

Proceeding Paper

# Refining IKONOS DEM for Dehradun Region Using Photogrammetry Based DEM Editing Methods, Orthoimage Generation and Quality Assessment of Cartosat-1 DEM <sup>†</sup>

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**Abstract:** The correct representation of the topography of terrain is an important requirement to generate photogrammetric products such as orthoimages and maps from high-resolution (HR) or very high-resolution (VHR) satellite datasets. The refining of the digital elevation model (DEM) for the generation of an orthoimage is a vital step with a direct effect on the final accuracy achieved in the orthoimages. The refined DEM has potential applications in various domains of earth sciences such as geomorphological analysis, flood inundation mapping, hydrological analysis, large-scale mapping in an urban environment, etc., impacting the resulting output accuracy. Manual editing is done in the presented study for the automatically generated DEM from IKONOS data consequent to the satellite triangulation with a root mean square error (RMSE) of 0.46, using the rational function model (RFM) and an optimal number of ground control points (GCPs). The RFM includes the rational polynomial coefficients (RPCs) to build the relation between image space and ground space. The automatically generated DEM initially represents the digital surface model (DSM), which is used to generate a digital terrain model (DTM) in this study for improving orthoimages for an area of approximately 100 km<sup>2</sup>. DSM frequently has errors due to mass points in hanging (floating) or digging, which need correction while generating DTM. The DTM assists in the removal of the geometric effects (errors) of ground relief present in the DEM (i.e., DSM here) while generating the orthoimages and thus improves the quality of orthoimages, especially in areas such as Dehradun that have highly undulating terrain with a large number of natural drainages. The difference image of reference, i.e., edited IKONOS DEM (now representing DTM) and automatically generated IKONOS DEM, i.e., DSM, has a mean difference of 1.421 m. The difference DEM (dDEM) for the reference IKONOS DEM and generated Cartosat-1 DEM at a 10 m posting interval (referred to as Carto10 DEM) results in a mean difference of 8.74 m.

**Keywords:** digital surface model; digital terrain model; difference DEM; rational function model; satellite triangulation; hanging (floating) mass points; digging mass points

## 1. Introduction

A digital elevation model (DEM) is the digital geometrical representation of elevation at a place (terrain), either in raster or vector form with regular or irregularly distributed points. DEM is often used as a generic term for elevation at a pixel and can refer to DSM and DTM as per the context or application [1–4]. The editing of a digital elevation model

is an important step in the production of an accurate topography for a region. Several automatic procedures have been developed over time; however, they are not able to match manually corrected DEMs. The disadvantage of manual corrections, on the other hand, includes the requirement of a trained work force, the cost, and high-end photogrammetric systems, in addition to time. However, for important tasks and study areas, still, manual corrections are the best option for achieving an accurate topography using photogrammetric techniques, which have the potential to affect the required application positively and improve results.

Application scientists and researchers have also explored the advantages with the improved DEMs for specific applications. Physically based GIS models, such as transient rainfall infiltration and grid-based regional slope stability (TRIGRS) using pore pressure calculations, computed the transient degradation of the hillslope stability due to rainfall infiltration to identify the landslide occurrences in Guwahati city. Significantly different outputs were obtained for the different DEMs tested in the experiment, highlighting the importance of analysis with different datasets [5]. The study showed that with an increase in slope by 1 degree, the initial factor of safety (FOS) against landslide triggering was reduced by 2.32% for a given soil material. Soil properties and rainfall intensity were found to be the primary factors controlling the instability of slopes due to rainfall, whereas the initial water table (WT) location and slope geometry plays a secondary role [6]. The source of the datasets is an important consideration, and at times, a finer resolution may not necessarily result in higher predictive accuracy due to artifacts and can have a significant influence on the accuracy of a landslide susceptibility analysis, as found in a study using the integration of AHP and the likelihood ratio (hybrid L-AHP) [7].

