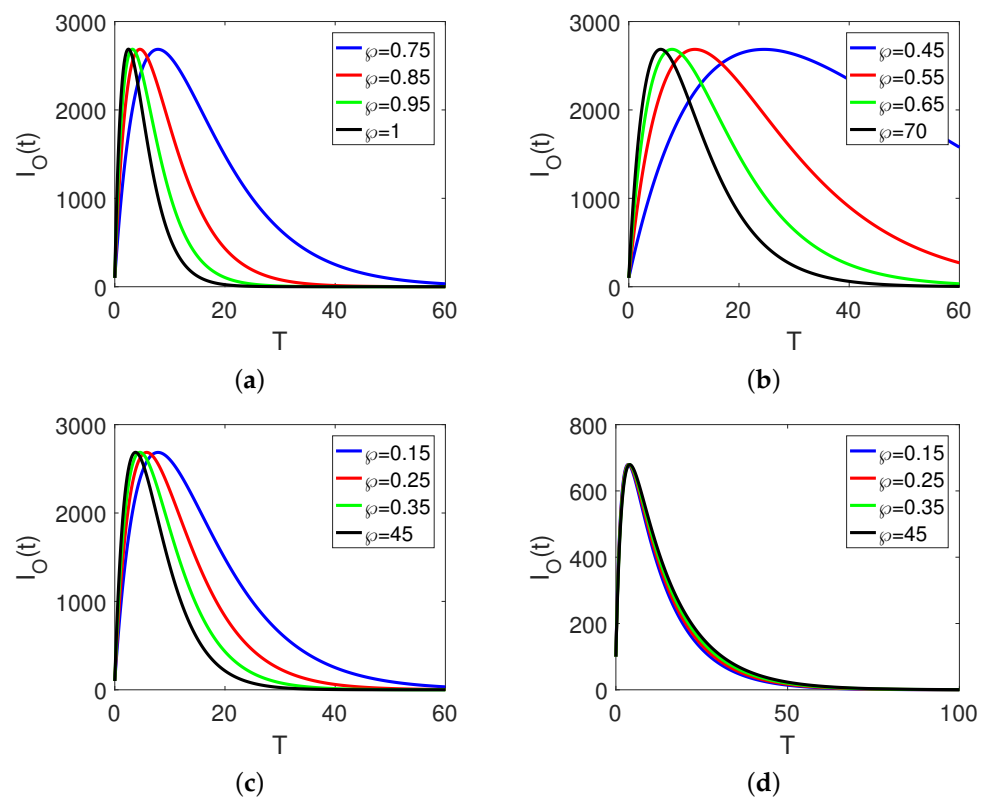
**Figure 2.** Dynamical behavior of exposed individuals  $\mathbb{E}(t)$  at different arbitrary fractional order  $\varphi$  on  $[0, T]$ , for different times durations.



**Figure 3.** Dynamical behavior of asymptomatic individuals  $\mathbb{I}_\alpha(t)$  at different arbitrary fractional order  $\varphi$  on  $[0, T]$ , for different time durations.

