

Special Issue

Gyroscopes and Accelerometers

Message from the Guest Editors

Inertial sensors, such as gyroscopes and accelerometers, are important components of inertial measurement units (IMUs). Inertial sensors provide an output that is proportional to angular velocity or angular acceleration. The output signal is corrupted by additive noise plus a random drift component. Many modeling, sensor fusion and calibration techniques are used to estimate and remove sensor bias. The objective of this Special Issue is to present significant work in this field. Papers will address wide range of applications such as gyroscope and accelerometer error modeling, modeling of array of low-cost sensors, calibration, bias estimation with Kalman filter or other techniques, GPS and/or other long-term bias-free integration methods with IMUs.

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Deadline for manuscript submissions

closed (20 September 2019)



Sensors

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CiteScore 7.3
Indexed in PubMed



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Sensors is a leading journal devoted to fast publication of the latest achievements of technological developments and scientific research in the huge area of physical, chemical and biochemical sensors, including remote sensing and sensor networks. Both experimental and theoretical papers are published, including all aspects of sensor design, technology, proof of concept and application. *Sensors* organizes Special Issues devoted to specific sensing areas and applications each year.

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