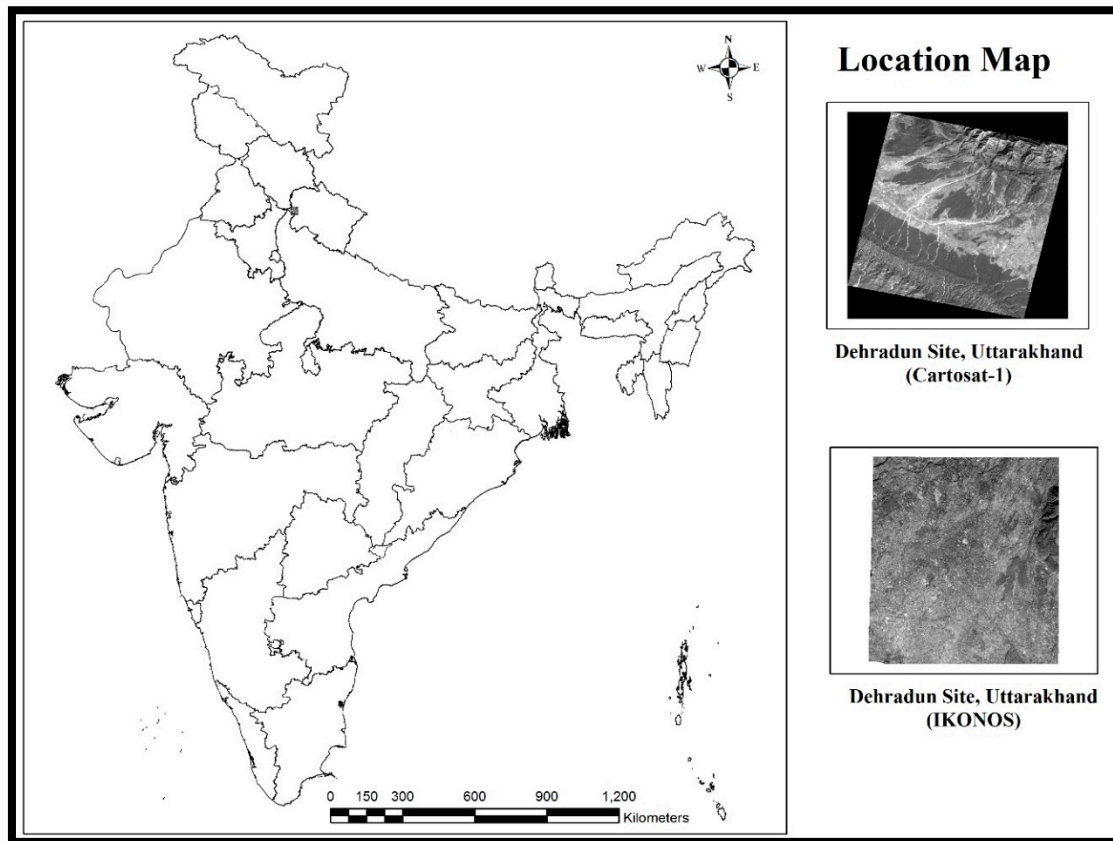
Researchers have attempted improvements in DEM using DEM fusion approaches and achieved significant accuracy through it at various experimental sites [8–13]. DEM fusion is also used for the generation of improved DEM at a global scale for various applications such as hydrological and flood analysis [11,12,14]. DEMs are used for monitoring and measuring gully erosion in geomorphologically unstable environments. Gully degradation rates measured based on DEMs are directly proportional to the square root of the gully area [15]. The mean water surface elevations (WSE) along the stream and the flood inundation area for five streams showed a strong positive linear relationship with DEM grid size under identical boundary conditions for all the sites [16]. Unmanned aerial vehicles (UAVs) and ground-based LiDAR solutions were used for DEM fusion using three methods available in the mosaic tool: ArcGIS (cover method, average method) and GRASS (MBlend method). The Cellular Automata Dual-DraInagE Simulation (CADDIES) model was used for the assessment of urban floods by the analysis of water depth and flow velocity to further estimate flood hazard along evacuation routes [17]. DEM and orthoimage maps provide basic layers for many geographic information system (GIS)-based analyses [18]. The present study showcases the DEM editing requirements for undulating terrain at Dehradun and improved representation of topography as a DTM for the experimental site. In addition, the present study aims to demonstrate the problems and quality assessment of automatically generated DEMs, which are DSMs generated as the primary product from the initial photogrammetric solutions.

## 2. Material and Methods

### 2.1. Study Area

The study area falls in the Dehradun district of Uttarakhand and covers a major part of Dehradun city, as shown in Figure 1. The site is marked with undulating terrain and has a dense drainage network, which is mostly seasonal. The area receives an average annual rainfall of about 207.3 cm. Dehradun is the provisional capital city of Uttarakhand state, India. It is located in Doon Valley, 260 km north of India's capital, New Delhi. The Dehradun site is characterized by highly rugged terrain comprising the Shivalik hills in the south and the higher Himalayas in the north, the River Ganga in the east, and the River

Yamuna in the west. In the south, it has plain agricultural fields. The forest area in the study site comprises Sal (dry deciduous), and mixed Sal (dry deciduous). The forest density in Dehradun site can be classified into various categories, namely, very dense forest (canopy density > 70%) and moderate dense forest (canopy density: 40%–70%). Some areas are open forest (canopy density: 10%–40%) and scrub (canopy density: <10%) [19].