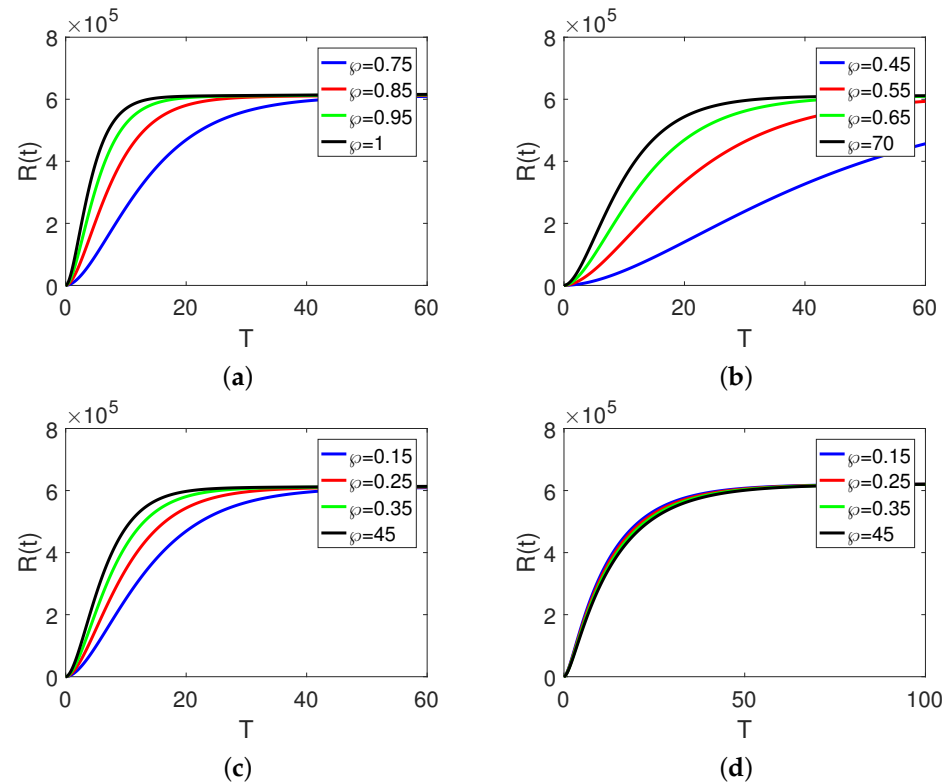


**Figure 4.** Dynamical behavior of symptomatic individuals  $I_s(t)$  at different arbitrary fractional orders  $\varphi$  on  $[0, T]$ , for different times durations.



**Figure 5.** Dynamical behavior of infection with Omicron virus  $I_O(t)$  at different arbitrary fractional orders  $r$  on  $[0, T]$ , for different times durations.

Figure 6a–d represents the dynamics of recovery from all types of infection given in the model on three different fractional orders and time durations showing the whole density dynamics. We also fluctuate the step size in the first two figures to know about its sensitivity. The said class grows, and after reaching the maximum value it become stable. The said class increases by transferring the population from all infection classes to it in the form of recovery. The increase is greater at a high fractional order and lower at low fractional orders while the decrease is the reverse.



**Figure 6.** Dynamical behavior of Recovered individuals  $\mathbb{R}(t)$  at different arbitrary fractional order  $\varphi$  on  $[0, T]$ , for different times durations.

## 6. Conclusions

We developed a scheme for the fractional dynamics of a non-integer order derivative model of Omicron virus infection by using modified Caputo–Fabrizio fractional operators in the investigated article. The dynamical analysis for the proposed model has been carried out on different fractional orders and time durations. With the help of this article, we will be able to give predictions about infection dynamics at different time intervals with different behaviors. The qualitative techniques for the considered model solution have been developed by using the concept of fixed point theory. In the modified Caputo–Fabrizio framework of order  $\varphi$ , the numerical solution for the model is evaluated using the Laplace Adomian decomposition procedure. The numerical simulation of all six compartments has been drawn for different data of fractional orders, step size, and time durations. This type of analysis can be applied to real-world dynamical phenomena where change or variation occurs. This investigation is a more realistic approach as the dynamics are changing differently at different time durations. Such an analysis describes the total property spectrum, which is very rarely given in both integer and fractional order deterministic and stochastic problems.

