# **Special Issue**

## Mobile Laser Scanning Systems

## Message from the Guest Editors

Three-dimensional data is a fundamental and essential part of a growing number of applications ranging from urban planning, cultural heritage documentation, intelligent transportation systems, autonomous driving, smart cities, to indoor/outdoor disaster simulation. Mobile laser scanning systems (including airborne, vehicle-borne, handheld and backpack systems), which provide geo-referenced high-density 3D point cloud data, have become an alternative powerful data source of 3D geospatial information. This Special Issue not only covers the traditional remaining challenges (multisensor calibration, multisource data registration, and 3D point cloud processing) in mobile laser scanning systems, but also focuses on solutions, methods and algorithms for low-cost sensor integration and mobile localization and mapping in GNSS-denied environments. Prof. Dr. Ayman Habib

## Guest Editors

Prof. Dr. Jonathan Li

Prof. Dr. Ayman F. Habib

Dr. Chenglu Wen

Deadline for manuscript submissions closed (31 July 2019)



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## Message from the Editor-in-Chief

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### Editor-in-Chief

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