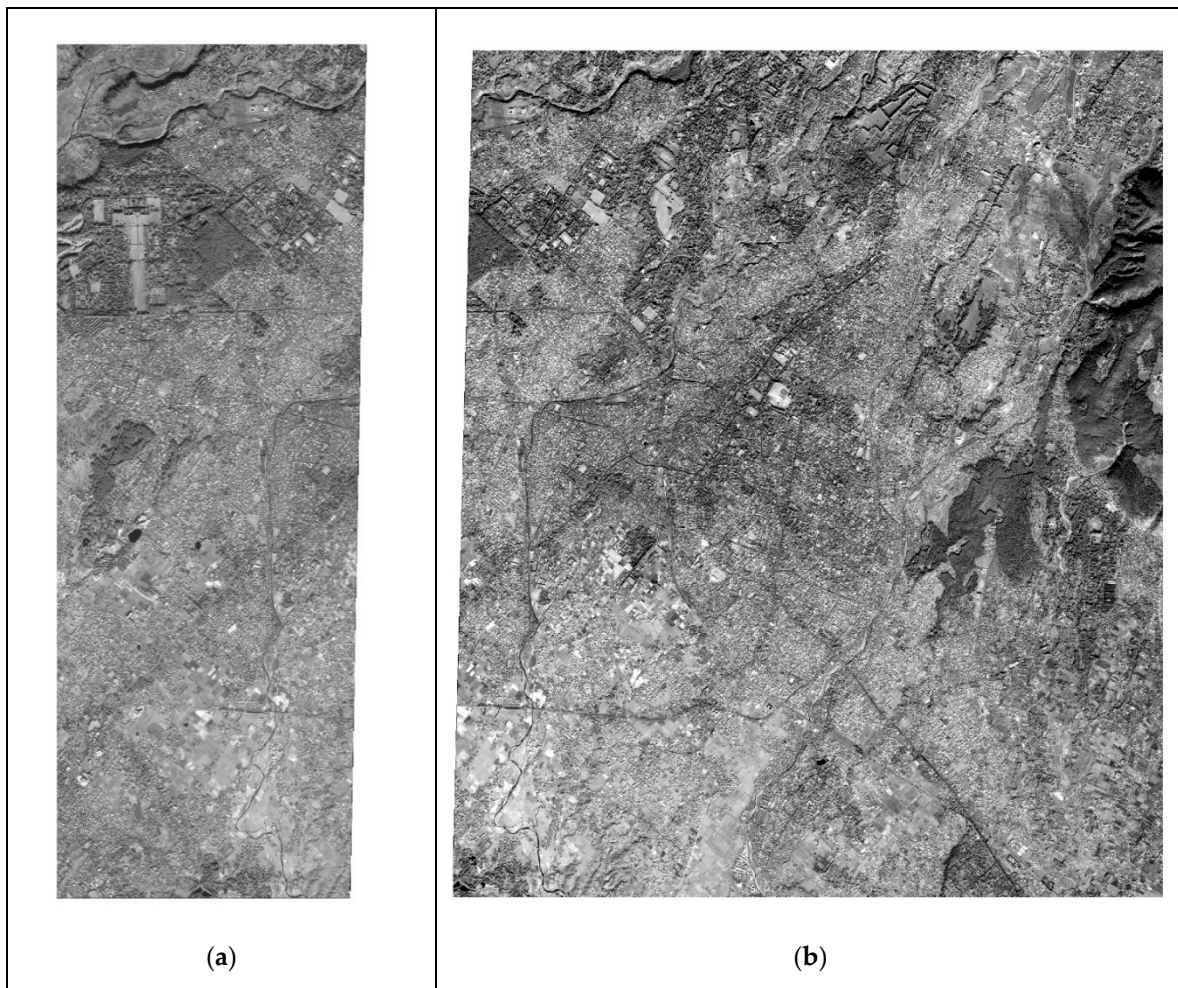


**Figure 1.** Location map of the experimental site.

## 2.2. Data Used

### 2.2.1. IKONOS-2 Geo Stereo

IKONOS-2, successfully launched by the United States on 24 September, 1999, was the first successful commercial remote sensing satellite that provided PAN stereo data with 1 m spatial resolution and 4 m multispectral data. The satellite was designed and built by Lockheed Martin Commercial Space Systems. The geometric models used for IKONOS basic imagery utilize the RFM, with RPCs distributed by the Space Imaging Company. The spacecraft provides precision pointing to an ultra-stable highly agile platform, giving it an excellent observation capability for the acquisition of VHR images (Table 1). IKONOS has 3800 pixels generating a swath width of 11.3 km in the case of a nadir view, with original pixel size on the ground of a spatial resolution of 82 cm [20,21]. Figure 1 shows the standard geometrically corrected Geo stereo product scenes of IKONOS-2 stereopairs (one each) with respective image IDs. The area of interest (AOI) was covered in two IKONOS-2 stereopairs, so the area covered by Figure 2a,b covers different regions as per the AOI, with a total area of 100 km<sup>2</sup>. A total of 100 km<sup>2</sup> was also the minimum data order size required for procurement of IKONOS stereo data.