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**Appendix A**

Now, substituting Equation (7), and Equation (9) into Equation (6), we obtain

$$\begin{aligned}
 \mathcal{L}\left(\sum_{n=0}^{\infty} S_n(t)\right) &= \frac{S(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left(\lambda - \frac{\alpha(\sum_{n=0}^{\infty} \mathbb{I}_{\beta n} + \kappa \sum_{n=0}^{\infty} \mathbb{I}_{sn} + u \sum_{n=0}^{\infty} A_n(S, \mathbb{I}_O))}{N} - \nu \sum_{n=0}^{\infty} S_n\right), \\
 \mathcal{L}\left(\sum_{n=0}^{\infty} E_n(t)\right) &= \frac{E(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left(\frac{\alpha(\sum_{n=0}^{\infty} \mathbb{I}_{\beta n} + \kappa \sum_{n=0}^{\infty} \mathbb{I}_{sn} + u \sum_{n=0}^{\infty} A_n(S, \mathbb{I}_O))}{N} - (\tau + \nu) \sum_{n=0}^{\infty} E_n\right), \\
 \mathcal{L}\left(\sum_{n=0}^{\infty} \mathbb{I}_{\beta n}(t)\right) &= \frac{\mathbb{I}_{\beta}(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left(\tau \Psi \sum_{n=0}^{\infty} E_n - (\Delta_1 + \nu) \sum_{n=0}^{\infty} \mathbb{I}_{\beta n}\right), \\
 \mathcal{L}\left(\sum_{n=0}^{\infty} \mathbb{I}_{sn}(t)\right) &= \frac{\mathbb{I}_s(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left((1 - \Psi - \phi) \tau \sum_{n=0}^{\infty} E_n - (\Delta_2 + \nu + \delta_1) \sum_{n=0}^{\infty} \mathbb{I}_{sn}\right), \\
 \mathcal{L}\left(\sum_{n=0}^{\infty} \mathbb{I}_{On}(t)\right) &= \frac{\mathbb{I}_O(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left(\phi \tau \sum_{n=0}^{\infty} E_n - (\Delta_3 + \nu) \sum_{n=0}^{\infty} \mathbb{I}_{On}\right), \\
 \mathcal{L}\left(\sum_{n=0}^{\infty} R_n(t)\right) &= \frac{R(0)}{s} + \frac{2(s + \wp(1-s))}{s(2-\wp)} \mathcal{L}\left(\Delta_1 \sum_{n=0}^{\infty} \mathbb{I}_{\beta n} + \Delta_2 \sum_{n=0}^{\infty} \mathbb{I}_{sn} + \Delta_3 \sum_{n=0}^{\infty} \mathbb{I}_{On} - \nu \sum_{n=0}^{\infty} R_n a\right).
 \end{aligned} \tag{A1}$$

