Special Issue

Soft Robotics

Message from the Guest Editor

The approach to take inspiration from nature and use soft deformable and variable stiffness technologies represents an innovative trend in robotics, which has generated new branches, such as bioinspired robotics and soft robotics, respectively. The integration of functions and the hybrid assembly of soft materials represent key aspects for achieving autonomous soft robots. Soft robotics is still taking its first steps, but it has already driven promising robotics application scenarios, which include biomedical, service, inspection, search-and-rescue, exploration, opening new perspectives for improving wellness and quality of life. We invite authors to submit original research and review articles, which stimulate the continuing efforts to understand and improve knowledge in this field.

Guest Editor

Dr. Barbara Mazzolai

Bioinspired Soft Robotics (BSR), Istituto Italiano di Tecnologia (IIT), Via Morego 30, 16163 Genova, Italy

Deadline for manuscript submissions

closed (31 July 2018)



an Open Access Journal by MDPI

Impact Factor 3.4 CiteScore 3.5 Indexed in PubMed



mdpi.com/si/8643

Biomimetics
MDPI, Grosspeteranlage 5
4052 Basel, Switzerland
Tel: +41 61 683 77 34
biomimetics@mdpi.com

mdpi.com/journal/biomimetics





an Open Access Journal by MDPI

Impact Factor 3.4
CiteScore 3.5
Indexed in PubMed



About the Journal

Message from the Editor-in-Chief

Editor-in-Chief

Prof. Dr. Stanislav N. Gorb

Department of Functional Morphology and Biomechanics, Zoological Institute, Kiel University, 24118 Kiel, Germany

Author Benefits

High Visibility:

indexed within Scopus, SCIE (Web of Science), PubMed, PMC, CAPlus / SciFinder, and other databases.

Journal Rank:

JCR - Q1 (Engineering, Multidisciplinary) / CiteScore - Q2 (Biomedical Engineering)

Rapid Publication:

manuscripts are peer-reviewed and a first decision is provided to authors approximately 19.5 days after submission; acceptance to publication is undertaken in 2.8 days (median values for papers published in this journal in the second half of 2024).