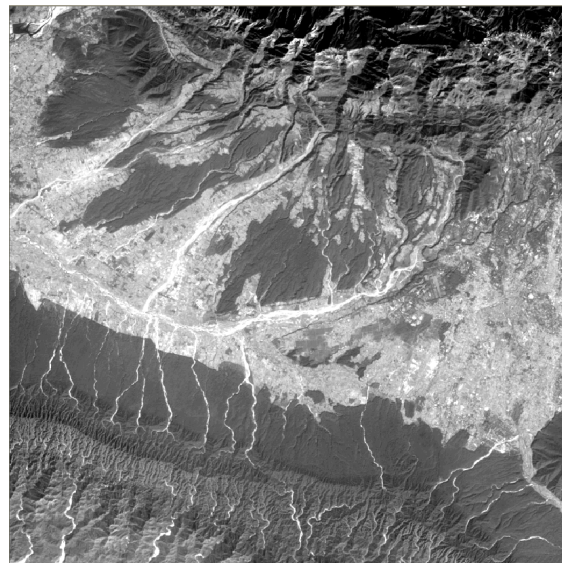
**Figure 2.** IKONOS-2 stereopair images (one each): (a) Scene 1 (source image ID: 201011260533456000011608311) and (b) Scene 2 (source image ID: 201011260533110000011608312).

**Table 1.** Specification of the IKONOS satellite.

Product	Specifications
Altitude	681 km
Orbit	Sun-synchronous orbit
Nodal crossing	10:30 a.m.
Spectral range	450–900 nm
Dynamic range	11 bits per pixel
Swath	11.3 km (at nadir)
Slew rate	10 s to slew 200 km
Data acquisition	51 × 112 km maximum mono collection per pass (5 strips) 11 × 120 km maximum stereo collection per pass (1 pair)
Datum	WGS84
Ellipsoid	WGS84

### 2.1.2. Cartosat-1 Stereopair

Cartosat-1, launched on 5 May, 2005, was the first Indian satellite capable of providing in-orbit along-track stereoscopic images and was designed for applications such as cartography, terrain modelling, natural resource management, and large-scale mapping. The Cartosat-1 image covering the Dehradun site is shown in Figure 3 and the specifications of Cartosat-1 are shown in Table 2.



**Figure 3.** Cartosat-1 image for the Dehradun site.

**Table 2.** Specifications of CARTOSAT-1 satellite and scene description of the stereopair.

Study Area	Dehradun Site	
Imaging mode	Stereo	Stereo
Processing level	STD (Standard Geometrically Corrected)	
Product ID	065121300101	065121300102
Product type	Orthokit	Orthokit
Image format	GeoTIFF	GeoTIFF
Date of acquisition	05 Feb.2006	05 Feb.2006
Image type (sensor)	PAN	PAN
Time	05:34:44:1560	05:35:36:2857
Orbit number	4091	4091
Stereo position	FORE	AFT
Path-row	0526–0258	0526–0258
SceneCenterLat	30.35142241	30.35141408
SceneCenterLon	77.91655232	77.91245328
Swath		30 km
Dynamic range		10 bits
Ellipsoid		WGS84
Datum		WGS84
Interpolation method	Cubic convolution	

**2.3. Toposheets**

Survey of India (SOI) toposheets, namely, 53F/15, 53F/16, 53J/3, and 53J/4, were used for the fieldwork and analysis during the study.