Comparing terms on both sides of the above equation, we get

$$\begin{aligned}
 \mathcal{L}(S_0) &= \frac{S(0)}{s}, \quad \mathcal{L}(E_0) = \frac{E(0)}{s}, \quad \mathcal{L}(\mathbb{I}_{\beta 0}) = \frac{\mathbb{I}_{\beta}(0)}{s}, \\
 \mathcal{L}(\mathbb{I}_{s0}) &= \frac{\mathbb{I}_s(0)}{s}, \quad \mathcal{L}(\mathbb{I}_{O0}) = \frac{\mathbb{I}_O(0)}{s}, \quad \mathcal{L}(R_0) = \frac{R(0)}{s}, \\
 \mathcal{L}(S_1) &= \Omega \mathcal{L}\left(\lambda - \frac{\alpha(\mathbb{I}_{\beta 0} + \kappa \mathbb{I}_{s0} + u A_0)}{N} - \nu S_0\right), \\
 \mathcal{L}(E_1) &= \Omega \mathcal{L}\left(\frac{\alpha(\mathbb{I}_{\beta 0} + \kappa \mathbb{I}_{s0} + u A_0)}{N} - (\tau + \nu) E_0\right), \\
 \mathcal{L}(\mathbb{I}_{\beta 1}) &= \Omega \mathcal{L}(\tau \Psi E_0 - (\Delta_1 + \nu) \mathbb{I}_{\beta 0}), \\
 \mathcal{L}(\mathbb{I}_{s1}(t)) &= \Omega \mathcal{L}((1 - \Psi - \phi) \tau E_0 - (\Delta_2 + \nu + \delta_1) \mathbb{I}_{s0}), \\
 \mathcal{L}(\mathbb{I}_{O1}(t)) &= \Omega \mathcal{L}(\phi \tau E_0 - (\Delta_3 + \nu) \mathbb{I}_{O0}), \\
 \mathcal{L}(R_1(t)) &= \Omega \mathcal{L}(\Delta_1 \mathbb{I}_{\beta 0} + \Delta_2 \mathbb{I}_{s0} + \Delta_3 \mathbb{I}_{O0} - \nu R_0 a), \\
 \mathcal{L}(S_2) &= \Omega \mathcal{L}\left(\lambda - \frac{\alpha(\mathbb{I}_{\beta 1} + \kappa \mathbb{I}_{s1} + u A_0)}{N} - \nu S_1\right), \\
 \mathcal{L}(E_2) &= \Omega \mathcal{L}\left(\frac{\alpha(\mathbb{I}_{\beta 1} + \kappa \mathbb{I}_{s1} + u A_0)}{N} - (\tau + \nu) E_1\right), \\
 \mathcal{L}(\mathbb{I}_{\beta 2}) &= \Omega \mathcal{L}(\tau \Psi E_1 - (\Delta_1 + \nu) \mathbb{I}_{\beta 1}), \\
 \mathcal{L}(\mathbb{I}_{s2}(t)) &= \Omega \mathcal{L}((1 - \Psi - \phi) \tau E_1 - (\Delta_2 + \nu + \delta_1) \mathbb{I}_{s1}), \\
 \mathcal{L}(\mathbb{I}_{O2}(t)) &= \Omega \mathcal{L}(\phi \tau E_1 - (\Delta_3 + \nu) \mathbb{I}_{O1}), \\
 \mathcal{L}(R_2(t)) &= \Omega \mathcal{L}(\Delta_1 \mathbb{I}_{\beta 1} + \Delta_2 \mathbb{I}_{s1} + \Delta_3 \mathbb{I}_{O1} - \nu R_1 a), \\
 &\vdots \\
 \mathcal{L}(S_{n+n}) &= \Omega \mathcal{L}\left(\lambda - \frac{\alpha(\mathbb{I}_{\beta n} + \kappa \mathbb{I}_{sn} + u A_0)}{N} - \nu S_n\right), \\
 \mathcal{L}(E_{n+n}) &= \Omega \mathcal{L}\left(\frac{\alpha(\mathbb{I}_{\beta n} + \kappa \mathbb{I}_{sn} + u A_0)}{N} - (\tau + \nu) E_n\right), \\
 \mathcal{L}(\mathbb{I}_{\beta n+n}) &= \Omega \mathcal{L}(\tau \Psi E_n - (\Delta_1 + \nu) \mathbb{I}_{\beta n}), \\
 \mathcal{L}(\mathbb{I}_{s(n+1)}(t)) &= \Omega \mathcal{L}((1 - \Psi - \phi) \tau E_n - (\Delta_2 + \nu + \delta_1) \mathbb{I}_{sn}), \\
 \mathcal{L}(\mathbb{I}_{O(n+1)}(t)) &= \Omega \mathcal{L}(\phi \tau E_n - (\Delta_3 + \nu) \mathbb{I}_{On}), \\
 \mathcal{L}(R_{n+n}(t)) &= \Omega \mathcal{L}(\Delta_1 \mathbb{I}_{\beta n} + \Delta_2 \mathbb{I}_{sn} + \Delta_3 \mathbb{I}_{On} - \nu R_n a),
 \end{aligned} \tag{A2}$$

where  $\Omega = \frac{2(s+\varphi(1-s))}{s(2-\varphi)}$ . Further, applying  $\mathcal{L}^{-1}$ , on both sides of the above equations, we get

$$\begin{aligned} S_0 &= S(0), E_0 = E(0), I_{\beta 0} = I_{\beta}(0), I_{s0} = I_s(0), I_{O0} = I_O(0), R_0 = R(0), \\ S_1 &= \Omega_1 \left( \lambda - \frac{\alpha(I_{\beta 0} + \kappa I_{s0} + u A_0)}{N} - \nu S_0 \right), \\ E_1 &= \Omega_1 \left( \frac{\alpha(I_{\beta 0} + \kappa I_{s0} + u A_0)}{N} - (\tau + \nu) E_0 \right), \\ I_{\beta 1} &= \Omega_1 (\tau \Psi E_0 - (\Delta_1 + \nu) I_{\beta 0}), \\ I_{s1}(t) &= \Omega_1 ((1 - \Psi - \phi) \tau E_0 - (\Delta_2 + \nu + \delta_1) I_{s0}), \\ I_{O1}(t) &= \Omega_1 \mathcal{L}(\phi \tau E_0 - (\Delta_3 + \nu) I_{O0}), \\ R_1(t) &= \Omega_1 \mathcal{L}(\Delta_1 I_{\beta 0} + \Delta_2 I_{s0} + \Delta_3 I_{O0} - \nu R_0 a). \end{aligned} \quad (A3)$$

More terms of the series can be calculated in the same way. Here  $\Omega_1 = \frac{2(1-\varphi+\varphi t)}{2-\varphi}$ .

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