

Special Issue

Dynamics Modeling and Conceptual Design of UAVs

Message from the Guest Editors

This Special Issue aims to collect papers (original research articles and review papers) to give insights into new developments in dynamic modeling and conceptual design of advanced UAVs. Potential topics include but are not limited to aerodynamic modeling of UAVs, system identification and parameter estimation of UAVs, development of control strategies for UAV stabilization and control, multi-disciplinary design optimization of UAVs, and design and analysis of novel UAV concepts and configurations. The contributions include but not limited to:

- Aerodynamic modeling of UAVs;
- System identification and parameter estimation of UAVs;
- Development of control strategies for UAV stabilization and control;
- Multi-disciplinary design optimization of UAVs;
- Design and analysis of novel UAV concepts and configurations.

We look forward to receiving your original research articles and reviews. Prof.

Guest Editors

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About the Journal

Message from the Editor-in-Chief

Drones is the only international open-access journal about the science, policy and technology of drones and its applications. Nowadays, the proliferation of drones is a reality for local policy makers, regulatory bodies, mapping authorities, startups and consolidated companies. There are many uses and benefits of drones: from the emergence of new sensors and the evolution of new platforms; to the development of specific software and the emergence of new applications. *Drones* publishes reviews, regular research papers, communications and short notes, without restriction on the length of papers. *Drones* seeks to provide a central forum for scholars engaged in drones' research and applications.

There is a need for high quality papers in this area and the *Drones* Editorial Board are widely recognized international leaders. *Drones* journal guarantees a serious peer review and a rapid publication across the whole discipline of drones.

Editor-in-Chief

Prof. Dr. Diego González-Aguilera

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