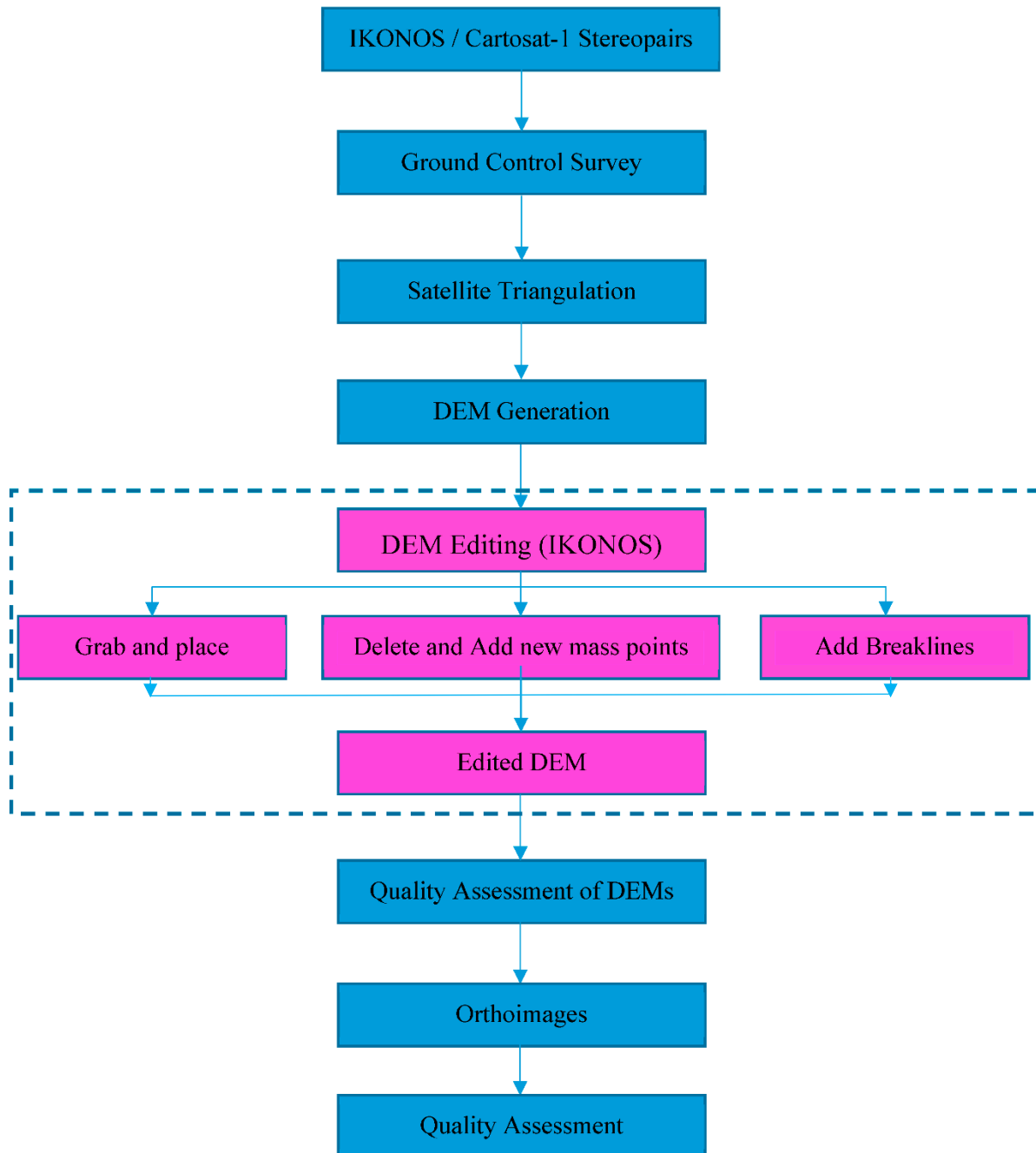
**2.4. GPS Data**

Differential GPS data were collected through field surveys using Leica 500 series and Trimble R7 GNSS receivers.

**3. Methodology**

Satellite triangulation was conducted using five (optimal) GCPs providing control at the periphery (corners) and near the center of stereopair along with the RPCs, resulting in a root mean square error (RMSE) of 0.46. The manual editing of the DEM was performed in the interactive terrain editor (ITE) of the Leica Photogrammetric Suite (LPS) software. The main steps are shown in Figure 4. Mainly three methods were used in ITE for DEM

correction: (a) grabbing and placing the mass point at the correct place on the terrain, (b) deletion of floating/digging mass points and placing the new mass points on the correct place over the terrain, and (c) break lines being added at locations of steep changes in elevation.



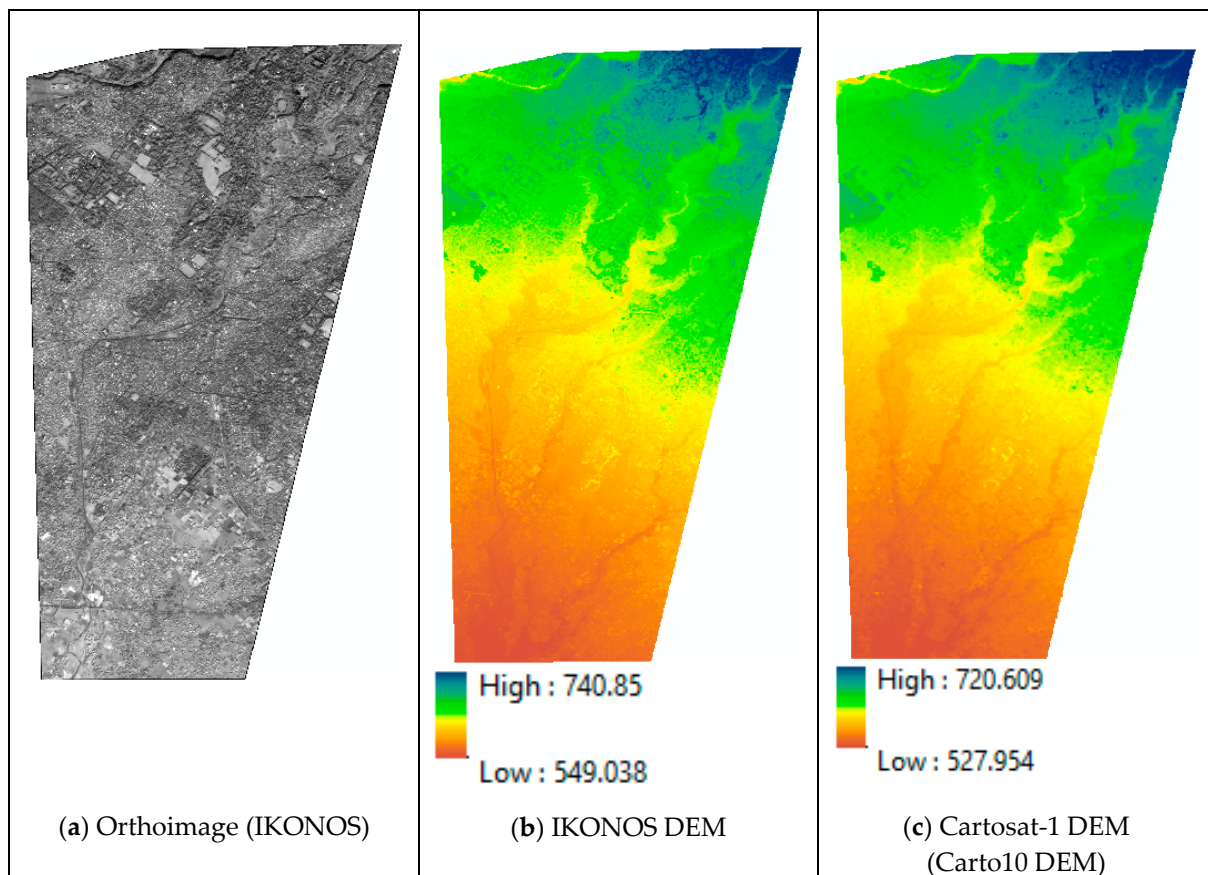
**Figure 4.** Photogrammetric methodology used for satellite triangulation, DEM, and orthoimage generation.

