

Special Issue

Motion Planning and Control of Robot Systems

Message from the Guest Editors

As various types of robots begin to be applied in industry and human life, research on systematic approaches for robot motion planning and control has been in progress in recent years. This Special Issue is devoted to coverage of motion planning and control for robotic systems in different applications. Original papers and survey papers are welcome. Topics of interest for this collection include but are not limited to:

- motion planning
- control algorithm
- force/torque control
- robust control
- manipulators
- mobile robotics
- multirobot systems

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