The quality assessment of automatically generated DEMs from IKONOS and Cartosat-1 stereopairs was done with respect to the reference DEM generated through manual editing of IKONOS DEM.

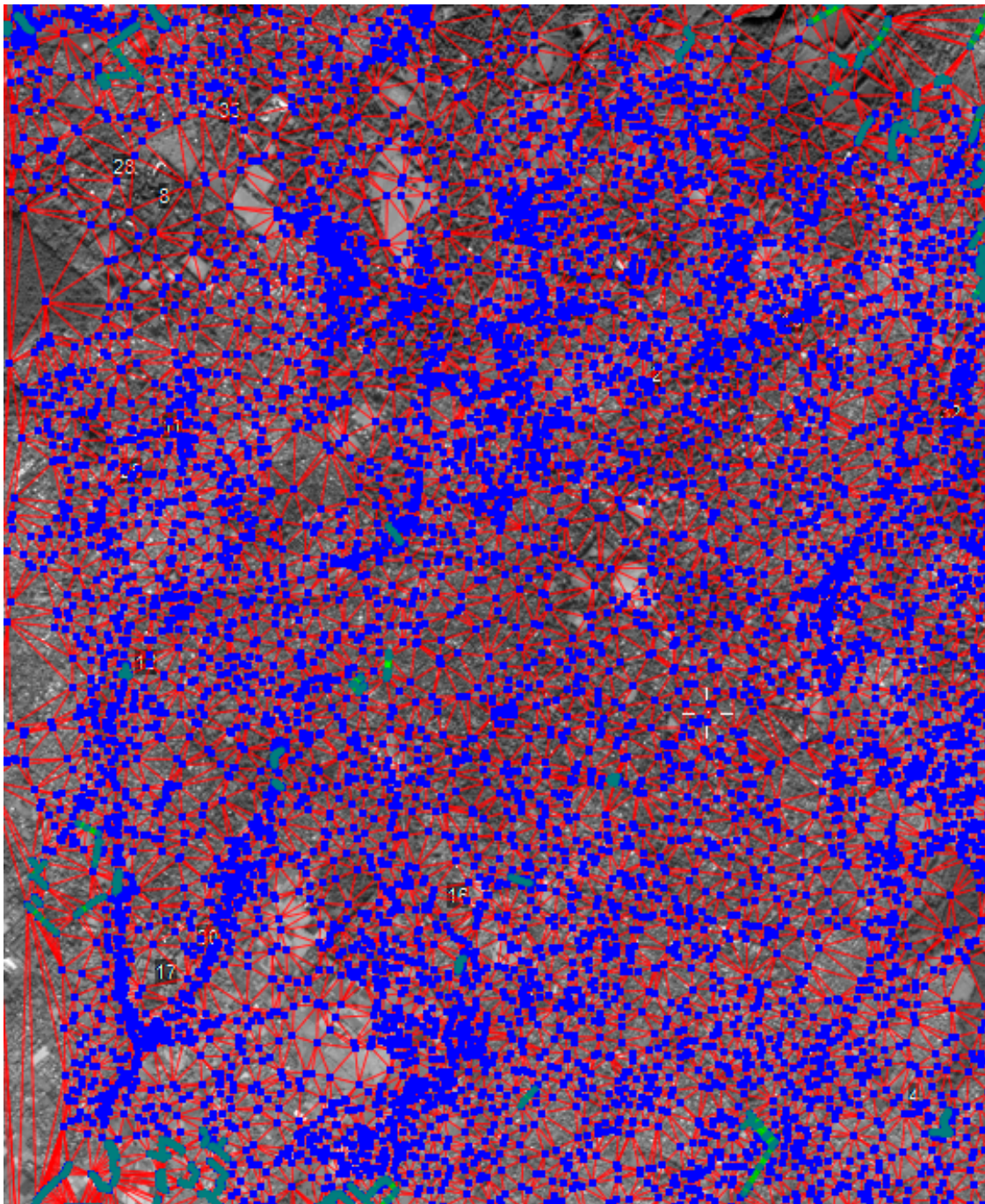


#### 4. Results and Discussion

A subset of the DEM generated from Cartosat-1 stereo data (RMSE = 0.7) was prepared for the common area with IKONOS DEM. Figure 5 shows the subsets of the IKONOS orthoimage as well as the corresponding DEMs generated from Cartosat-1 (Carto10 DEM) and IKONOS-2 datasets for the common area. Mass points are shown by blue dots in Figure 6, where a large amount of editing can be observed around the drainage features in the stereo environment of ITE in the LPS software. Corrections were done manually to remove erroneous (floating and digging) mass points. Additional mass points and break lines were added to represent the terrain correctly. The mass points constituting the triangular irregular network (TIN) depicting the facets on the ground are shown by the vertices of the triangles formed by the red-colored lines in Figure 6. The difference image of the reference IKONOS DEM and the automatically generated IKONOS had a mean difference of 1.421 m, whereas the difference DEM (dDEM) for the reference IKONOS DEM and Carto10 DEM had a mean difference of 8.74 m [22,23]. The mean difference between the DSMs of IKONOS and Cartosat-1 was approximately 7.32 m.



**Figure 5.** (a) Orthoimage for the reference DEM site, and comparison of (b) reference data (IKONOS DEM) with (c) Cartosat-1 data.

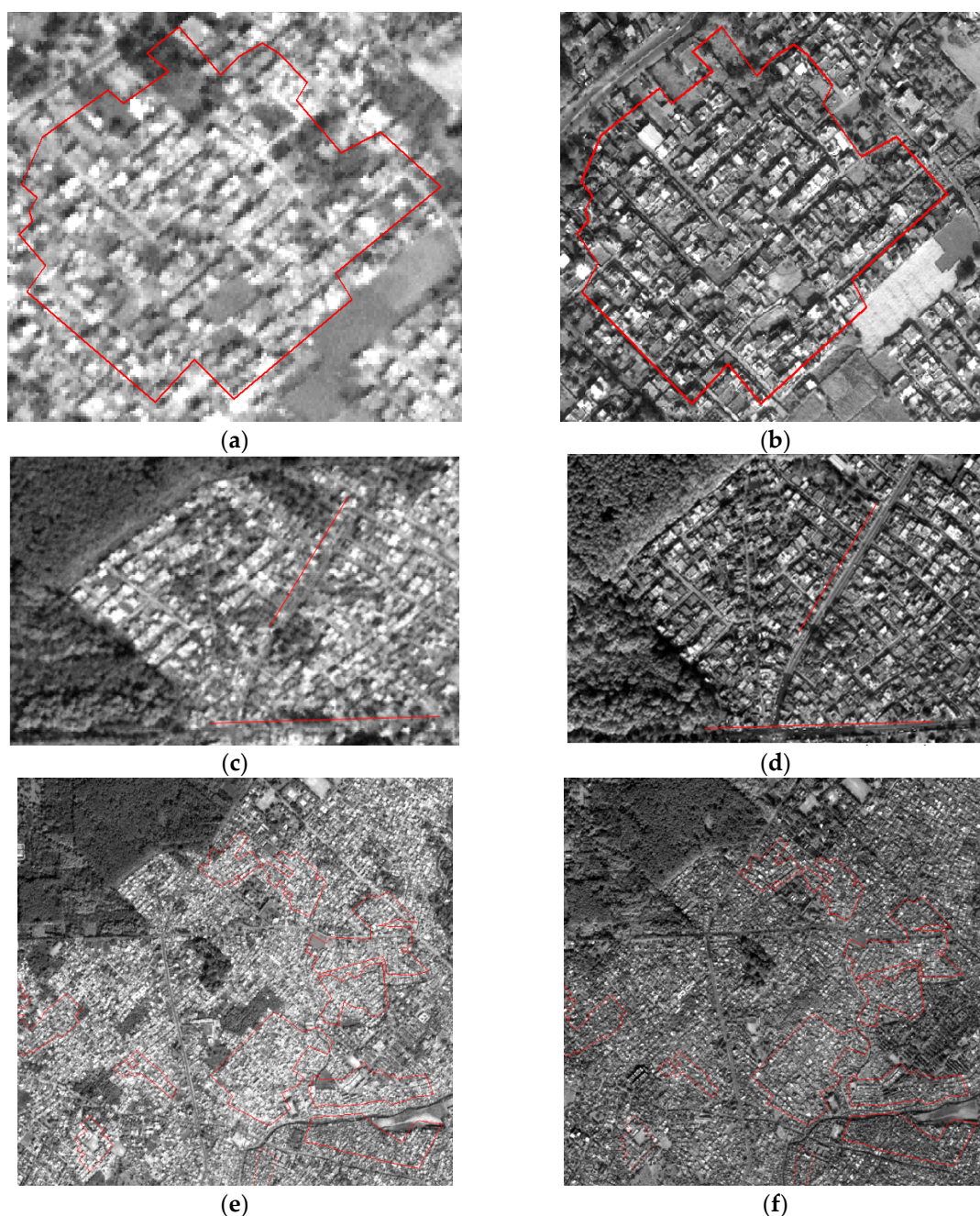


**Figure 6.** Screenshot of manual editing carried out in the Interactive Terrain Editor (ITE, LPS). The mass point, break lines, and TIN are visible in the figure on (overlaid) the IKONOS image in the stereo.

The effect of spatial resolution on optical remote sensing datasets is shown in Figure 7. The features in the IKONOS images with 1 m spatial resolution (11-bit dynamic range) were much clearly visible than the features in the Cartosat-1 data with 2.5 m spatial resolution (10-bit dynamic range). The boundary of the features and thus the transitional boundaries between two features or land use land cover (LULC) classes were more discernible in the VHR dataset, i.e., the IKONOS images as compared to the HR Cartosat-1 dataset, due to both higher spatial resolution and the dynamic range of IKONOS data. The higher spatial resolution, as well as the dynamic range of the IKONOS data, directly affected the contrast and improved image matching required for conjugate or homologous point selection while computing the parallax difference as part of height measurement. This shows a clear advantage for VHR data over HR data during the photogrammetric



processing and generation of resulting products, such as DEM and orthoimages. The quality assessment of the orthoimages showed improved matching while overlaying the orthoimages generated from the left and the right images due to the removal of ground relief in the DEM editing process and reduced haziness or stretching effects. The accuracies of the DEMs and orthoimages generated from satellite-based stereo datasets can be further improved significantly by the use of more well-distributed GCPs [9] strengthening the bundle lock adjustment as part of the satellite triangulation. This can further affect the applications significantly, which are influenced by the accuracy of the DEM.



**Figure 7.** Effect of spatial and spectral resolution on (a) an urban region (Cartosat-1), (b) an urban region (IKONOS), (c) a road (Cartosat-1), (d) a road (IKONOS), (e) an urban area (Cartosat-1), and (f) an urban area (IKONOS).

The study shows that the IKONOS-2 and Cartosat-1 data generate reasonably good DEMs, which can also be assessed using GCPs [9,24]. However, the quality of automatically generated DEMs needs manual editing for improvement due to the presence of mass

points in digging and floating. The mass points present in DEMs are due to contrast issues in optical data (stereopair) and require manual editing for necessary corrections. Figure 7 showcases the effect of spatial and spectral resolution in LULC, namely, (a) an urban region, (b) a road, and (c) an urban area across the LULC transition lines. Figure 7a,b, when seen with DSM in ITE, shows the mass points transiting from tree canopy to the adjoining urban building areas in a hanging (floating) state and thus requires manual corrections. Similar hanging and digging mass points are available in regions shown in Figure 7, which were manually corrected for the generation of the reference DEM from the IKONOS stereopair.

## 5. Conclusions

The study demonstrates and concludes that the use of edited DEMs results in the generation of geometrically improved orthoimages from IKONOS data. It was observed from the 3D visualization of an overlaid DEM on a stereoview that hanging mass points and digging mass points pose challenges in the correction or improvement of DEMs. This can be observed clearly from the visual interpretation of the generated improved orthoimages. Secondly, the edited DEM is used for quantitative assessment of the mean difference in the DEM generated from IKONOS as well as Cartosat-1 stereopairs, where the effect of spatial resolution and dynamic range is observed clearly. The study also reveals that the spatial and spectral resolution of IKONOS and Cartosat-1 datasets affect photogrammetric procedures directly, such as GCP marking/pointing, image matching, parallax computation, satellite triangulation, DEMs, and orthoimage generation.

**Author Contributions:** A.B., K.J., and R.S.C. conceived and designed the experiments; A.B. performed the experiments; A.B., K.J., and R.S.C. analyzed the data; A.B., K.J., and R.S.C. contributed materials and analysis tools; A.B. wrote the paper. All authors have read and agreed to the published version of the manuscript.

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